CSE 306 Operating Systems Memory Management

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Memory Management

- In uniprogramming environment
 - Main memory is divided into OS and another program
- In multiprogramming environment
 - The user part of memory is further divided for multiple processes
- Memory management
 - The task of dynamically subdividing memory performed by OS



- Relocation
- Protection
- Sharing
- Logical organization
- Physical organization



Relocation

- We cannot know where a program will be placed ahead of time
 - Programmers cannot know which other programs will be resident in main memory when their programs are being executed
- We must allow that programs may be moved in main memory
 - When a program is swapped back in, it may be placed in a memory region different than when it was swapped out



- RelocationOS needs to manage
 - Location of PCB
 - Stack
 - Program entry point
 - Memory references for branch operations and data





Protection

- Normally, a user process should not access OS's program nor data
- Without an agreement, a process should not access other processes' memory area
- Memory protection should be provided by HW rather than OS
 - It will be prohibitively time consuming to check each memory access



- Sharing
 - Allow several processes to access the same portion of memory
 - Processes executing the same program can share the same code rather than having their own copy
 - Collaborating processes can share the same data structure



- Logical organization
 - Most main memory in a computer system is organized as a linear (one-dimensional) address space
 - Most programs are organized into modules
 - Some of which are unmodifiable (read only, execution only)
 - Some of which contain modifiable data
- Desirable system capabilities
 - Memory references among modules are resolved at runtime
 - Different degrees of protection to different modules (read only, execution only)
 - Modules can be shared among processes



- Physical organization
 - Computer memory is organized into at least two levels
 - Main memory: fast, expensive, volatile
 - Secondary memory: slower, cheaper, nonvolatile
 - Moving information between the two levels of memory is a system responsibility



Memory Partitioning

Operating system 8M
8M

Fixed partitioning

- OS occupies some fixed portion of main memory
- The rest of main memory is available for multiple processes
- One simple scheme is to partition the available memory into fixed regions



Fixed Partitioning

- Equal size fixed partitioning
 - Any process whose size is less than or equal to the partition size can be loaded
- Issues
 - A process may be too big to fit into a partition
 - Overlays: only a portion of a program is loaded in memory
 - Modules loaded at runtime need to use the process' partition (possibly with overlay)
 - Memory utilization is low
 - Internal fragmentation: no matter how small a process is, it takes an entire partition
 - Unequal size partitioning can lessen the issue



Fixed Partitioning



Unequal size fixed partitioning

- Assign a process to the smallest partition that can hold the process
 - Minimize internal fragmentation
 - Larger partitions may remain unused

Disadvantages

- # of partitions specified at system generation time limits the # of active processes in the system
- Small jobs will not utilize partition space efficiently



Fixed Partitioning



- Left: processes are assigned to the smallest partition that can hold the process
- Right: processes can be assigned to the smallest available partition that can hold the process
 - When processes are swapped in, find the smallest available partition again



- The partitions are of variable length and number
 - When a process in loaded, it is allocated exactly as much memory as it requires





- External fragmentation
 - Memory that is external to all partitions becomes increasingly fragmented with time
 - Compaction: shift the processes so that they are contiguous and all free blocks are merged together



- Placement algorithm
 - Best-fit: choose the block that is closest in size to the request
 - Memory can be easily fragmented
 - First-fit: find the first available block from the beginning
 - Leave large free blocks at the end of memory
 - Next-fit: find the available block from the last placement
 - Large free block of memory that usually appear at the end of memory is quickly broken up into small fragments





Before and after allocating a 16 MB block





- Buddy system
 - Memory blocks are available in 2^k words L ≤ K ≤ U, where
 - 2^L : smallest size of block
 - 2^U: largest size of block (entire memory)





- Allocation algorithm
 - If the request size s is 2^{U-1} < s ≤ 2^U, the entire block is allocated



- Otherwise, split the block into two 2^{U-1} size blocks. If the request size s is 2^{U-2} < s ≤ 2^{U-1} the request is allocated to one of the blocks
- Otherwise, split one of the block, and continue until block size becomes 2^L
- Whenever two buddies are unallocated, they are coalesced into a single block



l-Mbyte block	1M			
Request 100K	A = 128K 128K	256K	512K	
Request 240K	A = 128K 128K	$\mathbf{B} = 256\mathbf{K}$	512K	
Request 64K	A = 128K C = 64K 64K	B = 256K	512K	
Request 256K	A = 128K C = 64K 64K	B = 256K	D = 256K	256K
Release B	A = 128K C = 64K 64K	256K	D = 256K	256K
Release A	128K C = 64K 64K	256K	D = 256K	256K
Request 75K	E = 128K C = 64K 64K	256K	D = 256K	256K
Release C	E = 128K 128K	256K	D = 256K	256K
Release E	512K		D = 256K	256K
Release D	1M			





Tree representation of the buddy system



Relocation

Relocation

- A process may be swapped in to a partition different than the one when it was swapped out
- After compaction processes are shifted while they are in memory
- Addresses
 - Logical address: reference to a memory location independent of the physical memory
 - Relative address: a logical address where addresses are relative to a known place (a register)
 - Physical address: absolute location in memory



Relocation



- HW support for relocation
 - Value in the base register is added to the relative address
 - Resulting address is compared to the value in the bounds register



Paging

- Paging
 - Main memory is divided into small fixed size chunks
 - Each process is also divided into the same size chunks
 - Chunks of a process, known as pages, could be assigned to available chunks of memory, known as frames.
- Page table
 - A table of base registers for each page of a process
 - Logical address consists of a page number and an offset within the page
 - Address translation: (page number, offset) → (frame number, offset)







Paging

- Address translation example
 - 16 bit address with the page size of 1KB
 - Page number: the first 6 bits
 - Offset: the last 10 bits
 - 0x05DE (0000 0101 1101 1110)



Segmentation

Segmentation

- Segments are unequal-size block of memory
- Logical addresses consist of two parts
 - A segment number and an offset
- A program may occupy more than one partition and the partitions need not be contiguous
 - No internal fragmentation
 - Less external fragmentation: a process is broken up into a number of smaller pieces



Segmentation

- Address translation example
 - I6 bit logical address with the first 4 bits for the segment number and the last 12 bits for the offset
 - 0x12F0 (0001 0010 1111 0000)



Logical Addresses





Linking and Loading





Absolute and Relocatable Load





Linking

- Each object module may contain references to symbols in other modules
 - Such references are expressed symbolically in an unlinked object module

- Linking
 - After combining the same sections, an address is assigned to the symbols in the modules
 - The symbol references in other modules are resolved



Linking



SUNY Korea

(a) Object modules