

# CSE214 Data Structures

## Heaps

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# Priority Queues

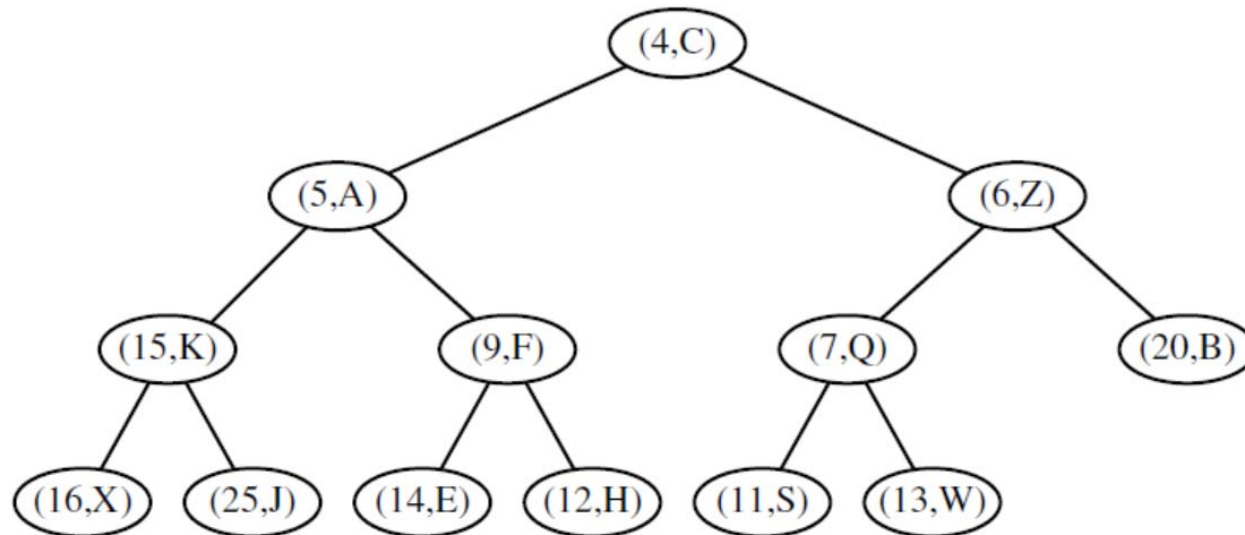
- Priority queue by **unsorted** list
  - $O(1)$  to insert
  - $O(n)$  to find or remove
- Priority queue by **sorted** list
  - $O(n)$  to insert
  - $O(1)$  to find or remove

# Priority Queues

- Priority queue by **binary heap**
  - $O(\log n)$  to insert
  - $O(\log n)$  to remove
  - $O(1)$  to find
- Binary heap
  - Use the structure of a binary tree
  - Data is neither entirely unsorted nor perfectly sorted

# Heap Data Structure

- A heap is a binary tree  $T$  that satisfies
  - A *relational* property and a *structural* property



# Heap Data Structure

- *Heap-order* property (*relational* property)
  - For every non-root position  $p$  in  $T$ , *the key of  $p$  is greater than or equal to its parent's key*
  - The keys encountered in a path from the root is non-decreasing order
  - The *minimal key* is always stored at the root

# Heap Data Structure

- *Complete binary tree* property (*structural property*)
  - A heap  $T$  with height  $h$  is a **complete** binary tree if levels  $0, 1, 2, \dots, h-1$  of  $T$  have the **maximal number of nodes** possible (level  $i$  has  $2^i$  nodes)
  - The remaining nodes at level  $h$  resides in the **leftmost possible positions** at that level

# Height of a Heap

- Proposition

- A heap  $T$  storing  $n$  entries has height  $h = \lfloor \log n \rfloor$

- Proof

- From the completeness,

- The number of nodes in level 0 through  $h-1$  is  $1 + 2 + 4 + \dots + 2^{h-1} = 2^h - 1$

- The number of nodes in level  $h$  is **at least 1** and **at most  $2^h$**

- Hence,  $2^h - 1 + 1 \leq n \leq 2^h - 1 + 2^h$   
 $2^h \leq n \leq 2^{h+1} - 1$

- Take log on both sides:  $h \leq \log n$  and  $h \geq \log(n+1) - 1$

- Because  $h$  is an integer,  $h = \lfloor \log n \rfloor$

# Adding to the Heap

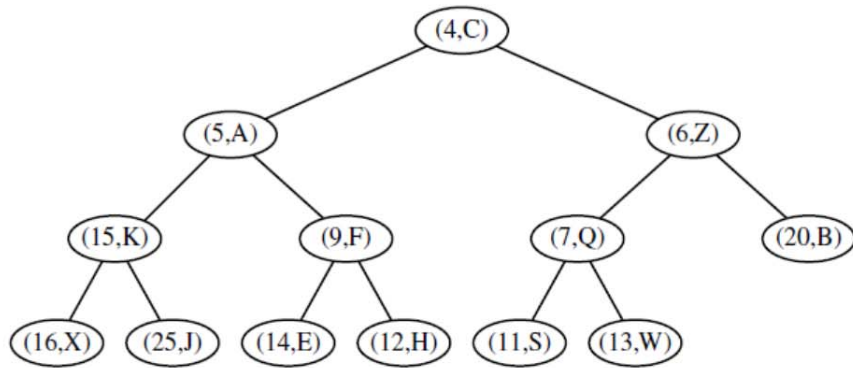
- Complete binary tree property
  - New node should be placed at just beyond the rightmost node at the bottom level
  - Or the leftmost position of a new level



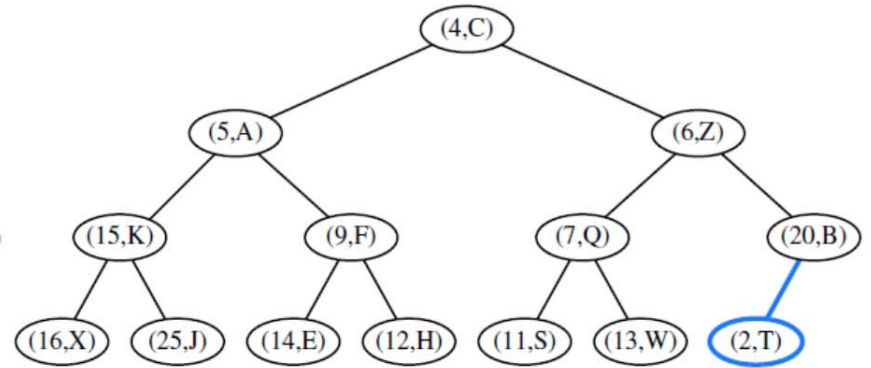
# Adding to the Heap

- Adding the new node may break the heap-order property
- **Up-heap bubbling**
  - Compare the key of position  $p$  and its parent's key
  - If the parent has a larger key, swap the entries
  - Repeat the above until the swapping stops
- The bound of up-heap bubbling is  $\lfloor \log n \rfloor$

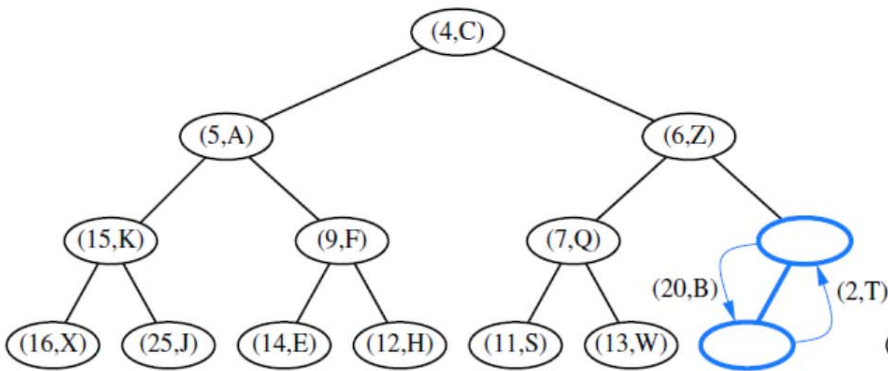
# Adding to the Heap



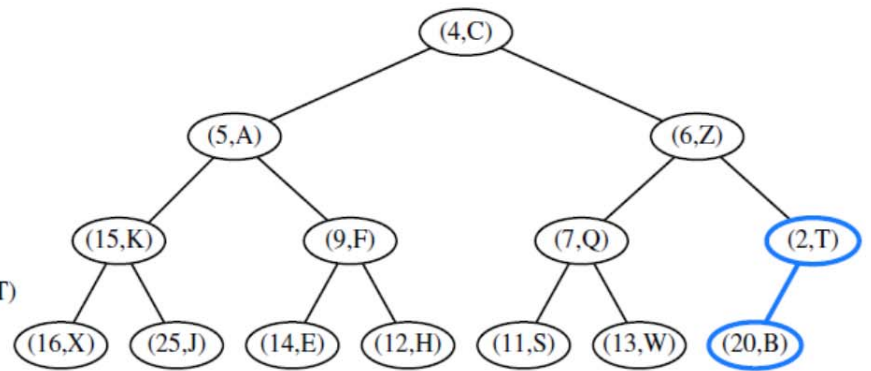
(a)



(b)

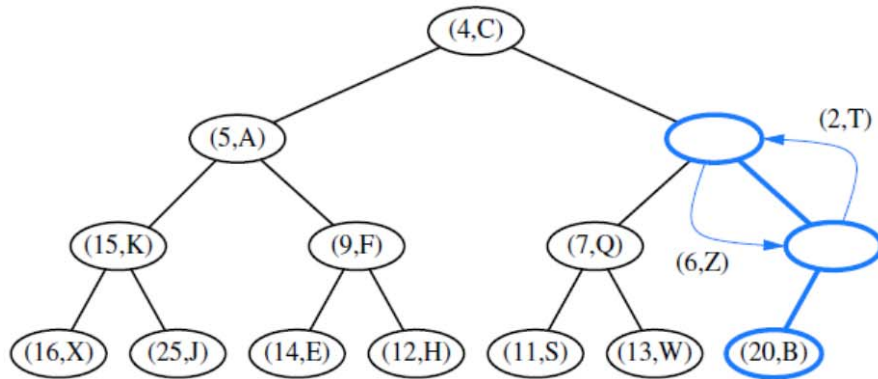


(c)

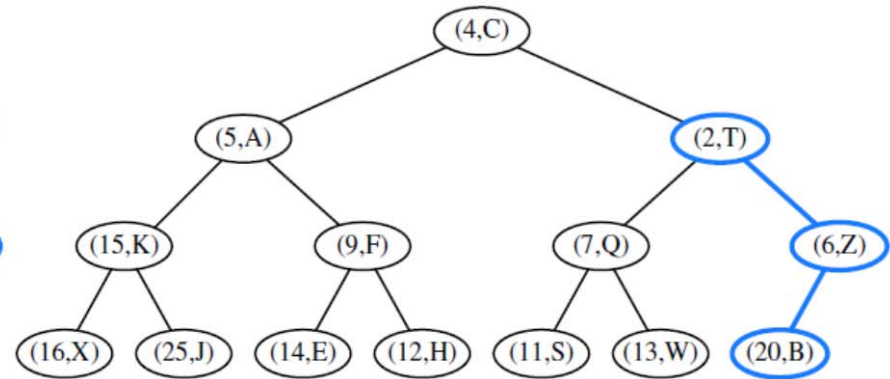


(d)

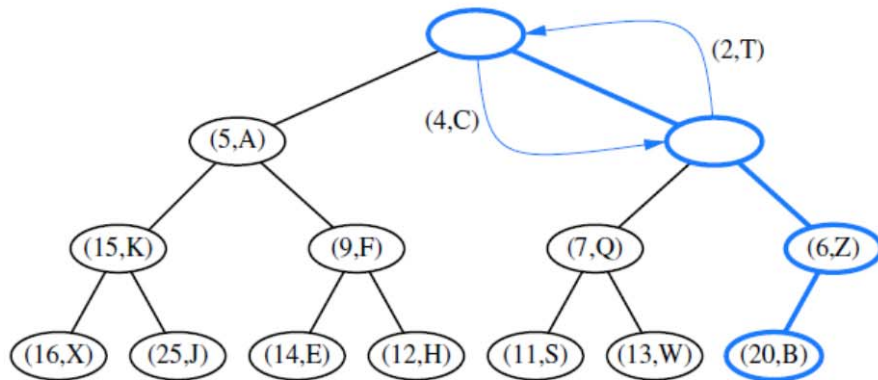
# Adding to the Heap



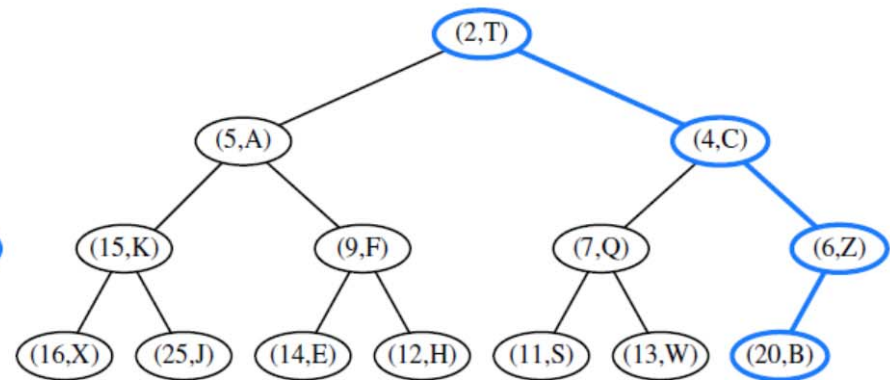
(e)



(f)



(g)



(h)

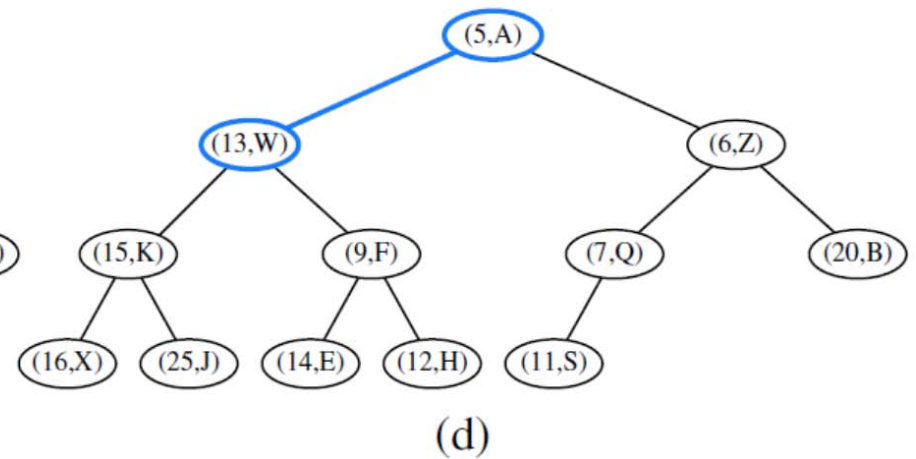
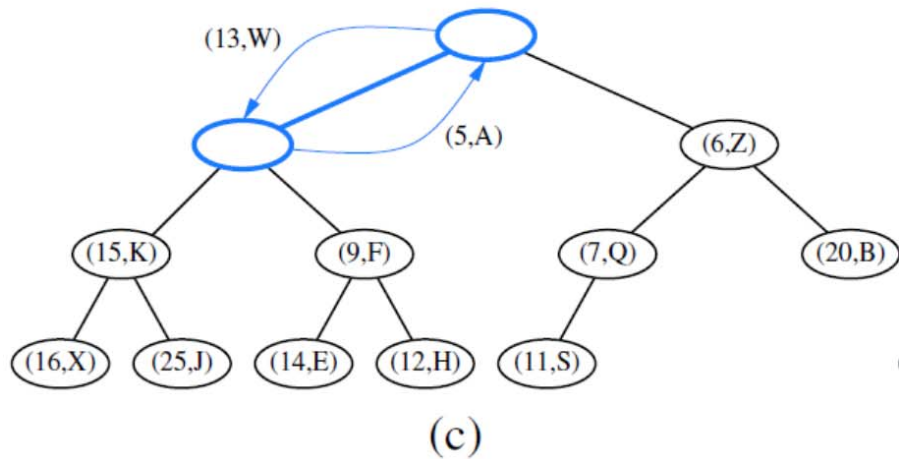
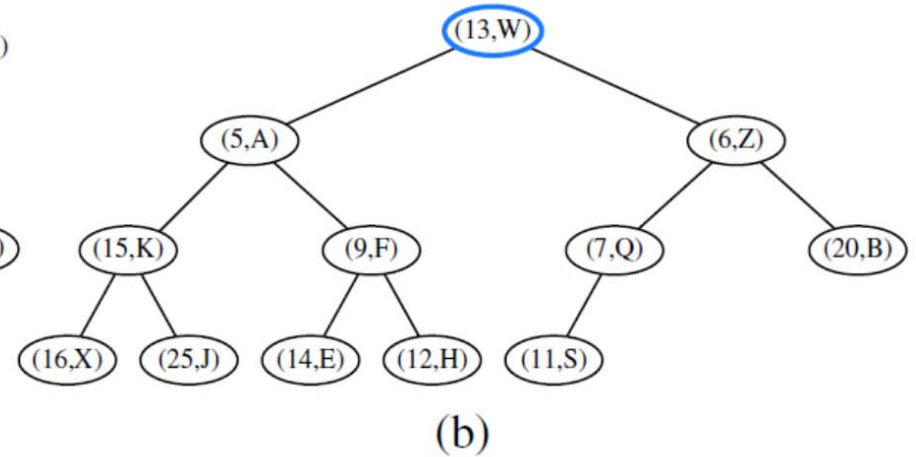
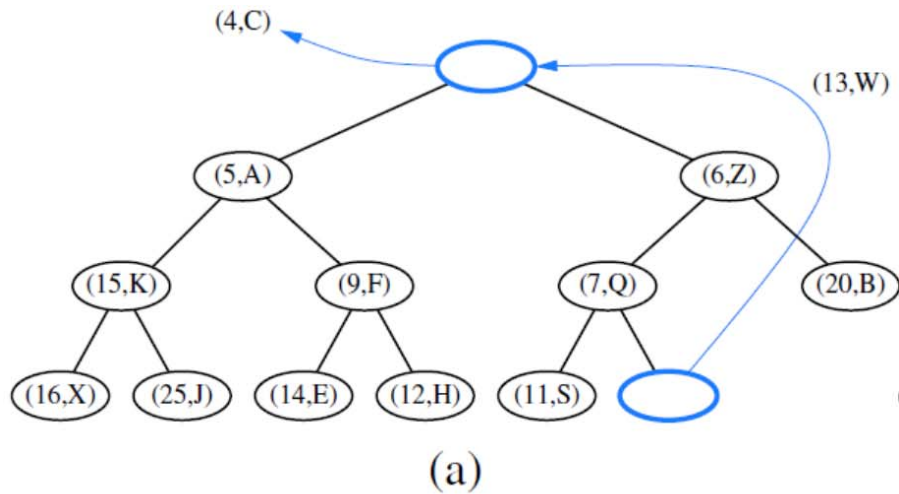
# Removing from the Heap

- Removing the entry with the minimal key
  - The entry with the smallest key is at the root
  - Deleting the root would leave two disconnected trees
- To maintain complete binary tree property
  - After deleting the root, move the rightmost node at the bottom level to the root

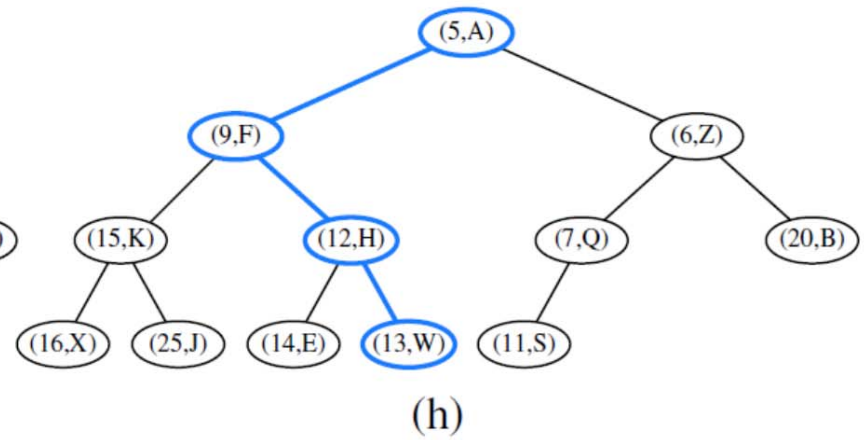
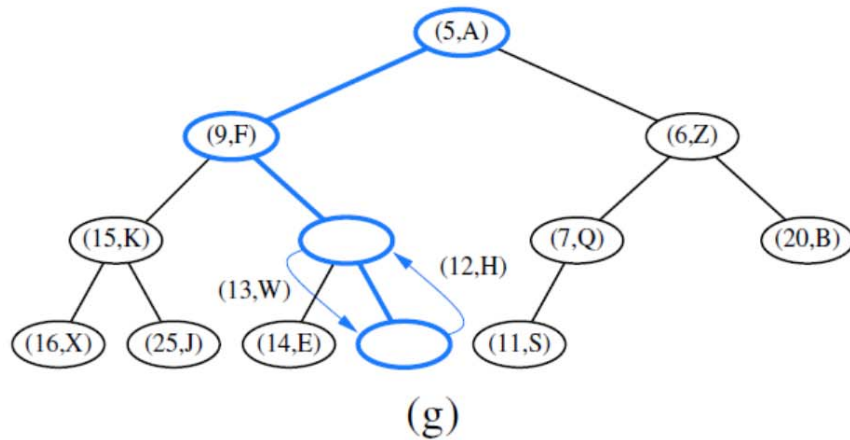
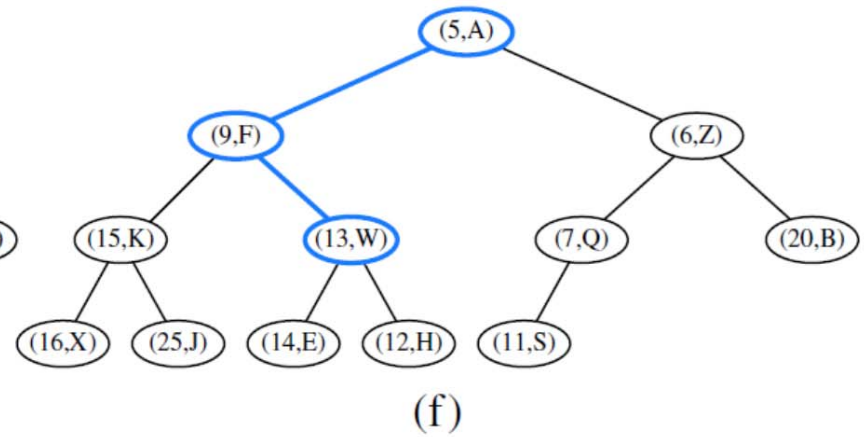
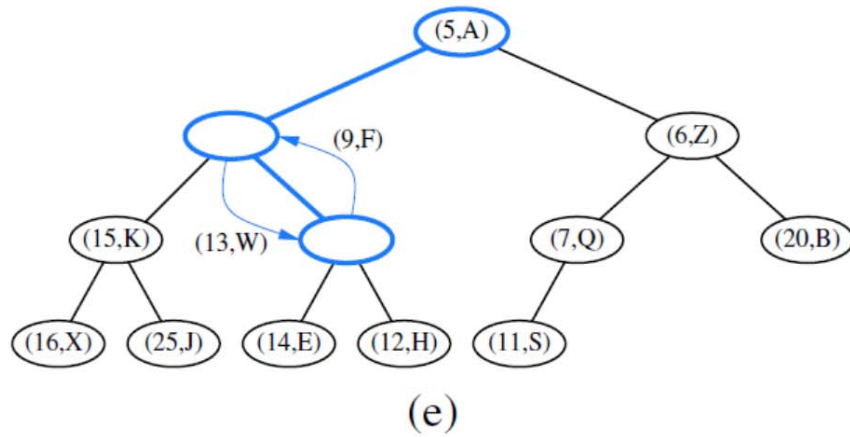
# Removing from the Heap

- Moving the node may break the heap-order property
- **Down-heap bubbling**
  - From a position  $p$ , find the **child  $c$**  that has the ***smaller key***
  - Compare the key of  $p$  and the key of  $c$
  - If the  $p$  has a larger key, swap the entries
  - Repeat the above until the swapping stops or  $p$  reaches the bottom level
- The bound of down-heap bubbling is  $\lfloor \log n \rfloor$

# Removing from the Heap



# Removing from the Heap

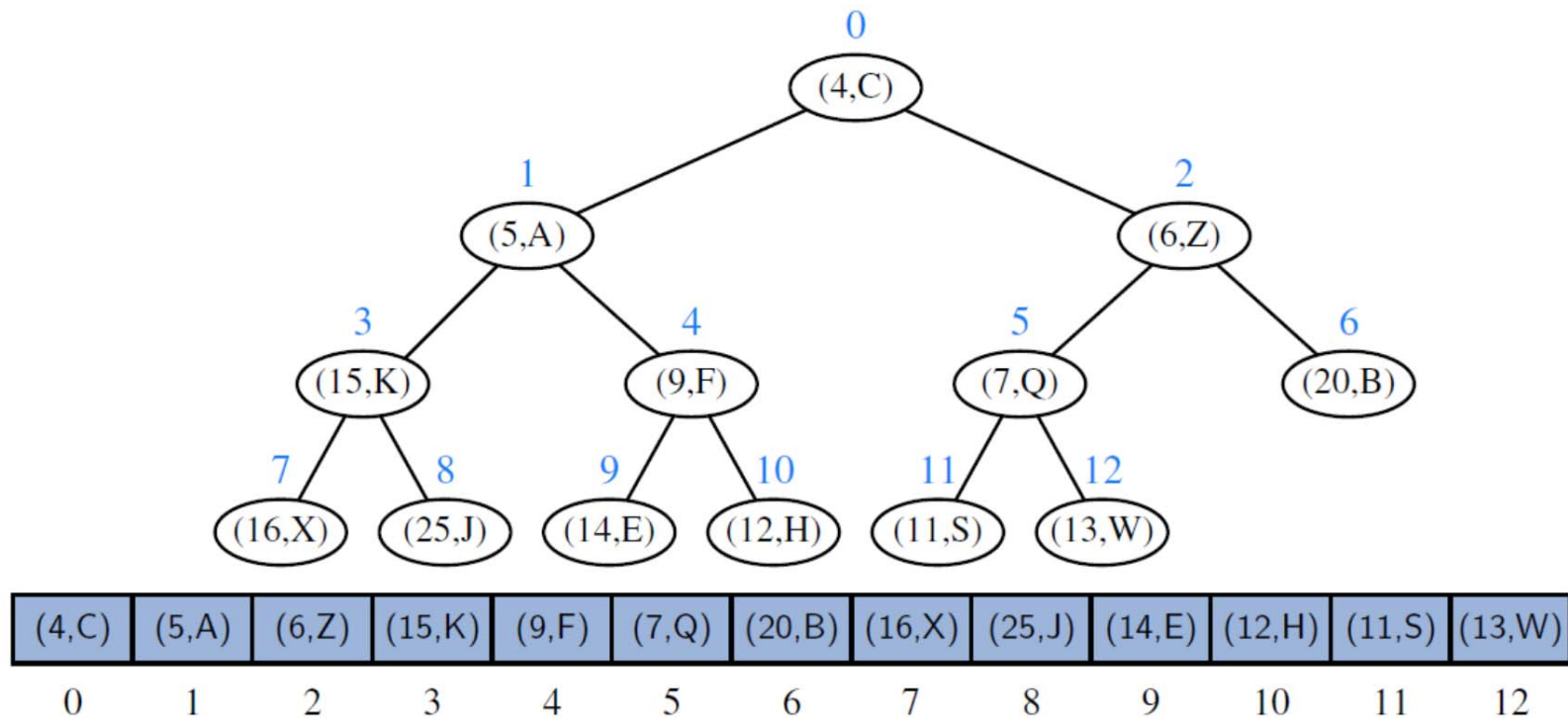


# Complete Binary Tree by **Array**

- Array based representation of binary trees
  - Especially useful for a complete binary tree
- Let *index* (*p*) be the index of position *p*
  - If *p* is the **root**, then  
 $index(p) = 0$
  - If *p* is the **left child** of *q*, then  
 $index(p) = 2 \cdot index(q) + 1$
  - If *p* is the **right child** of *q*, then  
 $index(p) = 2 \cdot index(q) + 2$



# Complete Binary Tree by Array



# Complete Binary Tree by Array

- Benefits of using arrays for heaps
  - *insert* and *removeMin* need to find the last position of the heap
  - In array, its position is  $n-1$  if the heap size is  $n$
- Space usage is  $O(n)$
- Time complexity of *insert*
  - $O(\log(n))$  for static array,  $O(n)$  for dynamic array
- Time complexity of *removeMin*
  - $O(\log(n))$

# Java Implementation of Heap

```
public class HeapPriorityQueue<K extends Comparable<K>, V>
    extends AbstractPriorityQueue<K, V> {
    protected ArrayList<Entry<K, V>> heap;

    //constructors
    public HeapPriorityQueue() {
        super();
        heap = new DynamicArrayList<Entry<K, V>>();
    }
    public HeapPriorityQueue(Comparator<K> comp) {
        super(comp);
        heap = new DynamicArrayList<Entry<K, V>>();
    }

    //protected utilities
    protected int parent(int j)      { return (j-1)/2; }
    protected int left(int j)       { return 2*j + 1; }
    protected int right(int j)      { return 2*j + 2; }
    protected boolean hasLeft(int j) { return left(j) < heap.size(); }
    protected boolean hasRight(int j) { return right(j) < heap.size(); }
```

```

//exchange entries
protected void swap(int i, int j) {
    Entry<K, V> tmp = heap.get(i);
    heap.set(i, heap.get(j));
    heap.set(j, tmp);
}

//up-heap
protected void upheap(int j) {
    while(j > 0) {
        int p = parent(j);
        if(compare(heap.get(j), heap.get(p)) >= 0)
            break;
        swap(j, p);
        j = p;
    }
}

```

```

//down-heap
protected void downheap(int j) {
    while(hasLeft(j)) {
        int l = left(j);
        int c = l; //child to compare (smaller of l and r)
        if(hasRight(j)) {
            int r = right(j);
            if(compare(heap.get(l), heap.get(r)) > 0)
                c = r;
        }

        if(compare(heap.get(c), heap.get(j)) >= 0)
            break;
        swap(j, c);
        j = c;
    }
}

```

```

//public methods
public int size()          { return heap.size(); }
public Entry<K, V> min() {
    if(heap.isEmpty())
        return null;
    return heap.get(0);
}
public Entry<K, V> insert(K key, V value)
    throws IllegalArgumentException {
    checkKey(key);
    Entry<K, V> newest = new PQEntry<K, V>(key, value);
    heap.add(heap.size(), newest);
    upheap(heap.size() - 1);
    return newest;
}
public Entry<K, V> removeMin() {
    if(heap.isEmpty())
        return null;
    Entry<K, V> ret = heap.get(0);
    swap(0, heap.size() - 1);
    heap.remove(heap.size() - 1);
    downheap(0);
    return ret;
}

```

```

//unit test methods
protected static void onFalseThrow(boolean b) {
    if(!b)
        throw new RuntimeException("Error: unexpected");
}
public static void main(String[] args) {
    HeapPriorityQueue<Integer, String> pq = new HeapPriorityQueue<>();
    pq.insert(9, "9"); pq.insert(6, "6");
    pq.insert(5, "5"); pq.insert(4, "4");
    pq.insert(2, "2"); pq.insert(8, "8");
    pq.insert(7, "7"); pq.insert(1, "1");
    pq.insert(3, "3"); pq.insert(0, "0");

    onFalseThrow(pq.size() == 10);
    for(int i = 0; i < 10; i++)
        onFalseThrow(pq.removeMin().getValue().equals("" + i));
    onFalseThrow(pq.isEmpty());
    System.out.println("Success!");
}
}

```

# Sorting with a Priority Queue

- Sorting algorithm
  - Phase 1: add elements of a list to a priority queue as keys using *insert*
  - Phase 2: extract elements from the priority queue and put the keys back to the list using *removeMin*



# Sorting with a Priority Queue

```
/** Sorts sequence S, using initially empty priority queue P to produce the order. */  
public static <E> void pqSort(PositionalList<E> S, PriorityQueue<E,?> P) {  
    int n = S.size();  
    for (int j=0; j < n; j++) {  
        E element = S.remove(S.first());  
        P.insert(element, null);    // element is key; null value  
    }  
    for (int j=0; j < n; j++) {  
        E element = P.removeMin().getKey();  
        S.addLast(element);    // the smallest key in P is next placed in S  
    }  
}
```

# Selection Sort

- If priority queue  $P$  is implemented as an *unsorted list*

		<i>Sequence S</i>	<i>Priority Queue P</i>
Input		(7, 4, 8, 2, 5, 3, 9)	()
Phase 1	(a)	(4, 8, 2, 5, 3, 9)	(7)
	(b)	(8, 2, 5, 3, 9)	(7, 4)
	⋮	⋮	⋮
	(g)	()	(7, 4, 8, 2, 5, 3, 9)
Phase 2	(a)	(2)	(7, 4, 8, 5, 3, 9)
	(b)	(2, 3)	(7, 4, 8, 5, 9)
	(c)	(2, 3, 4)	(7, 8, 5, 9)
	(d)	(2, 3, 4, 5)	(7, 8, 9)
	(e)	(2, 3, 4, 5, 7)	(8, 9)
	(f)	(2, 3, 4, 5, 7, 8)	(9)
	(g)	(2, 3, 4, 5, 7, 8, 9)	()

# Selection Sort

- Running time
  - Phase 1: insert takes  $O(1)$  time for each element
  - Phase 2: selecting min element in *removeMin* takes a time proportional to the number of elements

$$O(n + (n-1) + \dots + 2 + 1) = O\left(\sum_{i=1}^n i\right)$$

- Selection sort is  $O(n^2)$

# Insertion Sort

- If priority queue  $P$  is implemented as a *sorted list*

		<i>Sequence S</i>	<i>Priority Queue P</i>
Input		(7, 4, 8, 2, 5, 3, 9)	()
Phase 1	(a)	(4, 8, 2, 5, 3, 9)	(7)
	(b)	(8, 2, 5, 3, 9)	(4, 7)
	(c)	(2, 5, 3, 9)	(4, 7, 8)
	(d)	(5, 3, 9)	(2, 4, 7, 8)
	(e)	(3, 9)	(2, 4, 5, 7, 8)
	(f)	(9)	(2, 3, 4, 5, 7, 8)
	(g)	()	(2, 3, 4, 5, 7, 8, 9)
Phase 2	(a)	(2)	(3, 4, 5, 7, 8, 9)
	(b)	(2, 3)	(4, 5, 7, 8, 9)
	⋮	⋮	⋮
	(g)	(2, 3, 4, 5, 7, 8, 9)	()

# Insertion Sort

- Running time

- Phase 1: inserting an element to its position takes a time proportional to the number of elements

$$O(n + (n-1) + \dots + 2 + 1) = O\left(\sum_{i=1}^n i\right)$$

- Phase 2: *removeMin* takes  $O(1)$  time for each element
- Insertion sort is  $O(n^2)$

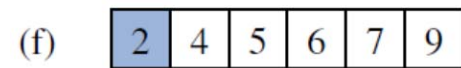
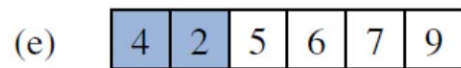
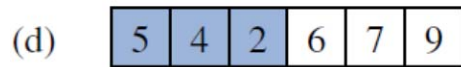
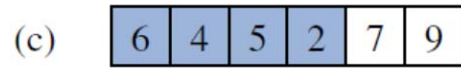
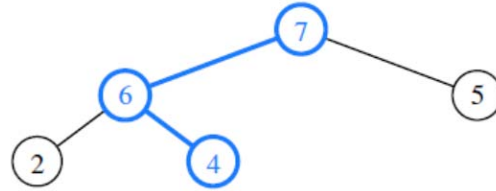
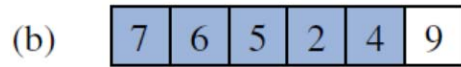
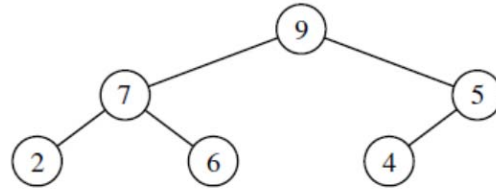
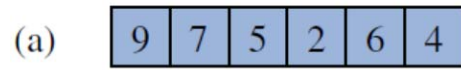
# Heap Sort

- Running time
  - Phase 1: the  $i^{\text{th}}$  *insert* operation takes  $O(\log i)$  time  
→ this phase takes  $O(n \log n)$  time
  - Phase 2: the  $j^{\text{th}}$  *removeMin* operation takes  $O(\log (n - j + 1))$  → this phase takes  $O(n \log n)$  time.

# Heap Sort In-place

- Heap sort without using extra space
  - Redefine heap operations to be maximum-oriented (**root is the maximum element**)
  - Starting as an empty heap, insert array elements at  $0 \dots n-1$  to the heap
  - Remove elements from the heap and place them from the end of the array

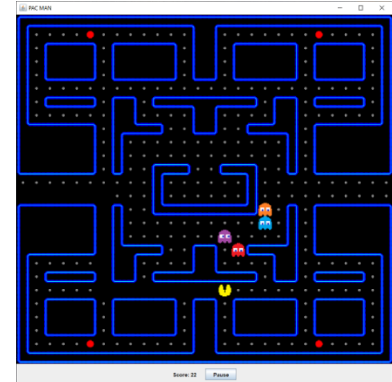
# Heap Sort In-place





# Assignment 8

- In this assignment, we will
  - Implement key methods of a heap
  - Find a shortest path using priority queue
  - Play a Pac-Man game
- Download hw8.zip
  - Implement all TODO lines
  - Zip the java files you modified and submit it
- Due date: TBD



# Assignment 8

- Java files to update
  - Heap.java: a heap
  - HeapQueue.java: a priority queue using Heap
  - Path.java: a shorted path algorithm
    - The paths with dots are shorter than the paths without them

# Assignment 8

- Find who is the Pac-Man champion

