

CSE 548 / AMS 542: Analysis of Algorithms

Prerequisites Review 8 (More Shortest Paths and Other Graph Algorithms)

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The Single-Source Shortest Paths (SSSP) Problem

We are given a weighted, directed graph $G = (V, E)$ with vertex set V and edge set E , and a weight function w such that for each edge $(u, v) \in E$, $w(u, v)$ represents its weight.

We are also given a source vertex $s \in V$.

Our goal is to find a shortest path (i.e., a path of the smallest total edge weight) from s to each vertex $v \in V$.

SSSP: Relaxation

INITIALIZE-SINGLE-SOURCE ($G = (V, E)$, s)

1. *for* each vertex $v \in G.V$ *do*
2. $v.d \leftarrow \infty$
3. $v.\pi \leftarrow NIL$
4. $s.d \leftarrow 0$

RELAX (u, v, w)

1. *if* $u.d + w(u, v) < v.d$ *then*
2. $v.d \leftarrow u.d + w(u, v)$
3. $v.\pi \leftarrow u$

SSSP: Properties of Shortest Paths and Relaxation

The **weight** $w(p)$ of path $p = \langle v_0, v_1, \dots, v_k \rangle$ is the sum of the weights of its constituent edges:

$$w(p) = \sum_{i=1}^k w(v_{i-1}, v_i)$$

We define the **shortest-path weight** $\delta(u, v)$ from u to v by

$$\delta(u, v) = \begin{cases} \min\{w(p) : p \text{ is } u \sim v\}, & \text{if there is a path from } u \text{ to } v, \\ \infty, & \text{otherwise.} \end{cases}$$

A **shortest path** from vertex u to vertex v is then defined as any path p with weight $w(p) = \delta(u, v)$.

SSSP: Properties of Shortest Paths and Relaxation

Triangle inequality (Lemma 24.10 of CLRS)

For any edge $(u, v) \in E$, we have $\delta(s, v) \leq \delta(s, u) + w(u, v)$.

Upper-bound inequality (Lemma 24.11 of CLRS)

We always have $v.d \geq \delta(s, v)$ for all vertices $v \in V$, and once $v.d$ achieves the value $\delta(s, v)$, it never changes.

No-path property (Corollary 24.12 of CLRS)

If there is no path from s to v , then we always have $v.d = \delta(s, v) = \infty$.

Convergence property (Lemma 24.14 of CLRS)

If $s \rightsquigarrow u \rightarrow v$ is a shortest path in G for some $u, v \in V$, and if $u.d = \delta(s, u)$ at any time prior to relaxing edge (u, v) , then $v.d = \delta(s, v)$ at all times afterward.

SSSP: Properties of Shortest Paths and Relaxation

Path-relaxation property (Lemma 24.15 of CLRS)

If $p = \langle v_0, v_1, \dots, v_k \rangle$ is a shortest path from $s = v_0$ to v_k , and we relax the edges of p in the order $(v_0, v_1), (v_1, v_2), \dots, (v_{k-1}, v_k)$, then $v_k.d = \delta(s, v_k)$. This property holds regardless of any other relaxation steps that occur, even if they are intermixed with relaxations on the edges of p .

Predecessor-subgraph property (Lemma 24.17 of CLRS)

Once $v.d = \delta(s, v)$ for all $v \in V$, the predecessor subgraph is a shortest-paths tree rooted at s .

Dijkstra's SSSP Algorithm for Directed Graphs (SSSP: Single-Source Shortest Paths)

Since we already discussed Dijkstra's SSSP algorithm when we talked about greedy algorithms, we will skip over it in this lecture.

Dijkstra's SSSP Algorithm with a Min-Heap (SSSP: Single-Source Shortest Paths)

Input: Weighted graph $G = (V, E)$ with vertex set V and edge set E , a non-negative weight function w , and a source vertex $s \in G[V]$.

Output: For all $v \in G[V]$, $v.d$ is set to the shortest distance from s to v .

Dijkstra-SSSP ($G = (V, E)$, w , s)

```
1.  for each vertex  $v \in G.V$  do
2.       $v.d \leftarrow \infty$ 
3.       $v.\pi \leftarrow \text{NIL}$ 
4.   $s.d \leftarrow 0$ 
5.  Min-Heap  $Q \leftarrow \emptyset$ 
6.  for each vertex  $v \in G.V$  do
7.      INSERT( $Q, v$ )
8.  while  $Q \neq \emptyset$  do
9.       $u \leftarrow \text{EXTRACT-MIN}(Q)$ 
10.     for each  $(u, v) \in G.E$  do
11.         if  $u.d + w(u, v) < v.d$  then
12.              $v.d \leftarrow u.d + w(u, v)$ 
13.              $v.\pi \leftarrow u$ 
14.         DECREASE-KEY( $Q, v, u.d + w(u, v)$ )
```

Let $n = |G[V]|$ and $m = |G[E]|$

Worst-case running time:

Using a binary min-heap
= $O((m + n) \log n)$

Using a Fibonacci heap
= $O(m + n \log n)$

SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

Input: Weighted DAG $G = (V, E)$ with vertex set V and edge set E , a weight function w , and a source vertex $s \in G[V]$. Negative-weight edges are allowed (unlike Dijkstra's SSSP algorithm).

Output: For all $v \in G[V]$, sets $v.d$ to the shortest distance from s to v .

INITIALIZE-SINGLE-SOURCE ($G = (V, E)$, s)

1. *for* each vertex $v \in G.V$ *do*
2. $v.d \leftarrow \infty$
3. $v.\pi \leftarrow NIL$
4. $s.d \leftarrow 0$

RELAX (u, v, w)

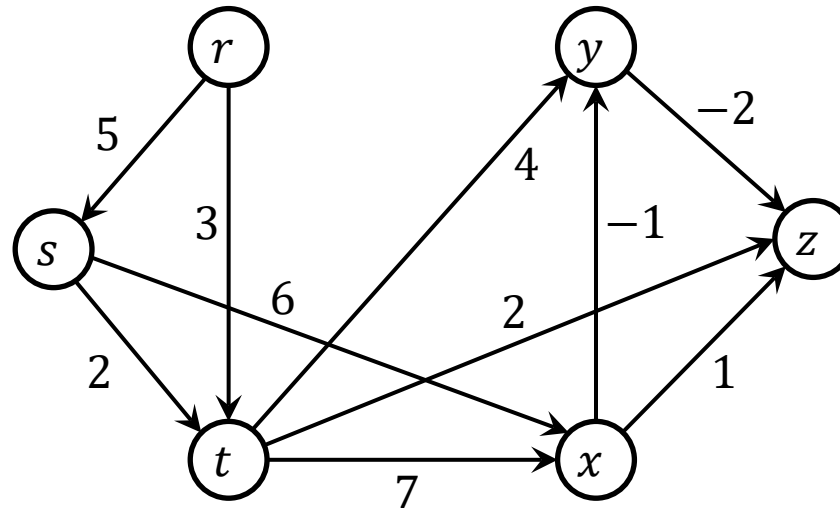
1. *if* $u.d + w(u, v) < v.d$ *then*
2. $v.d \leftarrow u.d + w(u, v)$
3. $v.\pi \leftarrow u$

DAG-SHORTEST-PATHS ($G = (V, E)$, w, s)

1. topologically sort the vertices of G
2. *INITIALIZE-SINGLE-SOURCE*(G, s)
3. *for* each $v \in V.G$ taken in topologically sorted order *do*
4. *for* each $(u, v) \in G.E$ *do*
5. *RELAX*(u, v, w)

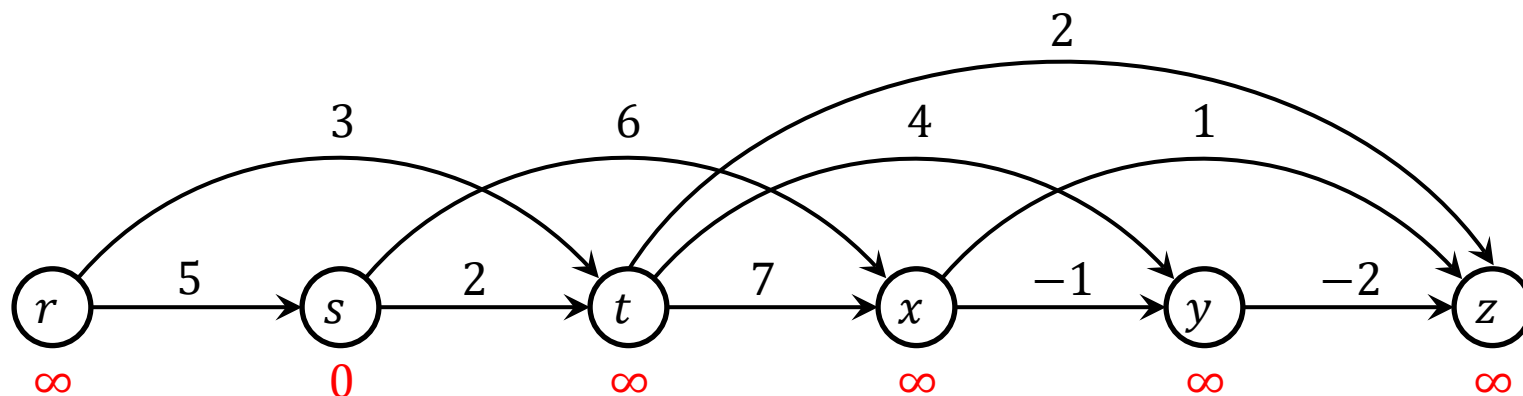
SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

Given DAG



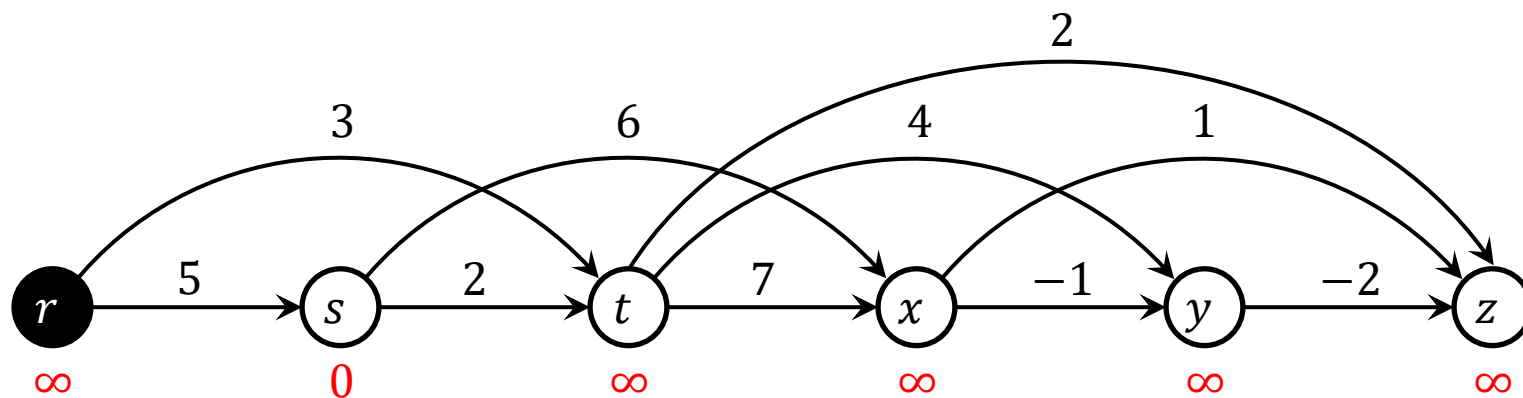
SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

After Topological Sorting (with initial tentative distances)



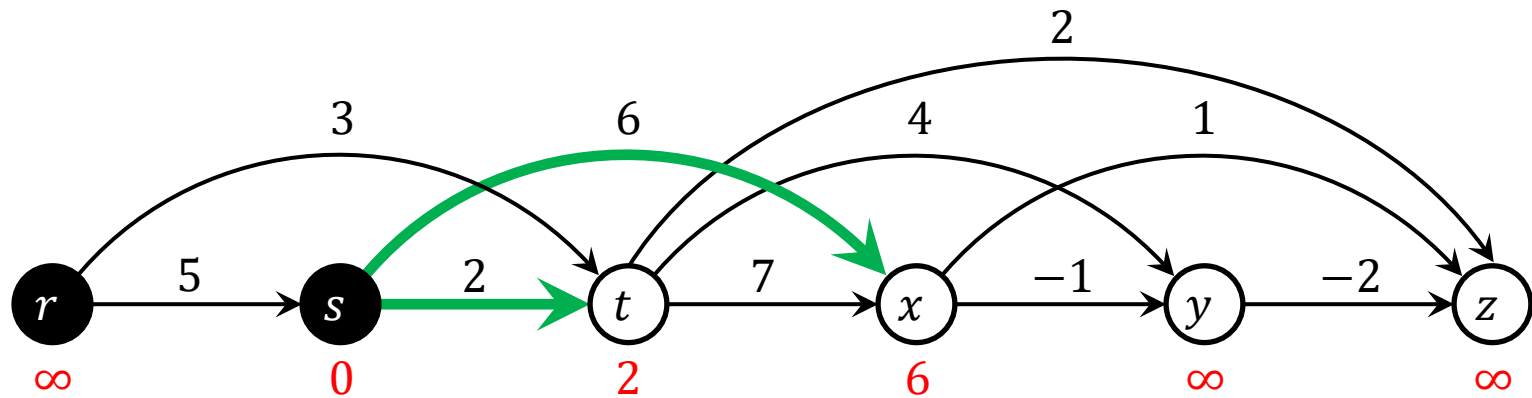
SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

After Iteration 1



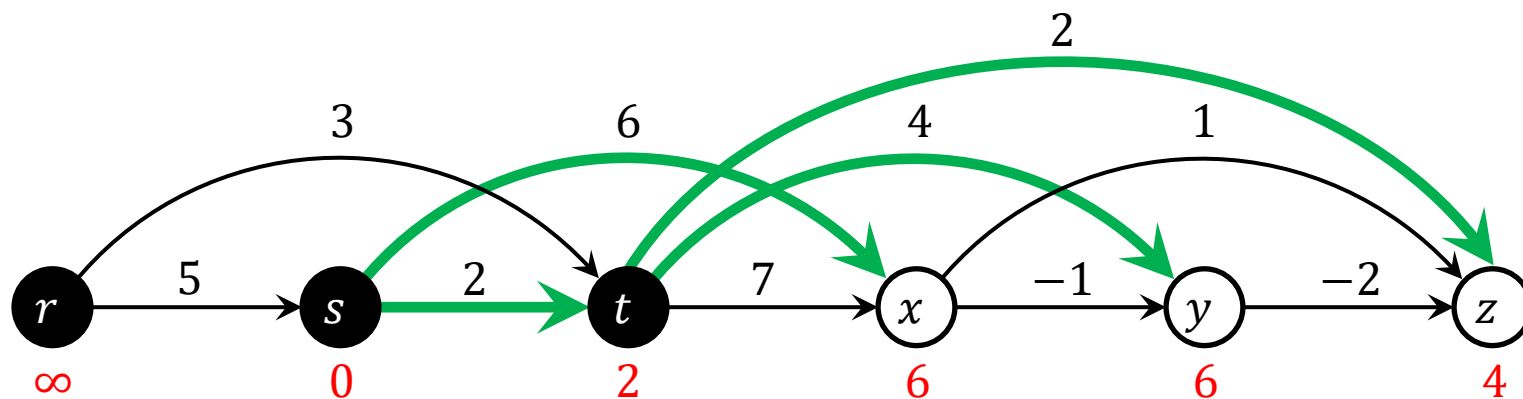
SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

After Iteration 2



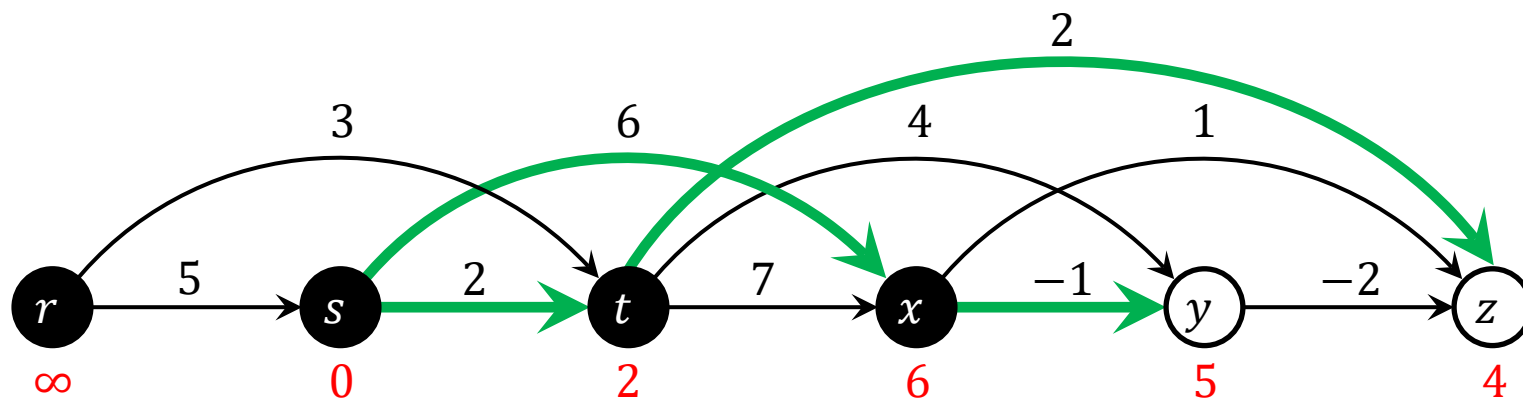
SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

After Iteration 3



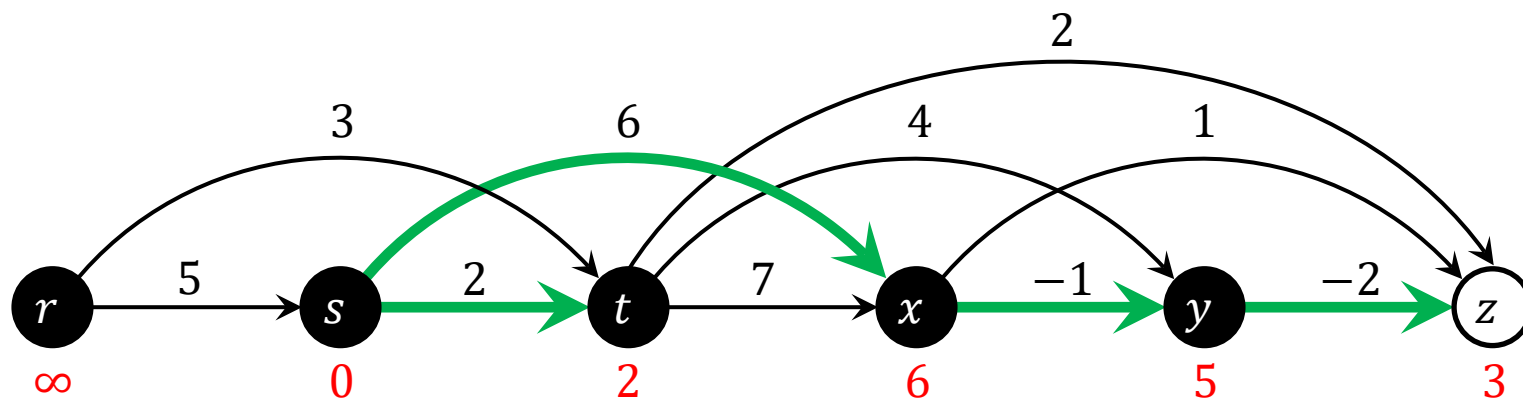
SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

After Iteration 4



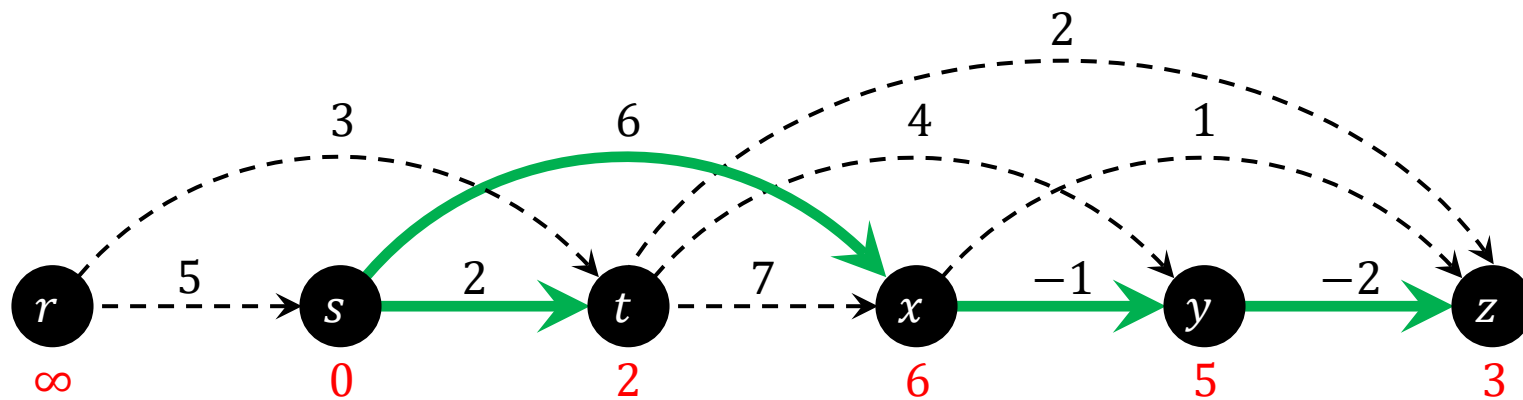
SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

After Iteration 5



SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

Done!



SSSP in Directed Acyclic Graphs (DAGs) (SSSP: Single-Source Shortest Paths)

INITIALIZE-SINGLE-SOURCE ($G = (V, E)$, s)

1. *for* each vertex $v \in G.V$ *do*
2. $v.d \leftarrow \infty$
3. $v.\pi \leftarrow NIL$
4. $s.d \leftarrow 0$

RELAX (u, v, w)

1. *if* $u.d + w(u, v) < v.d$ *then*
2. $v.d \leftarrow u.d + w(u, v)$
3. $v.\pi \leftarrow u$

DAG-SHORTEST-PATHS ($G = (V, E)$, w, s)

1. topologically sort the vertices of G
2. *INITIALIZE-SINGLE-SOURCE*(G, s)
3. *for* each $v \in V.G$ taken in topologically sorted order *do*
4. *for* each $(u, v) \in G.E$ *do*
5. *RELAX*(u, v, w)

Let $n = |V|$ and
 $m = |E|$

Time taken by: Line 1: $\Theta(n + m)$

Line 2: $\Theta(n)$

Lines 3 – 5: $\Theta(m)$

Total time: $\Theta(n + m)$

Correctness of DAG-SHORTEST-PATHS

THEOREM 24.5 (CLRS): If a weighted, directed graph $G = (V, E)$ has a source vertex s and no cycles, then at the termination of the **DAG-SHORTEST-PATHS** procedure, $v.d = \delta(s, v)$ for all vertices $v \in G.V$, and the predecessor subgraph G_π is a shortest-paths tree.

PROOF: Consider any $v \in G.V$.

If v is not reachable from s then $v.d = \delta(s, v) = \infty$ follows from the **no-path property**.

If v is reachable from s , and let $p = \langle v_0, v_1, \dots, v_k \rangle$, where $v_0 = s$ and $v_k = v$, be any shortest path from s to v . Since we process the vertices in topological order, we relax the edges on p in the order $(v_0, v_1), (v_1, v_2), \dots, (v_{k-1}, v_k)$. The **path-relaxation property** implies that $v_i.d = \delta(s, v_i)$ at termination for $i = 1, 2, \dots, k$.

By the **predecessor-subgraph property**, G_π is a shortest-paths tree.

The All-Pairs Shortest Paths (APSP) Problem

We are given a weighted, directed graph $G = (V, E)$ with vertex set V and edge set E , and a weight function w such that for each edge $(u, v) \in E$, $w(u, v)$ represents its weight.

Our goal is to find, for every pair of vertices $u, v \in G.V$, a shortest path (i.e., a path of the smallest total edge weight) from u to v .

The All-Pairs Shortest Paths (APSP) Problem

One can solve the APSP problem by running an SSSP algorithm $n = |G.V|$ times, once for each vertex as the source.

If all edge weights are nonnegative, one can use ***Dijkstra's SSSP algorithm***. Using a binary min-heap as the priority queue, one can solve the problem in $O(n(m + n) \log n)$ time, where $m = |G.E|$. Using a Fibonacci heap as the priority queue yields a running time of $O(n^2 \log n + mn)$.

If G has negative-weight edges, then one can use the slower ***Bellman-Ford SSSP algorithm*** resulting in a running time of $O(mn^2)$ which is $O(n^4)$ for dense graphs.

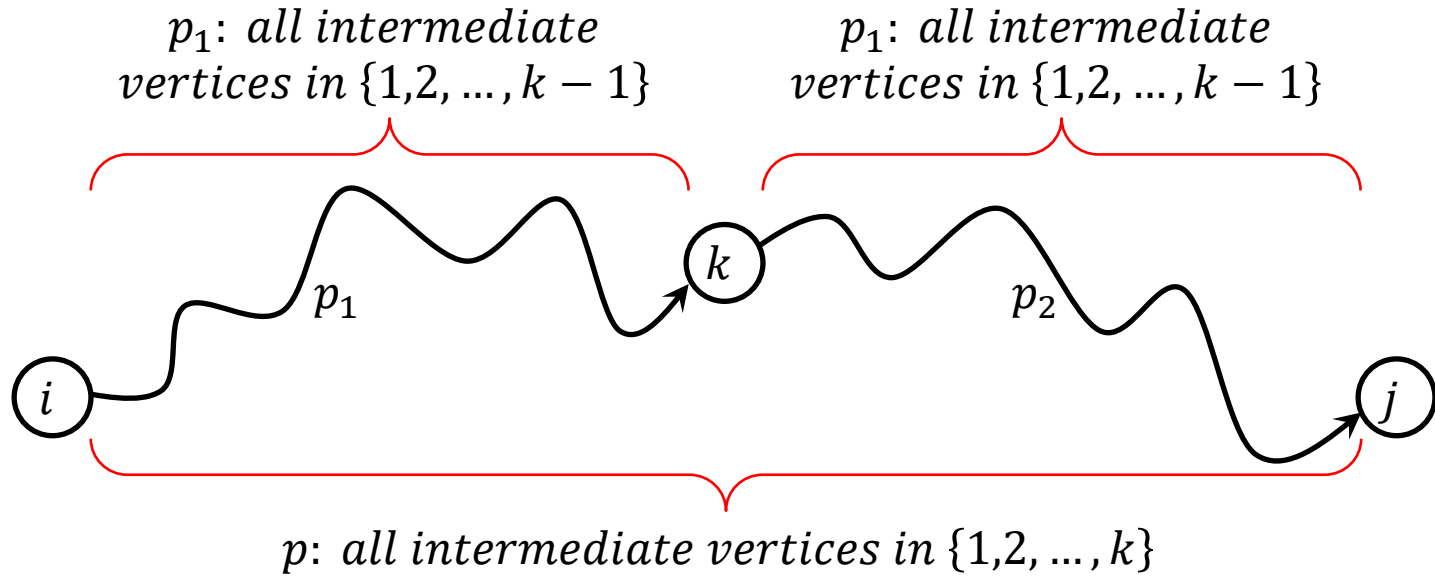
The All-Pairs Shortest Paths (APSP) Problem

We assume that the edge-weights are given as an $n \times n$ adjacency matrix $W = (w_{ij})$, where

$$w_{ij} = \begin{cases} 0, & \text{if } i = j, \\ \text{weight of directed edge } (i, j) & \text{if } i \neq j \text{ and } (i, j) \in E, \\ \infty & \text{if } i \neq j \text{ and } (i, j) \notin E. \end{cases}$$

We allow negative-weight edges, but we assume for the time being that G contains no negative-weight cycles.

APSP: Floyd-Warshall's Algorithm



Let $d_{ij}^{(k)}$ be the minimum weight of any path from vertex i to vertex j for which all intermediate vertices are in $\{1, 2, \dots, k\}$.

$$\text{Then } d_{ij}^{(k)} = \begin{cases} w_{ij}, & \text{if } k = 0, \\ \min\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\} & \text{if } k \geq 1. \end{cases}$$

Then $D^{(n)} = \left(d_{ij}^{(n)}\right)$ gives: $d_{ij}^{(n)} = \delta(i, j)$ for all $i, j \in G.V.$

APSP: Floyd-Warshall's Algorithm

FLOYD-WARSHALL (W)

1. $n \leftarrow W.rows$
2. $D^{(0)} \leftarrow W$
3. *for* $k \leftarrow 1$ *to* n *do*
4. let $D^{(k)} = (d_{ij}^{(k)})$ be a new $n \times n$ matrix
5. *for* $i \leftarrow 1$ *to* n *do*
6. *for* $j \leftarrow 1$ *to* n *do*
7. $d_{ij}^{(k)} \leftarrow \min (d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})$
8. *return* $D^{(n)}$

APSP: Floyd-Warshall with Predecessor Matrix

FLOYD-WARSHALL (W)

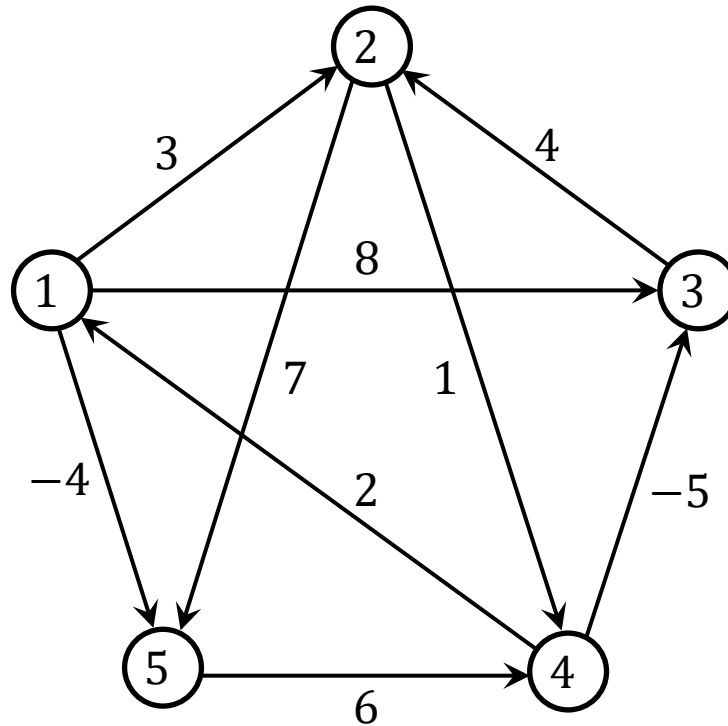
1. $n \leftarrow W.rows$
2. $D^{(0)} \leftarrow W$
3. let $\Pi^{(0)} = (\pi_{ij}^{(0)})$ be a new $n \times n$ matrix
4. **for** $i \leftarrow 1$ **to** n **do**
5. **for** $j \leftarrow 1$ **to** n **do**
6. **if** $i = j$ **or** $w_{ij} = \infty$ **then** $\pi_{ij}^{(0)} \leftarrow NIL$
7. **else** $\pi_{ij}^{(0)} \leftarrow i$
8. **for** $k \leftarrow 1$ **to** n **do**
9. let $D^{(k)} = (d_{ij}^{(k)})$ and $\Pi^{(k)} = (\pi_{ij}^{(k)})$ be new $n \times n$ matrices
10. **for** $i \leftarrow 1$ **to** n **do**
11. **for** $j \leftarrow 1$ **to** n **do**
12. **if** $d_{ij}^{(k-1)} \leq d_{ik}^{(k-1)} + d_{kj}^{(k-1)}$ **then** $\pi_{ij}^{(k)} \leftarrow \pi_{ij}^{(k-1)}$
13. **else** $\pi_{ij}^{(k)} \leftarrow \pi_{kj}^{(k-1)}$
14. $d_{ij}^{(k)} \leftarrow \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})$
15. **return** $D^{(n)}$ and $\Pi^{(n)}$

APSP: Floyd-Warshall with Predecessor Matrix

PRINT-ALL-PAIRS-SHORTEST-PATH (Π , i , j)

1. *if* $i = j$ *then*
2. print i
3. *elseif* $\pi_{ij} = NIL$ *then*
4. print “no path from” i “to” j “exists”
5. *else* *PRINT-ALL-PAIRS-SHORTEST-PATH* (Π , i , π_{ij})
6. print j

APSP: Floyd-Warshall with Predecessor Matrix



$$D^{(0)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$\Pi^{(0)} = \begin{pmatrix} \text{NIL} & 1 & 1 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & \text{NIL} & \text{NIL} \\ 4 & \text{NIL} & 4 & \text{NIL} & \text{NIL} \\ \text{NIL} & \text{NIL} & \text{NIL} & 5 & \text{NIL} \end{pmatrix}$$

APSP: Floyd-Warshall with Predecessor Matrix

$$D^{(0)} =$$

	1	2	3	4	5
1	0	3	8	∞	-4
2	∞	0	∞	1	7
3	∞	4	0	∞	∞
4	2	∞	-5	0	∞
5	∞	∞	∞	6	0

$$\Pi^{(0)} =$$

	1	2	3	4	5
1	NIL	1	1	NIL	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	NIL	NIL
4	4	NIL	4	NIL	NIL
5	NIL	NIL	NIL	5	NIL

APSP: Floyd-Warshall with Predecessor Matrix

$$D^{(0)} =$$

	1	2	3	4	5
1	0	3	8	∞	-4
2	∞	0	∞	1	7
3	∞	4	0	∞	∞
4	2	∞	-5	0	∞
5	∞	∞	∞	6	0

$$\Pi^{(0)} =$$

	1	2	3	4	5
1	NIL	1	1	NIL	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	NIL	NIL
4	4	NIL	4	NIL	NIL
5	NIL	NIL	NIL	5	NIL

$$D^{(1)} =$$

	1	2	3	4	5
1	0	3	8	∞	-4
2	∞	0	∞	1	7
3	∞	4	0	∞	∞
4	2	5	-5	0	-2
5	∞	∞	∞	6	0

$$\Pi^{(1)} =$$

	1	2	3	4	5
1	NIL	1	1	NIL	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	NIL	NIL
4	4	1	4	NIL	1
5	NIL	NIL	NIL	5	NIL

Include intermediate vertex 1

APSP: Floyd-Warshall with Predecessor Matrix

$$D^{(1)} =$$

	1	2	3	4	5
1	0	3	8	∞	-4
2	∞	0	∞	1	7
3	∞	4	0	∞	∞
4	2	5	-5	0	-2
5	∞	∞	∞	6	0

$$\Pi^{(1)} =$$

	1	2	3	4	5
1	NIL	1	1	NIL	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	NIL	NIL
4	4	1	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$$D^{(2)} =$$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	5	-5	0	-2
5	∞	∞	∞	6	0

$$\Pi^{(2)} =$$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	1	4	NIL	1
5	NIL	NIL	NIL	5	NIL

Include intermediate vertex 2

APSP: Floyd-Warshall with Predecessor Matrix

$$D^{(2)} =$$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	5	-5	0	-2
5	∞	∞	∞	6	0

$$\Pi^{(2)} =$$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	1	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$$D^{(3)} =$$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$$\Pi^{(3)} =$$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

Include intermediate vertex 3

APSP: Floyd-Warshall with Predecessor Matrix

$$D^{(3)} =$$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$$\Pi^{(3)} =$$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$$D^{(4)} =$$

	1	2	3	4	5
1					
2					
3					
4					
5					

$$\Pi^{(4)} =$$

	1	2	3	4	5
1					
2					
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{1,1}^{(3)} = 0 \leq d_{1,4}^{(3)} + d_{4,1}^{(3)} = 4 + 2 = 6$$

✓

No Change

$$d_{1,1}^{(4)} = d_{1,1}^{(3)} = 0, \quad \Pi_{1,1}^{(4)} = \Pi_{1,1}^{(3)} = \text{NIL}$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0				
2					
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL				
2					
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{1,2}^{(3)} = 3 \leq d_{1,4}^{(3)} + d_{4,2}^{(3)} = 4 - 1 = 3$$

✓

No Change

$$d_{1,2}^{(4)} = d_{1,2}^{(3)} = 3, \quad \Pi_{1,2}^{(4)} = \Pi_{1,2}^{(3)} = 1$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3			
2					
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1			
2					
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{1,3}^{(3)} = 8 \leq d_{1,4}^{(3)} + d_{4,3}^{(3)} = 4 - 5 = -1$$

×

Improved!

$$d_{1,3}^{(4)} = d_{1,4}^{(3)} + d_{4,3}^{(3)} = -1, \quad \Pi_{1,3}^{(4)} = \Pi_{4,3}^{(3)} = 4$$

Go Through Vertex 4

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1		
2					
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4		
2					
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{1,4}^{(3)} = 4 \leq d_{1,4}^{(3)} + d_{4,4}^{(3)} = 4 + 0 = 4$$



No Change

$$d_{1,4}^{(4)} = d_{1,4}^{(3)} = 4, \quad \Pi_{1,4}^{(4)} = \Pi_{1,4}^{(3)} = 2$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	
2					
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	
2					
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{1,5}^{(3)} = -4 \leq d_{1,4}^{(3)} + d_{4,5}^{(3)} = 4 - 2 = 2$$

✓

No Change

$$d_{1,5}^{(4)} = d_{1,5}^{(3)} = -4, \quad \Pi_{1,5}^{(4)} = \Pi_{1,5}^{(3)} = 1$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2					
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2					
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{2,1}^{(3)} = \infty \leq d_{2,4}^{(3)} + d_{4,1}^{(3)} = 1 + 2 = 3$$

×

Improved!

$$d_{2,1}^{(4)} = d_{2,4}^{(3)} + d_{4,1}^{(3)} = 3, \quad \Pi_{2,1}^{(4)} = \Pi_{4,1}^{(3)} = 4$$

Go Through Vertex 4

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

+

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3				
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4				
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{2,2}^{(3)} = 0 \leq d_{2,4}^{(3)} + d_{4,2}^{(3)} = 1 - 1 = 0$$

✓

No Change

$$d_{2,2}^{(4)} = d_{2,2}^{(3)} = 0, \quad \Pi_{2,2}^{(4)} = \Pi_{2,2}^{(3)} = \text{NIL}$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0			
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL			
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{2,3}^{(3)} = \infty \leq d_{2,4}^{(3)} + d_{4,3}^{(3)} = 1 - 5 = -4$$

×

Improved!

$$d_{2,3}^{(4)} = d_{2,4}^{(3)} + d_{4,3}^{(3)} = -4, \quad \Pi_{2,3}^{(4)} = \Pi_{4,3}^{(3)} = 4$$

Go Through Vertex 4

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

+

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4		
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4		
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{2,4}^{(3)} = 1 \leq d_{2,4}^{(3)} + d_{4,4}^{(3)} = 1 + 0 = 1$$

✓

No Change

$$d_{2,4}^{(4)} = d_{2,4}^{(3)} = 1, \quad \Pi_{2,4}^{(4)} = \Pi_{2,4}^{(3)} = 2$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{2,5}^{(3)} = 7 \leq d_{2,4}^{(3)} + d_{4,5}^{(3)} = 1 - 2 = -1$$

×

Improved!

$$d_{2,5}^{(4)} = d_{2,4}^{(3)} + d_{4,5}^{(3)} = -1, \quad \Pi_{2,5}^{(4)} = \Pi_{4,5}^{(3)} = 1$$

Go Through Vertex 4

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

+

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3					
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3					
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{3,1}^{(3)} = \infty \leq d_{3,4}^{(3)} + d_{4,1}^{(3)} = 5 + 2 = 7$$

×

Improved!

$$d_{3,1}^{(4)} = d_{3,4}^{(3)} + d_{4,1}^{(3)} = 7, \Pi_{3,1}^{(4)} = \Pi_{4,1}^{(3)} = 4$$

Go Through Vertex 4

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

+

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7				
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4				
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{3,2}^{(3)} = 4 \leq d_{3,4}^{(3)} + d_{4,2}^{(3)} = 5 - 1 = 4$$



No Change

$$d_{3,2}^{(4)} = d_{3,2}^{(3)} = 4, \quad \Pi_{3,2}^{(4)} = \Pi_{3,2}^{(3)} = 3$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4			
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3			
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{3,3}^{(3)} = 0 \leq d_{3,4}^{(3)} + d_{4,3}^{(3)} = 5 - 5 = 0$$



No Change

$$d_{3,3}^{(4)} = d_{3,3}^{(3)} = 0, \quad \Pi_{3,3}^{(4)} = \Pi_{3,3}^{(3)} = \text{NIL}$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0		
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL		
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{3,4}^{(3)} = 0 \leq d_{3,4}^{(3)} + d_{4,4}^{(3)} = 5 + 0 = 5$$

✓

No Change

$$d_{3,4}^{(4)} = d_{3,4}^{(3)} = 0, \quad \Pi_{3,4}^{(4)} = \Pi_{3,4}^{(3)} = 2$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	
4					
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{3,5}^{(3)} = 11 \leq d_{3,4}^{(3)} + d_{4,5}^{(3)} = 5 - 2 = 3$$

×

Improved!

$$d_{3,5}^{(4)} = d_{3,4}^{(3)} + d_{4,5}^{(3)} = 3, \quad \Pi_{3,5}^{(4)} = \Pi_{4,5}^{(3)} = 1$$

Go Through Vertex 4

$$D^{(3)} =$$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$$\Pi^{(3)} =$$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$$D^{(4)} =$$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4					
5					

$$\Pi^{(4)} =$$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4					
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{4,1}^{(3)} = 2 \leq d_{4,4}^{(3)} + d_{4,1}^{(3)} = 0 + 2 = 2$$



No Change

$$d_{4,1}^{(4)} = d_{4,1}^{(3)} = 2, \quad \Pi_{4,1}^{(4)} = \Pi_{4,1}^{(3)} = 4$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2				
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4				
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{4,2}^{(3)} = -1 \leq d_{4,4}^{(3)} + d_{4,2}^{(3)} = 0 - 1 = -1$$

✓

No Change

$$d_{4,2}^{(4)} = d_{4,2}^{(3)} = -1, \quad \Pi_{4,2}^{(4)} = \Pi_{4,2}^{(3)} = 3$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1			
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3			
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{4,3}^{(3)} = -5 \leq d_{4,4}^{(3)} + d_{4,3}^{(3)} = 0 - 5 = -5$$



No Change

$$d_{4,3}^{(4)} = d_{4,3}^{(3)} = -5, \quad \Pi_{4,3}^{(4)} = \Pi_{4,3}^{(3)} = 4$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5		
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4		
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{4,4}^{(3)} = 0 \leq d_{4,4}^{(3)} + d_{4,4}^{(3)} = 0 + 0 = 0$$



No Change

$$d_{4,4}^{(4)} = d_{4,4}^{(3)} = 0, \quad \Pi_{4,4}^{(4)} = \Pi_{4,4}^{(3)} = \text{NIL}$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{4,5}^{(3)} = -2 \leq d_{4,4}^{(3)} + d_{4,5}^{(3)} = 0 - 2 = -2$$



No Change

$$d_{4,5}^{(4)} = d_{4,5}^{(3)} = -2, \quad \Pi_{4,5}^{(4)} = \Pi_{4,5}^{(3)} = 1$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5					

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	1
5					

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{5,1}^{(3)} = \infty \leq d_{5,4}^{(3)} + d_{4,1}^{(3)} = 6 + 2 = 8$$

×

Improved!

$$d_{5,1}^{(4)} = d_{5,4}^{(3)} + d_{4,1}^{(3)} = 8, \quad \Pi_{5,1}^{(4)} = \Pi_{4,1}^{(3)} = 4$$

Go Through Vertex 4

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

+

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8				

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	1
5	4				

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{5,2}^{(3)} = \infty \leq d_{5,4}^{(3)} + d_{4,2}^{(3)} = 6 - 1 = 5$$

×

Improved!

$$d_{5,2}^{(4)} = d_{5,4}^{(3)} + d_{4,2}^{(3)} = 5, \quad \Pi_{5,2}^{(4)} = \Pi_{4,2}^{(3)} = 3$$

Go Through Vertex 4

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8	5			

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	1
5	4	3			

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{5,3}^{(3)} = \infty \leq d_{5,4}^{(3)} + d_{4,3}^{(3)} = 6 - 5 = 1$$

×

Improved!

$$d_{5,3}^{(4)} = d_{5,4}^{(3)} + d_{4,3}^{(3)} = 1, \quad \Pi_{5,3}^{(4)} = \Pi_{4,3}^{(3)} = 4$$

Go Through Vertex 4

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8	5	1	0	0

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	1
5	4	3	4	5	NIL

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{5,4}^{(3)} = 6 \leq d_{5,4}^{(3)} + d_{4,4}^{(3)} = 6 + 0 = 6$$



No Change

$$d_{5,4}^{(4)} = d_{5,4}^{(3)} = 6, \quad \Pi_{5,4}^{(4)} = \Pi_{5,4}^{(3)} = 5$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8	5	1	6	

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	1
5	4	3	4	5	

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

distance:

(avoiding vertex 4)

(through vertex 4)

$$d_{5,5}^{(3)} = 0 \leq d_{5,4}^{(3)} + d_{4,5}^{(3)} = 6 - 2 = 4$$



No Change

$$d_{5,5}^{(4)} = d_{5,5}^{(3)} = 0, \quad \Pi_{5,5}^{(4)} = \Pi_{5,5}^{(3)} = \text{NIL}$$

$D^{(3)} =$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$\Pi^{(3)} =$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$D^{(4)} =$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8	5	1	6	0

$\Pi^{(4)} =$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	1
5	4	3	4	5	NIL

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

In iteration k of the outermost loop of Floyd-Warshall's APSP (i.e., when improving shortest distances by going through vertex k): values in row k and column k remain unchanged.

$$D^{(3)} =$$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$$\Pi^{(3)} =$$

	1	2	3	4	5
1	NIL	1	1	2	1
2	NIL	NIL	NIL	2	2
3	NIL	3	NIL	2	2
4	4	3	4	NIL	1
5	NIL	NIL	NIL	5	NIL

$$D^{(4)} =$$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8	5	1	6	0

$$\Pi^{(4)} =$$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	1
5	4	3	4	5	NIL

Include intermediate vertex k

APSP: Floyd-Warshall with Predecessor Matrix

$$D^{(3)} =$$

	1	2	3	4	5
1	0	3	8	4	-4
2	∞	0	∞	1	7
3	∞	4	0	5	11
4	2	-1	-5	0	-2
5	∞	∞	∞	6	0

$$\Pi^{(3)} =$$

	1	2	3	4	5
1	<i>NIL</i>	1	1	2	1
2	<i>NIL</i>	<i>NIL</i>	<i>NIL</i>	2	2
3	<i>NIL</i>	3	<i>NIL</i>	2	2
4	4	3	4	<i>NIL</i>	1
5	<i>NIL</i>	<i>NIL</i>	<i>NIL</i>	5	<i>NIL</i>

$$D^{(4)} =$$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8	5	1	6	0

$$\Pi^{(4)} =$$

	1	2	3	4	5
1	<i>NIL</i>	1	4	2	1
2	4	<i>NIL</i>	4	2	1
3	4	3	<i>NIL</i>	2	1
4	4	3	4	<i>NIL</i>	1
5	4	3	4	5	<i>NIL</i>

Include intermediate vertex 4

APSP: Floyd-Warshall with Predecessor Matrix

$$D^{(4)} =$$

	1	2	3	4	5
1	0	3	-1	4	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8	5	1	6	0

$$\Pi^{(4)} =$$

	1	2	3	4	5
1	NIL	1	4	2	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	1
5	4	3	4	5	NIL

$$D^{(5)} =$$

	1	2	3	4	5
1	0	1	-3	2	-4
2	3	0	-4	1	-1
3	7	4	0	5	3
4	2	-1	-5	0	-2
5	8	5	1	6	0

$$\Pi^{(5)} =$$

	1	2	3	4	5
1	NIL	3	4	5	1
2	4	NIL	4	2	1
3	4	3	NIL	2	1
4	4	3	4	NIL	1
5	4	3	4	5	NIL

Include intermediate vertex 5

APSP: Floyd-Warshall's Algorithm

FLOYD-WARSHALL (W)

1. $n \leftarrow W.rows$
2. $D^{(0)} \leftarrow W$
3. *for* $k \leftarrow 1$ *to* n *do*
4. let $D^{(k)} = (d_{ij}^{(k)})$ be a new $n \times n$ matrix
5. *for* $i \leftarrow 1$ *to* n *do*
6. *for* $j \leftarrow 1$ *to* n *do*
7. $d_{ij}^{(k)} \leftarrow \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})$
8. *return* $D^{(n)}$

Running Time = $\Theta(n^3)$

Space Complexity = $\Theta(n^3)$

APSP: Floyd-Warshall's Algorithm

But $D^{(k)}$ depends only on $D^{(k-1)}$.

FLOYD-WARSHALL-QUADRATIC-SPACE (W)

1. $n \leftarrow W.rows$
2. let $D^{(0)} = (d_{ij}^{(0)})$ and $D^{(1)} = (d_{ij}^{(1)})$ be new $n \times n$ matrices
3. $D^{(0)} \leftarrow W$
4. **for** $k \leftarrow 1$ **to** n **do**
5. **for** $i \leftarrow 1$ **to** n **do**
6. **for** $j \leftarrow 1$ **to** n **do**
7. $d_{ij}^{(1)} \leftarrow \min(d_{ij}^{(0)}, d_{ik}^{(0)} + d_{kj}^{(0)})$
8. $D^{(0)} \leftarrow D^{(1)}$
9. **return** $D^{(0)}$

Running Time = $\Theta(n^3)$

Space Complexity = $\Theta(n^2)$

APSP: Floyd-Warshall's Algorithm

Can be solved in-place!

FLOYD-WARSHALL-IN-PLACE (W)

```
1.   n ← W.rows
2.   for k ← 1 to n do
3.     for i ← 1 to n do
4.       for j ← 1 to n do
5.         wij ← min(wij, wik + wkj)
6.   return W
```

Running Time = $\Theta(n^3)$

Space Complexity = $\Theta(n^2)$

Optional Breadth-First Search (BFS)

Breadth-First Search (BFS)

Input: Unweighted directed or undirected graph $G = (V, E)$ with vertex set V and edge set E , and a source vertex $s \in G.V$. For each $v \in V$, the adjacency list of v is $G.Adj[v]$.

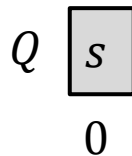
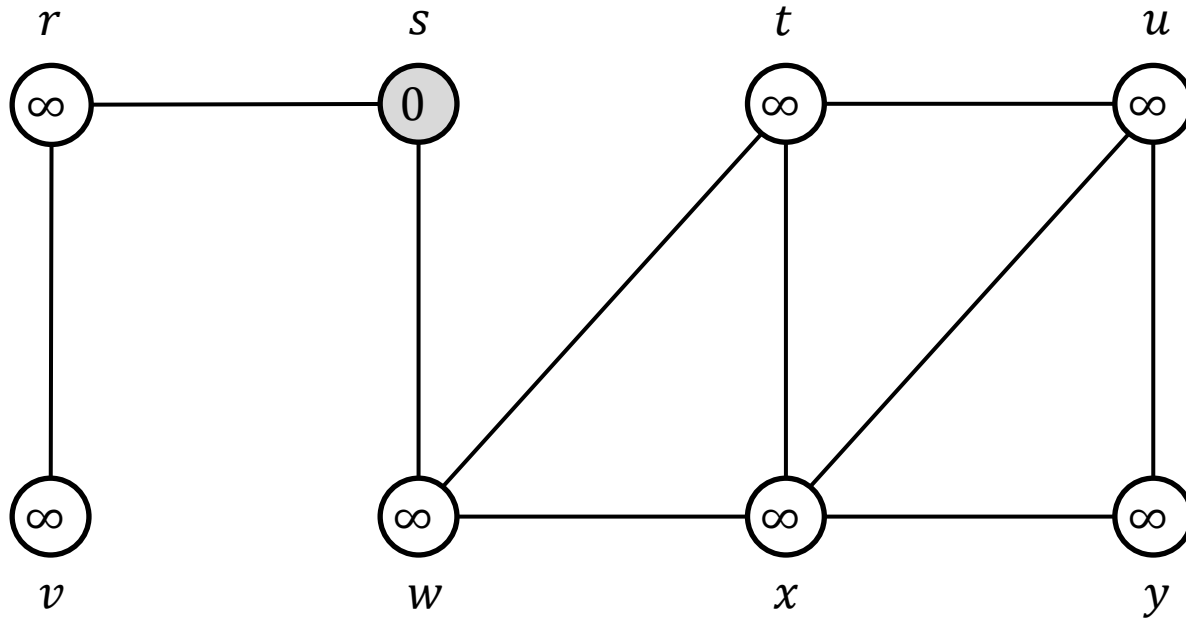
Output: For all $v \in G[V]$, $v.d$ is set to the shortest distance (in terms of the number of edges) from s to v . Also, $v.\pi$ pointers form a breadth-first tree rooted at s that contains all vertices reachable from s .

BFS (G, s)

1. *for* each vertex $u \in G.V \setminus \{s\}$ *do*
2. $u.color \leftarrow \text{WHITE}, u.d \leftarrow \infty, u.\pi \leftarrow \text{NIL}$
3. $s.color \leftarrow \text{GRAY}, s.d \leftarrow 0, s.\pi \leftarrow \text{NIL}$
4. Queue $Q \leftarrow \emptyset$
5. *ENQUEUE*(Q, s)
6. *while* $Q \neq \emptyset$ *do*
7. $u \leftarrow \text{DEQUEUE}(Q)$
8. *for* each $v \in G.Adj[u]$ *do*
9. *if* $v.color = \text{WHITE}$ *then*
10. $v.color \leftarrow \text{GRAY}, v.d \leftarrow u.d + 1, v.\pi \leftarrow u$
11. *ENQUEUE*(Q, v)
12. $u.color \leftarrow \text{BLACK}$

Breadth-First Search (BFS)

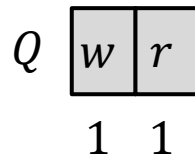
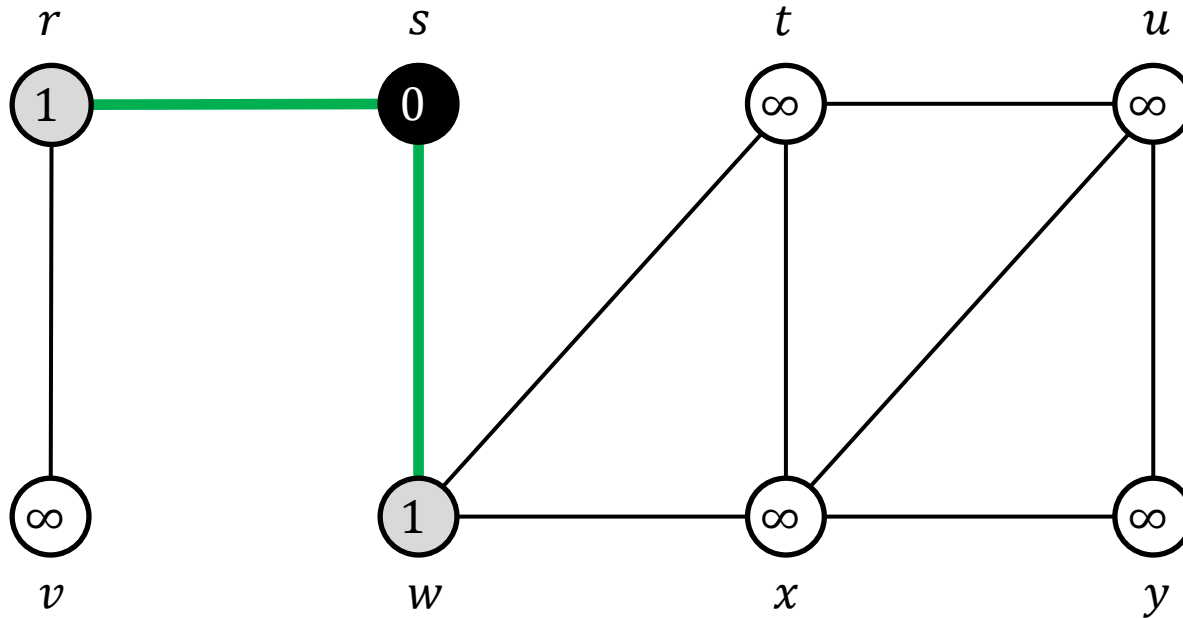
ENQUEUE (Q, s)



Breadth-First Search (BFS)

DEQUEUE (Q) \rightarrow s

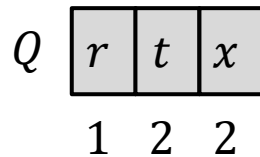
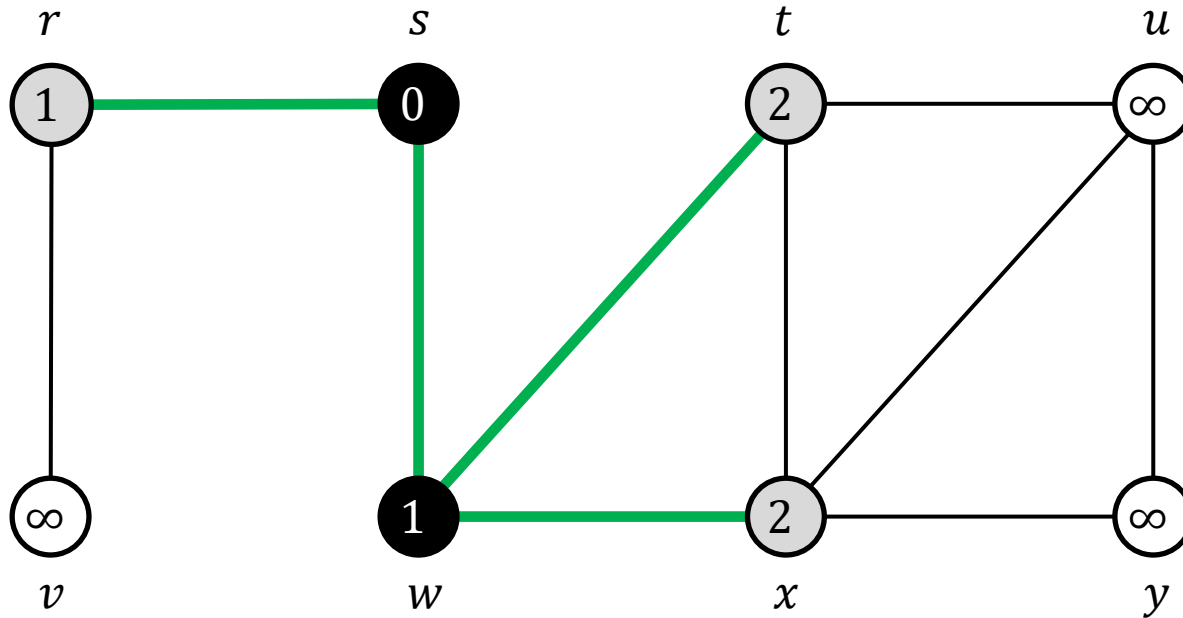
ENQUEUE (Q, w), ENQUEUE (Q, r)



Breadth-First Search (BFS)

DEQUEUE (Q) $\rightarrow w$

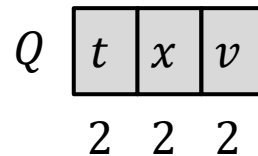
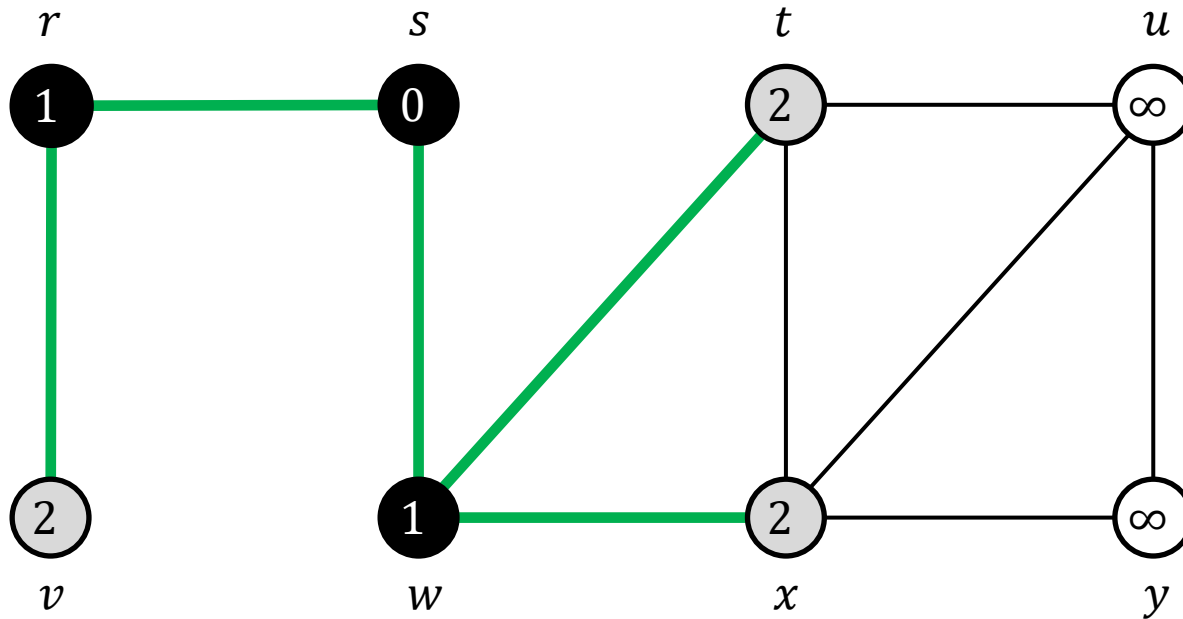
ENQUEUE (Q, t), ENQUEUE (Q, x)



Breadth-First Search (BFS)

DEQUEUE (Q) \rightarrow r

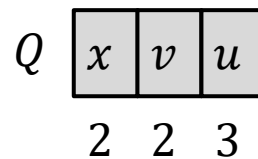
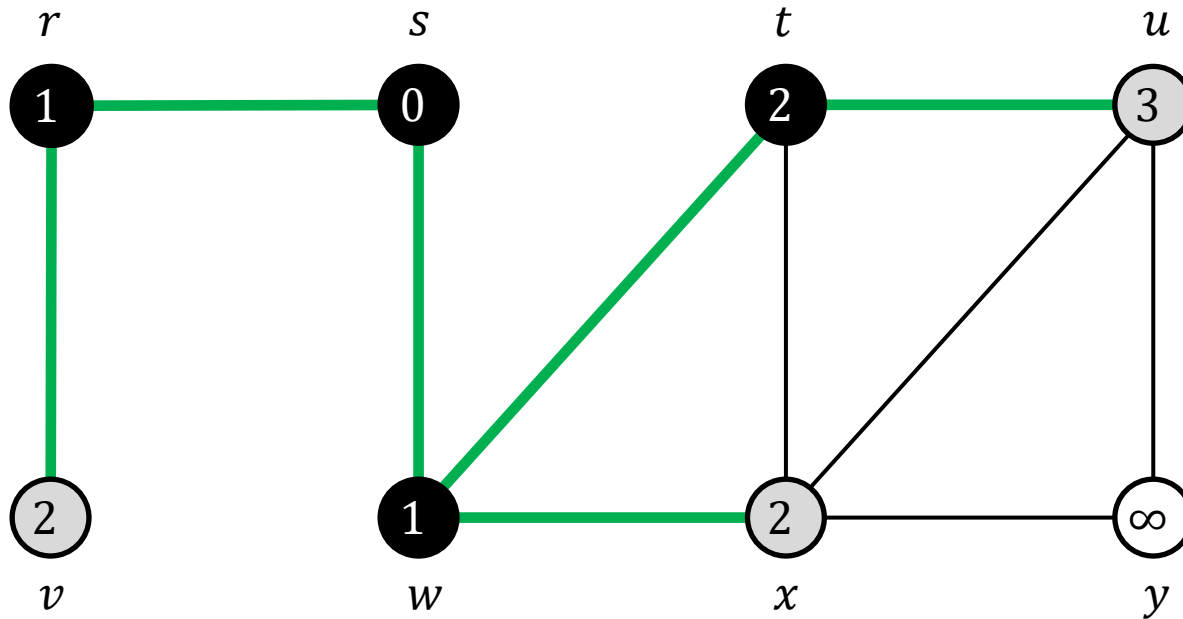
ENQUEUE (Q, x), ENQUEUE (Q, v)



Breadth-First Search (BFS)

DEQUEUE (Q) \rightarrow t

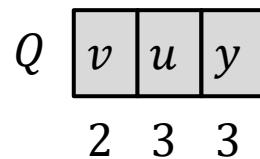
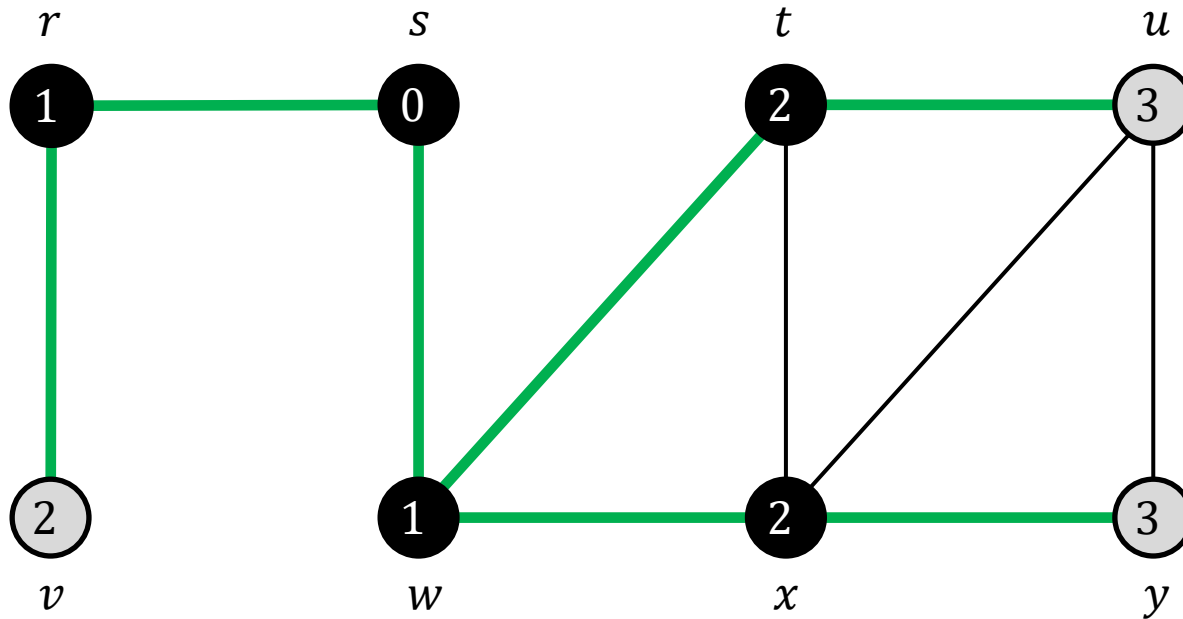
ENQUEUE (Q, u)



Breadth-First Search (BFS)

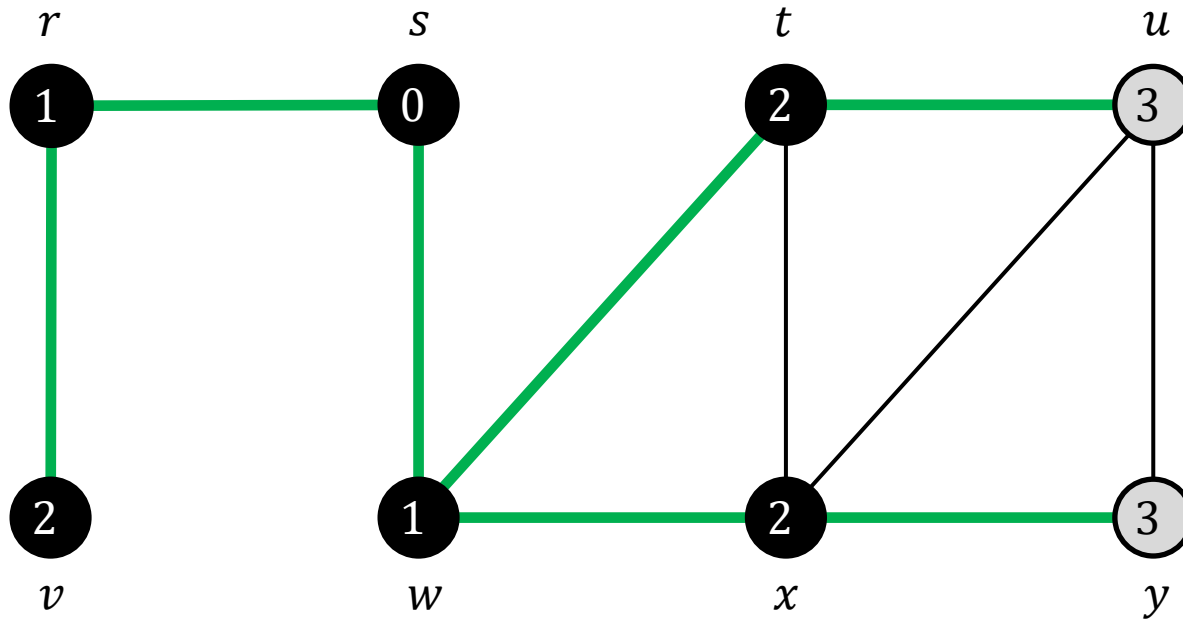
DEQUEUE (Q) \rightarrow x

ENQUEUE (Q, y)



Breadth-First Search (BFS)

DEQUEUE (Q) $\rightarrow v$



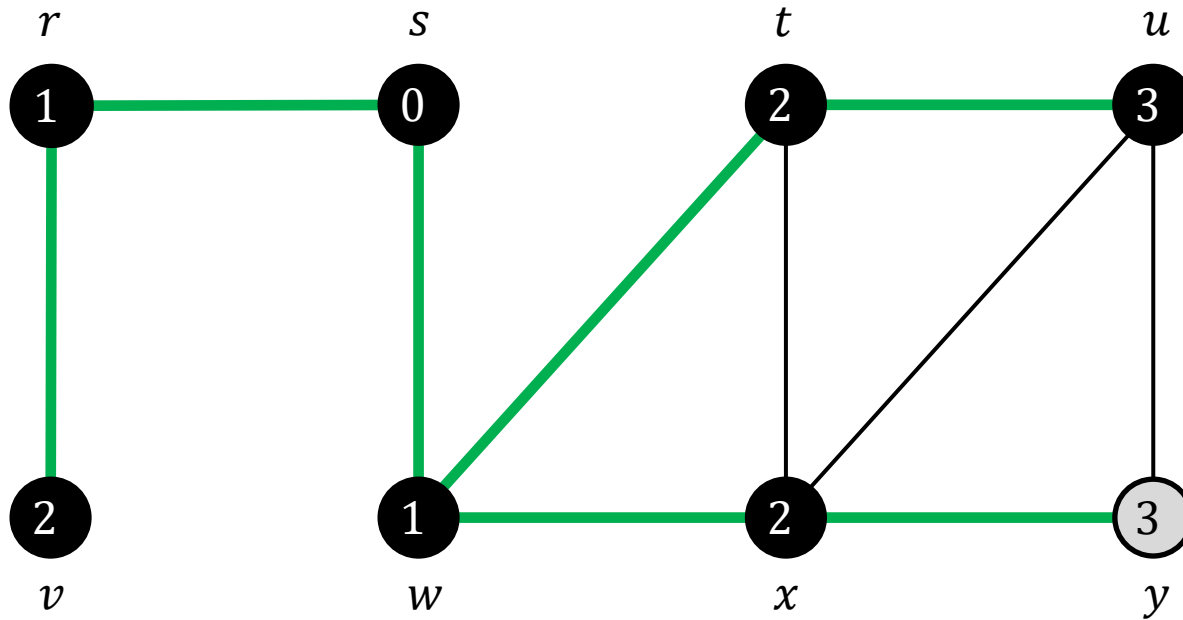
Q

u	y
-----	-----

3 3

Breadth-First Search (BFS)

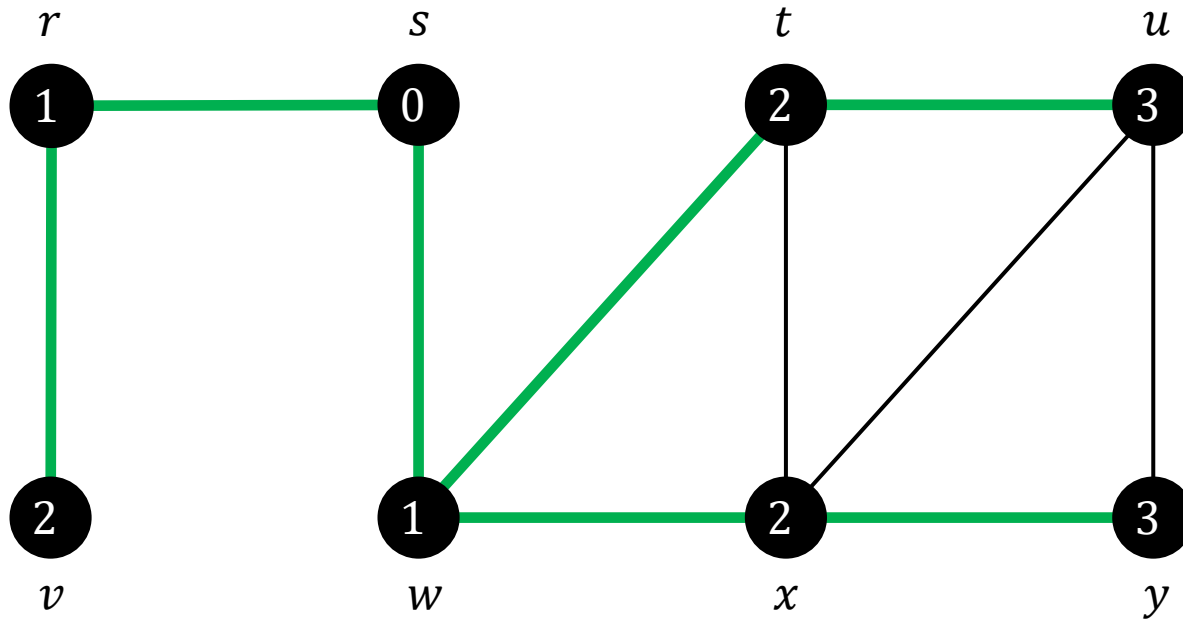
DEQUEUE (Q) $\rightarrow u$



Q y
3

Breadth-First Search (BFS)

DEQUEUE (Q) $\rightarrow y$



$Q \ \emptyset$

Breadth-First Search (BFS)

BFS (G, s)

1. *for* each vertex $u \in G.V \setminus \{s\}$ *do*
2. $u.color \leftarrow \text{WHITE}, u.d \leftarrow \infty, u.\pi \leftarrow \text{NIL}$
3. $s.color \leftarrow \text{GRAY}, s.d \leftarrow 0, s.\pi \leftarrow \text{NIL}$
4. Queue $Q \leftarrow \emptyset$
5. *ENQUEUE*(Q, s)
6. *while* $Q \neq \emptyset$ *do*
7. $u \leftarrow \text{DEQUEUE}(Q)$
8. *for* each $v \in G.Adj[u]$ *do*
9. *if* $v.color = \text{WHITE}$ *then*
10. $v.color \leftarrow \text{GRAY}, v.d \leftarrow u.d + 1, v.\pi \leftarrow u$
11. *ENQUEUE*(Q, v)
12. $u.color \leftarrow \text{BLACK}$

Let $n = |G.V|$ and $m = |G.E|$

Time spent

- initializing = $\Theta(n)$
- enqueueing / dequeueing
= $\Theta(n)$
- scanning the adjacency lists
= $\Theta(\sum_{v \in G.V} |G.Adj[v]|)$
= $\Theta(m)$

\therefore Total cost = $\Theta(m + n)$

Optional Depth-First Search (DFS)

Depth-First Search (DFS)

Input: Unweighted directed or undirected graph $G = (V, E)$ with vertex set V and edge set E . For each $v \in V$, the adjacency list of v is $G.Adj[v]$.

Output: For each $v \in G[V]$, $v.d$ is set to the time when v was first discovered and $v.f$ is set to the time when v 's adjacency list has been examined completely. Also, $v.\pi$ pointers form a breadth-first tree rooted at s that contains all vertices reachable from s .

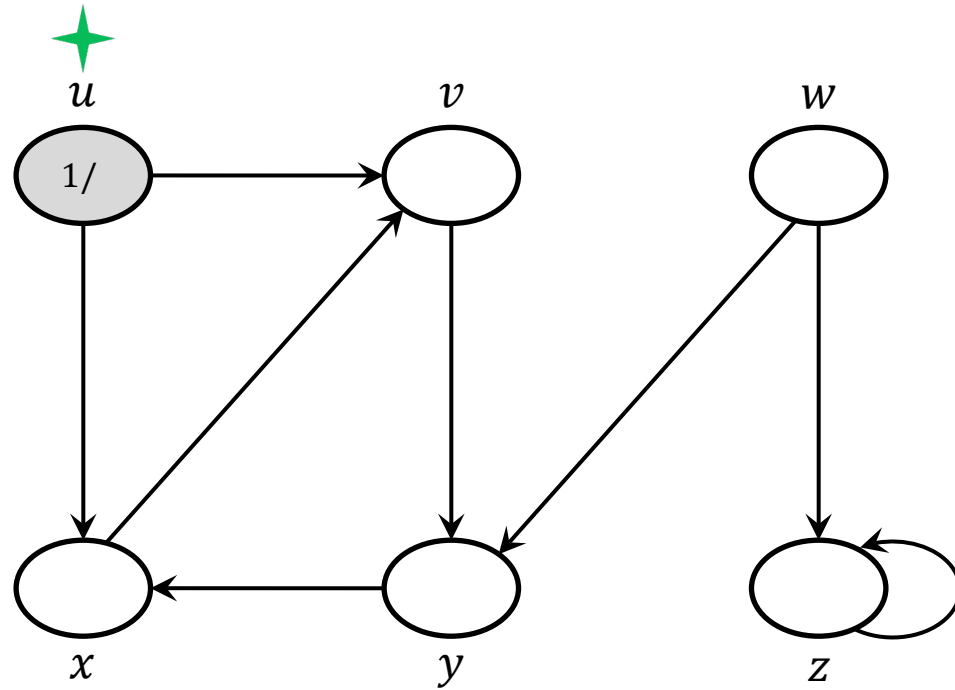
DFS (G)

1. *for each vertex $u \in G.V$ do*
2. $u.color \leftarrow \text{WHITE}, u.\pi \leftarrow \text{NIL}$
3. $time \leftarrow 0$
4. *for each $u \in G.V$ do*
5. *if $u.color = \text{WHITE}$ then*
6. $DFS-VISIT(G, u)$

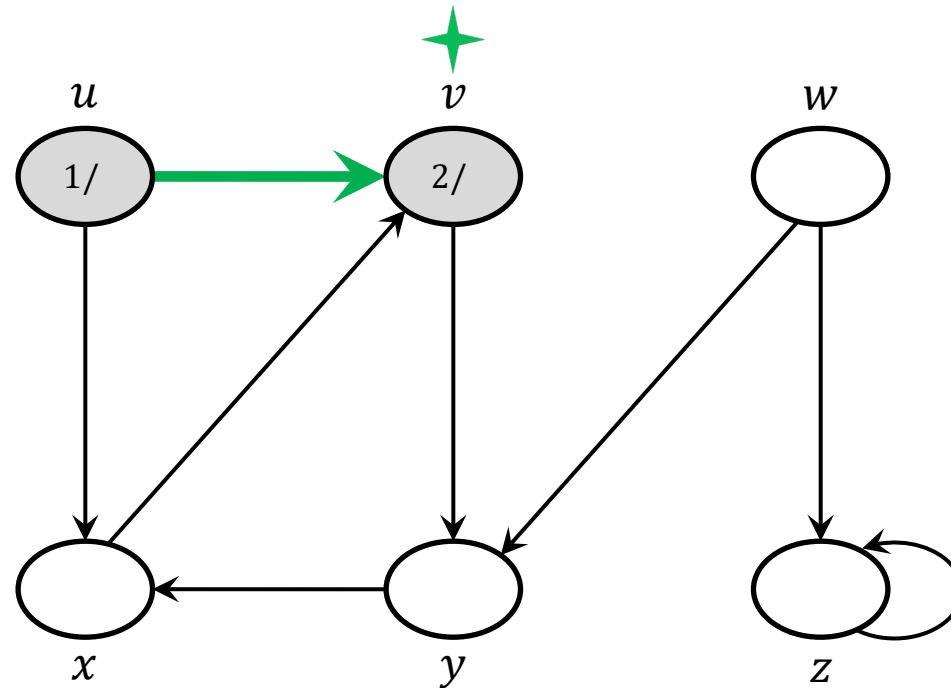
DFS-VISIT (G, u)

1. $time \leftarrow time + 1$
2. $u.d \leftarrow time$
3. $u.color \leftarrow \text{GRAY}$
4. *for each $v \in G.Adj[u]$ do*
5. *if $v.color = \text{WHITE}$ then*
6. $v.\pi \leftarrow u$
7. $DFS-VISIT(G, v)$
8. $u.color \leftarrow \text{BLACK}$
9. $time \leftarrow time + 1$
10. $u.f \leftarrow time$

Depth-First Search (DFS)

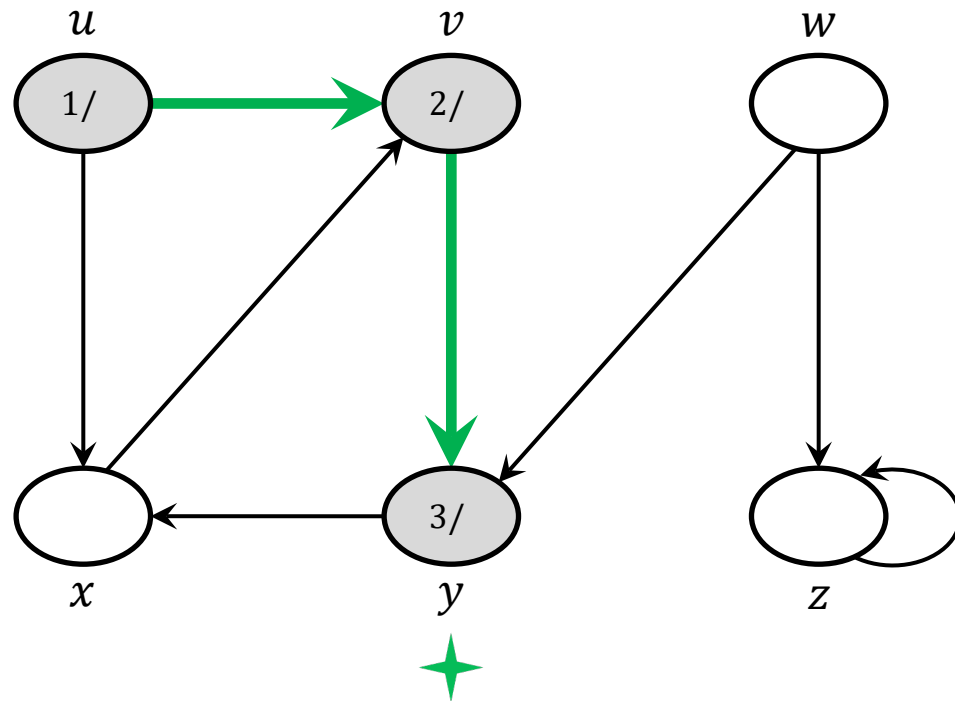


Depth-First Search (DFS)

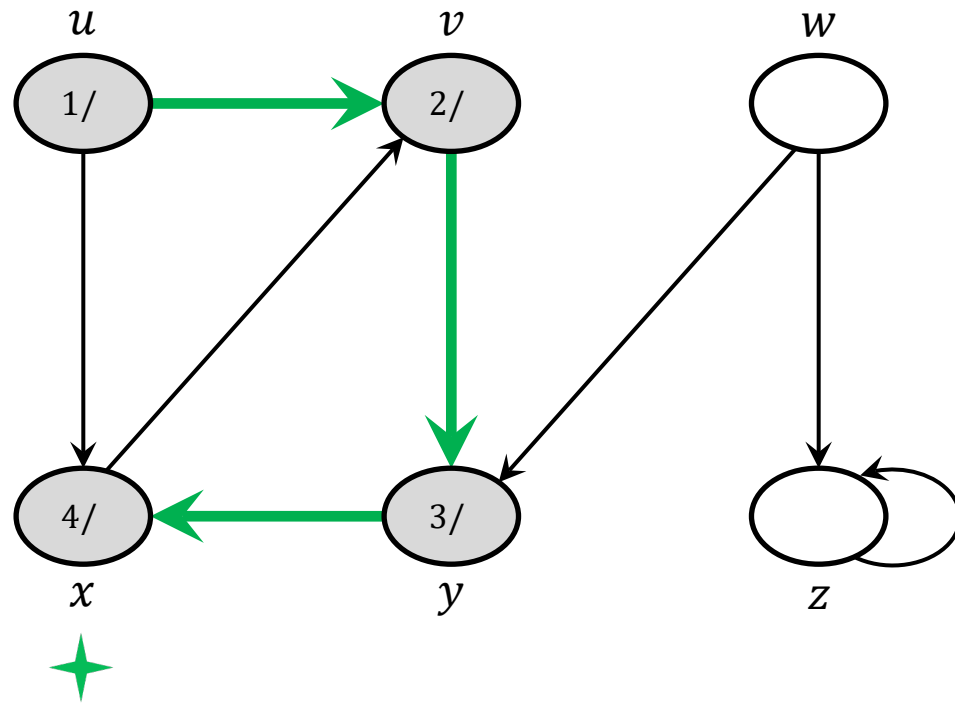


Tree Edge (T): These are edges in the depth-first forest G_π . Edge (u, v) is a tree edge if v was first discovered by exploring that edge. In the example above, we will make all tree edges green and thick.

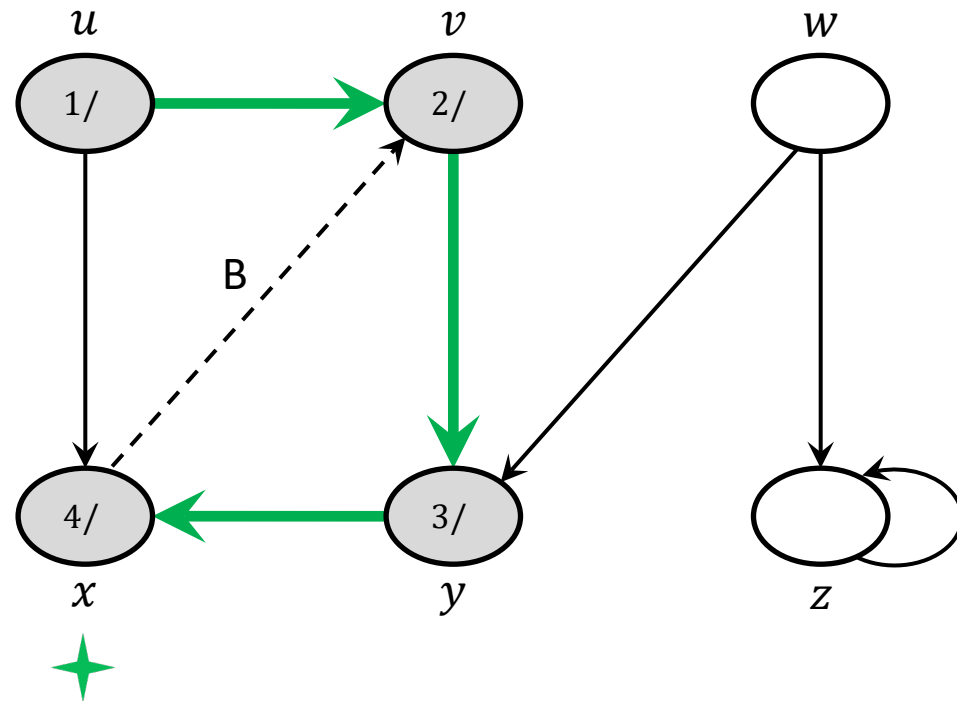
Depth-First Search (DFS)



Depth-First Search (DFS)

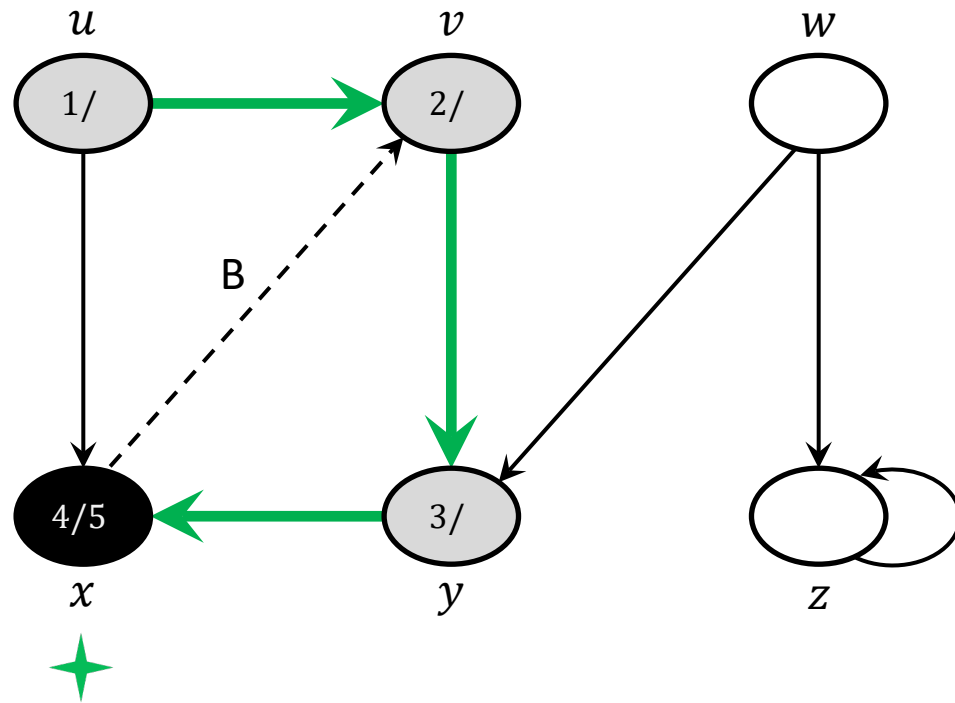


Depth-First Search (DFS)

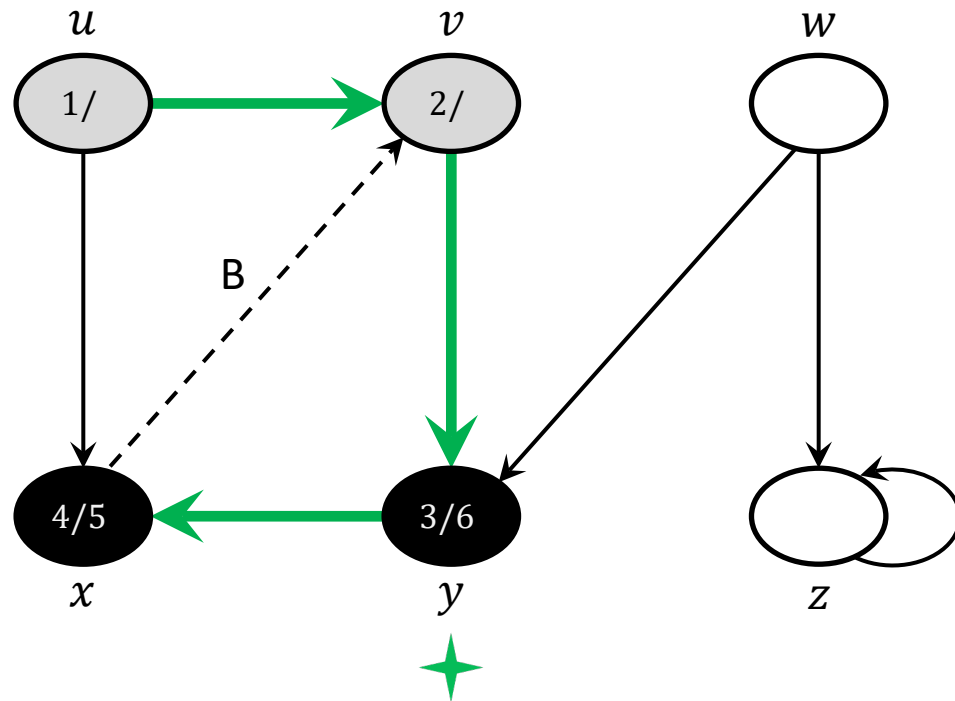


Back Edge (B): A back edge goes from a vertex to its ancestor in a depth-first tree. Self-loops are also considered back edges.

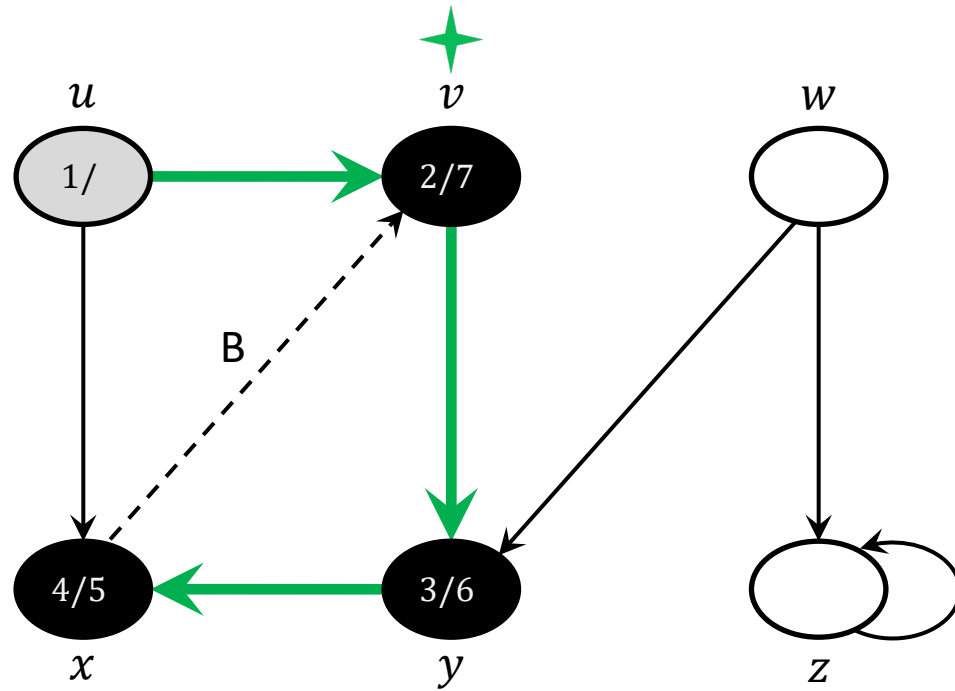
Depth-First Search (DFS)



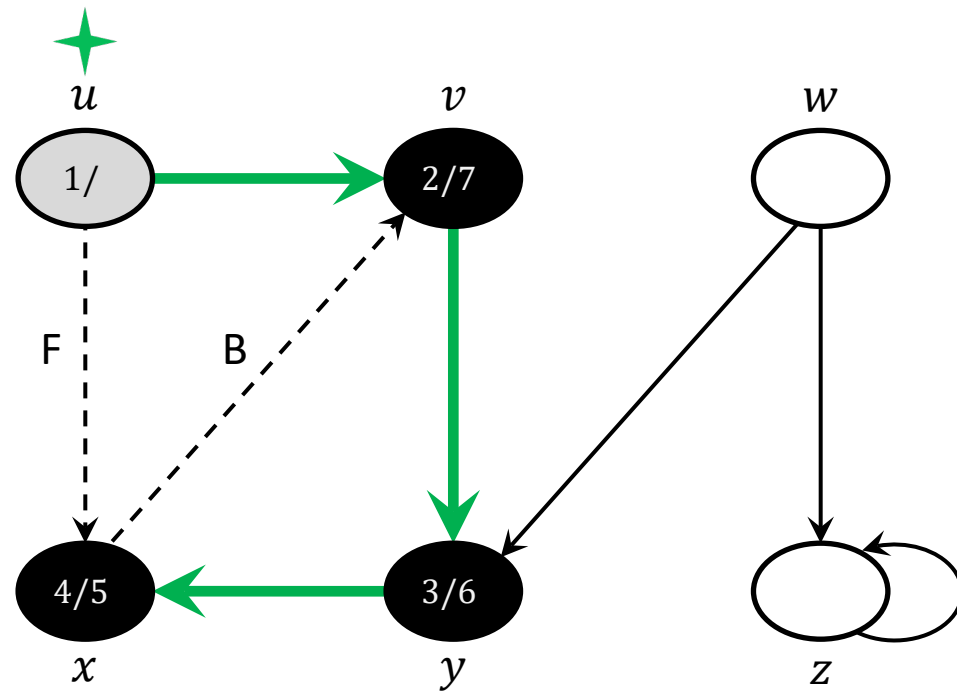
Depth-First Search (DFS)



Depth-First Search (DFS)

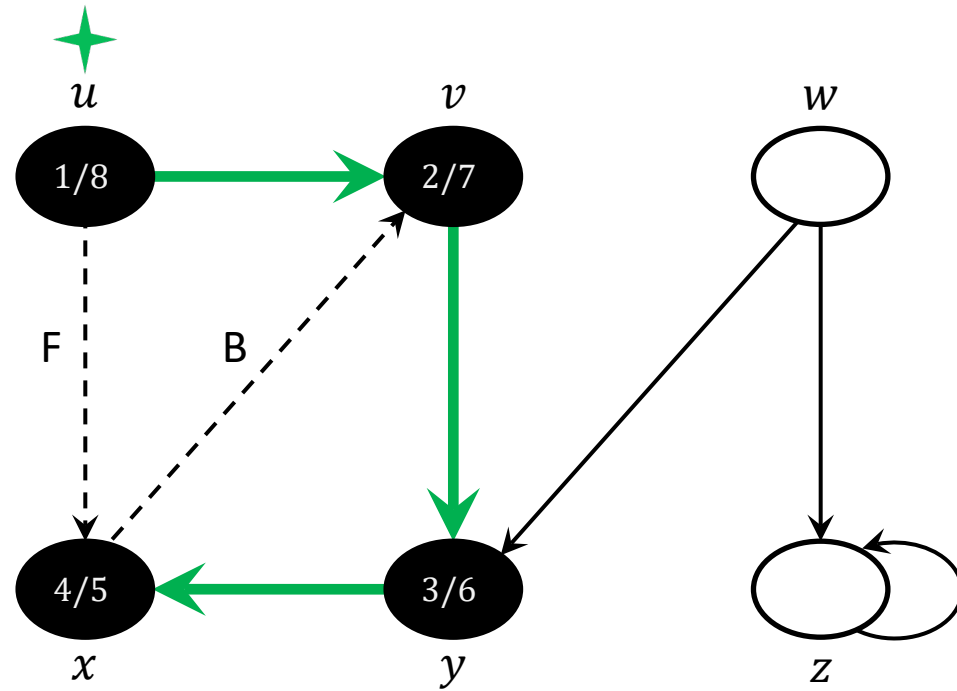


Depth-First Search (DFS)

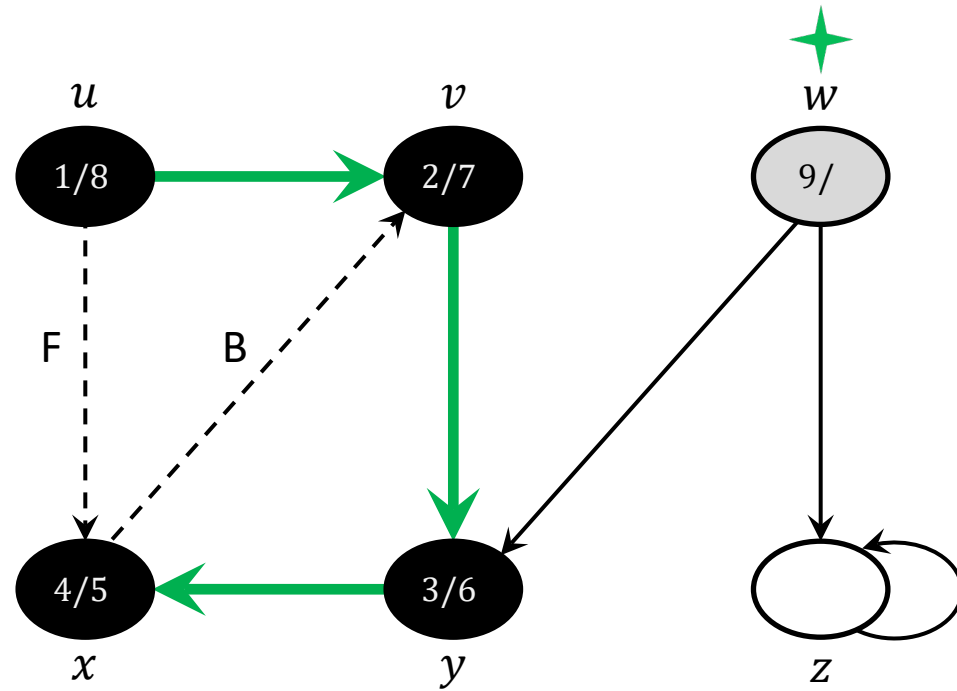


Forward Edge (F): A forward edge is a nontree edge that connects a vertex to a descendant in a depth-first tree.

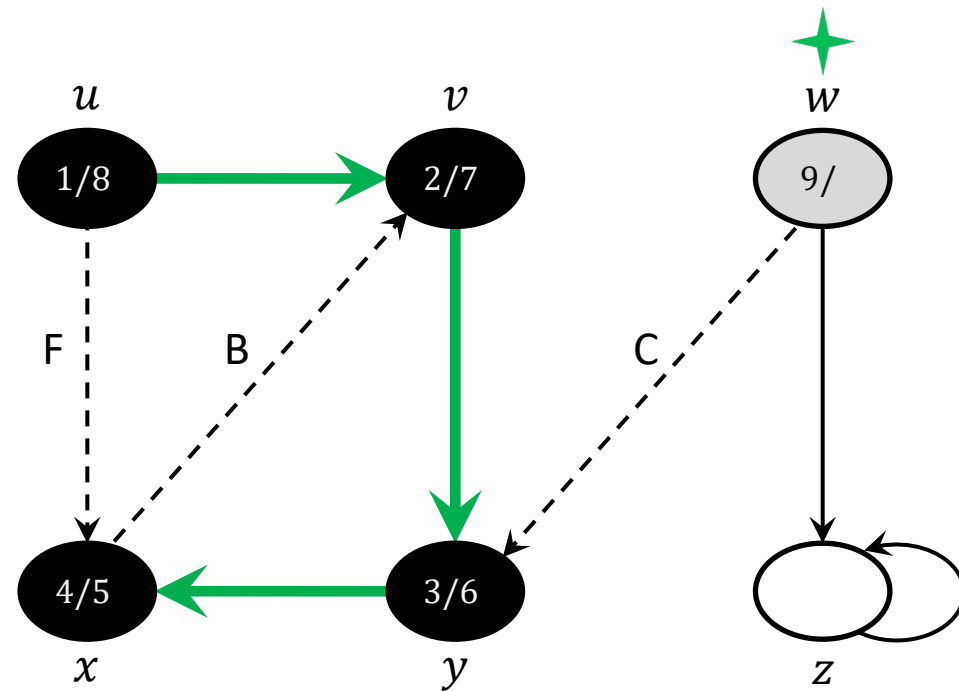
Depth-First Search (DFS)



Depth-First Search (DFS)

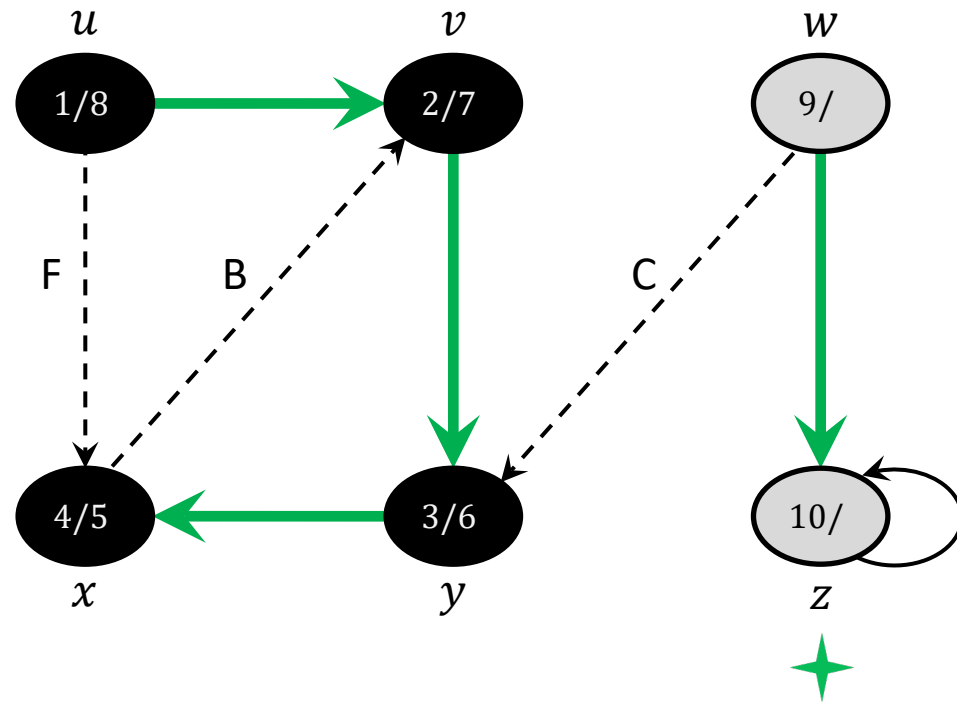


Depth-First Search (DFS)

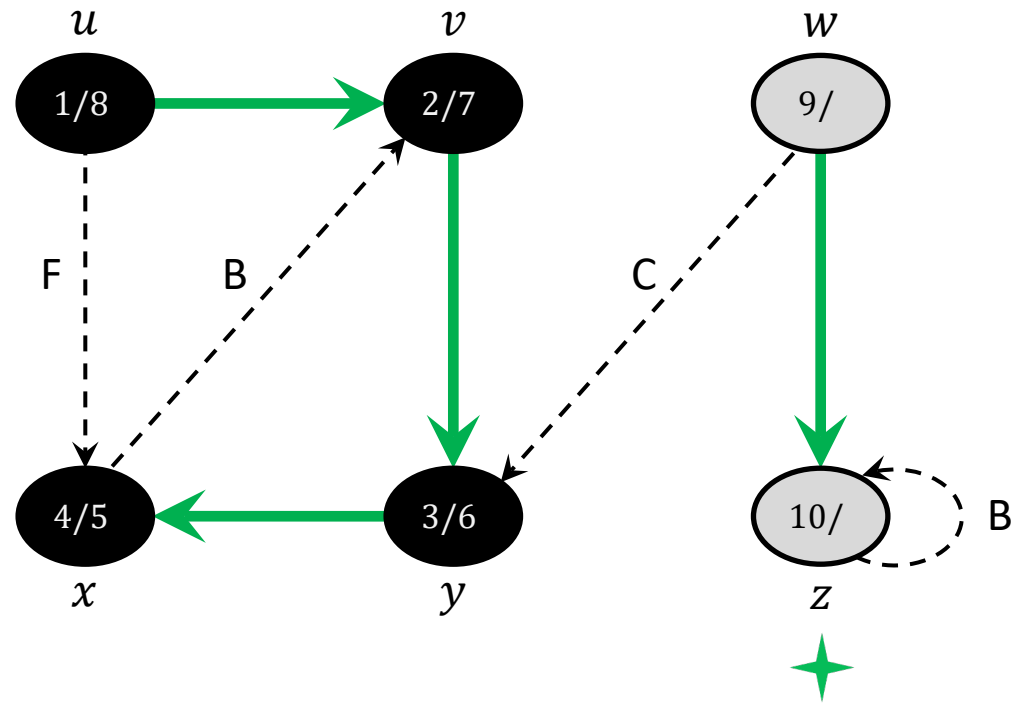


Cross Edge (C): If a non-tree edge is neither a back edge nor a forward edge then it's a cross edge. Cross edges can go between vertices in the same depth-first tree or in different depth-first trees.

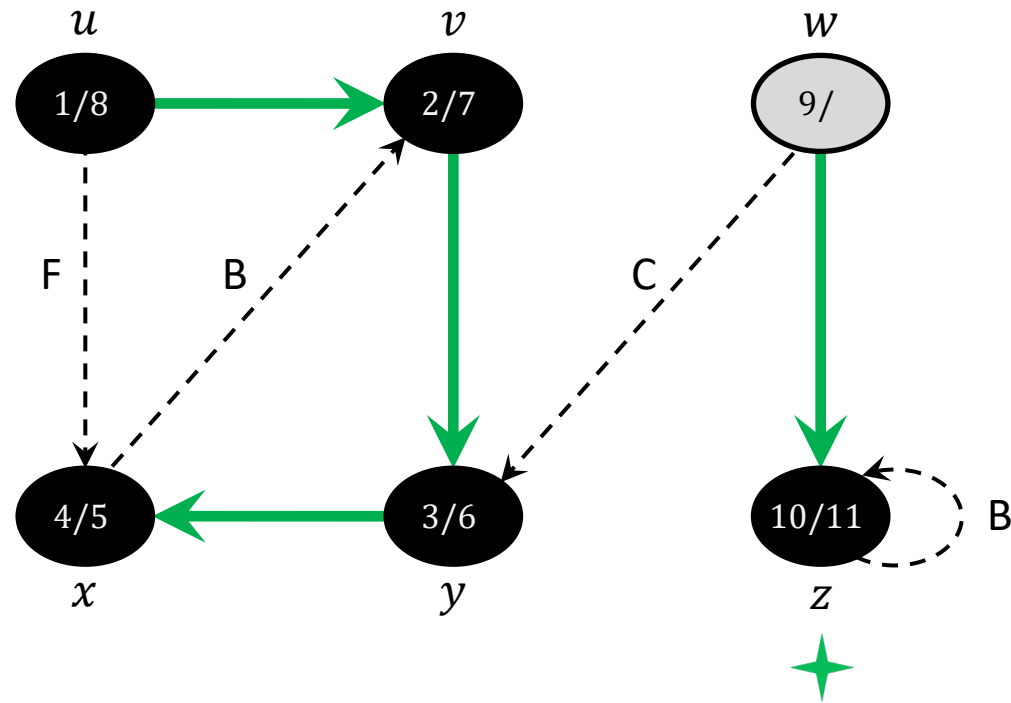
Depth-First Search (DFS)



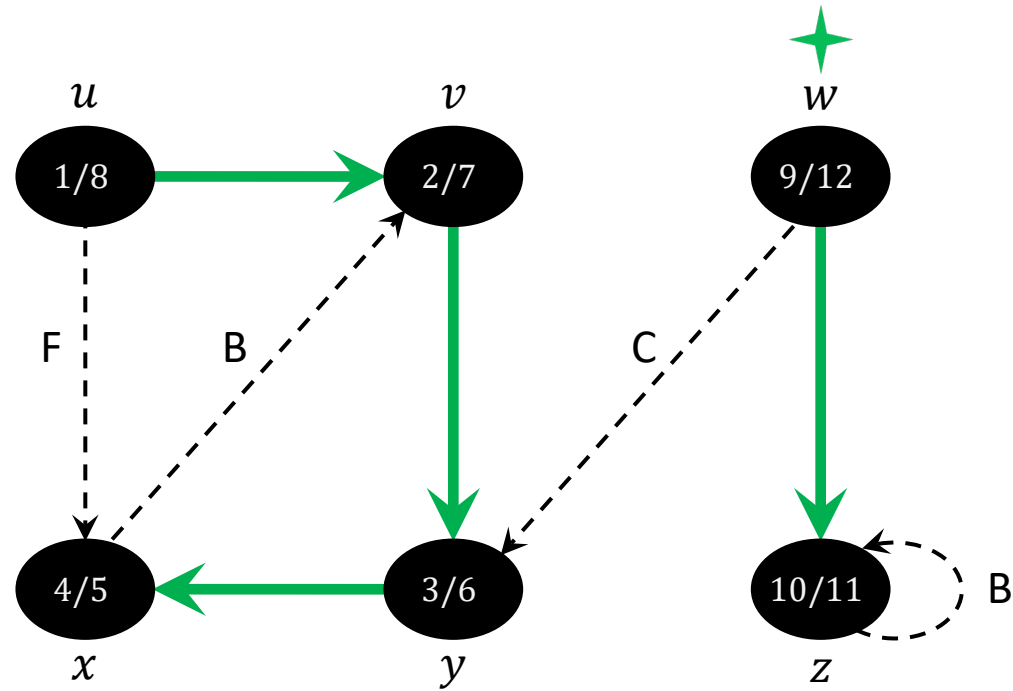
Depth-First Search (DFS)



Depth-First Search (DFS)



Depth-First Search (DFS)



Depth-First Search (DFS)

DFS (G)

1. *for* each vertex $u \in G.V$ *do*
2. $u.color \leftarrow \text{WHITE}, u.\pi \leftarrow \text{NIL}$
3. $time \leftarrow 0$
4. *for* each $u \in G.V$ *do*
5. *if* $u.color = \text{WHITE}$ *then*
6. *DFS-VISIT*(G, u)

DFS-VISIT (G, u)

1. $time \leftarrow time + 1$
2. $u.d \leftarrow time$
3. $u.color \leftarrow \text{GRAY}$
4. *for* each $v \in G.Adj[u]$ *do*
5. *if* $v.color = \text{WHITE}$ *then*
6. $v.\pi \leftarrow u$
7. *DFS-VISIT*(G, v)
8. $u.color \leftarrow \text{BLACK}$
9. $time \leftarrow time + 1$
10. $u.f \leftarrow time$

Let $n = |G.V|$ and $m = |G.E|$

Time spent

- in *DFS* (exclusive of calls to *DFS-VISIT*) = $\Theta(n)$
- in *DFS-VISIT* scanning the adjacency lists = $\Theta(\sum_{v \in G.V} |G.Adj[v]|)$
= $\Theta(m)$

\therefore Total cost = $\Theta(m + n)$

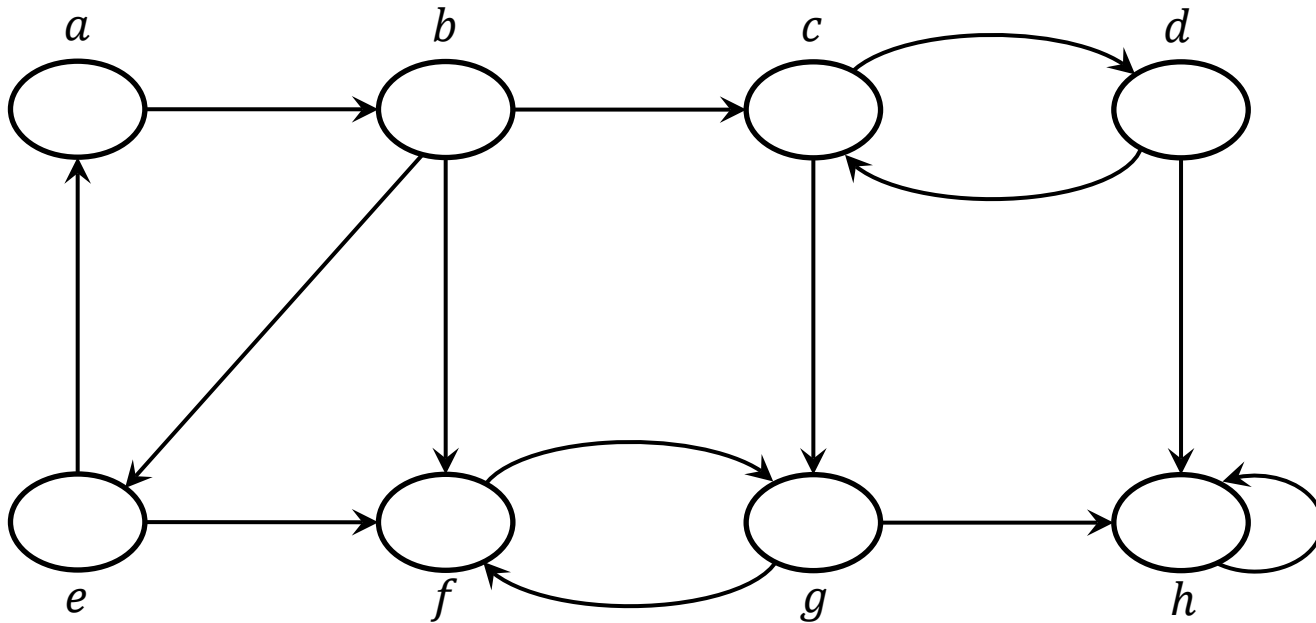
Optional
Strongly Connected
Components

Strongly Connected Components

A ***strongly connected component*** of a directed graph $G = (V, E)$ is a maximal set of vertices $C \subseteq V$ such that for every pair of vertices u and v in C , we have both $u \rightsquigarrow v$ and $v \rightsquigarrow u$; that is, vertices u and v are reachable from each other.

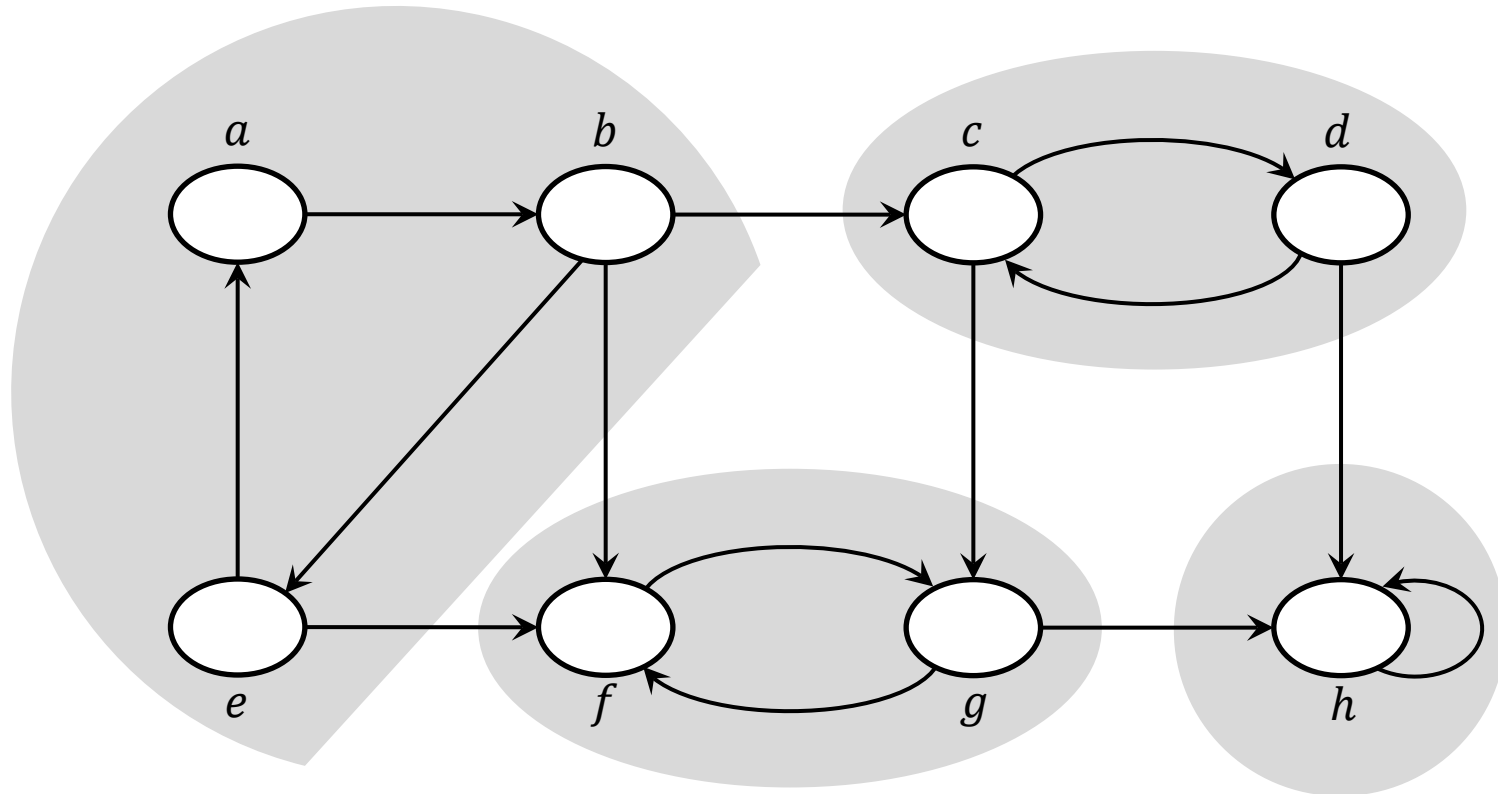
Strongly Connected Components

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Strongly Connected Components

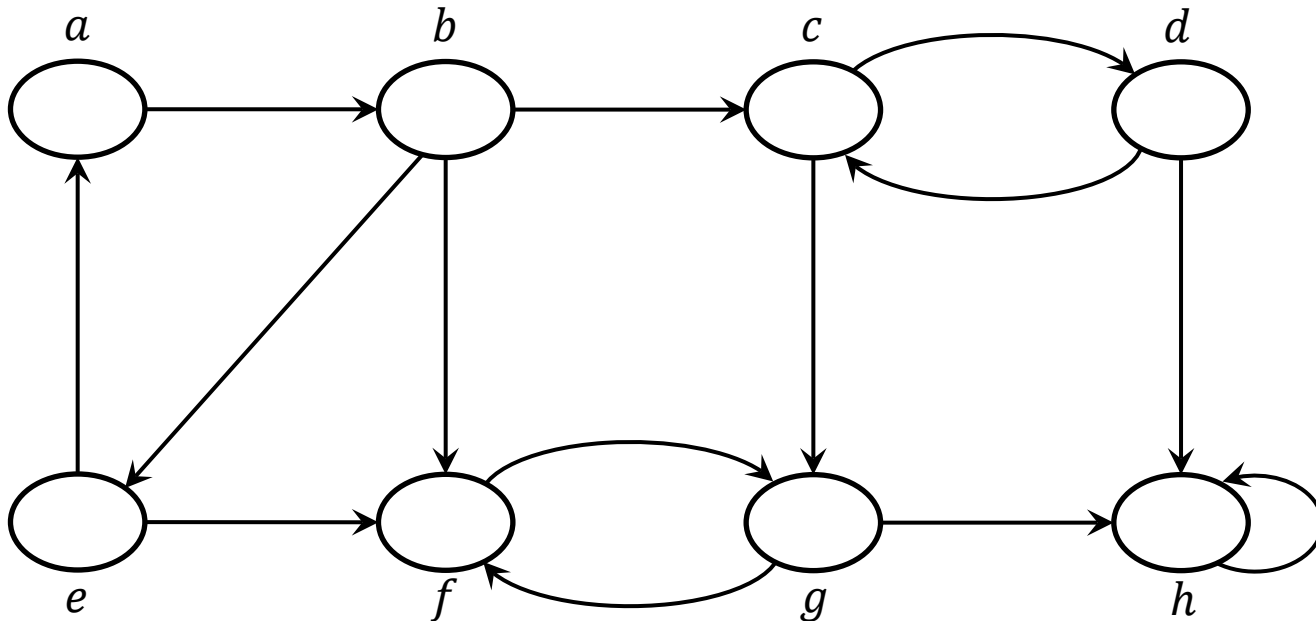
STRONGLY-CONNECTED-COMPONENTS (G)

1. call *DFS (G)* to compute the finish times $v.f$ for each vertex $v \in G.V$
2. compute G^T
3. call *DFS (G^T)*, but in the main loop of *DFS*, consider the vertices in order of decreasing $v.f$ (as computed in line 1)
4. output the vertices of each tree in the depth-first forest formed in line 3 as a separate strongly connected component

Strongly Connected Components

STRONGLY-CONNECTED-COMPONENTS (G)

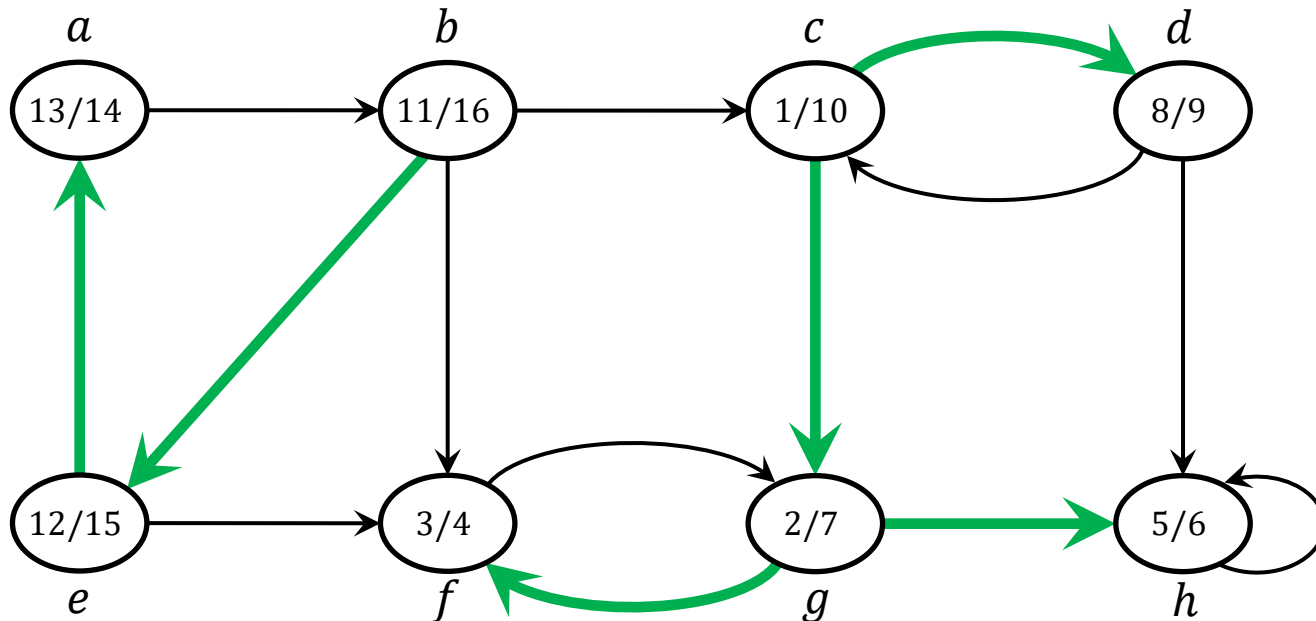
1. call $DFS (G)$ to compute the finish times $v.f$ for each vertex $v \in G.V$
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Strongly Connected Components

STRONGLY-CONNECTED-COMPONENTS (G)

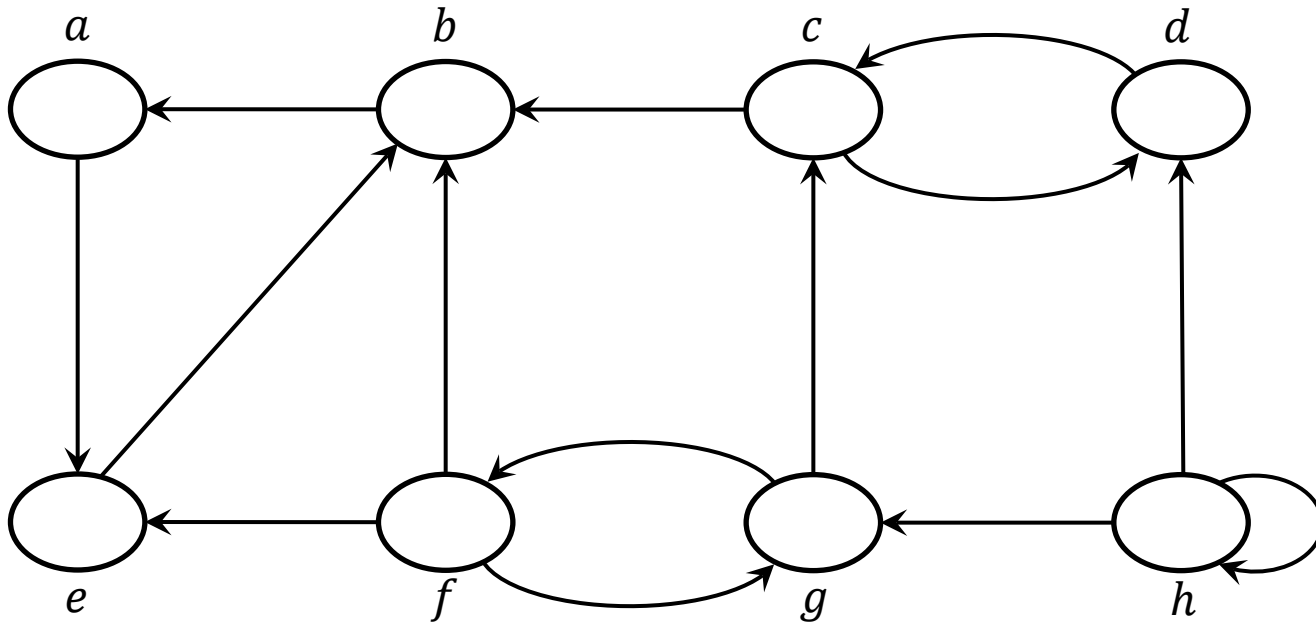
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Strongly Connected Components

STRONGLY-CONNECTED-COMPONENTS (G)

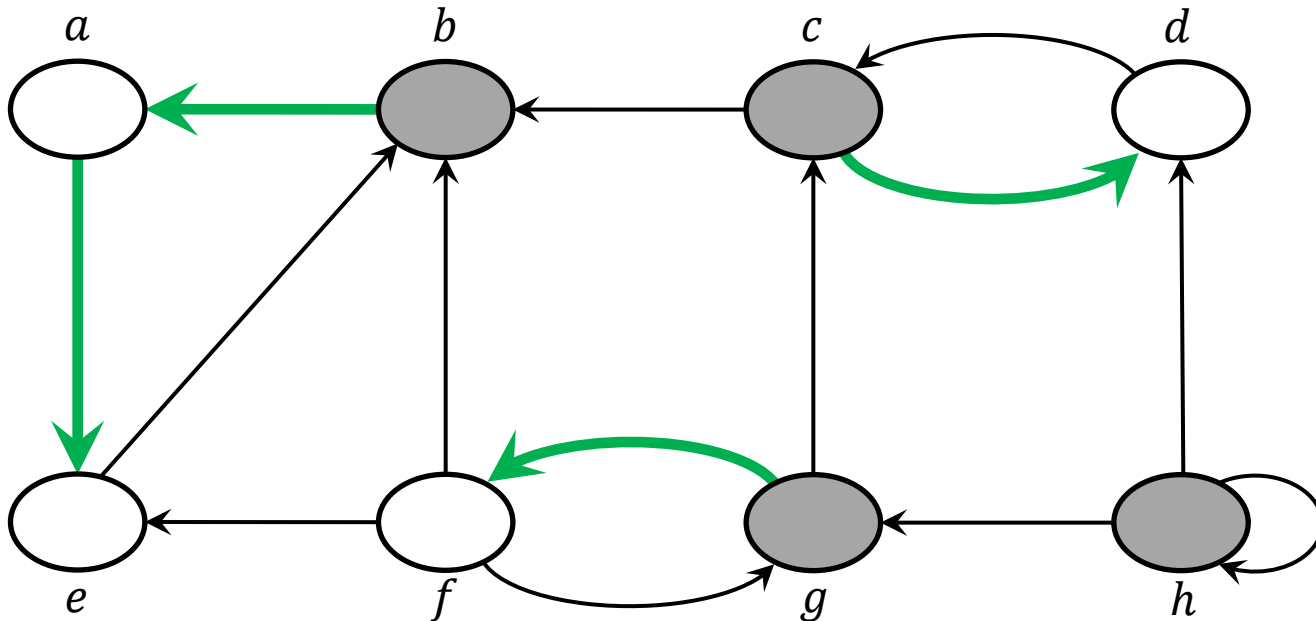
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Strongly Connected Components

STRONGLY-CONNECTED-COMPONENTS (G)

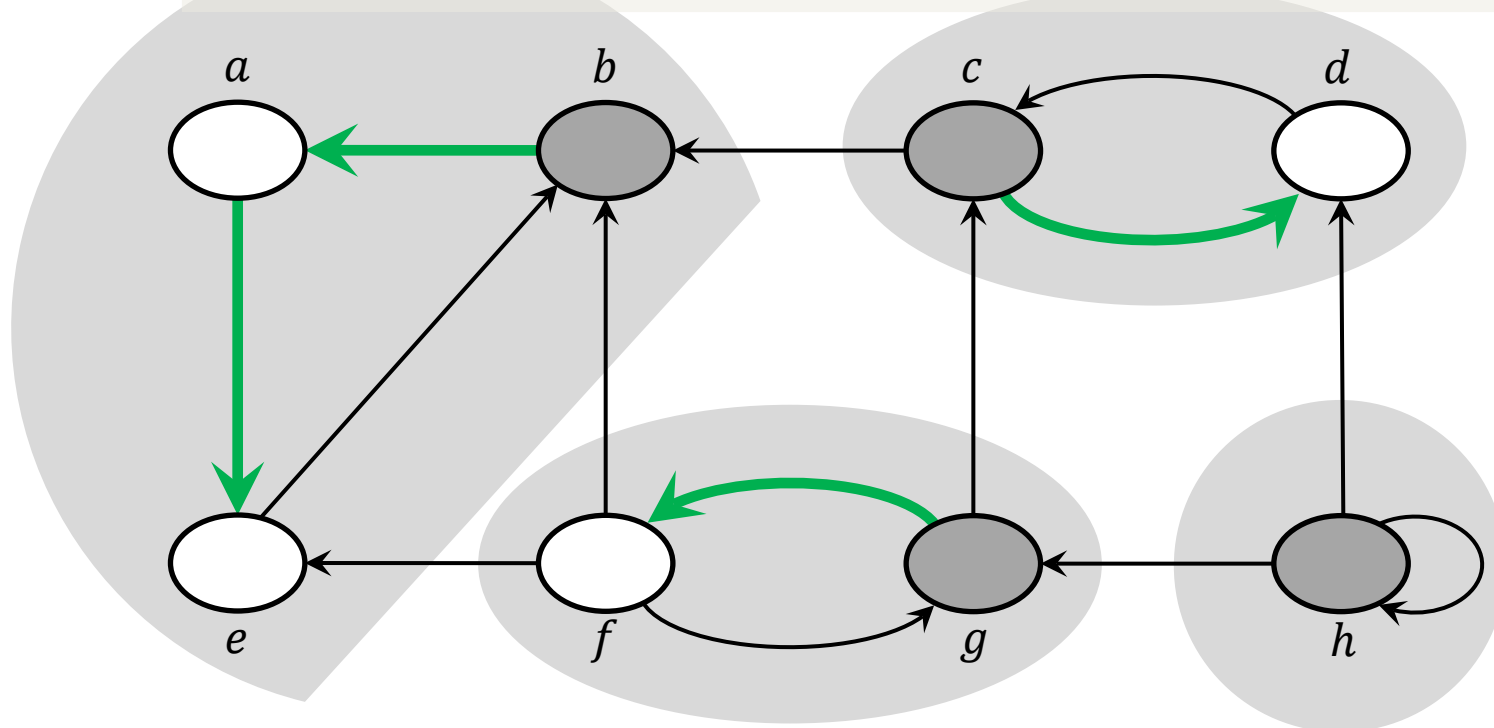
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Strongly Connected Components

STRONGLY-CONNECTED-COMPONENTS (G)

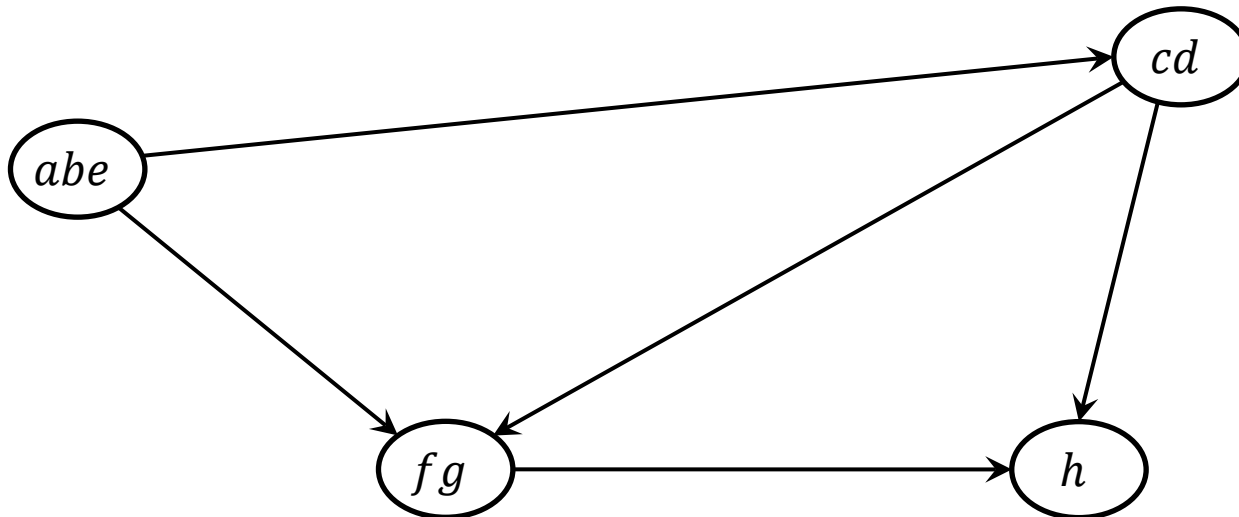
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Optional
Single-Source Shortest Paths
(SSSP):
The Bellman-Ford Algorithm

The Bellman-Ford (SSSP) Algorithm (SSSP: Single-Source Shortest Paths)

Input: Weighted graph $G = (V, E)$ with vertex set V and edge set E , a weight function w , and a source vertex $s \in G[V]$. Negative-weight edges are allowed (unlike Dijkstra's SSSP algorithm).

Output: Returns FALSE if a negative-weight cycle is reachable from s , otherwise returns TRUE and for all $v \in G[V]$, sets $v.d$ to the shortest distance from s to v .

INITIALIZE-SINGLE-SOURCE ($G = (V, E), s$)

1. *for* each vertex $v \in G.V$ *do*
2. $v.d \leftarrow \infty$
3. $v.\pi \leftarrow NIL$
4. $s.d \leftarrow 0$

RELAX (u, v, w)

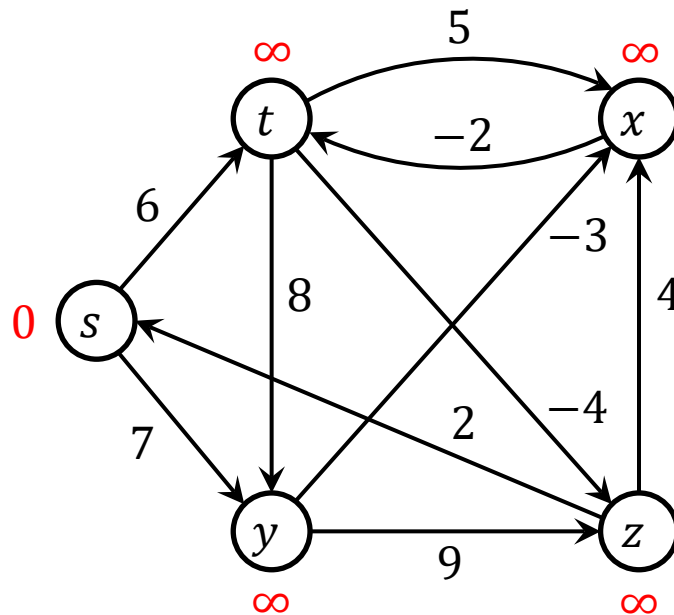
1. *if* $u.d + w(u, v) < v.d$ *then*
2. $v.d \leftarrow u.d + w(u, v)$
3. $v.\pi \leftarrow u$

BELLMAN-FORD ($G = (V, E), w, s$)

1. *INITIALIZE-SINGLE-SOURCE*(G, s)
2. *for* $i \leftarrow 1$ *to* $|G.V| - 1$ *do*
3. *for* each $(u, v) \in G.E$ *do*
4. *RELAX*(u, v, w)
5. *for* each $(u, v) \in G.E$ *do*
6. *if* $u.d + w(u, v) < v.d$ *then*
7. *return* FALSE
8. *return* TRUE

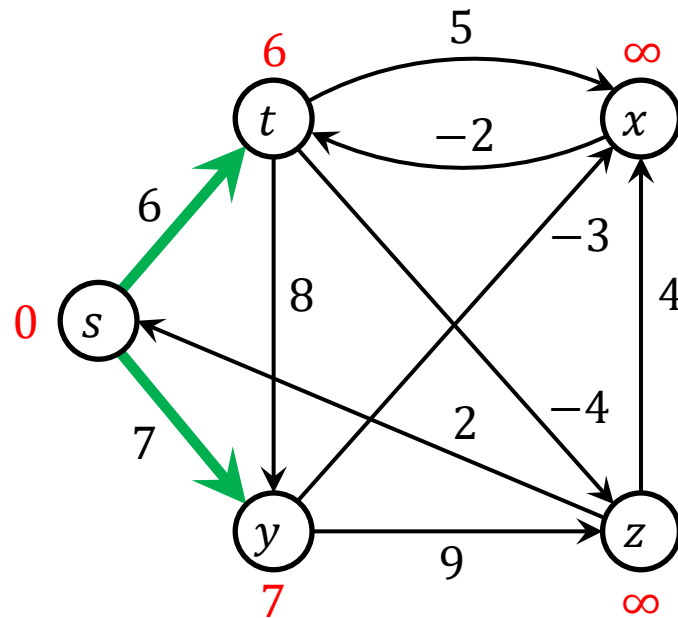
The Bellman-Ford (SSSP) Algorithm (SSSP: Single-Source Shortest Paths)

Initial State (with initial tentative distances)



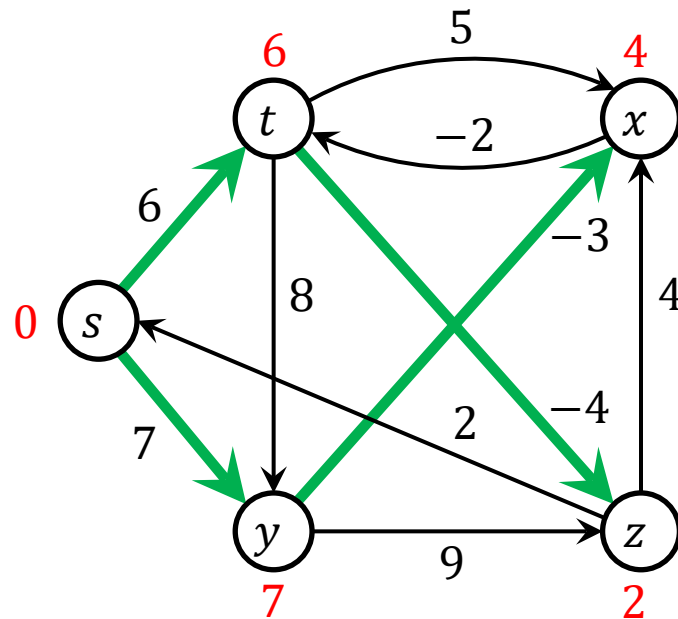
The Bellman-Ford (SSSP) Algorithm (SSSP: Single-Source Shortest Paths)

Iteration 1



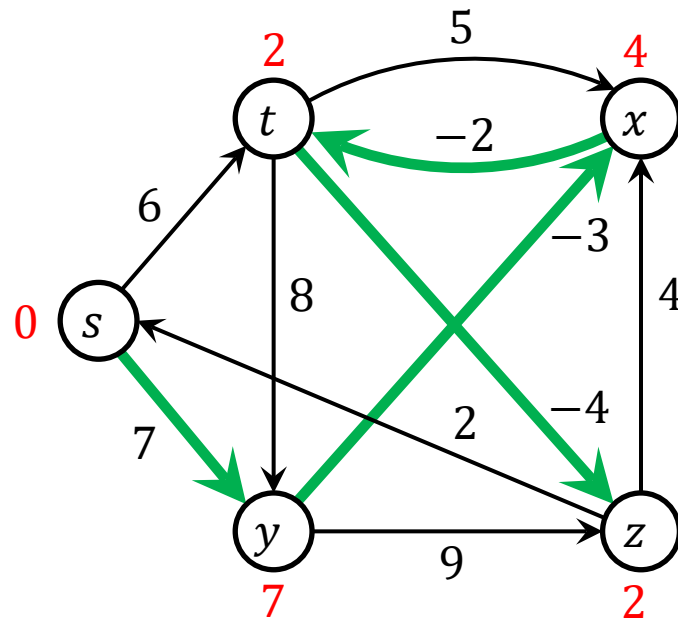
The Bellman-Ford (SSSP) Algorithm (SSSP: Single-Source Shortest Paths)

Iteration 2



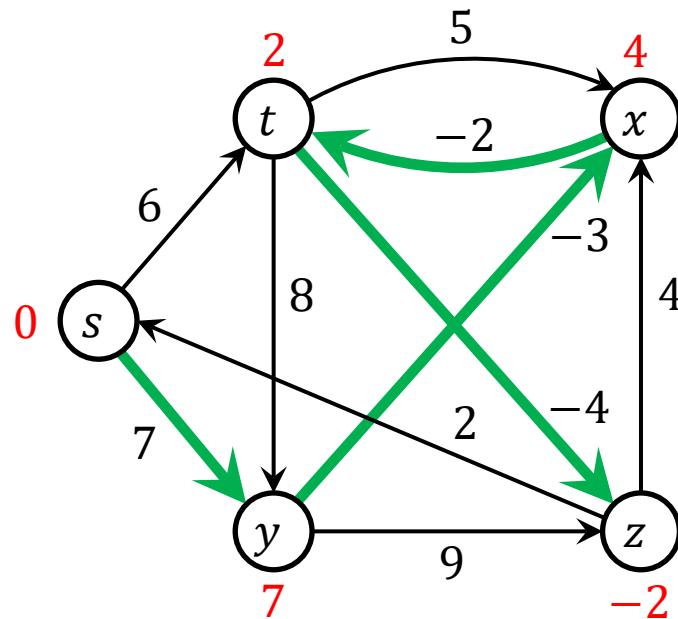
The Bellman-Ford (SSSP) Algorithm (SSSP: Single-Source Shortest Paths)

Iteration 3



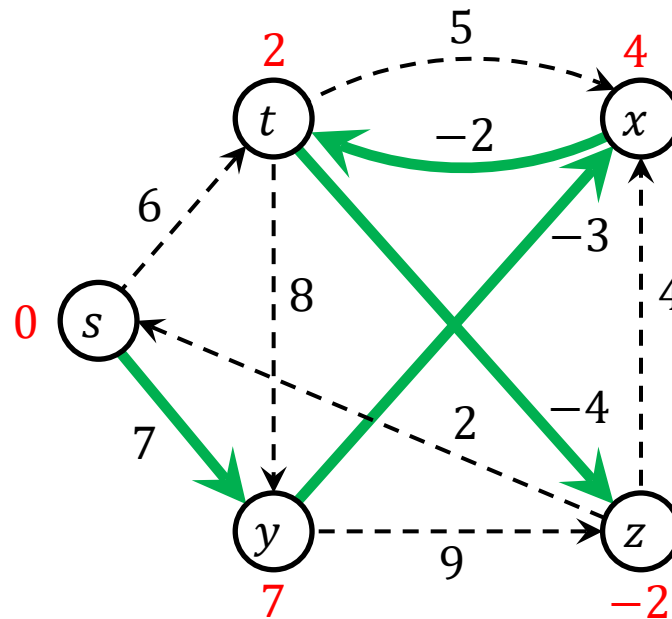
The Bellman-Ford (SSSP) Algorithm (SSSP: Single-Source Shortest Paths)

Iteration 4



The Bellman-Ford (SSSP) Algorithm (SSSP: Single-Source Shortest Paths)

Done!



The Bellman-Ford (SSSP) Algorithm (SSSP: Single-Source Shortest Paths)

INITIALIZE-SINGLE-SOURCE ($G = (V, E), s$)

1. *for* each vertex $v \in G.V$ *do*
2. $v.d \leftarrow \infty$
3. $v.\pi \leftarrow NIL$
4. $s.d \leftarrow 0$

RELAX (u, v, w)

1. *if* $u.d + w(u, v) < v.d$ *then*
2. $v.d \leftarrow u.d + w(u, v)$
3. $v.\pi \leftarrow u$

BELLMAN-FORD ($G = (V, E), w, s$)

1. *INITIALIZE-SINGLE-SOURCE*(G, s)
2. *for* $i \leftarrow 1$ *to* $|G.V| - 1$ *do*
3. *for* each $(u, v) \in G.E$ *do*
4. *RELAX*(u, v, w)
5. *for* each $(u, v) \in G.E$ *do*
6. *if* $u.d + w(u, v) < v.d$ *then*
7. *return* FALSE
8. *return* TRUE

Let $n = |V|$ and $m = |E|$

Time taken by: Line 1: $\Theta(n)$

Lines 2 – 4: $\Theta(mn)$

Lines 5 – 7: $\Theta(m)$

Total time: $\Theta(mn)$

Correctness of the Bellman-Ford Algorithm

LEMMA 24.2 (CLRS): Let $G = (V, E)$ be a weighted, directed graph with source s and weight function $w: E \rightarrow \mathbb{R}$, and suppose G contains no negative-weight cycles reachable from s . Then, after the $|V| - 1$ iterations of the for loop of lines 2–4 of **BELLMAN-FORD**, we have $v.d = \delta(s, v)$ for all vertices v that are reachable from s .

PROOF: The proof is based on the *path-relaxation property*.

Consider any $v \in G.V$ reachable from s , and let $p = \langle v_0, v_1, \dots, v_k \rangle$, where $v_0 = s$ and $v_k = v$, be any shortest path from s to v .

Because shortest paths are simple, p has at most $|V| - 1$ edges, and so $k \leq |V| - 1$. Each of the $|V| - 1$ iterations of the for loop of lines 2–4 relaxes all $|E|$ edges. Among the edges relaxed in the i^{th} iteration, for $i = 1, 2, \dots, k$, is (v_{i-1}, v_i) . By the path-relaxation property, therefore, $v.d = v_k.d = \delta(s, v_k) = \delta(s, v)$.

Correctness of the Bellman-Ford Algorithm

COROLLARY 24.3 (CLRS): Let $G = (V, E)$ be a weighted, directed graph with source s and weight function $w: E \rightarrow \mathbb{R}$, and suppose G contains no negative-weight cycles reachable from s . Then, for each $v \in V$, there is a path from s to v if and only if **BELLMAN-FORD** terminates with $v.d < \infty$ when it is run on G .

Correctness of the Bellman-Ford Algorithm

THEOREM 24.4 (CLRS): Let *BELLMAN-FORD* be run on a weighted, directed graph $G = (V, E)$ with source s and weight function $w: E \rightarrow \mathbb{R}$. If G contains no negative-weight cycles reachable from s , then the algorithm returns TRUE, we have $v.d = \delta(s, v)$ for all $v \in V$, and the predecessor subgraph G_π is a shortest-paths tree rooted at s . If G does contain a negative-weight cycle reachable from s , then the algorithm returns FALSE.

Correctness of the Bellman-Ford Algorithm

PROOF OF THEOREM 24.4: Two cases:

G contains no negative-weight cycles reachable from s :

If $v \in G.V$ is reachable from s then according to Lemma 24.2 we have $v.d = \delta(s, v)$ at termination. Otherwise, $v.d = \delta(s, v) = \infty$ follows from the *no-path property*.

The *predecessor-subgraph property*, along with $v.d = \delta(s, v)$, implies that G_π is a shortest-paths tree.

Now, since at termination, for all edges $(u, v) \in G.E$, we have, $v.d = \delta(s, v)$ and $u.d = \delta(s, u)$, then by *triangle inequality*:

$$v.d = \delta(s, v) \leq \delta(s, u) + w(u, v) = u.d + w(u, v).$$

So, none of the tests in line 6 causes **BELLMAN-FORD** to return FALSE.

Therefore, it returns TRUE.

Correctness of the Bellman-Ford Algorithm

PROOF OF THEOREM 24.4 (CONTINUED):

G contains a negative-weight cycle reachable from s :

Let $c = \langle v_0, v_1, \dots, v_k \rangle$ be the cycle, where $v_0 = v_k$. Then

$$\sum_{i=1}^k w(v_{i-1}, v_i) < 0.$$

Assume for the sake of contradiction that **BELLMAN-FORD** returns TRUE.

Then $v_i.d \leq v_{i-1}.d + w(v_{i-1}, v_i)$ for $i = 1, 2, \dots, k$. Thus,

$$\sum_{i=1}^k v_i.d \leq \sum_{i=1}^k (v_{i-1}.d + w(v_{i-1}, v_i)) = \sum_{i=1}^k v_{i-1}.d + \sum_{i=1}^k w(v_{i-1}, v_i)$$

But $\sum_{i=1}^k v_i.d = \sum_{i=1}^k v_{i-1}.d$, and by Corollary 24.3, each $v_i.d$ is finite.

Thus, $\sum_{i=1}^k w(v_{i-1}, v_i) \geq 0$, which contradicts our initial assumption that $c = \langle v_0, v_1, \dots, v_k \rangle$ is a negative-weight cycle.

Optional
All-Pairs Shortest Paths (APSP)
using an Operation Similar to
Matrix Multiplication

APSP: Extending SPs by One Edge at a Time

Let $l_{ij}^{(m)}$ be the minimum weight of any path from vertex i to vertex j that contains at most m edges. Then

$$l_{ij}^{(m)} = \begin{cases} 0, & \text{if } m = 0 \text{ and } i = j, \\ \infty & \text{if } m = 0 \text{ and } i \neq j, \\ \min_{1 \leq k \leq n} \{l_{ik}^{(m-1)} + w_{kj}\}, & \text{otherwise (i.e., } m > 0\text{)}. \end{cases}$$

If G has no negative-weight cycles, then for every pair of vertices i and j for which $\delta(i, j) < \infty$, there is a shortest path from i to j that is simple and thus contains at most $n - 1$ edges. A path from vertex i to vertex j with more than $n - 1$ edges cannot have lower weight than a shortest path from i to j . Hence,

$$\delta(i, j) = l_{ij}^{(n-1)} = l_{ij}^{(n)} = l_{ij}^{(n+1)} = \dots$$

APSP: Extending SPs by One Edge at a Time

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If G has no negative-weight cycles, then for every pair of vertices i and j for which $\delta(i, j) < \infty$, there is a shortest path from i to j that is simple and thus contains at most $n - 1$ edges. A path from vertex i to vertex j with more than $n - 1$ edges cannot have lower weight than a shortest path from i to j . Hence,

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APSP: Extending SPs by One Edge at a Time

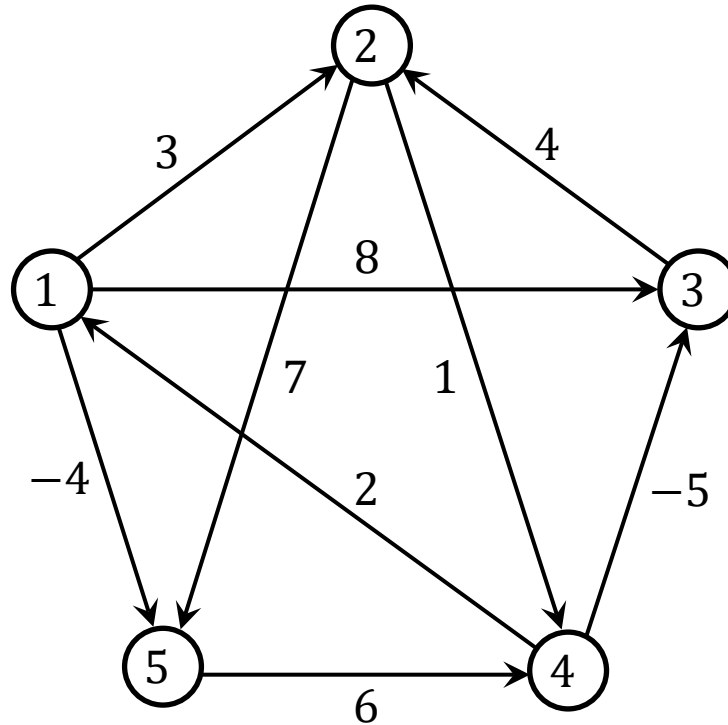
EXTEND-SHORTEST-PATHS (L, W)

1. $n \leftarrow L.rows$
2. let $L' = (l'_{ij})$ be a new $n \times n$ matrix
3. *for* $i \leftarrow 1$ *to* n *do*
4. *for* $j \leftarrow 1$ *to* n *do*
5. $l'_{ij} \leftarrow \infty$
6. *for* $k \leftarrow 1$ *to* n *do*
7. $l'_{ij} \leftarrow \min(l'_{ij}, l'_{ik} + w_{kj})$
8. *return* L'

SLOW-ALL-PAIRS-SHORTEST-PATHS (W)

1. $n \leftarrow W.rows$
2. $L^{(1)} \leftarrow W$
3. *for* $m \leftarrow 2$ *to* $n - 1$ *do*
4. let $L^{(m)}$ be a new $n \times n$ matrix
5. $L^{(m)} \leftarrow \text{EXTEND-SHORTEST-PATHS}(L^{(m-1)}, W)$
6. *return* $L^{(n-1)}$

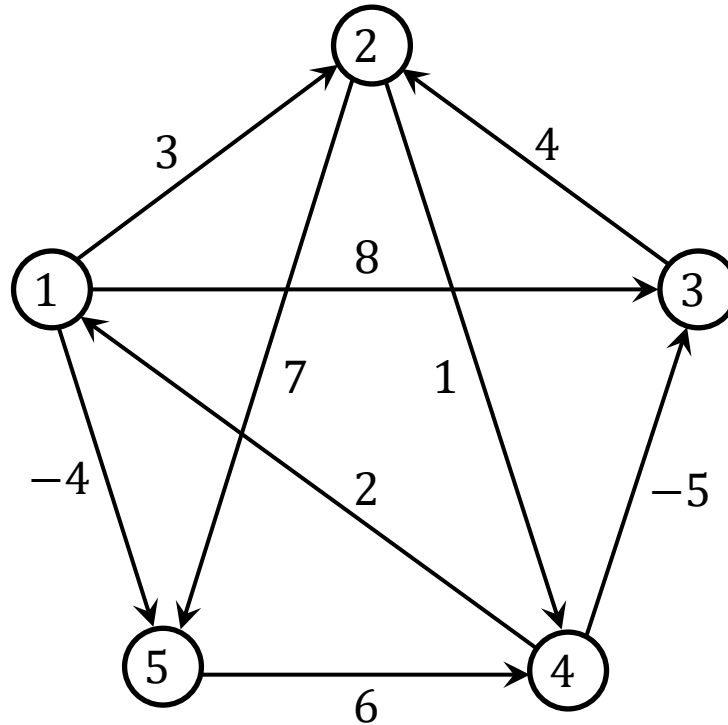
APSP: Extending SPs by One Edge at a Time



$$W = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$L^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

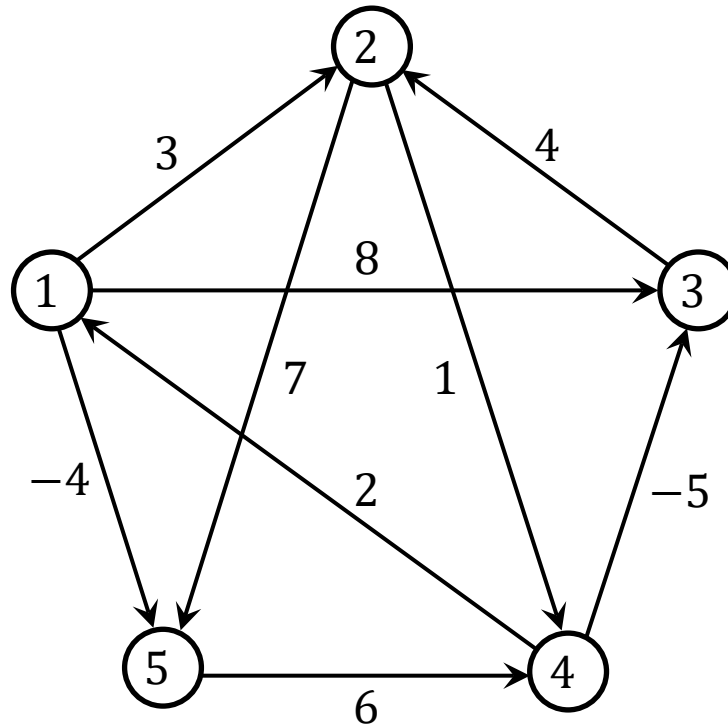
APSP: Extending SPs by One Edge at a Time



$$L^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$$L^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 2 & -4 \\ 3 & 0 & -4 & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & \infty & 1 & 6 & 0 \end{pmatrix}$$

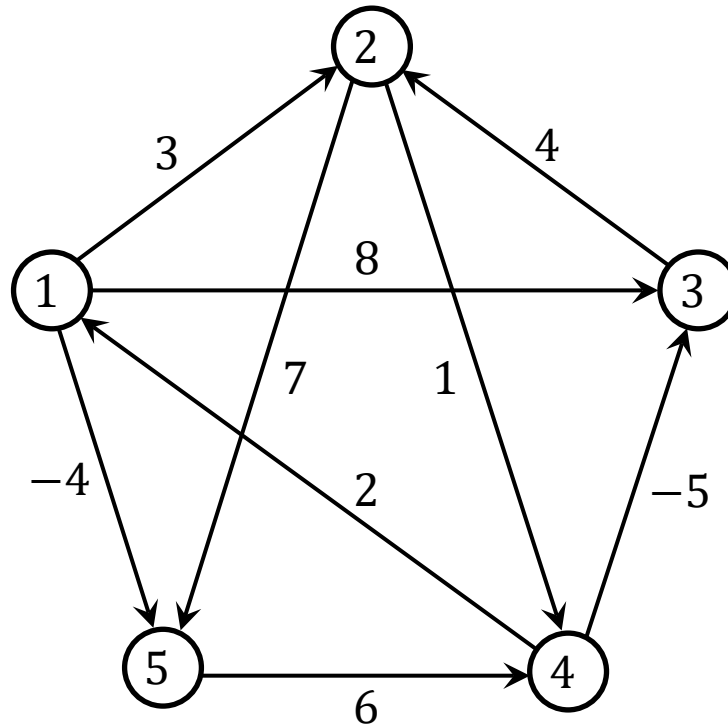
APSP: Extending SPs by One Edge at a Time



$$L^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 2 & -4 \\ 3 & 0 & -4 & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & \infty & 1 & 6 & 0 \end{pmatrix}$$

$$L^{(3)} = \begin{pmatrix} 0 & 3 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

APSP: Extending SPs by One Edge at a Time



$$L^{(3)} = \begin{pmatrix} 0 & 3 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

$$L^{(4)} = \begin{pmatrix} 0 & 1 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

APSP: Extending SPs by One Edge at a Time

Note the similarity between *EXTEND-SHORTEST-PATHS* and *SQUARE-MATRIX-MULTIPLY*:

EXTEND-SHORTEST-PATHS (L, W)

1. $n \leftarrow L.\text{rows}$
2. let $L' = (l'_{ij})$ be a new $n \times n$ matrix
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5. $l'_{ij} \leftarrow \infty$
6. *for* $k \leftarrow 1$ *to* n *do*
7. $l'_{ij} \leftarrow \min(l'_{ij}, l'_{ik} + w_{kj})$
8. *return* L'

SQUARE-MATRIX-MULTIPLY (A, B)

1. $n \leftarrow A.\text{rows}$
2. let $C = (c_{ij})$ be a new $n \times n$ matrix
3. *for* $i \leftarrow 1$ *to* n *do*
4. *for* $j \leftarrow 1$ *to* n *do*
5. $c_{ij} \leftarrow 0$
6. *for* $k \leftarrow 1$ *to* n *do*
7. $c_{ij} \leftarrow c_{ij} + a_{ik} \cdot b_{kj}$
8. *return* C

Both have the same $\Theta(n^3)$ running time.

APSP: Extending SPs by One Edge at a Time

EXTEND-SHORTEST-PATHS (L, W)

1. $n \leftarrow L.rows$
2. let $L' = (l'_{ij})$ be a new $n \times n$ matrix
3. *for* $i \leftarrow 1$ *to* n *do*
4. *for* $j \leftarrow 1$ *to* n *do*
5. $l'_{ij} \leftarrow \infty$
6. *for* $k \leftarrow 1$ *to* n *do*
7. $l'_{ij} \leftarrow \min(l'_{ij}, l'_{ik} + w_{kj})$
8. *return* L'

Running time
 $= \Theta(n^3)$

SLOW-ALL-PAIRS-SHORTEST-PATHS (W)

1. $n \leftarrow W.rows$
2. $L^{(1)} \leftarrow W$
3. *for* $m \leftarrow 2$ *to* $n - 1$ *do*
4. let $L^{(m)}$ be a new $n \times n$ matrix
5. $L^{(m)} \leftarrow \text{EXTEND-SHORTEST-PATHS}(L^{(m-1)}, W)$
6. *return* $L^{(n-1)}$

Running time
 $= n \times \Theta(n^3)$
 $= \Theta(n^4)$

APSP: Extending SPs by Repeated Squaring

EXTEND-SHORTEST-PATHS (L, W)

1. $n \leftarrow L.rows$
2. let $L' = (l'_{ij})$ be a new $n \times n$ matrix
3. *for* $i \leftarrow 1$ *to* n *do*
4. *for* $j \leftarrow 1$ *to* n *do*
5. $l'_{ij} \leftarrow \infty$
6. *for* $k \leftarrow 1$ *to* n *do*
7. $l'_{ij} \leftarrow \min(l'_{ij}, l'_{ik} + w_{kj})$
8. *return* L'

FASTER-ALL-PAIRS-SHORTEST-PATHS (W)

1. $n \leftarrow W.rows$
2. $L^{(1)} \leftarrow W$
3. $m \leftarrow 1$
4. *while* $m < n - 1$ *do*
5. let $L^{(2m)}$ be a new $n \times n$ matrix
6. $L^{(2m)} \leftarrow \text{EXTEND-SHORTEST-PATHS}(L^{(m)}, L^{(m)})$
7. $m \leftarrow 2m$
8. *return* $L^{(m)}$

APSP: Extending SPs by Repeated Squaring

EXTEND-SHORTEST-PATHS (L, W)

1. $n \leftarrow L.rows$
2. let $L' = (l'_{ij})$ be a new $n \times n$ matrix
3. *for* $i \leftarrow 1$ *to* n *do*
4. *for* $j \leftarrow 1$ *to* n *do*
5. $l'_{ij} \leftarrow \infty$
6. *for* $k \leftarrow 1$ *to* n *do*
7. $l'_{ij} \leftarrow \min(l'_{ij}, l'_{ik} + w_{kj})$
8. *return* L'

Running time
 $= \Theta(n^3)$

FASTER-ALL-PAIRS-SHORTEST-PATHS (W)

1. $n \leftarrow W.rows$
2. $L^{(1)} \leftarrow W$
3. $m \leftarrow 1$
4. *while* $m < n - 1$ *do*
5. let $L^{(2^m)}$ be a new $n \times n$ matrix
6. $L^{(2^m)} \leftarrow \text{EXTEND-SHORTEST-PATHS}(L^{(m)}, L^{(m)})$
7. $m \leftarrow 2m$
8. *return* $L^{(m)}$

Running time
 $= \lceil \log_2(n - 1) \rceil$
 $\times \Theta(n^3)$
 $= \Theta(n^3 \log n)$