# Algorithms

# (Algorithmic Problem Solving)

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### Algorithmic-problem-solving template



### Practical Algorithms (HOME)

# Webpage Ranking (HOME)

# Problem

#### Problem

- Design an algorithm to rank web pages efficiently.
- Input: A directed graph with transition probability Output: [0.310945, 0.415423, 0.248756, 0.0248756]



- Internet = directed graph
- Web pages = nodes
- Hyperlinks = edges
- Transitions are probabilistic

#### Meaning of page rank.

- Rank = relative importance
- Rank = number of times a user visits a page when they keep visiting pages via hyperlinks for a long time
- Rank = proportion of time a user spends in that page if the user spends long enough time

#### Stationary/stable distribution (SD).

• If a user visits pages of the Internet for a long period of time as per transition probabilities, the distribution stabilizes and this is called stationary/stable distribution (SD)

# Page rank algorithm

- Algorithm discovered by Sergey Brin and Lawrence Page
- Core idea behind Google
- A billion-dollar algorithm
- Ranks billions of pages efficiently
- Static page ranking = ranking of all web pages on the Internet Dynamic page ranking = ranking of web pages on the Internet related to the search terms
- The relative ranks of web pages returned for search queries might be very different from their relative ranks when they are measured statically (without search terms).
- Here, we will only learn about static ranking of all web pages

T[i, j] = Probability of a user transitioning from page i to page j



Transition matrix 
$$T = \begin{bmatrix} 0 & 0.6 & 0.4 & 0 \\ 0.7 & 0 & 0.3 & 0 \\ 0 & 0.9 & 0 & 0.1 \\ 0.8 & 0.2 & 0 & 0 \end{bmatrix}$$

- Row sum (sum of outgoing prob.) should be 1
- Col sum (sum of incoming prob.) does not mean anything

 $P_t[i] = \mathsf{Probability} \text{ of a user being at page } i \text{ at time } t$ 

 $P_t[i] = \mathsf{Probability}$  of a user being at page i at time t

$$P_{t}[i] = \left\{ \begin{array}{c} P_{t-1}[1] \times T[1,i] \\ +P_{t-1}[2] \times T[2,i] \\ \vdots \\ +P_{t-1}[n] \times T[n,i] \end{array} \right\} = \sum_{j=1}^{n} \left( P_{t-1}[j] \times T[j,i] \right)$$

 $P_t[i] =$ Probability of a user being at page i at time t

$$P_{t}[i] = \left\{ \begin{array}{c} P_{t-1}[1] \times T[1,i] \\ +P_{t-1}[2] \times T[2,i] \\ \vdots \\ +P_{t-1}[n] \times T[n,i] \end{array} \right\} = \sum_{j=1}^{n} \left( P_{t-1}[j] \times T[j,i] \right)$$

$$P_{t} = [P_{t}[1] \ P_{t}[2] \ \cdots \ P_{t}[n]]$$
$$= \left[\sum_{j=1}^{n} (P_{t-1}[j] \times T[j,1]) \ \cdots \ \sum_{j=1}^{n} (P_{t-1}[j] \times T[j,n])\right]$$
$$= P_{t-1} \times T$$

 $P_t[i] =$ Probability of a user being at page i at time t

$$P_{t}[i] = \left\{ \begin{array}{c} P_{t-1}[1] \times T[1,i] \\ +P_{t-1}[2] \times T[2,i] \\ \vdots \\ +P_{t-1}[n] \times T[n,i] \end{array} \right\} = \sum_{j=1}^{n} \left( P_{t-1}[j] \times T[j,i] \right)$$

$$P_{t} = [P_{t}[1] \ P_{t}[2] \ \cdots \ P_{t}[n]]$$
$$= \left[\sum_{j=1}^{n} (P_{t-1}[j] \times T[j,1]) \ \cdots \ \sum_{j=1}^{n} (P_{t-1}[j] \times T[j,n])\right]$$
$$= P_{t-1} \times T$$

$$P_t = \begin{cases} \left[\frac{1}{n} \ \frac{1}{n} \ \cdots \ \frac{1}{n}\right] & \text{if } t = 0, \\ P_{t-1} \times T & \text{if } t > 0. \end{cases}$$

Page ranks or stable distribution P is computed as:

### $P = P \times T$

#### Questions...

- Do we always get a stable distribution (convergence)?
- If there is a stable distribution, is it always unique?
- Does every initial distribution converge to a stable distribution?

There are three major algorithms to compute page ranks or SD  $P,\,$  if it exists:

- Brute force
- System of linear equations
- Eigenvector

### $\textbf{Solutions} \rightarrow \textbf{Brute force}$



$$T = \begin{bmatrix} 0 & 0.6 & 0.4 & 0 \\ 0.7 & 0 & 0.3 & 0 \\ 0 & 0.9 & 0 & 0.1 \\ 0.8 & 0.2 & 0 & 0 \end{bmatrix}$$

	$P_t$					
t	$P_t[1]$	$P_t[2]$	$P_t[3]$	$P_t[4]$		
0	0.25	0.25	0.25	0.25		
1	0.29166667	0.30833333	0.225	0.175		
2	0.31305556	0.34305556	0.21972222	0.12416667		
3	0.32186111	0.36550926	0.22252778	0.09010185		
4	0.32388673	0.38081019	0.22781759	0.06748549		
19	0.310945	0.415423	0.248756	0.0248756		

Page ranks P = [0.310945, 0.415423, 0.248756, 0.0248756]

### Solutions $\rightarrow$ System of linear equations



$$P_t[1] = 0.7 \cdot P_t[2] + 0.8 \cdot P_t[4]$$

$$P_t[2] = 0.6 \cdot P_t[1] + 0.9 \cdot P_t[3] + 0.2 \cdot P_t[4]$$

$$P_t[3] = 0.4 \cdot P_t[1] + 0.3 \cdot P_t[2]$$

$$P_t[4] = 0.1 \cdot P_t[3]$$

$$1 = P_t[1] + P_t[2] + P_t[3] + P_t[4]$$

Page ranks P = [0.310945, 0.415423, 0.248756, 0.0248756]

# $\textbf{Solutions} \rightarrow \textbf{Eigenvector}$



$$T = \begin{bmatrix} 0 & 0.6 & 0.4 & 0 \\ 0.7 & 0 & 0.3 & 0 \\ 0 & 0.9 & 0 & 0.1 \\ 0.8 & 0.2 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} P_t[1] \ P_t[2] \ P_t[3] \ P_t[4]] = \begin{bmatrix} P_t[1] \ P_t[2] \ P_t[3] \ P_t[4]] \times \begin{bmatrix} 0 & 0.6 & 0.4 & 0 \\ 0.7 & 0 & 0.3 & 0 \\ 0 & 0.9 & 0 & 0.1 \\ 0.8 & 0.2 & 0 & 0 \end{bmatrix}$$
$$\implies \begin{bmatrix} P_t[1] \\ P_t[2] \\ P_t[3] \\ P_t[4] \end{bmatrix} = \begin{bmatrix} 0 & 0.7 & 0 & 0.8 \\ 0.6 & 0 & 0.9 & 0.2 \\ 0.4 & 0.3 & 0 & 0 \\ 0 & 0 & 0.1 & 0 \end{bmatrix} \times \begin{bmatrix} P_t[1] \\ P_t[2] \\ P_t[3] \\ P_t[4] \end{bmatrix}$$

### $\textbf{Solutions} \rightarrow \textbf{Eigenvector}$



 $(P = P \cdot T) \implies (\operatorname{col}(P) = T^{\operatorname{transpose}} \cdot \operatorname{col}(P))$ 

## Solutions $\rightarrow$ Eigenvector



which is equivalent to the formula

 $\lambda \vec{v} = A \cdot \vec{v}$ 

where  $\lambda = 1$ ,  $A = T^{\text{transpose}}$ , and  $\vec{v} = \text{col}(P)$ and  $\vec{v}$  is the eigenvector of A corresponding to eigenvalue 1. So,

# Solutions $\rightarrow$ Eigenvector



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 $\lambda \vec{v} = A \cdot \vec{v}$ 

where  $\lambda = 1$ ,  $A = T^{\text{transpose}}$ , and  $\vec{v} = \text{col}(P)$ 

and  $\vec{v}$  is the eigenvector of A corresponding to eigenvalue 1. So,

col(P) is the eigenvector of  $T^{transpose}$  corresponding to eigenvalue 1

Page ranks P = [0.310945, 0.415423, 0.248756, 0.0248756]

#### There can be two types of problems.

- Page ranks can be zero
- Page ranks can be unstable

### **Problem** $\rightarrow$ **Page** rank being zero



• How can the rank of a page be equal to zero?

# $\textbf{Problem} \rightarrow \textbf{Page rank being zero}$



- How can the rank of a page be equal to zero?
- A sink subgraph is the subgraph of the given digraph that has no outgoing edges from it to the rest of the graph Example: The set  $\{1, 2, 3\}$  is a sink subgraph
- A strongly connected graph is a digraph such that there is a directed path between every two nodes Example: There is no path from any of  $\{1, 2, 3\}$  to 4

If the pagerank of at least one of the nodes in the digraph is zero,

then the graph is not strongly connected.

### Problem $\rightarrow$ Unstable page ranks



	$P_t$					
t	$P_{t}[1]$	$P_{t}[2]$	$P_{t}[3]$	$P_t[4]$		
0	1	0	0	0		
1	0	1	0	0		
2	0	0	0	1		
3	0	0	1	0		
4	1	0	0	0		

• How can the ranks of pages be unstable?

# **Problem** $\rightarrow$ **Unstable** page ranks



	$P_t$				
t	$P_{t}[1]$	$P_{t}[2]$	$P_{t}[3]$	$P_t[4]$	
0	1	0	0	0	
1	0	1	0	0	
2	0	0	0	1	
3	0	0	1	0	
4	1	0	0	0	

- How can the ranks of pages be unstable?
- A periodic Markov chain is a Markov chain such that the distribution oscillates between multiple distributions periodically
- An aperiodic Markov chain is a Markov chain that is not periodic

Pageranks do not converge for a periodic Markov chain

For a Markov chain that is strongly connected (i.e., no sink subgraph) and aperiodic:

- 1. A unique stable distribution P exists
- 2. All initial distributions  $P_0$  converge to P

• What should we do if a Markov chain is not strongly connected or periodic?

Idea: Transform it to Markov chain that is strongly connected and periodic

• How do you do this conversion/transformation?

Idea: Transform the given digraph into a complete graph by making each edge cost positive using uniform randomization (via a concept called teleportation factor) Intuition: When a user is stuck at a page (or a subgraph) there is a tiny nonzero probability that she will be teleported to a

random web page

# **Teleportation factor**

• How do you transform the digraph into a complete graph? Transform the given transition matrix T using a chosen teleportation factor  $\alpha \in (0, 1)$  as:

$$T[i,j] \leftarrow (1-\alpha)T[i,j] + \alpha\left(\frac{1}{n}\right)$$
 or 
$$T \leftarrow (1-\alpha)T + \frac{\alpha}{n}S$$

where S is an  $n\times n$  matrix with all 1s

# **Teleportation factor**

• How do you transform the digraph into a complete graph? Transform the given transition matrix T using a chosen teleportation factor  $\alpha \in (0, 1)$  as:

$$\frac{T[i,j] \leftarrow (1-\alpha)T[i,j] + \alpha\left(\frac{1}{n}\right)}{T \leftarrow (1-\alpha)T + \frac{\alpha}{n}S}$$
 or

where S is an  $n\times n$  matrix with all 1s

• What does this transformation mean? This transformation means that

 $T[i,j] \text{ will be } \left\{ \begin{aligned} &\text{incremented} & \text{if } T[i,j] \in [0,1/n) \\ &\text{the same} & \text{if } T[i,j] = 1/n \\ &\text{decremented} & \text{if } T[i,j] \in (1/n,1] \end{aligned} \right\}$ 

• After the transformation (for  $n \ge 2$ ),  $T[i, j] \in (0, 1)$  for all i, j

#### Algorithms

- Brute force
- Power method
- System of equations
- Eigenvector

 $\begin{array}{l} & \text{BruteForce}(T[1 \dots n, 1 \dots n]) \\ & \text{TRANSFORMTRANSITIONMATRIX}(T) \\ & \text{Create the pagerank arrays } P_{\text{old}}[1 \dots n] \text{ and } P_{\text{new}}[1 \dots n] \\ & P_{\text{old}}[1 \dots n] \leftarrow [1/n, 1/n, \dots, 1/n] \\ & P_{\text{new}}[1 \dots n] \leftarrow P_{\text{old}}[1 \dots n] \\ & \text{maxerror} \leftarrow 10^{-6}; \ error \leftarrow \infty \\ & \text{while } error > maxerror \ \text{do} \\ & \left| \begin{array}{c} P_{\text{new}} \leftarrow P_{\text{old}} \cdot T \\ error \leftarrow |P_{\text{new}} - P_{\text{old}}| \\ & P_{\text{old}} \leftarrow P_{\text{new}} \\ & \text{return } P_{\text{new}}[1 \dots n] \end{array} \right| \end{array}$ 

```
SystemOfEquations(T[1 \dots n, 1 \dots n])
```

```
TRANSFORMTRANSITIONMATRIX(T)
Create the pagerank array P[1...n]
P \leftarrow SolveSystemOfEquations(P = P \cdot T)
return P[1...n]
```

EIGENVECTORMETHOD $(T[1 \dots n, 1 \dots n])$ 

```
TRANSFORM TRANSITION MATRIX(T)

Create the pagerank array P[1...n]

P \leftarrow \text{SOLVEFORFIRSTEIGENVECTOR}(\operatorname{col}(P) = T^{\operatorname{transpose}} \cdot \operatorname{col}(P))

return P[1...n]
```
- Brute force takes time till convergence System of linear equations takes  $\mathcal{O}(n^3)$ Eigenvector method takes  $\mathcal{O}(n^3)$
- Which algorithm is the fastest? Brute force takes the least time for Internet-type graphs ( $\approx 50$  iterations)

Theoretically fast algos might not always be the best in practice

- GO Page rank video by Reducible
- GO AMS description of page rank
- GO Cornell tutorial for page rank
- GO Brin and Page's paper
- GO Linear algebra behind Google

## Stable Marriage (HOME)

#### Problem

• Given the preference/priority list of n guys and n gals, design an algorithm to determine if a set of stable marriages exists and find one such set.

## Problem

- A matching is a 1-to-1 correspondence b/w n guys and n gals.
- An unstable pair is a pair (m, w) who would have a love affair:
  - Man m prefers woman w to his matched partner and
  - $\bullet\,$  Woman w prefers man w to her matched partner
- An unstable matching is a set of marriages which has an unstable pair (C, p).

	Preference				
Guy	1st 2nd 3rd				
А	р	q	r		
В	q	r	р		
С	r	р	q		

	Preference				
Gal	1st 2nd 3rd				
р	В	С	А		
q	С	А	В		
r	А	В	С		

 This matching is unstable due to the unstable pair (C, p): C prefers p over C's matched partner q p prefers C over p's matched partner A

	Preference				
Guy	1st 2nd 3rd				
А	р	q	r		
В	q	r	р		
С	r	р	q		

	Preference			
Gal	1st	3rd		
р	В	С	А	
q	С	А	В	
r	А	В	С	

#### Answer

There are three sets of stable marriages.

- Give each man his first choice: {(A,p), (B,q), (C,r)} (Each woman gets her last choice)
- Give each woman her first choice: {(A,r), (B,p), (C,q)} (Each man gets his last choice)
- Give each man his second choice: {(A,q), (B,r), (C,p)} (Each woman gets her second choice)

All other sets are unstable.

	Preference					
Guy	1st	1st 2nd 3rd 4th				
А	р	q	r	s		
В	р	S	r	q		
С	q	р	r	S		
D	s	q	r	р		

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
s	С	В	A	D

#### Answer

There is only one set of stable marriages.

{(A,r), (B,s), (C,p), (D,q)}
 All men get their second choice, except A who gets third choice
 All women get their second choice
 All other sets are unstable.

- In 1962, David Gale and Lloyd Shapley discovered an algorithm based on deferred acceptance that guarantees that
  - (Matching) each man and each woman gets matched
  - (Stability) the matching is stable
  - (Optimality) the matching is always best for the group that proposes and worst for the group that handles proposals
- Applications:

Matching hospitals and medical residents

Matching roommates

- Shapley and Roth were awarded 2012 Nobel Memorial Prize in Economic Sciences (Gale died in 2008)
- Exists as functions in Python, MATLAB, and R

High level description of the algorithm

- 1. All individuals rank the members of the opposite set in order of preference
- 2. One of the two sets is chosen to make proposals
- 3. In a loop, run
  - *i*. An individual from the proposing group who is not already engaged will propose to their most preferable option who has not already rejected them
  - *ii*. The person being proposed to will:
    - Accept if this is their first offer
    - Reject if this is worse than their current offer
    - Accept if this is better than their current offer
- 4. When all members of the proposing group are matched, terminate. The current pairs represents stable set of marriages.

Let's understand the working of the algorithm on an example.

	Preference						
Guy	1st	1st 2nd 3rd 4th					
А	р	q	r	s			
В	р	s	r	q			
С	q	р	r	s			
D	s	q	r	р			

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
s	С	В	A	D

A proposes to p and p accepts the proposal A is p's first offer/proposal

	Preference			
Guy	1st	2nd	3rd	4th
А	р	q	r	s
В	р	s	r	q
С	q	р	r	s
D	s	q	r	р

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
s	С	В	А	D

B proposes to p and p rejects the proposal p's current partner A is better than B

	Preference			
Guy	1st	2nd	3rd	4th
А	р	q	r	s
В	р	s	r	q
С	q	р	r	s
D	s	q	r	р

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
s	С	В	А	D

B proposes to p and p rejects the proposal p's current partner A is better than B

	Preference			
Guy	1st	2nd	3rd	4th
А	р	q	r	s
В	р	s	r	q
С	q	р	r	s
D	s	q	r	р

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
S	С	В	A	D

C proposes to q and q accepts the proposal C is q's first offer/proposal

	Preference			
Guy	1st	2nd	3rd	4th
А	р	q	r	s
В	р	s	r	q
С	q	р	r	s
D	S	q	r	р

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
s	С	В	A	D

D proposes to s and s accepts the proposal D is s's first offer/proposal

	Preference			
Guy	1st	2nd	3rd	4th
А	р	q	r	s
В	р	s	r	q
С	q	р	r	s
D	s	q	r	р

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
s	С	В	A	D

B proposes to s and s accepts the proposal B is better than s's current partner D

	Preference			
Guy	1st	2nd	3rd	4th
А	р	q	r	s
В	р	s	r	q
С	q	р	r	s
D	s	q	r	р

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
s	С	В	A	D

D proposes to q and q accepts the proposal D is better than q's current partner C

	Preference			
Guy	1st	2nd	3rd	4th
А	р	q	r	s
В	р	s	r	q
С	q	р	r	s
D	s	q	r	р

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
s	С	В	А	D

C proposes to p and p accepts the proposal C is better than p's current partner A

	Preference			
Guy	1st	2nd	3rd	4th
А	р	q	r	s
В	р	s	r	q
С	q	р	r	s
D	s	q	r	р

	Preference			
Gal	1st	2nd	3rd	4th
р	D	С	А	В
q	В	D	А	С
r	D	А	В	С
s	С	В	А	D

A proposes to q and q rejects the proposal q's current partner D is better than A

	Preference					
Guy	1st	2nd	3rd	4th		
А	р	q	r	s		
В	р	s	r	q		
С	q	р	r	s		
D	s	q	r	р		

	Preference				
Gal	1st	2nd	3rd	4th	
р	D	C A		В	
q	В	D	А	С	
r	D	А	В	С	
s	С	В	А	D	

A proposes to r and r accepts the proposal A is r's first offer/proposal

	Preference				
Guy	1st	4th			
А	р	q	r	s	
В	р	s	r	q	
С	q	р	r	s	
D	s	q	r	р	

	Preference					
Gal	1st	2nd	3rd	4th		
р	D	С	А	В		
q	В	D	А	С		
r	D	А	В	С		
s	С	В	A	D		

There is no man who is not engaged Algorithm terminates Stable matching is achieved Matching best for men and worst for women

	Preference				
Gal	1st	2nd	3rd	4th	
р	D	С	А	В	
q	В	D	А	С	
r	D	А	В	С	
S	С	В	А	D	

	Preference				
Guy	1st	2nd	3rd	4th	
А	р	q	r	s	
В	р	s	r	q	
С	q	р	r	s	
D	s	q	r	р	

If women propose and men handle proposals you get the same stable matching in this specific example This is because this instance has only one stable matching In other examples, you can get different stable matchings

```
STABLEMARRIAGE-GALESHAPLEY(menpreferences, womenpreferences)
Input: n = number of men (or women), menpreferences = preference list
      of men, womenpreferences = preference list of women
Output: Stable matching
engaged = dictionary with initial empty mappings for men and women
while there is a man who is not engaged do
  man = next non-engaged man and
  woman = first woman in man's preferences list to whom man has not
   yet proposed
  if woman is not engaged then
    engage man and woman
  else if woman prefers man to her current partner then
    mark current partner as not engaged
    engage man and woman
  else if woman does not prefer man to her current partner then
    woman rejects man
return stable matching engaged mapping
```

- Time  $= \mathcal{O}\left(n^2
  ight)$
- Space =  $\mathcal{O}(n)$  for notengaged dequeue and engaged map

- Stable matching even when #men > #women or #women > #men
- There is no stable matching for stable roommate matching An even number of boys wish to divide up into pairs of roommates

Example: Boys A, B, C, D where A ranks B first, B ranks C first, C ranks A first, and A,B,C all rank D last. Then regardless of D's preferences there can be no stable pairing, for whoever has to room with D will want to move out and one of the other two will be willing to take him in.

- GO Gale-Shapley paper
- Go Gale-Shapley simulation

## String Matching HOME

• Given a text text[1...n] and a pattern pattern[1...m], design an algorithm to find the location of the first occurrence of the pattern in the text.



- 1. Check if the pattern matches the text starting from the 1st index of text.
- 2. If not, check if the pattern matches with the text starting from the 2nd index of the text.
- 3. Repeat this process until either the pattern is found or the end of the text is reached (without finding any pattern).

```
\begin{array}{l} \mbox{STRINGMATCHING-BRUTEFORCE}(text[1 \dots n], pattern[1 \dots m]) \\ \mbox{for} \quad i \leftarrow 1 \mbox{ to } n-m+1 \mbox{ do } \\ \mbox{ // If text window at position } i \mbox{ matches with pattern, return position} \\ \mbox{ if } text[i \dots (i+m-1)] = pattern \mbox{ then} \\ \mbox{ | return } i \\ \mbox{ return } -1 \end{array}
```

 $\langle \mathsf{PreprocessTime, MatchTime, Space} \rangle = \langle 0, \mathcal{O}(mn), \Theta(1) \rangle$ 

## $\textbf{Solutions} \rightarrow \textbf{Hashing}$



HASH(string[1...m], b, p)

 $\begin{array}{l} // \ \mbox{Polynomial hash: } s_1 b^{m-1} + s_2 b^{m-2} + \cdots + s_{m-1} b^1 + s_m b^0 \\ // \ \ \mbox{Use Horner's rule to compute polynomial hash} \\ hash \leftarrow 0 \\ \ \mbox{for } i \leftarrow 1 \ \mbox{to } m \ \mbox{do} \\ | \ \ hash \leftarrow (hash \times b + string[i]) \ \mbox{mod} \ p \\ \ \ \mbox{return } hash \end{array}$ 

 $\mathsf{Time} = \Theta\left(m\right)$ 

# $\textbf{Solutions} \rightarrow \textbf{Hashing}$

- 1. Check if patternhash matches the texthash at index 1.
- 2. If not, check if patternhash matches the texthash at index 2.
- Repeat this process until either the pattern is found or the end of the text is reached (without finding any pattern).

```
STRINGMATCHING-HASHING(text[1...n], pattern[1...m])
p \leftarrow a \text{ good prime}
                                                                // e.g.: 101
b \leftarrow size of ASCII set
                                                                 // i.e., 256
patternhash \leftarrow HASH(pattern, b, p)
texthash \leftarrow HASH(text[1...m], b, p)
for i \leftarrow 1 to n - m + 1 do
   // If hash value of text window matches the hash value of pattern and
       if the text window matches the pattern then there is a match
  if texthash = patternhash and text[i \dots (i + m - 1)] = pattern then
     return i
   // Compute hash value of the next text window in \Theta(m) time
  if i \neq n - m + 1 then
     texthash \leftarrow HASH(text[i+1...i+m])
return -1
```

 $\langle \mathsf{PreprocessTime, MatchTime, Space} \rangle = \langle \Theta(m), \mathcal{O}(mn), \Theta(1) \rangle$ 

STRINGMATCHING-RABINKARP(text[1...n], pattern[1...m])// e.g.: 101  $p \leftarrow a \text{ good prime}$  $b \leftarrow size of ASCII set$ // i.e., 256  $h \leftarrow b^{m-1} \mod p$ // highest term in the polynomial hash  $patternhash \leftarrow HASH(pattern, b, p)$  $texthash \leftarrow HASH(text[1...m], b, p)$ for  $i \leftarrow 1$  to n - m + 1 do if texthash = patternhash and  $text[i \dots (i + m - 1)] = pattern$  then return *i* // Rolling hash: Compute hash value of the next text window using the current text window in  $\Theta(1)$  time if  $i \neq n - m + 1$  then  $texthash \leftarrow \text{ROLLINGHASH}(texthash, text[i \dots i + m])$ return -1

 $\begin{aligned} & \text{RollingHash}(texthash, string[1 \dots m']) & (m' = m + 1) \\ & texthash \leftarrow ((texthash - string[1] \times h) \times b + string[m']) \text{ mod } p \\ & \text{return } texthash \end{aligned}$ 

 $\mathsf{Time} = \Theta\left(1\right)$ 

## Solutions → RabinKarp (rolling hash)





$$\begin{aligned} 1 \cdot 10^3 + 2 \cdot 10^2 + 3 \cdot 10^1 + 4 \cdot 10^0 &= 1234 \\ 6 \cdot 10^3 + 3 \cdot 10^2 + 2 \cdot 10^1 + 4 \cdot 10^0 &= 6324 \\ (6324 - 6 \cdot 10^3) \cdot 10 + 1 &= 3241 \\ (3241 - 3 \cdot 10^3) \cdot 10 + 2 &= 2412 \\ (2412 - 2 \cdot 10^3) \cdot 10 + 3 &= 4123 \\ (4123 - 4 \cdot 10^3) \cdot 10 + 4 &= 1234 \end{aligned}$$

## Solutions → RabinKarp (rolling hash)



$$\begin{aligned} &(1\cdot 10^3+2\cdot 10^2+3\cdot 10^1+4\cdot 10^0) \bmod 31=2\\ &(6\cdot 10^3+3\cdot 10^2+2\cdot 10^1+4\cdot 10^0) \bmod 31=8\\ &((8-6\cdot 10^3\bmod 31)\cdot 10+1) \bmod 31=25\\ &((25-3\cdot 10^3\bmod 31)\cdot 10+2) \bmod 31=2\\ &((2-2\cdot 10^3\bmod 31)\cdot 10+3) \bmod 31=8\\ &((8-4\cdot 10^3\bmod 31)\cdot 10+4) \bmod 31=2\end{aligned}$$



## Solutions $\rightarrow$ Boyer-Moore-Horspool



character	b	a	r	e	other
skip[character]	2	4	3	1	6

 $skip[\alpha] = \begin{cases} \text{distance from the end of the pattern of } \alpha's \text{ last occurrence} & \text{if } \alpha \neq pattern[m] \\ \text{distance from the end of the pattern of } \alpha's \text{ last but one occurrence} & \text{if } \alpha = pattern[m] \end{cases}$
## $\textbf{Solutions} \rightarrow \textbf{Boyer-Moore-Horspool}$

```
STRINGMATCHING-BMH(text[1...n], pattern[1...m])
skip[0...255] \leftarrow CONSTRUCTSKIPTABLE(pattern)
i \leftarrow m
while i < n do
  if text[(i - m + 1) \dots i] = pattern comparing from right to left then
     return i - m + 1
  else
  | i \leftarrow i + skip[text[i]]
return -1
CONSTRUCTSKIPTABLE(pattern[1...m])
// Initialize the skip table of ASCII characters to m
skip[0...255] \leftarrow [m...m]
for i \leftarrow 1 to m - 1 do
  skip[pattern[i]] \leftarrow m - i
return skip[0...255]
```

 $\langle \mathsf{PreprocessTime, MatchTime, Space} \rangle = \langle \Theta(m + |\Sigma|), \mathcal{O}(mn), \Theta(|\Sigma|) \rangle$ 

## $\textbf{Solutions} \rightarrow \textbf{Aho-Corasick}$





State	a	b	c	$\sum -\{a, b, c\}$
0	1	0	0	0
1	1	2	0	0
2	3	0	0	0
3	1	4	0	0
4	5	0	0	0
5	1	4	6	0
6	—	—	—	—

```
\begin{array}{l} \texttt{STRINGMATCHING-AHoCORASICK}(text[1 \dots n], pattern[1 \dots m]) \\ transitiontable[0 \dots m, 0 \dots 255] \leftarrow \texttt{BUILDTRANSITIONTABLE}(pattern) \\ state \leftarrow 0 \\ \texttt{for} \quad i \leftarrow 1 \; \texttt{to} \; n \; \texttt{do} \\ & | \; state \leftarrow transitiontable[state, text[i]] \\ & \texttt{if} \; state = m \; \texttt{then} \\ & | \; \texttt{return} \; i - m + 1 \\ \texttt{return} \; -1 \end{array}
```

 $\langle \mathsf{PreprocessTime, MatchTime, Space} \rangle = \langle \Theta(m), \mathcal{O}(n), \Theta(m) \rangle$ 

# $\textbf{Solutions} \rightarrow \textbf{Aho-Corasick}$

```
BUILD TRANSITION TABLE (pattern[1...m])
// Stage 1. Construct array X such that X[i] represents the length of
    the longest proper suffix at index i which is also the prefix at index 1
X[0\ldots m] \leftarrow [0\ldots 0]; len \leftarrow 0
for i \leftarrow 1 to m do
   if i < m and pattern[i+1] = pattern[len+1] then
      len \leftarrow len + 1; X[i] \leftarrow len
   else if len \neq 0 then
   len \leftarrow X[len - 1]; i \leftarrow i - 1
   else
    X[i] \leftarrow 0
// Stage 2. Compute table from X array
table[0 \dots m, 1 \dots |\Sigma|] \leftarrow [0 \dots 0, 0 \dots 0]; table[0, pattern[1]] \leftarrow 1
for i \leftarrow 1 to m do
   for j \leftarrow 1 to |\Sigma| do
      if i < m and j = pattern[i+1] then table[i, j] \leftarrow i+1
      else table[i, j] \leftarrow table[X[i-1], j]
return table
```

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta \left( m\Sigma \right), \Theta \left( m\Sigma \right) \rangle$$

Algorithm	Preprocess time	Matching time	Space
Brute force	_	$\mathcal{O}\left(mn ight)$	$\Theta(1)$
Rabin Karp	$\Theta\left(m ight)$	$\mathcal{O}\left(mn ight)$	$\Theta(1)$
Horspool	$\Theta\left(m+ \Sigma \right)$	$\mathcal{O}\left(mn ight)$	$\Theta\left( \Sigma \right)$
Aho-Corasick	$\Omega\left(m \Sigma  ight)$	$\mathcal{O}\left(n ight)$	$\Theta\left(m \Sigma \right)$



- Why care for bit tricks?
- Extensively used by compilers and programmers for achieving high performance
- Easily extends to Bit vector; Instead of working with 32 or 64 bits, bit vector can use an arbitrary size of bits and the operations and concepts remain the same
- Many algorithms make use these bit tricks Example: most-widely used HyperLogLog++ algorithm requires counting the number of trailing zeros in a word

• Let 
$$x = \langle x_{w-1} x_{w-2} \dots x_0 \rangle$$
 be a  $w$ -bit word

 $\bullet$  Unsigned integer value stored in x is

$$x = + x_{w-1}2^{w-1} + x_{w-2}2^{w-2} + \dots + x_02^0$$

• Signed integer value stored in x is

$$x = -x_{w-1}2^{w-1} + x_{w-2}2^{w-2} + \dots + x_02^0$$

- Prefix 0B represents a binary number in programming languages
- Examples:

Unsigned int x = 0B10010110 = 128 + 16 + 4 + 2 = 150Signed int x = 0B10010110 = -128 + 16 + 4 + 2 = -106

### **Bitwise operators**

A = 0B10110011

#### B = 0B01101001

Operator	Description	Operation
&	AND	A & B = 0B00100001
	OR	$A \mid B = 0B11111011$
$\oplus$	XOR	$A\oplus B=0B11011010$
$\sim$	NOT	$\sim A = 0B01001100$
>>	shift right	A >> 1 = 0B01011001
	shift right	A >> 2 = 0B00101100
<<	shift left	A >> 1 = 0B01100110
	shift left	A >> 2 = 0B11001100

## Complementation

#### Problem

 $\bullet\,$  Take the complement of a word x

1's complement 
$$= \sim x$$

2's complement 
$$= \sim x + 1 = -x$$

Term	Bits
x	1011110101101101
$\sim x$	01000101010010010
$\sim x+1$	0100001010010011

• Check if an integer is odd or even

$$A = x \& 1$$

Term	Bits
x	1011110101101101
1	$0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 0\ 1$
A = x & 1	0000000000000000000

• Extract the kth bit in a word x.

$$\boxed{mask = 1 << k}$$
$$A = (x \& mask) >> k$$

Term	Bits
x	1 0 1 1 1 1 0 1 <mark>1</mark> 1 1 0 1 1 0 1
mask = 1 << 7	0 0 0 0 0 0 0 0 <b>1</b> 0 0 0 0 0 0 0
x & mask	0 0 0 0 0 0 0 0 <b>1</b> 0 0 0 0 0 0 0
A = (x & mask) >> 7	0000000000000000000

• Set the kth bit in a word x.

$$mask = 1 << k$$
$$A = x \mid mask$$

Term	Bits
x	1011110101101101
mask=1<<7	0 0 0 0 0 0 0 0 <mark>1</mark> 0 0 0 0 0 0 0
$A = x \mid mask$	10111101 <mark>1</mark> 1101101

• Clear the kth bit in a word x.

$$\boxed{ mask = \sim (1 << k) }$$

$$\boxed{A = x \& mask}$$

Term	Bits
x	1 0 1 1 1 1 0 1 <mark>1</mark> 1 1 0 1 1 0 1
1 << 7	0 0 0 0 0 0 0 0 <b>1</b> 0 0 0 0 0 0 0
$mask = \sim (1 << 7)$	1 1 1 1 1 1 1 1 0 1 1 1 1 1 1 1
A = x & mask	1011110101101101

• Toggle the kth bit in a word x.

$$mask = 1 << k$$
$$A = x \oplus mask$$

Term	Bits
x	1011110101101101
mask = 1 << 7	00000000100000000
$A = x \oplus mask$	10111101 <mark>1</mark> 1101101

## Extract a bit field

#### Problem

• Extract a bit field in a word x.

$$A = (x \And mask) >> shift$$

Term	Bits
x	1011110101101101
mask	0000011110000000
x & mask	00000101000000000
(x & mask) >> shift	00000000000001010

• Set a bit field in a word x to a value y.

$$A = (x \& \sim mask) \mid ((y \ll shift) \& mask)$$

Term	Bits
x	1 0 1 1 1 <mark>1 0 1 0</mark> 1 1 0 1 1 0 1
mask	0000011110000000
$\sim mask$	$1\ 1\ 1\ 1\ 1\ 0\ 0\ 0\ 0\ 1\ 1\ 1\ 1\ 1\ 1\ 1$
$A_1 = x \& \sim mask$	10111000001101101
y	0000000000000000011
$A_2 = (y << 7) \& mask$	0000000110000000
$A = A_1 \mid A_2$	101110011101101

• Swap two integers x and y.

Using temporary variables: 
$$t = x; x = y; y = t;$$
  
No temporary variables:  $x = x \oplus y; y = x \oplus y; x = x \oplus y;$ 

Term	Bits
x	1011110101101101
y	0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1
$x=x\oplus y$	1011110110010010
$y = x \oplus y$	1011110101101101
$x = x \oplus y$	000000011111111

• How does { 
$$x = x \oplus y; y = x \oplus y; x = x \oplus y;$$
 } swap?

Core idea:

$$a \oplus a = 0 \implies b \oplus a \oplus a = a \oplus b \oplus a = a \oplus a \oplus b = b$$

• How do you apply this idea to this algorithm? Let's keep the x and y variables unchanged

$$a = x \oplus y$$
  

$$b = a \oplus y = x \oplus y \oplus y = x$$
  

$$c = a \oplus b = x \oplus y \oplus x = y$$

- Variables b and c store original values of x and y, respectively
- Variables b and c are the variables y and x, respectively

### Detect if two integers have opposite sign

#### Problem

• Detect if two integers x and y have opposite sign.

$$A = (x \oplus y) < 0$$

Term	Bits
x	$\frac{1}{1} 0 1 1 1 1 1 0 1 0 1 1 0 1 1 0 1 1 0 1$
y	<mark>0</mark> 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1
$(x\oplus y)$	$1 \\ 0 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 0 \\ 1 \\ 1 \\ $
$A = (x \oplus y) < 0$	0000000000000000
Term	Bits
x	$\frac{1}{1} 0 1 1 1 1 1 0 1 0 1 1 0 1 1 0 1 1 0 1$
$egin{array}{c} x \ y \end{array}$	1 0 1 1 1 1 0 1 0 1 0 1 1 0 1 1 0 1         1 1 1 1 1 1 1 1 0 0 0 0 0 0 0 0 0
$egin{array}{c} x & y \ y & (x \oplus y) \end{array}$	1 0 1 1 1 1 0 1 0 1 1 0 1 1 0 1         1 1 1 1 1 1 1 1 0 0 0 0 0 0 0 0 0         0 1 0 0 0 0 1 0 0 1 1 0 1 1 0 1

# Sign of an integer

#### Problem

• Determine the sign of an integer x (return +1/0/-1).

$$A = (x > 0) - (x < 0)$$

Term	Bits
x	1011110101101101
(x > 0)	0000000000000000000
(x < 0)	000000000000000000
A = (x > 0) - (x < 0)	111111111111111111
Term	Bits
x	0011110101101101
A = (x > 0) - (x < 0)	000000000000000001
Term	Bits
x	000000000000000000
A = (x > 0) - (x < 0)	00000000000000000

# Check if number is a power of 2

#### Problem

• Check if unsigned integer x is a power of 2.

$$A = x \land !(x \& (x - 1))$$

Term	Bits
x	1011110101101100
(x-1)	1011110101101011
(x & (x-1))	1011110101101000
!(x & (x-1))	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
$A = x \land !(x \& (x-1))$	000000000000000000
Term	Bits
x	00000000000100000
(x - 1)	0000000000011111
(x & (x-1))	0000000000000000000
!(x & (x-1))	0000000000000000001
$A = x \land \sim (x \& (x-1))$	000000000000000000

Create the table for x = 0.

## Minimum of two integers

#### Problem

• Find the minimum of two integers x and y.

$$A = y \oplus ((x \oplus y) \& -(x < y))$$

Term	Bits
x	1011110101101101
y	0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1
(x < y)	000000000000000001
-(x < y)	111111111111111111
$(x\oplus y)$	1011110110010010
$(x \oplus y) \And - (x < y)$	1011110110010010
$A = y \oplus ((x \oplus y) \& -(x < y))$	1011110101101101

•  $x < y \implies -(x < y) = -1 = 1 \dots 1 \implies A = y \oplus (x \oplus y) = x$ •  $x \ge y \implies -(x < y) = 0 = 0 \dots 0 \implies A = y \oplus 0 = y$ 

### Maximum of two integers

#### Problem

• Find the maximum of two integers x and y.

$$A = x \oplus ((x \oplus y) \& -(x < y))$$

Term	Bits
x	1011110101101101
y	0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1
(x < y)	$0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0$
-(x < y)	111111111111111111
$(x\oplus y)$	1011110110010010
$(x \oplus y) \And - (x < y)$	1011110110010010
$A = x \oplus ((x \oplus y) \& -(x < y))$	0000000011111111

•  $x < y \implies -(x < y) = -1 = 1 \dots 1 \implies A = x \oplus (x \oplus y) = y$ •  $x \ge y \implies -(x < y) = 0 = 0 \dots 0 \implies A = x \oplus 0 = x$ 

### Count set bits in unsigned int

#### Problem

• Count set bits in unsigned int x.

for 
$$(A = 0; x; A++) x \leftarrow x \& (x - 1)$$

Count	Term	Bits
A = 0	x	1000110101100101
A = 1	x = x & (x - 1)	$1 \ 0 \ 0 \ 0 \ 1 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 0$
A = 2	x = x & (x - 1)	1000110101100000
A = 3	x = x & (x - 1)	$1 \ 0 \ 0 \ 0 \ 1 \ 1 \ 0 \ 1 \ 0 \ 0 \ $
A = 4	x = x & (x - 1)	$1 \ 0 \ 0 \ 0 \ 1 \ 1 \ 0 \ 1 \ 0 \ 0 \ $
A = 5	x = x & (x - 1)	10001100000000000
A = 6	x = x & (x - 1)	$1 \ 0 \ 0 \ 0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ $
A = 7	x = x & (x - 1)	1000000000000000000
A = 8	x = x & (x - 1)	00000000000000000

# $\lceil \log_2 x \rceil$ for an unsigned int x

Problem

• Compute  $\lceil \log_2 x \rceil$  for an unsigned int x.

for 
$$(A = 0; x >>= 1; A++)$$
 ;

Log	Term	Bits
A = 0	x	0 0 0 0 0 0 0 0 0 0 1 0 1 1 0 1
A = 1	x >>= 1	0 0 0 0 0 0 0 0 0 0 0 1 0 1 1 0
A = 2	x >>= 1	$0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 1\; 1\; 1$
A = 3	x >>= 1	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
A = 4	x >>= 1	000000000000000010
A = 5	x >>= 1	$0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0\; 0$
A = 6	x >>= 1	00000000000000000

### Round to next power of 2

#### Problem

• Round to next power of 2, i.e.,  $2^{\lceil \log_2 x \rceil}$  of an unsigned int x.

x--;x|=x>>1;x|=x>>2;x|=x>>4;x|=x>>8;x|=x>>16;x|=x>>32;x++;

Term	Bits
x	0 0 <mark>1</mark> 0 0 0 0 0 0 0 0 0 0 1 0 0
x	0 0 <mark>1</mark> 0 0 0 0 0 0 0 0 0 0 1 1
x  = x >> 1	0 0 <mark>1 1</mark> 0 0 0 0 0 0 0 0 0 1 1
x  = x >> 2	0011110000000011
x  = x >> 4	0011111111000011
x  = x >> 8	00111111111111111
x  = x >> 16	00111111111111111
x  = x >> 32	00111111111111111
x + +	010000000000000000

x - - is used to correctly handle powers of 2.

### Polynomial Multiplication (HOME)

- Multiply two (n-1)-degree polynomials. For simplicity, we assume n is a power of 2.
- Formally, let A(x) and B(x) be (n-1)-degree polynomials. Compute (2n-2)-degree polynomial C(x) such that

$$C(x) = A(x) \times B(x) \text{ where}$$

$$A(x) = a_0 + a_1 x^1 + \dots + a_{n-1} x^{n-1}$$

$$B(x) = b_0 + b_1 x^1 + \dots + b_{n-1} x^{n-1}$$

$$C(x) = c_0 + c_1 x^1 + \dots + c_{2n-2} x^{2n-2}$$

$$\begin{split} \mathrm{MULT}(A[\ell..h],B[\ell..h]) &= \mathsf{Multiply two} \ (h-\ell) \text{ degree polynomials} \\ &A[\ell..h] \text{ and } B[\ell..h]. \\ & \mathsf{Compute } \mathrm{MULT}(A[0..n-1],B[0..n-1]). \end{split}$$

$$\begin{aligned} A \times B &= (A_L A_R) \times (B_L B_R) \\ &= (A_L + A_R \cdot x^{n/2}) \times (B_L + B_R \cdot x^{n/2}) \\ &= (A_L \times B_L) + (A_L \times B_R + A_R \times B_L) \cdot x^{n/2} \\ &+ (A_R \times B_R) \cdot x^n \\ &= (A_L \times B_L) \\ &+ \begin{pmatrix} (A_L + A_R) \times (B_L + B_R) \\ -(A_L \times B_L) - (A_R \times B_R) \end{pmatrix} \cdot x^{n/2} \\ &+ (A_R \times B_R) \cdot x^n \end{aligned}$$

## Step 3. Core idea



# Step 4. Example

Consider

$$\begin{split} A(x) &= [-6,11,-6,1] = -6 + 11x - 6x^2 + x^3 \\ B(x) &= [-120,74,-15,1] = -120 + 74x - 15x^2 + x^3 \\ \text{Now consider } A(x) \cdot B(x) \text{:} \end{split}$$

$$\begin{split} & [-6, 11, -6, 1] \times [-120, 74, -15, 1] \\ & = ([-6, 11] + [-6, 1]x^2) \times ([-120, 74] + [-15, 1]x^2) \\ & = [-6, 11] \times [-120, 74] \\ & + ([-6, 11] \times [-15, 1] + [-6, 1] \times [-120, 74])x^2 \\ & + ([-6, 1] \times [-15, 1])x^4 \\ & = [-6, 11] \times [-120, 74] + \\ & + \begin{pmatrix} ([-6, 11] + [-6, 1]) \times ([-120, 74] + [-15, 1]) \\ -([-6, 11] \times [-120, 74]) - ([-6, 1] \times [-15, 1]) \end{pmatrix} \cdot x^2 \\ & + ([-6, 1] \times [-15, 1])x^4 \end{split}$$

KARATSUBAPRODUCT $(A[\ell \dots h], B[\ell \dots h])$ 

Input: Two  $(h - \ell)$ -degree polynomials A and B, where  $\ell$  and h are the lower and higher order coefficients Output: Product of polynomials A and Bif  $\ell = h$  then return  $A[\ell] \times B[\ell]$  $mid \leftarrow \lfloor (h + \ell)/2 \rfloor; n \leftarrow h - \ell + 1$  $A_L \leftarrow A[\ell \dots mid], A_R \leftarrow A[mid + 1 \dots h]$  $B_L \leftarrow B[\ell \dots mid], B_R \leftarrow B[mid + 1 \dots h]$ parallel:  $P_1 \leftarrow \text{KARATSUBAPRODUCT}(A_L, B_L)$  $P_2 \leftarrow \text{KARATSUBAPRODUCT}((A_L + A_R), (B_L + B_R))$  $P_3 \leftarrow \text{KARATSUBAPRODUCT}(A_R, B_R)$ return  $(P_1 + (P_2 - P_1 - P_3) \cdot x^{n/2} + P_3 \cdot x^n)$ 

# Step 6. Complexity

$$\begin{aligned} & \text{Work } T(n) = \begin{cases} \Theta\left(1\right) & \text{if } n = 1, \\ 3T(n/2) + \Theta\left(n\right) & \text{if } n > 1. \end{cases} \in \Theta\left(n^{\log_2 3}\right) \\ & \text{Depth } D(n) = \begin{cases} \Theta\left(1\right) & \text{if } n = 1, \\ D(n/2) + \Theta\left(n\right) & \text{if } n > 1. \end{cases} \in \Theta\left(n\right) \\ & \text{Space } S(n) = \begin{cases} \Theta\left(1\right) & \text{if } n = 1, \\ 3S(n/2) + \Theta\left(n\right) & \text{if } n > 1. \end{cases} \in \Theta\left(n^{\log_2 3}\right) \\ & \text{Cache } Q(n) = \begin{cases} \mathcal{O}\left(M/B\right) & \text{if } n \leq \gamma M, \\ 3Q(n/2) + \Theta\left(n/B\right) & \text{if } n > \gamma M. \end{cases} \in \mathcal{O}\left(\frac{n^{\log_2 3}}{MB}\right) \end{aligned}$$

### 1. Coefficient representation

• (n-1)-degree polynomial can be represented using n coefficients

•  $A(x) = a_0 + a_1 x^1 + \dots + a_{n-1} x^{n-1} = \sum_{i=0}^{n-1} a_i x^i$ 

• 
$$A(x) = [a_0, a_1, \dots, a_{n-1}]$$
  $\triangleright$  coefficient vector

- 2. Root representation
- (n-1)-degree polynomial can be represented using n-1 roots

• 
$$A(x) = c(x - r_1)(x - r_1) \cdots (x - r_{n-1})$$
  
•  $A(x) = [c, \{r_1, r_1, \dots, r_{n-1}\}]$   $\triangleright$  set of roots

### 3. Point representation

- (n-1)-degree polynomial can be represented using n points
- $\{(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1})\}$  where  $y_i = A(x_i)$
- A(x) is the set of these sample points  $\triangleright$  set of samples
#### 1. Coefficient representation

• 3-degree polynomial can be represented using 4 coefficients

• 
$$A(x) = -6 + 11x - 6x^2 + x^3$$

• 
$$A(x) = [-6, 11, -6, 1]$$
  $\triangleright$  coefficient vector

- 2. Root representation
- $\bullet\ 3\text{-degree}$  polynomial can be represented using 3 roots

• 
$$A(x) = 1(x-1)(x-2)(x-3)$$
  
•  $A(x) = [1, \{1, 2, 3\}]$  > set of roots

- 3. Point representation
- 4-degree polynomial can be represented using 4 points
- $\{(0, -6), (10, 504), (20, 5814), (30, 21924)\}$
- A(x) is the set of these sample points  $\triangleright$  set of samples

#### **Operations on polynomials**



## **Operations on polynomials**



- Root representation is not very useful. Let's remove it.
- Polynomial multiplication can be done in two different ways:
  - 1. Multiply in coefficient representation using Karatsuba's idea
  - 2. Convert coefficient to point representation Multiply in point representation Convert point to coefficient representation

# **Evaluation and interpolation**

$$\begin{bmatrix} A(x_0) \\ A(x_1) \\ A(x_2) \\ \vdots \\ A(x_{n-1}) \end{bmatrix} = \begin{bmatrix} 1 & x_0 & x_0^2 & \cdots & x_0^{n-1} \\ 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \cdots & x_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n-1} & x_{n-1}^2 & \cdots & x_{n-1}^{n-1} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{bmatrix}$$
$$\boxed{X = \{x_0, x_1, \dots, x_{n-1}\}} \text{ and } \boxed{Y = V_X A}$$

#### • Evaluation.

Convert coefficient to point representation.

A is known, X is chosen, Y is computed.

Y can be computed in  $\Theta\left(n^2\right)$  time using Horner's formula.

#### • Interpolation.

Convert point to coefficient representation.

X and Y are known, A is computed.

A can be computed in  $\Theta\left(n^2\right)$  time using Lagrange's formula.

#### Problem

• Can we perform evaluation & interpolation better than  $\Theta\left(n^2\right)$ ?

#### Great idea

- We can perform evaluation and interpolation in  $\Theta(n \log n)$  using roots of 1 and divide-and-conquer.
- Evaluation of (n-1)-degree polynomial A(x) at n roots of unity can be done in  $\Theta(n \log n)$  using divide-and-conquer. Interpolation of n roots of unity to an (n-1)-degree polynomial can be done in  $\Theta(n \log n)$  using divide-and-conquer.



• Core idea.

$$\begin{split} A(x) &= A^{\mathsf{even}}(x^2) + x A^{\mathsf{odd}}(x^2) \\ A(-x) &= A^{\mathsf{even}}(x^2) - x A^{\mathsf{odd}}(x^2) \end{split}$$

Example.

$$7 + 3x + 2x^{2} + 6x^{3} = (7 + 2x^{2}) + x(3 + 6x^{2})$$
  

$$7 + 3(-x) + 2(-x)^{2} + 6(-x)^{3} = (7 + 2x^{2}) - x(3 + 6x^{2})$$

#### Interpretation.

If we have the results of  $A^{\mathsf{even}}(x^2)$  and  $A^{\mathsf{odd}}(x^2)$ , we can compute A(x) and A(-x) in constant time. Because we take square roots repeatedly, we use roots of unity. This leads to the amalgamation of ideas from mathematics (roots of unity) and computation (divide-and-conquer).

## **Roots of unity**



•  $\Theta(n \log n)$  evaluation: Use  $X = \{\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}\}$ .

$$\begin{bmatrix} A(\omega_n^1) \\ A(\omega_n^1) \\ A(\omega_n^2) \\ \vdots \\ A(\omega_n^{n-1}) \end{bmatrix} = \begin{bmatrix} 1 & \omega_n^0 & (\omega_n^0)^2 & \cdots & (\omega_n^0)^{n-1} \\ 1 & \omega_n^1 & (\omega_n^1)^2 & \cdots & (\omega_n^1)^{n-1} \\ 1 & \omega_n^2 & (\omega_n^2)^2 & \cdots & (\omega_n^2)^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_n^{n-1} & (\omega_n^{n-1})^2 & \cdots & (\omega_n^{n-1})^{n-1} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{bmatrix}$$

•  $\Theta(n \log n)$  interpolation: Use  $X = \frac{1}{n} \{ \omega_n^{-0}, \omega_n^{-1}, \dots, \omega_n^{-(n-1)} \}$ .

$$\begin{bmatrix} a_0\\ a_1\\ a_2\\ \vdots\\ a_{n-1} \end{bmatrix} = \frac{1}{n} \begin{bmatrix} 1 & \omega_n^{-0} & (\omega_n^{-0})^2 & \cdots & (\omega_n^{-0})^{n-1}\\ 1 & \omega_n^{-1} & (\omega_n^{-1})^2 & \cdots & (\omega_n^{-1})^{n-1}\\ 1 & \omega_n^{-2} & (\omega_n^{-2})^2 & \cdots & (\omega_n^{-2})^{n-1}\\ \vdots & \vdots & \vdots & \ddots & \vdots\\ 1 & \omega_n^{-(n-1)} & (\omega_n^{-(n-1)})^2 & \cdots & (\omega_n^{-(n-1)})^{n-1} \end{bmatrix} \begin{bmatrix} A(\omega_n^1)\\ A(\omega_n^1)\\ A(\omega_n^2)\\ \vdots\\ A(\omega_n^{n-1}) \end{bmatrix}$$





### Step 4. Example (Evaluation)



## Step 5. Algorithm

 $FFT([a_0, a_1, \dots, a_{n-1}])$ ▷ Evaluation **Input:** Coefficients of polynomial A(x):  $[a_0, a_1, \ldots, a_{n-1}]$ **Output:** Point values vector Y for X values  $[\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}]$ if n = 1 then return  $a_0$  $\omega_n \leftarrow e^{2\pi i/n}$  $\omega \leftarrow 1$ // [Stage 1. Divide].....  $A^{\mathsf{even}} \leftarrow [a_0, a_2, \dots, a_{n-2}]$  $A^{\mathsf{odd}} \leftarrow [a_1, a_3, \ldots, a_{n-1}]$ // [Stage 2. Conquer]..... parallel:  $Y^{\text{even}} \leftarrow \text{FFT}(A^{\text{even}})$  $Y^{\mathsf{odd}} \leftarrow \mathrm{FFT}(A^{\mathsf{odd}})$ // [Stage 3. Combine] . for  $k \leftarrow 0$  to n/2 - 1 do  $y_k \leftarrow Y_k^{\mathsf{even}} + \omega Y_k^{\mathsf{odd}}$  $y_{n/2+k} \leftarrow Y_k^{\mathsf{even}} - \omega Y_k^{\mathsf{odd}}$  $\omega \leftarrow \omega \omega_n$ return  $[y_0, y_1, \ldots, y_{n-1}]$ 

INVERSEFFT( $[y_0, y_1, \ldots, y_{n-1}]$ ) ▷ Interpolation **Input:** Point values vector Y for X values  $[\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}]$ **Output:** Coefficients of polynomial A(x):  $[a_0, a_1, \ldots, a_{n-1}]$ if n = 1 then return  $y_0$  $\omega_n \leftarrow (1/n)e^{-2\pi i/n}$  $\omega \leftarrow 1$ // [Stage 1. Divide].....  $Y^{\mathsf{even}} \leftarrow [y_0, y_2, \dots, y_{n-2}]$  $Y^{\mathsf{odd}} \leftarrow [y_1, y_3, \dots, y_{n-1}]$ // [Stage 2. Conquer]..... parallel:  $A^{\text{even}} \leftarrow \text{INVERSEFFT}(Y^{\text{even}})$  $A^{\mathsf{odd}} \leftarrow \mathrm{INVERSEFFT}(Y^{\mathsf{odd}})$ // [Stage 3. Combine] . . for  $k \leftarrow 0$  to n/2 - 1 do  $a_k \leftarrow A_k^{\mathsf{even}} + \omega A_k^{\mathsf{odd}}$  $a_{n/2+k} \leftarrow A_k^{\mathsf{even}} - \omega A_k^{\mathsf{odd}}$  $\omega \leftarrow \omega \omega_n$ return  $[a_0, a_1, \ldots, a_{n-1}]$ 

COOLEYTUKEYPRODUCT(A(x), B(x))**Input:** Polynomials A(x) and B(x) of same degree **Output:** Polynomial product  $C(x) = A(x) \times B(x)$  $[a_0, a_1, \ldots, a_{n-1}] \leftarrow \text{COEFFICIENTS}(A(x))$  $[b_0, b_1, \ldots, b_{n-1}] \leftarrow \text{COEFFICIENTS}(B(x))$ // [Stage 1. Add high-order coefficients] .....  $[a_n, a_{n+1}, \ldots, a_{2n-1}] \leftarrow [0, 0, \ldots, 0]$  $[b_n, b_{n+1}, \ldots, b_{2n-1}] \leftarrow [0, 0, \ldots, 0]$ // [Stage 2. Evaluate]..... parallel:  $[y_0^A, y_1^A, \dots, y_{2n-1}^A] \leftarrow FFT([a_0, a_1, \dots, a_{2n-1}])$  $[y_0^B, y_1^B, \dots, y_{2n-1}^B] \leftarrow FFT([b_0, b_1, \dots, b_{2n-1}])$ // [Stage 3. Pointwise multiply] ..... parallel: for  $k \leftarrow 0$  to 2n - 1 do  $| y_k^C \leftarrow y_k^A \times y_k^B$ // [Stage 4. Interpolate] ......  $[c_0, c_1, \ldots, c_{2n-1}] \leftarrow \text{INVERSEFFT}([y_0^C, y_1^C, \ldots, y_{2n-1}^C])$  $C(x) \leftarrow [c_0, c_1, \ldots, c_{2n-1}]$ return C(x)

# Step 6. Complexity

$$\begin{array}{l} \text{Work } T(n) = \begin{cases} \Theta\left(1\right) & \text{if } n = 1, \\ 2T(n/2) + \Theta\left(n\right) & \text{if } n > 1. \end{cases} \in \Theta\left(n \log n\right) \\ \text{Depth } D(n) = \begin{cases} \Theta\left(1\right) & \text{if } n = 1, \\ D(n/2) + \Theta\left(n\right) & \text{if } n > 1. \end{cases} \in \Theta\left(n\right) \\ \text{Space } S(n) = \begin{cases} \Theta\left(1\right) & \text{if } n = 1, \\ 2S(n/2) + \Theta\left(n\right) & \text{if } n > 1. \end{cases} \in \Theta\left(n \log n\right) \\ \text{Cache } Q(n) = \begin{cases} \mathcal{O}\left(M/B\right) & \text{if } n \leq \gamma M, \\ 2Q(n/2) + \Theta\left(n/B\right) & \text{if } n > \gamma M. \end{cases} \in \mathcal{O}\left(\frac{n}{B}\log\frac{n}{M}\right) \end{cases}$$

#### Probabilistic Algorithms (HOME)



- Given a positive integer greater than 1, check if the number is prime or not.
- A prime is a natural number greater than 1 that has no positive divisors other than 1 and itself.
- Input: n = 11

Output: prime

• Input: n = 15

Output: composite

• If n is divisible by any number in the range [2, n-1], then n is composite, else, n is prime

PRIMALITY-NAIVEALGORITHM(n)

for  $i \leftarrow 2$  to n - 1 do if  $n \mod i = 0$  then | return composite return prime

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(n), \Theta(1) \rangle$ 

- If n is divisible by any number in the range [2, n-1], then n is composite, else, n is prime
- This is because a larger factor of n must be a multiple of a smaller factor that has been already checked

```
PRIMALITY-SCHOOLALGORITHM(n)
```

for 
$$i \leftarrow 2$$
 to  $\lfloor \sqrt{n} \rfloor$  do  
 $\mid$  if  $n \mod i = 0$  then  
 $\mid$  return composite  
return prime

$$\langle \mathsf{Time, Space} 
angle = \left\langle \mathcal{O}\left(\sqrt{n}
ight), \Theta\left(1
ight) 
ight
angle$$

# Solutions $\rightarrow$ Optimized school algorithm

- All integers can be expressed as (6k + i), where  $i \in \{-1, 0, 1, 2, 3, 4\}$ .
- Test whether n is divisible by 2 or 3. But 2 divides (6k+0), (6k+2), (6k+4) and 3 divides (6k+3). So, simply check if n is divisible by any number in the form  $(6k \pm 1)$  not greater than  $\sqrt{n}$ .

PRIMALITY-OPTIMIZEDSCHOOLALGORITHM(n)

if n = 2 or n = 3 then return prime if  $n \mod 2 = 0$  or  $n \mod 3 = 0$  then return composite // Check if n is divisible by a number of the form  $6k \pm 1$ for  $i \leftarrow 5$  to  $(\lfloor \sqrt{n} \rfloor - 2)$  increment 6 do | if  $n \mod i = 0$  then | return composite // i = 6k - 1if  $n \mod (i + 2) = 0$  then | return composite // i = 6k + 1return prime

$$\langle \mathsf{Time, Space} 
angle = \left\langle \mathcal{O}\left(\sqrt{n}
ight), \Theta\left(1
ight) 
ight
angle$$

PRIMALITY-SIEVEOFERATOSTHENES(n) $last \leftarrow \left|\sqrt{n}\right|$ Create a Boolean array P[2...last] to indicate prime numbers for  $i \leftarrow 2$  to *last* do  $P[i] \leftarrow \mathsf{true}$ for  $j \leftarrow 2$  to *last* do if P[j] = true then for  $k \leftarrow 2$  to  $\lfloor last/j \rfloor$  do  $| i \leftarrow j \times k$  $P[i] \leftarrow \mathsf{false}$ if  $n \mod j = 0$  then return composite return prime

$$\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(\sqrt{n}\log\log n), \Theta(\sqrt{n}) \rangle$$

## Solutions $\rightarrow$ Wilson's theorem

• Wilson's theorem: A positive integer n > 1 is prime iff  $((n-1)!+1) \mod n = 0$ 

n	(n-1)!	$((n-1)!+1) \bmod n$	Is Prime?
2	1	0	1
3	2	0	1
4	6	2	X
5	24	0	1
6	120	1	X
7	720	0	1
8	5040	1	X
9	40320	1	X
10	362880	1	X
11	3628800	0	1
12	39916800	1	X
13	479001600	0	1

• Wilson's theorem: A positive integer n > 1 is prime iff  $((n-1)!+1) \mod n = 0$ 

PRIMALITY-WILSON THEOREM(n)

 $\begin{array}{l} factorial \leftarrow 1 \\ \textbf{for } i \leftarrow 2 \ \textbf{to } n-1 \ \textbf{do} \\ \mid \ factorial \leftarrow (factorial \times i) \ \textbf{mod } n \\ \textbf{if } (factorial + 1) = n \ \textbf{then return prime} \\ \textbf{return composite} \end{array}$ 

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(1) \rangle$ 

#### Solutions $\rightarrow$ Fermat's theorem

•  $n \ge 4$  is prime iff for all  $a \in [2, n-2]$ , we have  $(a^{n-1}-1) \mod n = 0$ .

n:a	2	3	4	5	6	7	8	9	10	11	12	13
4	3											
5	0	0										
6	1	2	3									
7	0	0	0	0								
8	7	2	7	4	7							
9	3	8	6	6	8	3						
10	1	2	3	4	5	6	7					
11	0	0	0	0	0	0	0	0				
12	7	2	3	4	11	6	7	8	3			
13	0	0	0	0	0	0	0	0	0	0		
14	1	2	3	4	5	6	7	8	9	10	11	
15	3	8	0	9	5	3	3	5	9	0	8	3

 PRIMALITY-FERMATTHEOREM(n)

 if n = 2 or n = 3 then return prime

 for  $a \leftarrow 2$  to n - 2 do

 // If  $(a^{n-1} - 1) \mod n \neq 0$ , then n is definitely composite

 if POWER $(a, n - 1, n) \neq 1$  then

 | return composite

 return prime

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}\left(n \log n\right), \Theta\left(1\right) \rangle$ 

POWER(a, b, c)

 $\begin{array}{l} \textbf{Output: Computes } (a^b) \bmod c \text{ in } \Theta \left( \log b \right) \text{ time} \\ result \leftarrow 1 \\ \textbf{while } b > 0 \text{ do} \\ \left| \begin{array}{c} \textbf{if } b \bmod 2 = 1 \text{ then } result \leftarrow (result \times a) \bmod c \\ b = b/2; \ a = (a \times a) \bmod c \\ return \ result \end{array} \right. \end{array}$ 

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta \left( \log b \right), \Theta \left( 1 \right) \rangle$ 

If a cell in the nth row of the table is nonzero, then n is definitely composite.

Bad news.

- If a cell in the *n*th row of the table is 0, then *n* may or may not be prime.
- Formally, for all  $n \ge 4$ , for some  $a \in [2, n-2]$ , if  $(a^{n-1}-1) \mod n = 0$ , then n may or may not be prime.
- Example: Cell in n = 13, a = 8 is zero and n is prime Example: Cell in n = 15, a = 11 is zero but n is composite Good news.
- There are very few cases when *n* is composite and it has some cells as zeros in its row
- So, we run this check multiple times to increase our success probability of guessing whether *n* is prime or composite

```
PRIMALITY-FERMATTEST(n)if n = 2 or n = 3 then return prime// More trials increases the probability of successfor count \leftarrow 1 to #trials doa \leftarrow RandomNumber(\{2, 3, 4, \dots, n - 2\})// If (a^{n-1} - 1) \mod n \neq 0, then n is definitely compositeif POWER(a, n - 1, n) \neq 1 then| return compositereturn prime
```

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O} \left( \# trials \cdot \log n \right), \Theta (1) \rangle$ 

Miller's theorem:

Suppose p is an odd prime. Let  $p-1=2^k\cdot m,$  where m is odd. Then, for every  $a\in[2,p-2],$  either

• 
$$a^m \equiv 1 \pmod{p}$$
 or  
•  $a^{2^i \cdot m} \equiv -1 \pmod{p}$  for some  $i \in [0, k-1]$ .

#### Solutions $\rightarrow$ Miller's theorem

For odd integer n > 1,  $n - 1 = 2^k m$ , where  $k \ge 1$  and m is odd

$$(x^{2^{k_m}} - 1) = ((x^{2^{k-1}m})^2 - 1)$$
  
=  $(x^{2^{k-1}m} - 1)(x^{2^{k-1}m} + 1)$   
=  $(x^{2^{k-2}m} - 1)(x^{2^{k-2}m} - 1)(x^{2^{k-1}m} + 1)$   
...  
=  $(x^m - 1)(x^m + 1)(x^{2m} + 1)(x^{4m} + 1) \cdots (x^{2^{k-1}m} + 1)$ 

If n is prime and  $a \in [1, n-1]$ , then  $a^{n-1} - 1 \equiv 0 \mod n$  by Fermat's theorem, so, using the factorization above we get

$$(a^m - 1)(a^m + 1)(a^{2m} + 1)(a^{4m} + 1) \cdots (a^{2^{k-1}m} + 1) \equiv 0 \mod n$$

When n is odd prime, one of these factors must be  $0 \mod n$ , so

$$a^m \equiv 1 \mod n$$
 or  $a^{2^i m} \equiv -1 \mod n$  for some  $i \in [0, \ldots k-1]$ 

										$a \in$	= [2, n]	-2]										
n	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
5	1	1																				
7	-1	0	-1	0																		
9	١	-	-	-	-	-																
11	0	$^{-1}$	-1	$^{-1}$	0	0	0	-1														
13	1	-1	0	1	1	1	1	-1	0	1												
15	I	-	-	_	_	_	_	_	-	-	-	-										
17	2	3	1	3	3	3	2	2	3	3	3	1	3	2								
19	0	0	-1	-1	-1	-1	0	-1	0	-1	0	0	0	0	-1	-1						
21	I	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
23	-1	$^{-1}$	$^{-1}$	0	$^{-1}$	0	$^{-1}$	0	0	$^{-1}$	$^{-1}$	0	0	$^{-1}$	0	0	0	0	0	0		
25	I	-	-	-	-	1	-	-	-	-	-	-	-	-	-	-	1	-	-	-	-	-
																				\ \		
		Cel		Test	1	Tes	t 2	Co	mm	ents	;											
		-1	L	1		?	•	Te	Test 1 passed; We don't care about Test 2													
		$\geq 0$	)	X		~	·	Ce	Cell = least $i \in [0, k - 1]$ that passes Test 2													
		_		X		X	ſ	Te	Test 1 failed: Test 2 failed													

- Rows for prime numbers have no dashes
- Rows for composite numbers have at least one dash

## Solutions $\rightarrow$ Miller's theorem

PRIMALITY-MILLERTHEOREM(n)if n > 2 and n is even then return composite // Find exponent k and odd number m such that  $(n-1) = 2^k \times m$  $k \leftarrow 0: m \leftarrow n-1$ while  $m \mod 2 = 0$  do {  $m \leftarrow m/2; k \leftarrow k+1$  } // Apply Miller's theorem. a = 1 & a = n - 1 are redundant. for  $a \leftarrow 2$  to n-2 do  $T \leftarrow \text{POWER}(a, m, n)$ // Check test 1; If test 1 fails, check test 2 for i = 0if T = 1 or T = n - 1 then continue // Check test 2 for  $i \in [1, k-1]$ for  $i \leftarrow 1$  to k - 1 do  $T \leftarrow \text{POWER}(T, 2, n)$ // If T = 1, we only get 1's for future values of i if T = 1 then return composite if T = n - 1 then break if  $T \neq n-1$  then return composite return prime

$$\langle \mathsf{Time, Space} 
angle = \left\langle \mathcal{O}\left(n \log^2 n\right), \Theta\left(1
ight) 
ight
angle$$

## Solutions $\rightarrow$ Miller-Rabin's test

```
PRIMALITY-MILLERRABINTEST(n)
if n > 2 and n is even then return composite
// Find exponent k and odd number m such that (n-1) = 2^k \times m
k \leftarrow 0: m \leftarrow n-1
while m \mod 2 = 0 do { m \leftarrow m/2; k \leftarrow k+1 }
// Apply Miller's constraints in a randomized way as suggested by Rabin
for count \leftarrow 1 to \#trials do
  a \leftarrow \mathsf{RandomNumber}(\{2, 3, 4, \dots, n-2\})
  T \leftarrow \text{POWER}(a, m, n)
   // Check test 1; If test 1 fails, check test 2 for i = 0
  if T = 1 or T = n - 1 then continue
   // Check test 2 for i \in [1, k-1]
  for i \leftarrow 1 to k - 1 do
     T \leftarrow \text{POWER}(T, 2, n)
     if T = 1 then return composite
     if T = n - 1 then break
  if T \neq n-1 then return composite
return prime
```

 $\langle \mathsf{Time, Space} \rangle = \left\langle \mathcal{O}\left( \# trials \cdot \log^2 n \right), \Theta(1) \right\rangle$ 

#### Solutions $\rightarrow$ Naive AKS's test

•  $n \ge 2$  is prime iff all coefficients, except first and last, of the nth row in the Pascal's triangle are multiples of n

	0	1	2	3	4	5	6	7	8	9
0	1									
1	1	1								
2	1	2	1							
3	1	3	3	1						
4	1	4	6	4	1					
5	1	5	10	10	5	1				
6	1	6	15	20	15	6	1			
7	1	7	21	35	35	21	7	1		
8	1	8	28	56	70	56	28	8	1	
9	1	9	36	84	126	126	84	36	9	1
#### Solutions $\rightarrow$ Naive AKS's test

•  $n \ge 2$  is prime iff for all  $i \in [1, n-1]$ ,  ${}^{n}C_{i}$  is a multiple of n.

PRIMALITY-NAIVEAKSTEST(n)

$$\langle \mathsf{Time, Space} 
angle = \left\langle \Theta\left(n^2\right), \Theta\left(n\right) 
ight
angle$$

Algorithm	Time	Space	Probabilistic?
Naive algorithm	$\mathcal{O}\left(n ight)$	$\Theta(1)$	×
School algorithm	$\mathcal{O}\left(\sqrt{n} ight)$	$\Theta(1)$	×
Opt. school algo.	$\mathcal{O}\left(\sqrt{n} ight)$	$\Theta(1)$	×
SieveOfEratosthenes	$\mathcal{O}\left(\sqrt{n}\log\log n\right)$	$\Theta\left(\sqrt{n}\right)$	×
Wilson's theorem	$\Theta\left(n ight)$	$\Theta(1)$	×
Fermat's theorem	$\mathcal{O}\left(n\log n ight)$	$\Theta(1)$	×
Fermat's test	$\mathcal{O}\left(\#trials \cdot \log n\right)$	$\Theta(1)$	1
Miller's theorem	$\mathcal{O}\left(n\log^2 n\right)$	$\Theta\left(1 ight)$	×
Miller-Rabin's test	$\mathcal{O}\left(\#trials \cdot \log^2 n\right)$	$\Theta\left(1\right)$	1
Naive AKS test	$\Theta(n^2)$	$\Theta\left(n ight)$	×

# Membership HOME

# Problem

#### Problem

• Design a data structure to implement a set with add and search operations.

#### Solutions

	Add	Search	Comments
Balanced tree	$\mathcal{O}\left(\log n\right)$	$\mathcal{O}\left(\log n\right)$	works for sort-related ops.
Hash table	$\mathcal{O}\left(n ight)$	$\mathcal{O}\left(n ight)$	worst case is worse
	$\mathcal{O}\left(1 ight)*$	$\mathcal{O}\left(1 ight)*$	amortized case is awesome
Bloom filter	$\mathcal{O}\left(1 ight)$	$\mathcal{O}\left(1 ight)$	has false positive errors

• There are many more solutions.

- A probabilistic data structure to check set membership discovered by Burton Howard Bloom in 1970.
- Takes less space than a hash table and answers approximately
- Has false positives but no false negatives, i.e., If BF returns found/present, then there is a small chance that the item is not present
   If BF returns not found then the item is definitely not present

If BF returns not found, then the item is definitely not presentBloom filter has two main components:

# A bit array $A[0 \dots N-1]$ Independent hash functions $h_1, h_2, \dots, h_k$ such that $h_i: \Sigma^* \to \{0, 1, 2, \dots, N-1\}$ such that the mapping is uniform

#### **Bloom filter class**

#### class BLOOMFILTER(n, p)

**Input:**  $n \leftarrow$  number of elements;  $p \leftarrow$  desired false probability

$$k \leftarrow \text{number of hash functions; } N \leftarrow \text{Bloom filter/table size}$$

```
A \leftarrow \mathsf{Bloom} \ \mathsf{filter} \ \mathsf{bit} \ \mathsf{array}/\mathsf{table} \ \mathsf{of} \ \mathsf{size} \ N
```

INITIALIZE(); ADD(x); SEARCH(x)

INITIALIZE()

$$\begin{aligned} k \leftarrow \left\lfloor \frac{-\ln p}{\ln 2} \right\rfloor; N \leftarrow \left\lfloor n \cdot \frac{k}{\ln 2} \right\rfloor \\ A[0 \dots N - 1] \leftarrow [0 \dots 0] \end{aligned}$$

ADD(x)

for 
$$i \leftarrow 1$$
 to  $k$  do  
  $| A[h_i(x)] \leftarrow 1$ 

SEARCH(x)

for  $i \leftarrow 1$  to k do if  $A[h_i(x)] \neq 1$  then i return false return true

#### Add

ADD(x)

for 
$$i \leftarrow 1$$
 to  $k$  do  
  $\mid A[h_i(x)] \leftarrow 1$ 



Source: Medjedovic-Tahirovic-Dedovic's Algorithms and Data Structures for Massive Datasets

#### Search

SEARCH(x)



### **Complexity analysis**

- $\bullet\,$  Given number of elements n
- $\bullet\,$  Given the false positive rate p
- Compute the number of hash functions as

$$k \leftarrow \left\lfloor \frac{-\ln p}{\ln 2} \right\rfloor$$

 $\bullet\,$  Compute the Bloom filter bit array size N as

$$N \leftarrow \left\lfloor n \cdot \tfrac{k}{\ln 2} \right\rfloor$$

Feature	Complexity
Add	$\mathcal{O}(k) = \mathcal{O}(\ln(1/p))$
Search	$\mathcal{O}\left(k\right) = \mathcal{O}\left(\ln\left(1/p\right)\right)$
Space	$\mathcal{O}(N) = \mathcal{O}(nk) = \mathcal{O}(n\ln(1/p))$

• Incorrect formula for computing the false positive prob. was given by [Bloom 1970] as

False positive prob. 
$$= p = \left(1 - (1 - 1/N)^{nk}
ight)^k$$

• Incorrect formula for computing the false positive prob. was given by [Bose et al. 2008] as

False positive prob. = 
$$p* = \left(\frac{1}{N^{k(n+1)}}\right) \cdot \sum_{i=1}^{m} i^k i! \ ^mC_i \ ^{kn}C_i$$

- Fortunately, the incorrect *p* gives a very good approximation to correct *p*\* for practical values
- We show Bloom's derivation to derive the incorrect p so that you can be careful when you do probabilistic analysis

#### **Error** analysis

Prob. that a bit will be 0 after 1 insertion  $= (1 - 1/N)^k$ Prob. that a bit will be 0 after n insertions  $= (1 - 1/N)^{nk}$ Prob. that a bit will be 1 after n insertions  $= (1 - (1 - 1/N)^{nk})^k$ Prob. that k bits are 1 after n insertions  $= (1 - (1 - 1/N)^{nk})^k$ Simplify.

Prob. of false positives

= Prob. that k bits are 1 after n insertions

$$= \left(1 - (1 - 1/N)^{nk}\right)^k = \left(1 - \left((1 - 1/N)^N\right)^{\frac{nk}{N}}\right)^k$$
$$\approx \left(1 - e^{\frac{nk}{N}}\right)^k \quad (\because (1 - 1/x)^x \approx e)$$

So,

False positive probability 
$$= p = \left(1 - e^{\frac{nk}{N}}\right)^k$$

n	p = 0.0001	p = 0.001	p = 0.01	p = 0.1
10 <sup>1</sup>	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01} n \rfloor, k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$
$10^{2}$	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01} n \rfloor, k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$
$10^{3}$	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01}n \rfloor$ , $k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$
$10^{4}$	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01} n \rfloor, k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$
$10^{5}$	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01}n \rfloor$ , $k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$
$10^{6}$	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01} n \rfloor, k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$
$10^{7}$	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01}n \rfloor$ , $k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$
$10^{8}$	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01} n \rfloor, k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$
$10^{9}$	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01}n \rfloor$ , $k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$
$10^{10}$	$N = \lfloor N_{0.0001} n \rfloor, k = 13$	$N = \lfloor N_{0.001} n \rfloor, k = 10$	$N = \lfloor N_{0.01} n \rfloor, k = 7$	$N = \lfloor N_{0.1}n \rfloor, k = 3$

- $N_{0.0001} = 19.170116754734877$ ,  $N_{0.001} = 14.37758756605116$  $N_{0.01} = 4.792529188683719$ ,  $N_{0.1} = 0.9965784284662087$
- Note that Bloom filter bit array size N is in bits

- GO BF simulator
- GO BF parameter calculator
- GO BF extensions
- GO BF applications
- GO BF false positive prob. analysis in [Bose et al. 2008]



## Problem

#### Problem

• Design a data structure that can estimate the frequencies of items.

Solutions			
	Update	Estimate	Comments
Balanced tree	$\mathcal{O}\left(\log n\right)$	$\mathcal{O}\left(\log n\right)$	works for sort-related
			ops.
Hash table	$\mathcal{O}\left(n ight)$	$\mathcal{O}\left(n ight)$	worst case is worse
	$\mathcal{O}\left(1 ight)*$	$\mathcal{O}\left(1 ight)*$	amortized case is awe-
			some
Count-min sketch	$\mathcal{O}\left(1\right)$	$\mathcal{O}\left(1\right)$	has false positive errors
			with approximations

• There are many more solutions.

#### Count-min sketch

- A probabilistic data structure to estimate frequencies, discovered by Graham Cormode and Shan Muthukrishnan in 2005
- Takes less space than a hash table and answers approximately and probabilistically
- Always overestimates, never underestimates, i.e., If CMS returns x, then x is greater than or equal to actual frequency
- Count-min sketch has two main components: A 2-D count matrix  $A[1 \dots k, 1 \dots w]$ Independent hash functions  $h_1, h_2, \dots, h_k$  such that  $h_i: \Sigma^* \to \{1, 2, \dots, m\}$  such that the mapping is uniform

#### **Count-min sketch class**

class CountMinSketch( $\epsilon, \delta$ )
<b>Input:</b> $\epsilon \leftarrow$ approximation parameter; $\delta \leftarrow$ error probability parameter $k \leftarrow$ number of hash functions; $w \leftarrow$ width of CMS $A \leftarrow$ 2-D CMS matrix of size $k \times w$
INITIALIZE(); UPDATE $(x, c_x)$ ; ESTIMATE $(x)$
Initialize()
$\begin{array}{l} k \leftarrow \left\lceil \ln \frac{1}{\delta} \right\rceil; \ w \leftarrow \left\lceil \frac{e}{\epsilon} \right\rceil \\ A[1 \dots k, 1 \dots w] \leftarrow [0 \dots 0, 0 \dots 0] \end{array}$
$UPDATE(x,c_x)$
for $i \leftarrow 1$ to $k$ do $\mid A[i, h_i(x)] \leftarrow A[i, h_i(x)] + c_x$
Estimate $(x)$
$\begin{array}{l} \min \leftarrow A[1, h_1(x)] \\ \text{for } i \leftarrow 2 \text{ to } k \text{ do} \\ \mid & \text{if } A[i, h_i(x)] < \min \text{ then} \\ \mid & \min \leftarrow A[i, h_i(x)] \end{array}$ $\textbf{return } \min$

#### Update

UPDATE $(x, c_x)$ 

for  $i \leftarrow 1$  to k do  $\mid A[i, h_i(x)] \leftarrow A[i, h_i(x)] + c_x$ 



Source: Medjedovic-Tahirovic-Dedovic's Algorithms and Data Structures for Massive Datasets

#### Estimate

#### ESTIMATE(x)

$$\begin{array}{l} \min \leftarrow A[1, h_1(x)] \\ \text{for } i \leftarrow 2 \text{ to } k \text{ do} \\ \mid & \text{if } A[i, h_i(x)] < \min \text{ then} \\ \mid & \min \leftarrow A[i, h_i(x)] \\ \text{return } \min \end{array}$$



Source: Medjedovic-Tahirovic-Dedovic's Algorithms and Data Structures for Massive Datasets

#### **Complexity analysis**

- $\bullet$  Given approximation fixed parameter  $\epsilon$
- $\bullet\,$  Given error probability fixed parameter  $\delta\,$
- $\bullet\,$  Compute the number of hash functions k as

$$k \leftarrow \left\lceil \ln \frac{1}{\delta} \right\rceil$$

 $\bullet\,$  Compute the CMS matrix width size w as

$$w \leftarrow \left\lceil \tfrac{e}{\epsilon} \right\rceil$$

Feature	Complexity
Update	$\mathcal{O}\left(k\right) = \mathcal{O}\left(1\right)$
Estimate	$\mathcal{O}\left(k\right) = \mathcal{O}\left(1\right)$
Space	$\mathcal{O}\left(mk\right) = \mathcal{O}\left(1\right)$

#### Error and approximation analysis

- Let the data stream be  $(a_1,c_1),(a_2,c_2),\ldots,(a_t,c_t)$
- Let  $N = \text{sum of all frequencies} = c_1 + c_2 + \dots + c_t$
- Let  $f_x^{\text{true}} =$  true frequency of item x in CMS Let  $f_x^{\text{est}} =$  estimated frequency of item x in CMS Then

$$f_x^{\text{est}} \text{ is in } \left\{ \begin{array}{ll} [f_x^{\text{true}}, f_x^{\text{true}} + \epsilon \cdot N] & \text{with probability} \geq 1 - \delta \\ (f_x^{\text{true}} + \epsilon \cdot N, \infty) & \text{with probability} \leq \delta \end{array} \right\}$$

where,  $\epsilon,\delta\in(0,1)$ 

Feature	Bloom filter	CMS
Duplicates	Set	Multiset
Array	1-D	2-D
Hash function	Maps to entire array	Maps to portions of 2-D array
Query	Existential queries	Counting queries
Size	Typ. linear w.r.t set size	Typ. sublinear w.r.t total freq
Randomness	Uniformly random	Uni. random & pairwise ind.



#### Problem

- Given a data stream, compute the number of distinct elements efficiently.
- Input: [4,8,9,4,4,8] Output: 3

### $\textbf{Solutions} \rightarrow \textbf{Brute force}$

- 1. Check all previous values for duplicates
- 2. Count a value only if no previous duplicate

```
BRUTEFORCE(A[1...n])
distinct \leftarrow 1
for i \leftarrow 2 to n do
  j \leftarrow 1
  while j < i do
     // Check current element with previous (j < i) or current (j = i)
     if A[i] = A[j] then break
     j \leftarrow j + 1
   // If there is no previous duplicate, then increment distinct
  if i = i then
     distinct \leftarrow distinct + 1
return distinct
```

$$\langle \mathsf{Time, Space} \rangle = \left\langle \mathcal{O}\left(n^2\right), \Theta\left(1\right) \right\rangle$$

- 1. Sort the array
- 2. Equal values are together in the sorted input
- 3. Count the first occurrence of each value

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta(n \log n), \Theta(n) \rangle$$

#### Solutions $\rightarrow$ Bit vector

- 1. Create a bit vector  $B[1 \dots U]$ , where U is the maximum value in the universe or in the array
- 2. For value A[i], set B[A[i]] to true
- 3. Count the number of true values in the bit vector

```
\begin{array}{c} \hline & \texttt{BitVector}(A[1 \dots n]) \\ \hline & distinct \leftarrow 0 \\ U \leftarrow \mathsf{Max}(A[1 \dots n]) & // \text{ max element in the array/universe} \\ B[1 \dots U] \leftarrow [0 \dots 0] \\ // \text{ For value } A[i], \text{ set } B[A[i]] \text{ to true} \\ & \texttt{for } i \leftarrow 1 \text{ to } n \text{ do } B[A[i]] \leftarrow 1 \\ // \text{ Count the number of true values in the bit vector} \\ & \texttt{for } i \leftarrow 1 \text{ to } U \text{ do} \\ & \mid \texttt{ if } B[i] = 1 \texttt{ then } distinct \leftarrow distinct + 1 \\ & \texttt{return } distinct \end{array}
```

 $\left< \mathsf{Time, Space} \right> = \left< \Theta\left(n + U\right), \Theta\left(U\right) \right>, \text{ where } U \geq \mathsf{Max}(A[1 \dots n]$ 

- 1. Create a hash set to store unique values
- 2. Add each element to the hash set
- 3. Return the size of the hash set

```
HASHSET(A[1...n])Create a hash set H to store unique valuesfor i \leftarrow 1 to n do| H.Add(A[i])distinct \leftarrow H.Size()// #elements in the hash setreturn distinct
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(n) \rangle$ 

- Like Bloom filter, linear counter is a bit vector of size m and does not store hash keys
- Linear counter length m is proportional to n but requires 1 bit per element
- There can be hard collisions that are not handled
- #Distinct elements is estimated based on the observed fraction of empty bits in the set

- 1. Use a hash function  $\boldsymbol{h}$
- 2. Create and initialize a bit array of size proportional to  $\boldsymbol{n}$  to zeros
- 3. Set h(A[1]) index in the bit array to 1
- 4. Set h(A[2]) index in the bit array to 1
- 5. so on...
- 6. Set h(A[n]) index in the bit array to 1

#Distinct elements = #zeros in the bit array



$$\langle \mathsf{Time, Space} 
angle = \langle \Theta\left(n
ight), \Theta\left(n
ight) 
angle$$

- 1. Use a hash function h
- 2. Let  $z_1 = ( \#$ trailing zeros in h(A[1]) ) + 1
- 3. Let  $z_2 = ( \#$ trailing zeros in h(A[2]) ) + 1
- 4. so on...
- 5. Let  $z_n = ( \#$ trailing zeros in h(A[n]) ) + 1
- 6. Let  $z_{\max} = Max(z_1, z_2, ..., z_n)$

#Distinct elements =  $2^{z_{\max}}$ 

# $\textbf{Solutions} \rightarrow \textbf{Probabilistic counting}$



#distinct=7, 16-bit hashes, estimated #distinct=  $2^5 = 32$ 

Source: Medjedovic-Tahirovic-Dedovic's Algorithms and Data Structures for Massive Datasets

 PROBABILISTICCOUNTING(A[1...n])

  $z_{max} \leftarrow 0$  // denotes max #trailing zeros in a hash value

 for  $i \leftarrow 1$  to n do

  $z \leftarrow CountTrailingZeros(h(A[i]))$  

 if  $z > z_{max}$  then  $z_{max} \leftarrow z$  

 distinct  $\leftarrow 2^{z_{max}}$  

 return distinct

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(1) \rangle$ 

# Why does the algorithm work?

Among  $\boldsymbol{k}$  random generated bit strings

- $\bullet \ \approx k/2$  bit strings have 0 as the last digit
- $pprox k/2^2$  bit strings have 00 as the last digits
- $pprox k/2^3$  bit strings have 000 as the last digits
- $\approx k/2^j$  bit strings have  $\underbrace{0\ldots 0}_{}$  as the last digits

# Why does the algorithm work?

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- $pprox k/2^3$  bit strings have 000 as the last digits
- $\approx k/2^j$  bit strings have  $\underbrace{0\ldots0}_{}$  as the last digits

Probability of generating a hash value for item A[i]

- having  $z_1 = 1$  (hash ends with 1) is 1/2
- having  $z_2 = 2$  (hash ends with 10) is  $1/2^2$
- having  $z_3 = 3$  (hash ends with 100) is  $1/2^3$
- having  $z_j = j$  (hash ends with  $1 \underbrace{0 \dots 0}_{j-1}$ ) is  $1/2^j$
## Why does the algorithm work?

Among k random generated bit strings •  $\approx k/2$  bit strings have 0 as the last digit •  $\approx k/2^2$  bit strings have 00 as the last digits •  $\approx k/2^3$  bit strings have 000 as the last digits •  $\approx k/2^j$  bit strings have  $0\ldots 0$  as the last digits Probability of generating a hash value for item A[i]• having  $z_1 = 1$  (hash ends with 1) is 1/2• having  $z_2 = 2$  (hash ends with 10) is  $1/2^2$ • having  $z_3 = 3$  (hash ends with 100) is  $1/2^3$ • having  $z_j = j$  (hash ends with  $1 \underbrace{0 \dots 0}$ ) is  $1/2^j$ An event having prob.  $1/2^{j}$  occurs if on avg.  $2^{j}$  trials are

performed An event having prob.  $1/2^{z_{\max}}$  occurs if on avg.  $2^{z_{\max}}$  trials are

performed

Problem:

- Probabilistic counting does not approximate well
- $\bullet\,$  Idea: Use m hash functions and take the average
- Flaw: But, using m hash functions is very expensive

Problem:

- Probabilistic counting does not approximate well
- $\bullet\,$  Idea: Use m hash functions and take the average
- Flaw: But, using m hash functions is very expensive

Idea: Bucketing

- Have  $m = 2^b$  buckets
- Find the bucket using the last b bits of the hash value
- Perform probabilistic counting with the remaining bits.
- Add the distinct items in all buckets

- 1. Let  $z_1 = \text{estimator/prediction for bucket } 1$
- 2. Let  $z_2 = \text{estimator/prediction for bucket 2}$

3. so on...

4. Let  $z_m = \text{estimator/prediction for bucket } m$ 

5. Let 
$$z_{avg} = \frac{z_1 + z_2 + \dots + z_m}{m}$$

= average estimator/prediction of all buckets

#Distinct elements = Round  $(m \cdot 2^{z_{avg}})$ 

## Solutions $\rightarrow$ Stochastic averaging



#### #distinct=7, 16-bit hashes, 4 buckets, estimated #distinct= Round $(4 \cdot 2^{2.5}) = 23$

Source: Medjedovic-Tahirovic-Dedovic's Algorithms and Data Structures for Massive Datasets

STOCHASTICAVERAGING (A[1...n])// Initialize estimators in m buckets Create an array  $z_{\max}[0, 1, ..., m-1] \leftarrow [0, 0, ..., 0]$ // Compute estimators in m buckets for  $i \leftarrow 1$  to n do  $bucket \leftarrow h(A[i]) \mod m$ // determines bucket  $buckethash \leftarrow \lceil h(A[i])/m \rceil$ // determines hash in bucket  $z \leftarrow \text{CountTrailingZeros}(buckethash)$ if  $z > z_{\max}[bucket]$  then  $z_{\max}[bucket] \leftarrow z$ // Find the average of estimators in m buckets  $z_{avg} \leftarrow \frac{1}{m} \cdot (z_{max}[0] + z_{max}[1] + \dots + z_{max}[m-1])$ // Estimate the #distinct elements in all buckets  $distinct \leftarrow \mathsf{Round}\left(m \cdot 2^{z_{avg}}\right)$ return distinct

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(1) \rangle$ 

- 1. Let  $z_1 = \text{estimator/prediction for bucket } 1$
- 2. Let  $z_2 = \text{estimator/prediction for bucket 2}$
- 3. so on...
- 4. Let  $z_m = \text{estimator/prediction for bucket } m$

5. Let 
$$z_{avg} = \frac{z_1 + z_2 + \dots + z_m}{m}$$

= average estimator/prediction of all buckets

$$\frac{\#\text{Distinct elements} = \text{Round} \left(\alpha_m \cdot m \cdot 2^{z_{\text{avg}}}\right)}{\alpha_m}, \text{ where,}$$
$$\alpha_m = \begin{cases} 0.39701 - \frac{2\pi^2 + \ln^2 2}{48m} & \text{if } m < 64, \\ 0.39701 & \text{if } m \ge 64. \end{cases}$$



#distinct=7, 16-bit hashes, 4 buckets, estimated #distinct= Round  $(0.29169926137 \cdot 4 \cdot 2^{2.5}) = 7$ 

Source: Medjedovic-Tahirovic-Dedovic's Algorithms and Data Structures for Massive Datasets

LogLog(A[1...n])// Initialize estimators in m buckets Create an array  $z_{\max}[0, 1, \ldots, m-1] \leftarrow [0, 0, \ldots, 0]$ // Compute estimators in m buckets for  $i \leftarrow 1$  to n do  $bucket \leftarrow h(A[i]) \mod m$ // determines bucket  $buckethash \leftarrow \lceil h(A[i])/m \rceil$ // determines hash in bucket  $z \leftarrow \text{CountTrailingZeros}(buckethash)$ if  $z > z_{\max}[bucket]$  then  $z_{\max}[bucket] \leftarrow z$ // Find the average of estimators in m buckets  $z_{\text{avg}} \leftarrow \frac{1}{m} \cdot (z_{\max}[0] + z_{\max}[1] + \dots + z_{\max}[m-1])$ // Estimate the #distinct elements in all buckets  $distinct \leftarrow \mathsf{Round}\left(\alpha_m \cdot m \cdot 2^{z_{\mathsf{avg}}}\right)$ return distinct

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta \left( n \right), \Theta \left( 1 \right) \rangle$ 

# $\textbf{Solutions} \rightarrow \textbf{HyperLogLog}$

1. Let  $z_1 = \text{estimator/prediction for bucket } 1$ 

- 2. Let  $z_2 = \text{estimator/prediction for bucket 2}$
- 3. so on...

4. Let 
$$z_m = \text{estimator/prediction for bucket } m$$

5. Let 
$$B = \frac{m}{\frac{1}{2^{z_1} + \frac{1}{2^{z_2}} + \dots + \frac{1}{2^{z_m}}}}$$

= average estimator/prediction of all buckets

 $\# \text{Distinct elements} = \text{Round} \left(\beta_m \cdot m \cdot B\right)$  $\beta_m = \begin{cases} 0.541 & \text{if } m = 4, \\ 0.627 & \text{if } m = 8, \\ 0.673 & \text{if } m = 16, \\ 0.697 & \text{if } m = 32, \\ 0.709 & \text{if } m = 64, \\ \frac{0.723}{1+1.079/m} & \text{if } m \ge 128. \end{cases}$ 



#distinct=7, 16-bit hashes, 4 buckets, estimated #distinct= Round  $(0.541 \cdot 4 \cdot 3.88) = 8$ 

Source: Medjedovic-Tahirovic-Dedovic's Algorithms and Data Structures for Massive Datasets



Time, Space 
$$\langle \Theta(n), \Theta(1) \rangle$$

Algorithm	Time	Space
Brute force	$\mathcal{O}\left(n^2\right)$	$\Theta(1)$
Sort and count	$\Theta\left(n\log n\right)$	$\Theta\left(n ight)$
Bit vector	$\Theta\left(n+U\right)$	$\Theta\left(U ight)$
Hash table	$\Theta\left(n ight)$	$\Theta\left(n ight)$
Linear counting	$\Theta\left(n ight)$	$\Theta\left(n ight)$
Probabilistic counting	$\Theta\left(n ight)$	$\Theta\left(1 ight)$
Stochastic averaging	$\Theta\left(n ight)$	$\Theta(1)$
LogLog	$\Theta\left(n ight)$	$\Theta(1)$
HyperLogLog	$\Theta\left(n ight)$	$\Theta(1)$

- Book: Algorithms and Data Structures for Massive Datasets
- Book: Probabilistic Data Structures and Algorithms for Big Data Applications

### External-Memory Algorithms HOME

#### Merge k Sorted Arrays (HOME)

- Merge k sorted arrays each with size n.
- Input: Sorted arrays  $A_1, A_2, \ldots, A_k$  each with size nOutput: Sorted array consisting of kn elements
- Input:  $A_1 = [3, 5, 8]$ ,  $A_2 = [4, 6, 7]$ ,  $A_3 = [1, 2, 9]$ Output: [1, 2, 3, 4, 5, 6, 7, 8, 9]

- Copy elements in all arrays to a single array
- Sort the array using merge sort

```
      NAIVESOLUTION(A_1[1 \dots n], \dots, A_k[1 \dots n])

      Create a dynamic array A \leftarrow []

      for i \leftarrow 1 to k do

      | for j \leftarrow 1 to n do

      | A.Add(A_i[j])

      SORT(A)

      return A
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(kn \log(kn)), \Theta(kn) \rangle$ 

- Create an empty dynamic array
- Merge each array with the evolving array one-by-one

```
NAIVEMERGING(A_1[1 \dots n], \dots, A_k[1 \dots n])Create two dynamic arrays B_0 \leftarrow [] and B_1 \leftarrow []j \leftarrow 0for i \leftarrow 1 to k doj \leftarrow (j+1) \mod 2B_j \leftarrow MERGE(B_{(j+1) \mod 2}, A_i)return B_j
```

$$\left< \mathsf{Time, Space} \right> = \left< \Theta\left(k^2 n 
ight), \Theta\left(k n 
ight) 
ight>$$

 $B_0$  and  $B_1$  are empty and j = 0



Return  $B_j$ , where j = 1

## $\textbf{Solutions} \rightarrow \textbf{Divide-and-conquer}$

- Merge arrays in groups of two to get k/2 arrays
- Merge arrays in groups of two to get k/4 arrays
- Repeat this process until there is only one array
- That single array is the merged sorted array

MERGEKSORTEDARRAYS $(A_1[1 \dots n], \dots, A_k[1 \dots n])$ 

return MERGE-D&C( $A_1[1 \dots n], \dots, A_k[1 \dots n]$ )

```
MERGE-D&C(A_{low}, \ldots, A_{high})
```

$$\begin{array}{l} n \leftarrow (high - low + 1) \\ \text{if } n = 1 \text{ then return } A_{low} \\ mid \leftarrow (low + high)/2 \\ // \text{ Split the arrays into left and right sets} \\ A_{left} \leftarrow \text{MERGE-D\&C}([A_{low}, A_{low+1}, \ldots, A_{mid}]) \\ A_{right} \leftarrow \text{MERGE-D\&C}([A_{mid+1}, A_{mid+2}, \ldots, A_{high}] \\ // \text{ Merge the left and right sets} \\ A_{merged} \leftarrow \text{MERGE}(A_{left}, A_{right}) \\ \text{return } A_{merged} \end{array}$$

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta \left( kn \log k \right), \Theta \left( kn \right) \rangle$ 

### $\textbf{Solutions} \rightarrow \textbf{Divide-and-conquer}$



#### Core idea.

- In 2-way merge, we take the minimum of elements from the two sorted arrays and add it to the merged array
- In *k*-way merge, we take the minimum of elements from all the *k* sorted arrays and add it to the merged array
- We compute the minimum of k elements using a naive approach of scanning all these k elements and taking the minimum

#### Implementation details.

- Maintain a  $pointer[1 \dots k]$  array where pointer[i] points to the next element in  $A_i$  to be compared for finding the minimum element
- We take the minimum element of  $\{A_1[pointer[1]], A_2[pointer[2]], \ldots, A_k[pointer[k]]\}$ . If all elements of an array are exhausted, i.e., pointer[i] = n + 1 then we do not consider that array for computing the minimum element

```
NAIVEkWAYMERGE(A_1[1 \dots n], \dots, A_k[1 \dots n])
A_{merged} \leftarrow []
pointer[1 \dots k] \leftarrow [1 \dots 1]
                              // initialize a pointer for each array
// Get all the elements of A_{merged} in the sorted order
while true do
   // Find the minimum element among the current pointers of the k arrays
  minval \leftarrow \infty: minindex \leftarrow -1
  for i \leftarrow 1 to k do
     if pointer[i] \leq n and A_i[pointer[i]] < minval then
         minval \leftarrow A_i[pointer[i]]
       mininder \leftarrow i
   // If no minimum element is found, we are done
  if minindex = -1 then break
  A_{meraed}. Append (minval)
   // Move the pointer of the array from which the minimum element was taken
  pointer[minindex] \leftarrow pointer[minindex] + 1
return A_{merged}
```

$$\langle \mathsf{Time, Space} \rangle = \left\langle \Theta\left(k^2 n\right) \right\rangle, \Theta\left(k n\right) \right\rangle$$

## Solutions $\rightarrow$ Naive k-way merge



## Solutions $\rightarrow$ Naive k-way merge (continued)

		$A_{merged}$	pointer
$\begin{array}{c} A_1 \\ A_2 \\ A_3 \end{array}$	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	1 2 2 3 3	4 3 1
$\begin{array}{c} A_1 \\ A_2 \\ A_3 \end{array}$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1 2 2 3 3 3	$\begin{array}{c} 4\\ 3\\ 2 \end{array}$
$\begin{array}{c} A_1 \\ A_2 \\ A_3 \end{array}$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1 2 2 3 3 4	$\begin{array}{c} 4\\ 4\\ 2 \end{array}$
$\begin{array}{c} A_1 \\ A_2 \\ A_3 \end{array}$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1 2 2 3 3 4 4	$\begin{array}{c} 4\\ 4\\ 3 \end{array}$
$\begin{array}{c} A_1 \\ A_2 \\ A_3 \end{array}$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1 2 2 3 3 3 4 4 5	

## Solutions $\rightarrow$ Improved *k*-way merge

#### Core idea.

- In the naive k-way merge algorithm, we compute the minimum of k elements using a naive approach of scanning all these k elements and taking the minimum. This takes exactly k operations per element, even if some arrays are fully processed.
- In the improved k-way merge algorithm, we compute the minimum of k elements in a hash map. This takes at most k operations per element. If arrays are fully processed, then there will be no comparisons for their elements.

#### Implementation details.

- Maintain a *pointer* hash map where *pointer*[*key*] points to the next element in A<sub>key</sub> to be compared for finding minimum.
- We take the minimum element of  $A_{key}[pointer[key]]$  for all keys in the hash map. If all elements of an array are exhausted, i.e., pointer[key] = n + 1 then that array number will not be in the hash map.

## Solutions $\rightarrow$ Improved *k*-way merge

```
IMPROVED k WAYMERGE(A_1[1 \dots n], \dots, A_k[1 \dots n])
A_{meraed} \leftarrow []; Create a hash map pointer where the key is the array number
and the value is the index inside that array
for i \leftarrow 1 to k do pointer.Add((i, 1))
// Get all the elements of A_{merged} in the sorted order
while true do
   // Find the minimum element among the current pointers of the keys (i.e.,
       array numbers) in the hash map
  minval \leftarrow \infty; minindex \leftarrow -1
   foreach key in pointer.Keys() do
     if A_{key}[pointer[key]] < minval then
        minval \leftarrow A_{key}[pointer[key]]
        minindex \leftarrow key
   // If no minimum element is found, we are done
  if minindex = -1 then break
  A_{merged}. Append (minval)
   // Move the pointer of the array from which the minimum element was taken
  pointer[minindex] \leftarrow pointer[minindex] + 1
   // If the array is fully processed, remove its entry from the hash map
   if pointer[minindex] > n then pointer.Remove(minindex)
return A_{merged}
```

$$\langle \mathsf{Time, Space} 
angle = \left\langle \mathcal{O}\left(k^2n\right) 
ight
angle, \Theta\left(kn
ight
angle 
ight
angle$$

## Solutions $\rightarrow$ Best *k*-way merge

• We create a min-heap of size k and add the first elements of all arrays. When we poll, we check if the element on the right is available, if so, then add it to the heap. Once the heap is empty,  $A_{merged}$  is the answer.

```
\operatorname{Best}_k \operatorname{WayMerge}(A_1[1 \dots n], \dots, A_k[1 \dots n])
A_{merged} \leftarrow []
Create a min-heap H and initialize with the first element of each array
for i \leftarrow 1 to k do
  H.Add((A_i[1], i, 1))
                                           // (element, arrayindex, elementindex)
while min-heap H is not empty do
   // Extract the minimum element from the min-heap
   (minelement, arrayindex, elementindex) \leftarrow H.RemoveMin()
  A_{meraed}. Append (minelement)
   // Move to the next element in the array that contributed the min element
  elementindex \leftarrow elementindex + 1
   // If there are more elements in the current array, insert the next element
       into the heap
  if elementindex \leq n then
      H.\mathsf{Add}((A_{arrayindex}[elementindex], arrayindex, elementindex))
return A_{merged}
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(nk \log k), \Theta(kn) \rangle$ 

### Solutions $\rightarrow$ Best *k*-way merge



## Solutions $\rightarrow$ Best *k*-way merge (continued)



5

#### Solutions $\rightarrow$ External-memory *k*-way merge



Source: Medjedovic-Tahirovic-Dedovic's Algorithms and Data Structures for Massive Datasets

### Solutions $\rightarrow$ External-memory *k*-way merge

```
kWAYMERGE(F_1, F_2, \ldots, F_k, M, B)
For each file F_i, create an inputbuf fer[i] of size B elements in RAM
Initialize each input buffer with the first data block from its input file
Create a min-heap H to keep track of the minimum from each input buffer, and an empty outputbuffer
to store the result
Initialize min-heap H with the first element of every input buffer
for i \leftarrow 1 to k do
   element \leftarrow \text{ReadNextElementFromInputBuffer}(inputbuffer[i])
   if element is not none then H.Add(element, i)
while min-heap H is not empty do
    // Remove from min-heap H the min and input buffer index; and write to output buffer
   minelement, bufferindex \leftarrow H.RemoveMin()
   WRITEELEMENTTOOUTPUTBUFFER(minelement, outputbuffer)
   if output buffer is full then
       WRITEOUTPUTBUFFERTODISK(outputbuffer, merged file Fmerged)
      Clear contents of outputbuffer
    // Add to min-heap H the next element from input buffer having index bufferindex
   element \leftarrow \text{READNEXTELEMENTFROMINPUTBUFFER}(inputbuffer[bufferindex])
   if element is none then
      inputbuffer[bufferindex] \leftarrow \text{READNEXTDATABLOCKFROMDISK}(F_{bufferindex})
      element \leftarrow \text{READNEXTELEMENTFROMINPUTBUFFER} in putbuffer [bufferindex]
   H.Add(element, bufferindex)
return F_{merged}
```

$$\langle \mathsf{Time, Space} \rangle = \left\langle \Theta\left(\frac{kn}{B}\right) \mathsf{I}/\mathsf{Os}, \Theta\left(kn\right) \right\rangle$$

Algorithm	Time	Space		
Internal-memory algorithms				
Naive solution	$\Theta\left(kn\log\left(kn\right)\right)$	$\Theta\left(kn\right)$		
Naive merging	$\Theta\left(k^2n\right)$	$\Theta\left(kn\right)$		
Divide-and-conquer	$\Theta\left(kn\log k\right)$	$\Theta\left(kn\right)$		
Naive $k$ -way merge	$\Theta\left(k^2n\right)$	$\Theta\left(kn\right)$		
Improved $k$ -way merge	$\mathcal{O}\left(k^2n\right)$	$\Theta\left(kn\right)$		
Best $k$ -way merge	$\Theta\left(nk\log k\right)$	$\Theta\left(kn\right)$		
External-memory algorithms				
External-memory $k$ -way merge	$\Theta\left(\frac{kn}{B}\right)$ I/Os	$\Theta\left(kn\right)$		



# Solutions $\rightarrow$ Merge sort (Recursive)

$$\label{eq:MERGESORT} \begin{split} & \text{MERGESORT}(unsortedfile, M, B) \\ & // \ \text{Step 1: Divide} \\ & \text{Divide } unsortedfile \ \text{into} \ \lceil n/M \rceil \ \text{chunks, each of size at most } M \end{split}$$

foreach unsorted chunk do Load the unsorted chunk into RAM Sort the chunk using 2-way merge sort Write back the sorted chunk to the hard disk Create sortedchunks to contain pointers to all sorted chunks // Step 2: Conquer and combine (k-way merge), where k = M/B ...... sortedfile  $\leftarrow$  RECURSIVEMERGE(sortedchunks, k) return sortedfile

RecursiveMerge(sortedchunks, k)

if there is only one chunk in *sortedchunks* then

return the only sorted chunk

Create  $newsortedchunks \leftarrow [$ ] to contain pointers to merged chunks while there sortedchunks has more than one chunk **do** 

Divide all sorted chunks into groups of k, except possibly the last group  ${\bf foreach}$  group of at most k sorted chunks  ${\bf do}$ 

Merge the k chunks into a single sorted chunk using k-way merge

Add this merged chunk to *newsortedchunks* 

return RECURSIVEMERGE(newsortedchunks, k)

$$\langle \mathsf{Time, Space} \rangle = \left\langle \Theta\left(\frac{n}{B}\log_{\frac{M}{B}}\frac{n}{B}\right) \mathsf{I}/\mathsf{Os}, \Theta\left(n\right) \right\rangle$$
# Solutions $\rightarrow$ Merge sort (Non-recursive)

MERGESORTNONRECURSIVE(unsortedfile, M, B)// Step 1: Divide ..... Divide *unsortedfile* into  $\lceil n/M \rceil$  chunks, each of size at most M foreach unsorted chunk do Load the unsorted chunk into RAM Sort the chunk using 2-way merge sort Write back the sorted chunk to hard disk Create *sortedchunks* to contain pointers to all sorted chunks // Step 2: Conquer (k-way merge), where k = M/B ..... while *sortedchunks* has more than one sorted file **do** Create *newsortedchunks* to contain pointers to merged chunks Divide all sorted chunks in groups of k, except possibly the last group **foreach** group of k sorted chunks **do** Merge the k chunks into a single sorted chunk using k-way merge Append this merged chunk to *newsortedchunks*  $sorted chunks \leftarrow newsorted chunks$ Let the only file in *sortedchunks* be called *sortedfile* return sortedfile

 $\left< \mathsf{Time, Space} \right> = \left< \Theta\left(\frac{n}{B} \log_{\frac{M}{B}} \frac{n}{B}\right) \ \mathsf{I}/\mathsf{Os}, \Theta\left(n\right) \right>$ 

# Quantum Algorithms (HOME)



### Definition

• The inner/dot/scalar product  $\vec{v} \bullet \vec{w}$  of two vectors  $\vec{v}$  and  $\vec{w}$  is a mathematical operation between two vectors of the same dimension that returns a scalar number.

Suppose 
$$\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$
 and  $\vec{w} = \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{bmatrix}$ . Then,  
 $\vec{v} \bullet \vec{w} = \overline{v_1}w_1 + \overline{v_2}w_2 + \dots + \overline{v_n}w_n$ .

• Hilbert space is a complex vector Euclidean space with welldefined inner product.

# What is superposition?



### Energy of an electron in an atom

- This is a k-level quantum mechanical system
- After measuring, electron is in exactly one of the states.
- Before measuring, electron is in all k quantum states.

Superposition is when a quantum particle

is in multiple states simultaneously

### Energy of an electron in an atom

• After measuring, the electron can be in any one of  $|0\rangle$ ,  $|1\rangle$ , ...,  $|k-1\rangle$  quantum energy states, where  $|0\rangle = \begin{bmatrix} 1\\0\\ \vdots\\0 \end{bmatrix}$ ,  $|1\rangle = \begin{bmatrix} 0\\1\\ \vdots\\0 \end{bmatrix}$ ,  $|k-1\rangle = \begin{bmatrix} 0\\0\\ \vdots\\1 \end{bmatrix}$  are the computational basis and they represent the orthonormal basis of a *k*-dimensional vector space

#### Energy of an electron in an atom

• Before measuring, the electron is in a superposition of all k quantum energy states i.e.,  $\begin{aligned}
|\psi\rangle &= c_0|0\rangle + c_1|1\rangle + \dots + c_{k-1}|k-1\rangle \\
\therefore |\psi\rangle &= c_0 \begin{bmatrix} 1\\0\\\vdots\\0 \end{bmatrix} + c_1 \begin{bmatrix} 0\\1\\\vdots\\0 \end{bmatrix} + \dots + c_{k-1} \begin{bmatrix} 0\\0\\\vdots\\1 \end{bmatrix} = \begin{bmatrix} c_0\\c_1\\\vdots\\c_{k-1} \end{bmatrix}, \\
\text{where } c_i\text{'s are complex numbers and } |\psi\rangle \text{ is a unit vector,} \\
\text{i.e., } |c_0|^2 + |c_1|^2 + \dots + |c_{k-1}|^2 = 1.
\end{aligned}$  A qubit represents the superpositioned state

of a 2-state quantum system

Example: A qubit can be made from a photon being polarized either horizontally or vertically

$$|0
angle = egin{bmatrix} 1 \\ 0 \end{bmatrix}$$
 and  $|1
angle = egin{bmatrix} 0 \\ 1 \end{bmatrix}$ 

$$\begin{split} |\psi\rangle &= a|0\rangle + b|1\rangle = a \begin{bmatrix} 1\\ 0 \end{bmatrix} + b \begin{bmatrix} 0\\ 1 \end{bmatrix} = \begin{bmatrix} a\\ b \end{bmatrix} \\ \text{where } |a|^2 + |b|^2 = 1 \\ \text{Qubit } |\psi\rangle \text{ is invalid if } |a|^2 + |b|^2 \neq 1 \end{split}$$

A qubit when measured collapses to one of the two basis states

Suppose 
$$|\psi\rangle = a|0\rangle + b|1\rangle = a \begin{bmatrix} 1\\0 \end{bmatrix} + b \begin{bmatrix} 0\\1 \end{bmatrix} = \begin{bmatrix} a\\b \end{bmatrix}$$

Probability of measuring qubit $ \psi\rangle$	as $ 0\rangle$ is $ a ^2$
Probability of measuring qubit $ \psi\rangle$	as $ 1\rangle$ is $ b ^2$

Observe that the sum of all collapsing probabilities must be 1

## Comparison between classical and quantum bit

Feature	Bit	Qubit
Implementation	Transistor	Quantum system
Exclusive states	0 and 1	0 angle and $ 1 angle$
State after measuring	0 or 1	0 angle or $ 1 angle$
State before measuring	0 or 1	Superposition of $ 0 angle$ and $ 1 angle$
Representation	$bit \in \{0,1\}$	qubit = a  0 angle + b  1 angle

## Schrödinger's cat



Source: https://www.rms.com/blog/2018/09/04/schrodingers-cat-model

## Schrödinger's cat



### Problem

• Suppose the probabilities of cat being alive and the cat being dead are the same. Then, what are the values of *a* and *b*?

- Suppose  $|\psi\rangle = (a+ib)|0\rangle + (c+i\underline{d})|1\rangle$
- There are 4 variables! However,  $\sqrt{(a^2+b^2)}+\sqrt{(c^2+d^2)}=1$
- So, we can say there are only 3 independent variables
- This implies we can visualize this state on a 3-D unit sphere

What should be the three basis vectors or axes?

## How to visualize a qubit? Block sphere



Source: https://www.quantum-inspire.com/kbase/bloch-sphere/

## How to visualize a qubit? Block sphere



Source: https://logosconcarne.com/2021/03/15/qm-101-bloch-sphere/

Axis	Basis	Meaning
Z	0 angle and $ 1 angle$	0 angle and $ 1 angle$
Y	i angle and $ -i angle$	$\frac{ 0 angle+i 1 angle}{\sqrt{2}}$ and $\frac{ 0 angle-i 1 angle}{\sqrt{2}}$
X	+ angle and $ - angle$	$rac{ 0 angle+ 1 angle}{\sqrt{2}}$ and $rac{ 0 angle- 1 angle}{\sqrt{2}}$

## How does a quantum system evolve?

- Both classical and quantum systems evolve through state transformations
- Arbitrary transformations of a quantum state are not possible

Time evolution of a quantum system happens through

a series of unitary transformations

- A unitary transformation simply means multiplying by a unit matrix
- $\bullet\,$  Multiplying by any unitary matrix U is a valid quantum state transformation

$$U \cdot |\psi_1\rangle = |\psi_2\rangle$$

A matrix U is a unitary matrix if  $UU^{\dagger} = U^{\dagger}U = I$ 

A matrix U is a unitary matrix if  $U^{\dagger}=U^{-1}$ 

where  $U^{\dagger}$  is the conjugate transpose of U.

Examples • Pauli matrices  $I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ • Hadamard matrix  $H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$  The conjugate transpose of a matrix M is a matrix  $M^{\dagger}$  obtained by

taking the complex conjugate of all elements of  $\boldsymbol{M}$  and

taking the transpose of the resulting matrix.

#### Examples

• Suppose 
$$M = \begin{bmatrix} 1+i & 2+2i & 3+3i\\ 10-10i & 20-20i & 30-30i \end{bmatrix}$$
.  
Then,  $M^{\dagger} = \begin{bmatrix} 1-i & 10+10i\\ 2-2i & 20+20i\\ 3-3i & 30+30i \end{bmatrix}$ .

### Definition

- A quantum operation transforms a quantum state to another quantum state.
- Any quantum operation can be represented by a unitary matrix. Similarly, any unitary matrix represents a possible quantum operation.
- Every quantum operation can be thought as a rotation in the Block sphere

#### Examples

• All unitary matrices

Every quantum operation, except measurement, is reversible.

- If  $U|\psi_1\rangle = |\psi_2\rangle$ , then it is possible to reverse the transformation, i.e.,  $U^{\dagger}|\psi_2\rangle = |\psi_1\rangle$
- Suppose you have a sequence of quantum operations  $U_1U_2U_3\cdots U_k|\psi_1\rangle = |\psi_2\rangle$ , then it is possible to reverse the transformation by using  $U_k^{\dagger}U_{k-1}^{\dagger}U_{k-2}^{\dagger}\cdots U_1|\psi_2\rangle = |\psi_1\rangle$

# Single-qubit operations (quantum-algorithm level)

Non-Clifford gate •  $T = \begin{bmatrix} 1 & 0 \\ 0 & e^{i\pi/4} \end{bmatrix}$  $(45^{\circ} \text{ rotation around } Z \text{ axis})$ Clifford gates •  $H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$  (create equal superposition of  $|0\rangle$  and  $|1\rangle$ ) •  $S = \begin{bmatrix} 1 & 0 \\ 0 & i \end{bmatrix} = T^2$ (90° rotation around Z axis) •  $X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = HT^4H$  (NOT; 180° rotation around X axis) •  $Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = T^2 H T^4 H T^6$  (180° rotation around Y axis) •  $Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = T^4$  $(180^{\circ} \text{ rotation around } Z \text{ axis})$ • Pauli operators =  $\{X, Y, Z\}$ 

> These operations can be composed to approximate any unitary transformation on a single qubit

# Single-qubit operations (function-description level)

• 
$$R_z(\theta) = e^{-i\theta Z/2} = \begin{bmatrix} e^{-i\theta/2} & 0\\ 0 & e^{i\theta/2} \end{bmatrix}$$
  
•  $R_x(\theta) = e^{-i\theta X/2} = HR_z(\theta)H = \begin{bmatrix} \cos(\theta/2) & -i\sin(\theta/2)\\ -i\sin(\theta/2) & \cos(\theta/2) \end{bmatrix}$   
•  $R_y(\theta) = e^{-i\theta Y/2} = SHR_z(\theta)HS^{\dagger} = \begin{bmatrix} \cos(\theta/2) & -\sin(\theta/2)\\ \sin(\theta/2) & \cos(\theta/2) \end{bmatrix}$ 

These rotations can be composed to perform any unitary transformation on a single qubit

For every unitary matrix U, there exists  $\alpha, \beta, \gamma, \delta$  such that

$$U = e^{i\alpha} R_x(\beta) R_z(\gamma) R_x(\delta)$$

## Single-qubit operations



# Single-qubit gates

- Classical Boolean computing consists of circuits of NOT, AND, and, OR gates
- Quantum computing consists of circuits of quantum gates

A quantum gate is a quantum operation

A quantum circuit is a model to visualize operations on qubits

$$\begin{array}{c} a|0\rangle + b|1\rangle & \hline X & b|0\rangle + a|1\rangle \\ a|0\rangle + b|1\rangle & \hline Y & -ib|0\rangle + ia|1\rangle \\ a|0\rangle + b|1\rangle & \boxed Z & a|0\rangle - b|1\rangle \\ a|0\rangle + b|1\rangle & \hline H & a|+\rangle - b|-\rangle \\ a|0\rangle + b|1\rangle & \boxed S & a|0\rangle + be^{i\pi/2}|1\rangle \\ a|0\rangle + b|1\rangle & \hline T & a|0\rangle + be^{i\pi/4}|1\rangle \end{array}$$

## Random Number Generator HOME

### Problem

• Generate a truly random bit.

#### Solution

- Cannot be solved in classical computing
- Can be solved in quantum computing

## **Random number generation**



### Problem

• Generate 37 truly random bits when your quantum computer has only 5 qubits.

### Solution

• Generate 5 random bits in parallel for 7 times and then generate 2 random bits in parallel

- 1-qubit introduces superposition
- >1-qubits introduces interference and entanglement

#dimensions is directly proportional to  $2^{\#qubits}$ 

• Increase in 1 qubit doubles the computational power. This exponential speedup is the reason that a quantum computer with 100 qubits can surpass the most powerful supercomputers

## **Multi-qubit states**

- First qubit is in the state  $|\psi_1\rangle = \begin{bmatrix} a \\ b \end{bmatrix}$  Second qubit is in the state  $|\psi_2\rangle = \begin{bmatrix} c \\ d \end{bmatrix}$
- Corresponding 2-qubit state is given by the tensor product or Kronecker product

$$|\psi_1\rangle \otimes |\psi_2\rangle = \begin{bmatrix} a \\ b \end{bmatrix} \otimes \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} a \begin{bmatrix} c \\ d \\ b \begin{bmatrix} c \\ d \end{bmatrix} \end{bmatrix} = \begin{bmatrix} ac \\ ad \\ bc \\ bd \end{bmatrix}$$

• This idea can be generalized to *n*-qubits which gives a normalized vector of size  $2^n$ 

## Multi-qubit states

A 2-qubit state is written as  $|\psi\rangle = a|00\rangle + b|01\rangle + c|10\rangle + d|11\rangle = \begin{vmatrix} a \\ b \\ c \\ c \end{vmatrix}$  where •  $|00\rangle = |0\rangle \otimes |0\rangle = \begin{bmatrix} 1\\0 \end{bmatrix} \otimes \begin{bmatrix} 1\\0 \end{bmatrix} = \begin{bmatrix} 1\\0\\0\\0\\0 \end{bmatrix}$ •  $|01\rangle = |0\rangle \otimes |1\rangle = \begin{bmatrix} 1\\0 \end{bmatrix} \otimes \begin{bmatrix} 0\\1\\1 \end{bmatrix} = \begin{bmatrix} 0\\1\\0\\0\\1\\0 \end{bmatrix}$ •  $|10\rangle = |1\rangle \otimes |0\rangle = \begin{bmatrix} 0\\1\\0\\1 \end{bmatrix} \otimes \begin{bmatrix} 1\\0\\0\\1\\0 \end{bmatrix} = \begin{bmatrix} 0\\0\\1\\0\\0\\1 \end{bmatrix}$ 

### Small vs. Large quantum systems



### Small vs. Large quantum systems



# Quantum system transformation: Small $\rightarrow$ Large

### Definition

- A joint system of n small 2-D quantum systems, each having 2 quantum states can be thought as a large 2<sup>n</sup>-D quantum mechanical system having 2<sup>n</sup> quantum states.
- The tensor product  $\otimes$  (or Kronecker product) of n one-qubits can be thought to denote a quantum mechanical system having  $2^n$  quantum states.

#### Examples

• 3 qubits can be thought to denote an 8-D quantum system.  $\Gamma 07$ 

$$\mathsf{E}.\mathsf{g}.: |1\rangle \otimes |0\rangle \otimes |1\rangle = \begin{bmatrix} 0\\1 \end{bmatrix} \otimes \begin{bmatrix} 1\\0 \end{bmatrix} \otimes \begin{bmatrix} 0\\1 \end{bmatrix} = \begin{bmatrix} 0\\0\\0\\0\\1\\0\\0 \end{bmatrix} = |101\rangle.$$

## Quantum system transformation: Small $\rightarrow$ Large



#### Examples

• Alice has quantum state  $|\psi\rangle = a|0\rangle + b|1\rangle$ . Bob has quantum state  $|\phi\rangle = c|0\rangle + d|1\rangle$ . Then, their combined quantum state is  $|\psi\phi\rangle = |\psi\rangle \otimes |\phi\rangle = (a|0\rangle + b|1\rangle) \otimes (c|0\rangle + d|1\rangle)$  $= \begin{bmatrix} a \\ b \end{bmatrix} \otimes \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} ac \\ ad \\ bc \\ bd \end{bmatrix}$ .
# Quantum system transformation: Large $\rightarrow$ Small

#### Definition

- A large 2<sup>n</sup>-D quantum mechanical system having 2<sup>n</sup> quantum states can be thought as a joint system of n small 2-D quantum systems, each having 2 quantum states.
- A quantum mechanical system having  $2^n$  quantum states can be thought as a tensor product  $\otimes$  (or Kronecker product) of n one-qubits.

#### Examples

• An 8-D quantum system can be represented using 3 qubits.

$$\mathsf{E}.\mathsf{g}.: |101\rangle = \begin{bmatrix} 0\\0\\0\\1\\0\\0\\0 \end{bmatrix} = \begin{bmatrix} 0\\1 \end{bmatrix} \otimes \begin{bmatrix} 1\\0 \end{bmatrix} \otimes \begin{bmatrix} 0\\1 \end{bmatrix} = |1\rangle \otimes |0\rangle \otimes |1\rangle.$$



#### Definition

• The two-qubit state  $|\Psi
angle$  is separable if

 $|\Psi\rangle = |\psi\rangle \otimes |\phi\rangle$  for some one-qubit states  $|\psi\rangle$  and  $|\phi\rangle$ .

#### What is a separable state?



#### Examples

• The combined state of Alice and Bob is  $|\Psi\rangle = \frac{1}{2}(|00\rangle + |01\rangle - |10\rangle - |11\rangle)$ . Find the individual states of Alice and Bob. Let  $|\Psi\rangle = |\psi\rangle \otimes |\phi\rangle = \begin{bmatrix} \psi_1 \\ \psi_2 \end{bmatrix} \otimes \begin{bmatrix} \phi_1 \\ \phi_2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} = \begin{bmatrix} \psi_1 \phi_1 \\ \psi_1 \phi_2 \\ \psi_2 \phi_1 \\ \psi_2 \phi_2 \end{bmatrix}$ .

Solving the system of equations, we find that Alice's state  $|\psi\rangle = |-\rangle$  and Bob's state  $|\phi\rangle = |+\rangle$ .

#### What is an entangled state?



#### Definition

 $\bullet\,$  The two-qubit state  $|\Psi\rangle$  is entangled if

 $|\Psi\rangle \neq |\psi\rangle \otimes |\phi\rangle$  for any one-qubit states  $|\psi\rangle$  and  $|\phi\rangle$ .

- A two-qubit state is called an entangled state if it cannot be written as the tensor product of single-qubit states.
- A two-qubit gate is called an entangled gate if it cannot be written as the tensor product of single-qubit gates.

#### What is an entangled state?



#### Examples

• The combined state of Alice and Bob is  $|\Psi\rangle = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle)$ . Find the individual states of Alice and Bob.

Let 
$$|\Psi\rangle = |\psi\rangle \otimes |\phi\rangle = \begin{bmatrix} \psi_1\\ \psi_2 \end{bmatrix} \otimes \begin{bmatrix} \phi_1\\ \phi_2 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1\\ 0\\ 0\\ 1 \end{bmatrix} = \begin{bmatrix} \psi_1\phi_1\\ \psi_1\phi_2\\ \psi_2\phi_1\\ \psi_2\phi_2 \end{bmatrix}$$

The system of equations is not solvable. Hence, the state  $|\Psi\rangle$  is entangled. This implies that it is impossible to obtain the individual states of Alice and Bob.

#### Definition

• The following two-qubit states are known as the Bell states. They represent an orthonormal, entangled basis for two qubits.

Bell states
$ \Phi^+\rangle = \frac{1}{\sqrt{2}}( 00\rangle +  11\rangle)$
$ \Phi^{-}\rangle = \frac{1}{\sqrt{2}}( 00\rangle -  11\rangle)$
$ \Psi^+\rangle = \frac{1}{\sqrt{2}}( 01\rangle +  10\rangle)$
$ \Psi^{-}\rangle = \frac{1}{\sqrt{2}}( 01\rangle -  10\rangle)$

Single-qubit gate.

$$\begin{array}{c} a|0\rangle+b|1\rangle & \hline U \\ \hline a'|0\rangle+b'|1\rangle \\ \hline \begin{bmatrix} a'\\b' \end{bmatrix} = U \begin{bmatrix} a\\b \end{bmatrix} \end{array}$$

#### Two-qubit gate.

# 

#### Technical Problems and Solutions (HOME)

#### Majority Vote HOME

• An election was held in a democratic nation to elect their next leader. The citizens of the nation voted for their favorite candidates. It is now time to find whether someone won the election. Winning the election means getting a majority of votes. Given a set of elements, an element is a majority in that set if that element occurs greater than 50% of the number of elements in that set. If there is no majority in an election, there will be a re-election and the process repeats until there is a majority. So, how do you find whether someone won an election? • Assumption: Equality comparison (A[i] = A[j]) between elements are allowed. Inequality comparisons  $(A[i] \le A[j] \text{ or } A[i] < A[j])$  between elements are not allowed.

- Input: Array of natural numbers Output: Majority if it exists, -1 if there is no majority
- Input: [3, 3, 4, 2, 4, 4, 2, 4, 4]Output: 4
- Input: [3, 3, 4, 2, 4, 4, 2, 4]Output: -1

# $\textbf{Solutions} \rightarrow \textbf{Brute force}$

- 1. Count occurrences of each element
- 2. Find the majority

```
\begin{array}{l} \hline \text{MAJORITY-BRUTEFORCE}(A[1 \dots n]) \\ \hline \text{Input: Array } A[1 \dots n] \text{ of natural numbers.} \\ \hline \text{Output: Majority element if it exists and } -1 \text{ otherwise.} \\ \hline \text{for } i \leftarrow 1 \text{ to } \lfloor n/2 \rfloor \text{ do} \\ \mid count \leftarrow \text{COUNTOCCURRENCES}(A[i \dots n], A[i]) \\ \mid \text{if } count > \lfloor n/2 \rfloor \text{ then} \\ \mid \text{ return } A[i] \\ \mid \text{ return } A[i] \\ \hline \text{return } -1 \end{array}
```

COUNTOCCURRENCES $(A[\ell \dots h], k)$ 

```
\begin{array}{c} count \leftarrow 0\\ \textbf{for } i \leftarrow \ell \textbf{ to } h \textbf{ do}\\ \mid \textbf{if } A[i] = k \textbf{ then}\\ \mid count \leftarrow count + 1\\ \textbf{return } count \end{array}
```

$$\langle \mathsf{Time, Space} \rangle = \left\langle \Theta\left(n^2\right), \Theta\left(1\right) \right\rangle$$

# $\textbf{Solutions} \rightarrow \textbf{Sorting}$

- 1. Sort the array
- 2. Count occurrences of each element
- 3. Find the majority

```
\begin{tabular}{|c|c|c|c|} \hline \textbf{MAJORITY-SORT}(A[1...n]) \\ \hline A[1...n] \leftarrow \textbf{SORT}(A[1...n]) \\ i \leftarrow 1 \\ \textbf{for } j \leftarrow 2 \textbf{ to } n \textbf{ do} \\ & | \textbf{ if } A[j] \neq A[i] \textbf{ then} \\ & | \textbf{ if } A[j] \neq A[i] \textbf{ then} \\ & | \textbf{ if } (j-i) > \lfloor n/2 \rfloor \textbf{ then} \\ & | \textbf{ if } (n-i+1) > \lfloor n/2 \rfloor \textbf{ then} \\ & | \textbf{ return } A[i] \\ & | \textbf{ return } -1 \\ \hline \end{tabular}
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n \log n), \Theta(n) \rangle$ 

# $\textbf{Solutions} \rightarrow \textbf{Divide-and-conquer}$

- 1. Split the array into two halves
- 2.  $\ell majority \leftarrow majority$  in the left half
- 3.  $rmajority \leftarrow$  majority in the right half
- 4. Check if  $\ell majority$  or rmajority is the array majority

```
MAJORITY-D&C(A[1 \dots n])
return D\&C(A[1...n])
D\&C(A[low...high])
if low = high then return A[low]
size \leftarrow (high - low + 1); mid \leftarrow |(low + high)/2|
\ell majority \leftarrow D\&C(A[low \dots mid])
rmajority \leftarrow D\&C(A[(mid + 1) \dots high])
\ell count \leftarrow COUNTOCCURRENCES(A[low ... high], \ell majority)
rcount \leftarrow COUNTOCCURRENCES(A[low...high], rmajority)
if \ell count > |size/2| then return \ell majority
if rcount > |size/2| then return rmajority
return -1
```

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta \left( n \log n \right), \Theta \left( \log n \right) \rangle$$

- 1. Store  $\langle unique element, frequency \rangle$  pairs in hash map
- 2. Find majority

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(n) \rangle$$

- 1. Find the median element
- 2. Check if the median is the majority

```
\begin{array}{l} \text{MAJORITY-MEDIAN}(A[1 \dots n]) \\ \hline median \leftarrow \text{SELECTION}(A[1 \dots n], \lfloor n/2 \rfloor) \\ count \leftarrow \text{COUNTOCCURRENCES}(A[1 \dots n], median) \\ \text{if } count > \lfloor n/2 \rfloor \text{ then} \\ \mid \text{ return } median \\ \text{return } -1 \end{array}
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(1) \rangle$ 

- 1. Select a random element and check if it is majority
- 2. Repeat Step 1 for at most  $\left|\log_2 \frac{1}{\epsilon}\right|$  number of times
- 3. Return majority

 $\begin{array}{c|c} \text{MAJORITY-PROBABILISTIC}(A[1 \dots n]) \\ \hline \text{for } i \leftarrow 1 \text{ to } \left\lfloor \log_2 \frac{1}{\epsilon} \right\rfloor \text{ do} \\ & \left\lceil random \leftarrow \text{RANDOM}(A[1 \dots n]) \\ count \leftarrow \text{COUNTOCCURRENCES}(A[1 \dots n], random) \\ & \text{if } count > \lfloor n/2 \rfloor \text{ then} \\ & \left| \text{ return } random \\ & \text{return } -1 \end{array} \right. \end{array}$ 

$$\left< \mathsf{Time, Space} \right> = \left< \Theta\left(n\log rac{1}{\epsilon}\right), \Theta\left(1
ight) \right>$$



Remove two unequal elements from A to get B

If A has a majority M, then B also has majority M

If B has a majority M, then A need not have majority M

## Solutions $\rightarrow$ BoyerMoore-Multipass

1. If a pair is different, then discard

If a pair is same, then keep one copy

- 2. Repeat step 1 until only one element if left
- 3. If array has majority, then final element is majority

If array has no majority, then final element has no meaning



Final element is the majority

Final element has no meaning

## Solutions $\rightarrow$ BoyerMoore-Multipass

```
MAJORITY-BOYERMOORE-MULTIPASS(A[1...n])
MAJORITY-MULTIPASS(A[1...n], -1)
MAJORITY-MULTIPASS(A[1...n], tiebreaker)
Create a dynamic array B \leftarrow []
for i \leftarrow 1 to n-1 increment 2 do
  if A[i] = A[i+1] then
     B.\mathsf{Add}(A[i])
if n \mod 2 = 1 then tiebreaker \leftarrow A[n]
if B is empty then C \leftarrow tiebreaker
else C \leftarrow MAJORITY-MULTIPASS(B, tiebreaker)
if C = -1 then return -1
count \leftarrow COUNTOCCURRENCES(A[1...n], C)
if count > \lfloor n/2 \rfloor or (count = \lfloor n/2 \rfloor and C = tiebreaker) then
  return C
return -1
```

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(n) \rangle$$

#### $\textbf{Solutions} \rightarrow \textbf{BoyerMoore-Multipass}$



- 1. Create a stack. Scan the elements one at a time.
- 2. If stack is empty or if element considered is the same as stack top, then push element. Else, pop an element from stack.
- 3. If stack is non-empty, check if stack top is the majority element. Else, return -1.

#### Solutions $\rightarrow$ BoyerMoore-Twopass

```
MAJORITY-BOYERMOORE-TWOPASS(A[1...n])
// Stage 1. Eliminate all except one candidate C
Create a stack S
for i \leftarrow 1 to n do
  if S is empty then S.Push(A[i])
  else
     top \leftarrow S.\mathsf{Top}()
     if A[i] = top then S.Push(A[i])
     else S.Pop()
// Stage 2. Check whether C is the majority
if S is empty then return -1
C \leftarrow S.\mathsf{Top}()
count \leftarrow COUNTOCCURRENCES(A[1...n], C)
if count > |n/2| then return C
return -1
```

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \mathcal{O}(n) \rangle$$

## Solutions $\rightarrow$ BoyerMoore-Twopass

i	A[i]	S
1	a	[a]
2	a	[a,a]
3	a	[a, a, a]
4	b	[a,a]
5	b	[a]
6	b	$\phi$
7	b	[b]

i	A[i]	S
1	a	[a]
2	b	$\phi$
3	a	[a]
4	b	$\phi$
5	a	[a]
6	b	$\phi$
$\overline{7}$	c	[c]

i	A[i]	S
1	a	[a]
2	b	$\phi$
3	a	[a]
4	b	$\phi$
5	a	[a]
6	b	$\phi$

- 1. Let C be majority candidate; m be #unpaired occurrences of C
- 2. In iteration 1, we set  $C \leftarrow 1$ st element and  $m \leftarrow 1$
- 3. In iteration  $i \in [2, n]$ , if m is zero, then set  $C \leftarrow i$ th element and  $m \leftarrow 1$ . Otherwise, compare if *i*th element is same as C. If same, then increment m, else, decrement m.
- 4. If m is positive, then check if C is majority

#### Solutions $\rightarrow$ BoyerMoore-Twopass-Inplace

```
MAJORITY-BOYERMOORE-TWOPASS-INPLACE(A[1...n])
C \leftarrow A[1]; m \leftarrow 1
// Stage 1. Eliminate all except one candidate c
for i \leftarrow 2 to n do
  if m = 0 then
  | \{ C \leftarrow A[i]; m \leftarrow 1 \}
  else
     if C = A[i] then m \leftarrow m + 1
     else m \leftarrow m - 1
// Stage 2. Check whether c is the majority
if m \neq 0 then
  count \leftarrow COUNTOCCURRENCES(A[1...n], C)
  if count > |n/2| then return C
return -1
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(1) \rangle$ 

### $\textbf{Solutions} \rightarrow \textbf{BoyerMoore-Twopass-Inplace}$

- 1. Let C be majority candidate; m be  $\# {\sf unpaired}$  occurrences of C
- 2. In iteration 1, we set  $C \leftarrow \mathsf{1st}$  element and  $m \leftarrow 1$
- 3. In iteration  $i \in [2, n]$ , if m is zero, then set  $C \leftarrow i$ th element and  $m \leftarrow 1$ . Otherwise, compare if *i*th element is same as C. If same, then increment m, else, decrement m.
- 4. If m is positive, then check if C is majority

i	A[i]	C	m
1	a	a	1
2	a	a	2
3	a	a	3
4	b	b	2
5	b	b	1
6	b	b	0
7	b	b	1

i	A[i]	C	m
1	a	a	1
2	b	a	0
3	a	a	1
4	b	a	0
5	a	a	1
6	b	a	0
7	c	c	1

i	A[i]	C	m
1	a	a	1
2	b	a	0
3	a	a	1
4	b	a	0
5	a	a	1
6	b	a	0

# $\textbf{Solutions} \rightarrow \textbf{FischerSalzberg}$

```
MAJORITY-FISCHERSALZBERG(A[1...n])
// Stage 1. Find the majority candidate C
Create two stacks S_1 and S_2
for i \leftarrow 1 to n do
  if S_1 is empty or S_1.Top() \neq A[i] then
     S_1.Push(A[i]) if S_2 is not empty then S_1.Push(S_2.Pop())
  else S_2.Push(A[i])
C \leftarrow S_1.\mathsf{Top}()
// Stage 2. Confirm if the candidate is the majority
while S_1 is not empty do
  item \leftarrow S_1.\mathsf{Pop}()
  if item = C then
     if S_1 is empty then S_2.Push(C)
     else S_1.Pop()
  else
     if S_2 is empty then return -1
     else S_2.Pop()
if S_2 is not empty then return C
return -1
```

 $\left<\mathsf{Time, Space}\right> = \left<\Theta\left(n\right), \Theta\left(n\right)\right>$ 

## Solutions $\rightarrow$ FischerSalzberg

i	A[i]	$S_1$	$S_2$
1	a	[a]	$\phi$
2	a	[a]	[a]
3	a	[a]	[a,a]
4	b	[a,b,a]	[a]
5	b	$\left[a,b,a,b,a\right]$	$\phi$
6	b	$\left[a,b,a,b,a,b\right]$	$\phi$
7	b	$\left[a,b,a,b,a,b\right]$	[b]
		[a,b,a,b]	[b]
		[a,b]	[b]
		$\phi$	[b]

i	A[i]	$S_1$	$S_2$
1	a	[a]	$\phi$
2	b	[a, b]	$\phi$
3	a	[a, b, a]	$\phi$
4	b	[a,b,a,b]	$\phi$
5	a	$\left[a,b,a,b,a\right]$	$\phi$
6	b	$\left[a,b,a,b,a,b\right]$	$\phi$
7	c	$\left[a,b,a,b,a,b,c\right]$	$\phi$
		$\left[a,b,a,b,a ight]$	$\phi$
		[a,b,a,b]	$\phi$

i	A[i]	$S_1$	$S_2$
1	a	[a]	$\phi$
2	b	[a,b]	$\phi$
3	a	[a,b,a]	$\phi$
4	b	$\left[ a,b,a,b ight]$	$\phi$
5	a	$\left[a,b,a,b,a\right]$	$\phi$
6	b	$\left[a,b,a,b,a,b\right]$	$\phi$
		[a,b,a,b]	$\phi$
		[a, b]	$\phi$
		$\phi$	$\phi$

Algorithm	Time	Extra Space	Comments
Brute force	$\Theta\left(n^2\right)$	$\Theta(1)$	-
Sorting-based	$\Theta\left(n\log n\right)$	$\Theta\left(n ight)$	Can't solve.
Divide-and-conquer	$\Theta\left(n\log n\right)$	$\Theta(\log n)$	_
Probabilistic	$\Theta\left(n\log\frac{1}{\epsilon}\right)$	$\Theta(1)$	Can't solve. Success $> 1 - \epsilon$ .
Hashing-based	$\Theta(n)$	$\Theta\left(n ight)$	Can't solve.
Median-based	$\Theta(n)$	$\Theta(n)$	Can't solve.
BoyerMoore multipass	$\Theta(n)$	$\Theta(n)$	_
BoyerMoore twopass	$\Theta(n)$	$\mathcal{O}\left(n ight)$	_
BoyerMoore twopass inplace	$\Theta(n)$	$\Theta(1)$	_
FischerSalzberg	$\Theta(n)$	$\Theta(n)$	-

• Puzzle book

### Longest Palindromic Substring (HOME)

#### Problem

- Design an algorithm to compute a longest palindromic substring of a string.
- Input: s = bababaeabaedOutput: s[4, 10] = abaeaba

• oddp[i] = largest radius of odd-sized palindrome centered at index i s[i]oddp[i]  $\overbrace{\cdots \ a \ t \ v \ k \ z \ d \ z \ k \ v \ t \ x \ \cdots}$ 

• evenp[i] =largest radius of even-sized palindrome centered at indices i and i + 1

s[i]	 a	t	v	k	z	z	k	v	t	x	• • •
evenp[i]					4						

• Longest odd-length palindrome whose center is at index i is  $s[(i-oddp[i])\ldots(i+oddp[i])]$ 

• Longest even-length palindrome whose left center is at index i is  $s[(i-evenp[i]+1)\dots(i+evenp[i])]$
Compute  $oddp[1 \dots n]$  and  $evenp[1 \dots n]$ 

Computing the LPS from  $oddp[1 \dots n]$  and  $evenp[1 \dots n]$  is easy

# $\textbf{Solutions} \rightarrow \textbf{Brute force algorithm}$

- 1. Find all substrings
- 2. Check which of these substrings are palindromes
- 3. If palindromes, update oddp and evenp arrays accordingly

```
BRUTEFORCE(s[1 \dots n])
Create arrays oddp[1 \dots n] \leftarrow [0 \dots 0] and evenp[1 \dots n] \leftarrow [0 \dots 0]
for i \leftarrow 1 to n do
   for j \leftarrow i to n do
      if ISPALINDROME(s[i \dots j]) then
          length \leftarrow j - i + 1
                                                                   // palindrome length
         radius \leftarrow \left|\frac{length}{2}\right|
                                                                   // palindrome radius
        center \leftarrow \left| \frac{i+j}{2} \right|
                                                                   // palindrome center
         if length is odd then
             oddp[center] \leftarrow Max(oddp[center], radius)
          else
             evenp[center] \leftarrow Max(evenp[center], radius)
```

return (oddp, evenp)

$$\langle \mathsf{Time, Space} \rangle = \left\langle \mathcal{O}\left(n^3\right), \Theta\left(n\right) \right\rangle$$

## Solutions $\rightarrow$ Standard algorithm

```
STANDARDALGORITHM(s[1...n])
Create arrays oddp[1 \dots n] \leftarrow [0 \dots 0] and evenp[1 \dots n] \leftarrow [0 \dots 0]
// For each palindrome center i, compute oddp[i]
for i \leftarrow 1 to n do
   \ell \leftarrow i - oddp[i] - 1
  r \leftarrow i + oddp[i] + 1
  while \ell \geq 1 and r \leq n and s[\ell] = s[r] do
     oddp[i] \leftarrow oddp[i] + 1
      \ell \leftarrow \ell - 1
      r \leftarrow r + 1
// For each palindrome center i, compute evenp[i]
for i \leftarrow 1 to n do
   \ell \leftarrow i - evenp[i]
  r \leftarrow i + evenp[i] + 1
   while \ell > 1 and r < n and s[\ell] = s[r] do
     evenp[i] \leftarrow evenp[i] + 1
      \ell \leftarrow \ell - 1
       r \leftarrow r+1
return (oddp, evenp)
```

$$\langle \mathsf{Time, Space} 
angle = \left\langle \mathcal{O}\left(n^2\right), \Theta\left(n\right) 
ight
angle$$

# Solutions $\rightarrow$ Rabin-Karp + Binary search

```
BINARYSEARCH(s[1...n])
```

```
low \leftarrow 1; high \leftarrow n
longest palindrome \leftarrow empty string
while low < high do
  mid \leftarrow \left| \frac{high-low}{2} \right|
  palindrome \leftarrow FINDPALINDROME(s, mid)
   // There is no palindrome with size mid as it is too big
   // So check for palindromes with smaller sizes
  if palindrome is an empty string then
     high \leftarrow mid - 1
   // There is a palindrome with size mid, maybe it is too small
   // So check for palindromes with larger sizes
  else
     longest palindrome \leftarrow palindrome
     low \leftarrow mid + 1
return longestpalindrome
```

$$\begin{split} \langle \mathsf{Time, Space} \rangle &= \langle \Theta \left( n \cdot \log n \right) \mathsf{w.h.p}, \Theta \left( 1 \right) \rangle \\ \langle \mathsf{Time, Space} \rangle &= \left\langle \mathcal{O} \left( n^2 \log n \right), \Theta \left( 1 \right) \right\rangle \end{split}$$

## Solutions $\rightarrow$ Rabin-Karp + Binary search

FINDPALINDROME( $s[1 \dots n], m$ ) // Step 1: Initialize parameters and variables  $p \leftarrow \mathsf{RandomLargePrime}([1 \dots nm^2])$  $b \leftarrow Size of ASCII set$  $h \leftarrow b^{(m-1)} \mod p, r \leftarrow \text{Reverse of string } s$  $hash1 \leftarrow HASH(s[1 \dots m], b, p)$  $hash2 \leftarrow HASH(r[n-m+1...n], b, p)$ // Step 2: Create a rolling hash for substrings of size m for  $i \leftarrow 1$  to (n - m + 1) do  $i \leftarrow n - m - i + 2$ // index of substring in r// Probability of hash collision is less than 1/nif hash1 = hash2 and s[i...(i + m - 1)] = r[j...(j + m - 1)] then return  $s[i \dots (i+m-1)]$ // Rolling hash: Compute hash value of the next text window using the current text window in  $\Theta(1)$  time if  $i \neq (n - m + 1)$  then  $hash1 \leftarrow \text{ROLLINGHASH-LTOR}(hash1, s[i] \times h, s[i+m], b, p)$  $hash2 \leftarrow \text{RollingHash-Rtol}(hash2, r[j+m-1], r[i-1] \times h, b, p)$ return empty string

ROLLINGHASH-LTOR(hash, subtract, add, b, p)

 $hash \leftarrow ((hash - subtract) \times b + add) \mod p$ return hash

ROLLINGHASH-RTOL(hash, subtract, add, b, p)

 $hash \leftarrow \left((hash - subtract) \times b^{-1} + add\right) \mod p$ return hash

$$\mathsf{Time} = \Theta\left(1\right)$$

 $b^{-1}$  is modulo multiplicative inverse of b

 $b^{-1}$  always exists if the modulus is w.r.t a prime

 $b^{-1}$  can be computed using extended Euclidean algorithm More information: Modulo multiplicative inverse

- $\bullet$  This algorithm is an optimization over  $\mathcal{O}\left(n^2\right)$  algorithm
- Instead of computing oddp[i] and evenp[i] from scratch at every value of i, we reuse the already computed values to reduce computations

indices s[i]positions oddp[i]

1	2	3	4	5	6	7	8	9	10	11	12
b	a	b	a	b	a	e	a	b	a	e	d
			L	j				i	R		
0	1	2	2	1	0	3	0				

- Suppose we have  $oddp[1 \dots 8]$ ; we want to compute oddp[9]
- Let  $s[L \dots R] =$  palindromic substring that ends as far to the right as possible so far
- For i = 9,  $s[L \dots R] = s[4 \dots 10] = abaeaba$  with center at 7
- There are two scenarios to consider:
  - $i \geq R$ : Use the standard algorithm logic to compute oddp[i]
  - i < R: Use oddp[mirror image of i] to compute oddp[i]

indices s[i] positions oddp[i]

1	2	3	4	5	6	7	8	9	10	11	12
b	a	b	a	b	a	e	a	b	a	e	d
			L	j				i	R		
0	1	2	2	1	0	3	0				

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- There are two scenarios to consider:
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  - i < R: Use oddp[mirror image of i] to compute oddp[i]

When i < R, the mirror image of i is j = (L + R - i)

with respect to the center of  $s[L \dots R]$ .

Case 1. 
$$i \ge R$$

indices s[i]positions oddp[i]

1	2	3	4	5	6	7	8	9	10	11	12
b	a	e	a	b	a	e	a	c	a	e	a
				j	L		R	i			
0	0	2	0	4	0	1	0				

In this case, compute oddp[i] using standard algorithm logic

Case 1. 
$$i \ge R$$

indices s[i]positions oddp[i]

1	2	3	4	5	6	7	8	9	10	11	12
b	a	e	a	b	a	e	a	c	a	e	a
				j	L		R	i			
0	0	2	0	4	0	1	0				

In this case, compute oddp[i] using standard algorithm logic

- $i \ge R$ , i.e.,  $9 \ge 8$
- Therefore, we compute oddp[9] as per standard algorithm logic
- We have oddp[9] = 3. We do not save any computations



In this case, set oddp[i] to oddp[j], and extend oddp[i]



In this case, set oddp[i] to oddp[j], and extend oddp[i]

- i < R, i.e., 9 < 10
- s[j oddp[j], j + oddp[j]] is inside  $s[L \dots R]$ , i.e.,  $s[4 \dots 6]$  is inside  $s[4 \dots 10]$
- Therefore, set oddp[9] to oddp[5], i.e., oddp[9] = 1, and extend oddp[9] as per standard algorithm logic
- We have oddp[9] = 2. We save one computation



In this case, set oddp[i] to (R-i), and extend oddp[i]



In this case, set oddp[i] to (R-i), and extend oddp[i]

- i < R, i.e., 9 < 10
- s[j − oddp[j], j + oddp[j]] is not inside s[L...R], i.e., s[1...9] is not completely inside s[4...10]
- Therefore, set oddp[9] to (R i) = (j L), i.e., oddp[9] = 1, and extend oddp[9] as per standard algorithm logic
- We have oddp[9] = 1. We save one computation

```
MANACHERODD(s[1...n])
Create array oddp[1 \dots n] \leftarrow [0 \dots 0]
L \leftarrow 1
R \leftarrow -1
for i \leftarrow 1 to n do
   if i < R then
      oddp[i] \leftarrow \mathsf{Min}(oddp[L+R-i], R-i)
   \ell \leftarrow i - oddp[i] - 1
   r \leftarrow i + oddp[i] + 1
   while \ell \geq 1 and r \leq n and s[\ell] = s[r] do
      oddp[i] \leftarrow oddp[i] + 1
      \ell \leftarrow \ell - 1
      r \leftarrow r+1
   if i + oddp[i] > R then
       L \leftarrow i - oddp[i]
       R \leftarrow i + oddp[i]
return oddp
```

$$\left< \mathsf{Time, Space} \right> = \left< \Theta\left(n
ight), \Theta\left(n
ight> 
ight>$$

```
MANACHEREVEN(s[1 \dots n])
Create array evenp[1...n] \leftarrow [0...0]
L \leftarrow 1
R \leftarrow -1
for i \leftarrow 1 to n do
   if i < R then
      evenp[i] \leftarrow \mathsf{Min}(evenp[L+R-i], R-i)
   \ell \leftarrow i - evenp[i]
   r \leftarrow i + evenp[i] + 1
   while \ell \geq 1 and r \leq n and s[\ell] = s[r] do
      evenp[i] \leftarrow evenp[i] + 1
      \ell \leftarrow \ell - 1
      r \leftarrow r+1
   if i + evenp[i] > R then
      L \leftarrow i - evenp[i] + 1
      R \leftarrow i + evenp[i]
return evenP
```

$$\left< \mathsf{Time, Space} \right> = \left< \Theta\left(n
ight), \Theta\left(n
ight> 
ight>$$

Algorithm	Time	Space	All pal. substr?
Brute force	$\mathcal{O}\left(n^3 ight)$	$\Theta(n)$	✓
Standard algo	$\mathcal{O}\left(n^{2} ight)$	$\Theta\left(n ight)$	1
Rabin-Karp+bin. search	$\mathcal{O}\left(n\log n ight)$ w.h.p	$\Theta(1)$	×
	$\mathcal{O}\left(n^2\log n\right)$	$\Theta(1)$	×
Manacher	$\Theta\left(n ight)$	$\Theta\left(n ight)$	1
Suffix trees	$\Theta\left(n ight)$	$\Theta\left(n ight)$	1

#### Selection Two Sorted Arrays HOME

- Find the kth smallest element among two sorted arrays  $A[1 \dots m]$  and  $B[1 \dots n]$ , where  $k \in [1, (m + n)]$ .
- Input: [10, 30, 40, 60, 70, 80, 100], [20, 50, 90, 110], and k = 9Output: 90
- Input: [10, 30, 40, 60, 70, 80, 100], [20, 50, 90, 110], and k = 4Output: 40

- 1. Concatenate the two arrays and sort it
- 2. Return the kth smallest element

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta\left((m+n)\log(m+n)\right), \Theta\left(m+n\right) \rangle$ 

## Solutions $\rightarrow$ Concatenate and heapify

- 1. Concatenate the two arrays and build a heap
- 2. Return the kth smallest element

SELECTION-CONCATENATE&HEAPIFY(A[1...m], B[1...n], k) Create a heap H[1...(m+n)]  $H[1...m] \leftarrow A[1...m]$  // Copy the first array to H  $H[(m+1)...(m+n)] \leftarrow B[1...n]$  // Copy the second array to HHEAPIFY(H[1...(m+n)]) // Construct heap from H in linear time // RemoveMin from H for a total of k times for  $i \leftarrow 1$  to k do | result  $\leftarrow H$ .RemoveMin() return result

 $\left< \mathsf{Time, Space} \right> = \left< \Theta \left( \left( m + n \right) + k \log(m + n) \right), \Theta \left( m + n \right) \right>$ 

# $\textbf{Solutions} \rightarrow \textbf{Merge}$

1. Merge the two sorted arrays

2. Return the kth smallest element

```
SELECTION-MERGE(A[1 \dots m], B[1 \dots n], k)
i \leftarrow 1; j \leftarrow 1; \ell \leftarrow 1
Create an array M[1 \dots (m+n)]
// Merge the two sorted arrays to M until an array becomes empty
while i < m and j < n do
   if A[i] \leq B[j] then \{ M[\ell] \leftarrow A[i]; i \leftarrow i+1 \}
   else { M[\ell] \leftarrow B[j]; j \leftarrow j+1 }
  \ell \leftarrow \ell + 1
// Copy the remaining elements to M
if i > m then M[\ell \dots (m+n)] \leftarrow B[j \dots n]
else if j > n then M[\ell \dots (m+n)] \leftarrow A[i \dots m]
// Return the kth smallest element of M
return M[k]
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(m+n), \Theta(m+n) \rangle$ 

# $\textbf{Solutions} \rightarrow \textbf{Merge optimized}$

1. Merge the two sorted arrays without using extra space to find the kth smallest element

```
SELECTION-MERGEOPTIMIZED(A[1 \dots m], B[1 \dots n], k)
i \leftarrow 1; j \leftarrow 1
// Iterate for k elements
while k > 0 do
   // If one of the arrays is reached
  if i > m then return B[j + k - 1]
  if j > n then return A[i + k - 1]
   // Merge-like operations
  if A[i] < B[j] then i \leftarrow i+1
  else if A[i] \ge B[j] then j \leftarrow j+1
  k \leftarrow k - 1
return \min(A[i], B[j])
```

```
\langle \mathsf{Time, Space} \rangle = \langle \Theta(k), \Theta(1) \rangle
```

- 1. Find the middle indices mid1 and mid2 of the two arrays
- 2. Compare mid1 + mid2 and k and compare A[mid1] and B[mid2]. Recursively call the algorithm on a smaller subproblem depending on the four cases.

#### Core idea

- Step 1. Select mid1 and mid2 of arrays A and B, respectively
- Step 2. We get 4 cases:
  - Case 1: mid1 + mid2 < k and A[mid1] > B[mid2]
  - Case 2: mid1 + mid2 < k and  $A[mid1] \leq B[mid2]$
  - Case 3:  $mid1 + mid2 \ge k$  and A[mid1] > B[mid2]
  - Case 4:  $mid1 + mid2 \ge k$  and  $A[mid1] \le B[mid2]$
- Step 3. Eliminate half of an array in each case and recurse

• Case 1: mid1 + mid2 < k and A[mid1] > B[mid2]



kth smallest can't be in the first half of the second array BEliminate the first half of the second array BFind and return (k - mid2)th smallest in the remaining elementsSELECTION-DE&C(A, B[(mid2 + 1) ... n], k - mid2)

• Case 2: mid1 + mid2 < k and  $A[mid1] \leq B[mid2]$ 



kth smallest can't be in the first half of the first array AEliminate the first half of the first array AFind and return (k - mid1)th smallest in the remaining elementsSELECTION-DE&C(A[(mid1 + 1) ... m], B, k - mid1)

• Case 3:  $mid1 + mid2 \ge k$  and A[mid1] > B[mid2]



kth smallest can't be in the second half of the first array AEliminate the second half of the first array AFind and return kth smallest in the remaining elementsSELECTION-DE&C(A[1...mid1], B, k)

• Case 4:  $mid1 + mid2 \ge k$  and  $A[mid1] \le B[mid2]$ 



kth smallest can't be in the second half of the second array BEliminate the second half of the second array BFind and return kth smallest in the remaining elementsSELECTION-DE& $C(A, B[1 \dots mid2], k)$ 

SELECTION-DE&C( $A[1 \dots m], B[1 \dots n], k$ ) // If an array is empty, return kth element of other array if m = 0 then return B[k]if n = 0 then return A[k]// Recursive case: Find the midpoint of each array  $mid1 \leftarrow \lfloor m/2 \rfloor; mid2 \leftarrow \lfloor n/2 \rfloor$ if mid1 + mid2 < k and A[mid1] > B[mid2] then // kth smallest can't be in the first half of the second array B return SELECTION-DE&C( $A, B[(mid2 + 1) \dots n], k - mid2$ ) else if mid1 + mid2 < k and  $A[mid1] \leq B[mid2]$  then // kth smallest can't be in the first half of the first array A return SELECTION-DE&C( $A[(mid1 + 1) \dots m], B, k - mid1$ ) else if  $mid1 + mid2 \ge k$  and A[mid1] > B[mid2] then // kth smallest can't be in the second half of the first array A return SELECTION-DE&C(A[1...mid1], B, k)else if mid1 + mid2 > k and A[mid1] < B[mid2] then // kth smallest can't be in the second half of the second array B return SELECTION-DE& $C(A, B[1 \dots mid2], k)$ 

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}\left(\log(m+n)\right), \mathcal{O}\left(\log(m+n)\right) \rangle$ 

- 1. Select index i in the first array A, where  $i = \min(m, \lfloor k/2 \rfloor)$
- 2. Select index j in the second array  $\boldsymbol{B},$  where j=k-i
- 3. Compare A[i] and B[j]
- 4. If A[i] > B[j], discard the first j elements of BFind the (k - j)th smallest element recursively
- 5. If  $A[i] \leq B[j]$ , discard the first i elements of AFind the (k - i)th smallest element recursively

Does index j always exist in array B? No!

Problem can be solved by considering the shorter array as A.

# Solutions $\rightarrow$ Binary search (recursive)

• Case 1:  $i + j \le k$  and A[i] > B[j]



kth smallest can't be in the first j elements of the second array B

Eliminate the first j elements of the second array BFind and return (k - j)th smallest in the remaining elements SELECTION-BINARYSEARCH(A, B[j + 1 ... n], k - j)

## Solutions $\rightarrow$ Binary search (recursive)

• Case 2:  $i + j \le k$  and  $A[i] \le B[j]$ 



kth smallest can't be in the first *i* elements of the first array *A* Eliminate the first *i* elements of the first array *A* Find and return (k - i)th smallest in the remaining elements SELECTION-BINARYSEARCH(A[i + 1...n], B, k - i)

# Solutions $\rightarrow$ Binary search (recursive)

SELECTION-BINARYSEARCH $(A[1 \dots m], B[1 \dots n], k)$ // First array should be the shorter of the two arrays if m > n then return Selection-BinarySearch(B[1...n], A[1...m], k)// If first array is empty, return the kth element of the second array if m = 0 then return B[k]// If k = 1, return the minimum of the first elements of the two arrays if k = 1 then return min(A[1], B[1])// Pick the number of elements that will be discarded in the two arrays  $i \leftarrow \min(m, \lfloor k/2 \rfloor); j \leftarrow k - i$ // If A[i] > B[j], then discard the first j elements of B if A[i] > B[j] then **return** SELECTION-BINARYSEARCH(A, B[j+1...n], k-j)// If  $A[i] \leq B[j]$ , then discard the first *i* elements of A else if  $A[i] \leq B[j]$  then return SELECTION-BINARYSEARCH(A[i+1...n], B, k-i)

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(\log k), \Theta(\log k) \rangle$ 

Algorithm	Time	Extra Space
Concatenate-sort	$\Theta\left((m+n)\log(m+n)\right)$	$\Theta\left(m+n ight)$
Concatenate-heapify	$\Theta\left((m+n)+k\log(m+n)\right)$	$\Theta\left(m+n\right)$
Merge	$\Theta\left(m+n\right)$	$\Theta\left(m+n\right)$
Merge optimized	$\Theta\left(k ight)$	$\Theta(1)$
De&C (recursive)	$\Theta\left(\log(m+n)\right)$	$\Theta\left(\log(m+n)\right)$
Binary search (recursive)	$\Theta\left(\log k ight)$	$\Theta\left(\log k\right)$
#### Largest Subarray Sum (HOME)

• Given an array of reals, find the subarray with the largest sum, and return its sum.

• Input: 
$$[-2, 1, -3, \underbrace{4, -1, 2, 1}_{, -5, 4}]$$
  
Output: 6

• Input: [5, 4, -1, 7, 8]Output: 23 BRUTEFORCE(A[1...n])

$$\begin{array}{c|c} max \leftarrow -\infty \\ \textbf{for } i \leftarrow 1 \ \textbf{to } n \ \textbf{do} \\ & & \\ \textbf{for } j \leftarrow i \ \textbf{to } n \ \textbf{do} \\ & & \\ & & \\ sum \leftarrow \text{Sum}(A[i \dots j]) \\ & & \\ & & \\ \textbf{if } sum > max \ \textbf{then} \ max \leftarrow sum \\ \textbf{return } max \end{array}$$

$$\left< \mathsf{Time, Space} \right> = \left< \Theta\left(n^3\right), \Theta\left(1\right) \right>$$

# Solutions $\rightarrow$ Optimized brute force

• For all subarrays, calculate the sum of the subarray as you travel the array.

```
      OPTIMIZEDBRUTEFORCE(A[1...n])

      max \leftarrow -\infty

      for i \leftarrow 1 to n do

      sum \leftarrow 0

      for j \leftarrow i to n do

      |sum \leftarrow sum + A[j]|

      |if sum > max then max \leftarrow sum

      return max
```

$$\left< \mathsf{Time, Space} \right> = \left< \Theta\left(n^2\right), \Theta\left(1
ight) \right>$$

### Solutions $\rightarrow$ Optimized brute force



# $\textbf{Solutions} \rightarrow \textbf{Divide-and-conquer}$

- 1. Divide the given array in two halves
- 2. Return the maximum of the following three:
  - (a) Max subarray sum in left half (recurse)
  - (b) Max subarray sum in right half (recurse)
  - $\left(c\right)\,$  Max subarray sum so that the subarray crosses the midpoint

#### DIVIDEANDCONQUER $(A[1 \dots n])$

```
\begin{split} & \text{if } n = 1 \text{ then return } A[1] \\ & mid \leftarrow \left\lfloor \frac{n}{2} \right\rfloor \\ & S_{\mathsf{left}} \leftarrow \mathsf{DIVIDEANDCONQUER}(A[1 \dots mid]) \\ & S_{\mathsf{right}} \leftarrow \mathsf{DIVIDEANDCONQUER}(A[mid + 1 \dots n]) \\ & S_{\mathsf{merge}} \leftarrow \mathsf{MERGE}(A[1 \dots n], mid) \\ & \mathsf{return } \mathsf{Max}(S_{\mathsf{left}}, S_{\mathsf{right}}, S_{\mathsf{merge}}) \end{split}
```

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta(n \log n), \Theta(\log n) \rangle$$

```
MERGE(A[1...n], mid)
// Find the maximum suffix in the first half
suffixmax \leftarrow -\infty; sum \leftarrow 0
for i \leftarrow mid to 1 do
  sum \leftarrow sum + A[i]
  if sum > suffixmax then suffixmax \leftarrow sum
// Find the maximum prefix in the second half
prefixmax \leftarrow -\infty; sum \leftarrow 0
for i \leftarrow mid + 1 to n do
  sum \leftarrow sum + A[i]
  if sum > prefixmax then prefixmax \leftarrow sum
// Max subarray sum so that subarray crosses the midpoint
return (suffixmax + prefixmax)
```

# $\textbf{Solutions} \rightarrow \textbf{Divide-and-conquer}$



suffixmax+prefixmax

# $\textbf{Solutions} \rightarrow \textbf{Improved divide-and-conquer}$

- 1. Create a class called Node for any subproblem (subarray)
- For any subproblem/subarray, we define a node with four values: sum = largest subarray sum, total = total subarray sum prefixmax = max prefix sum, suffixmax = max suffix sum
- 3. Compute and return the sum corresponding to the node of  $A[1 \dots n]$  using D&C

```
IMPROVEDDIVIDEANDCONQUER(A[1...n])
```

Node  $answer \leftarrow \text{GetMaxSumSubarray}(A[1...n])$ 

 $return \ answer.sum$ 

GetMaxSumSubarray $(A[low \dots high])$ 

if low = high then return NODE(A[low])  $mid \leftarrow \lfloor (low + high)/2 \rfloor$   $node_{\ell} \leftarrow GETMAXSUMSUBARRAY(A[low ... mid])$   $node_r \leftarrow GETMAXSUMSUBARRAY(A[mid + 1... high])$ return  $MERGE(node_{\ell}, node_r)$ 

```
\begin{array}{l} & \operatorname{Merge}(\ell, r) \\ & x \leftarrow \operatorname{NODE}(0) \\ & // \operatorname{Max} \operatorname{prefix} \operatorname{subarray} \operatorname{sum} \\ & x.prefixmax \leftarrow \operatorname{Max}(\ell.prefixmax, \ell.total + r.prefixmax, \ell.total + r.total) \\ & // \operatorname{Max} \operatorname{suffix} \operatorname{subarray} \operatorname{sum} \\ & x.suffixmax \leftarrow \operatorname{Max}(r.suffixmax, r.total + \ell.suffixmax, \ell.total + r.total) \\ & // \operatorname{Total} \operatorname{subarray} \operatorname{sum} \\ & x.total \leftarrow \ell.total + r.total \\ & // \operatorname{Max} \operatorname{subarray} \operatorname{sum} \\ & x.sum \leftarrow \operatorname{Max}(x.prefixmax, x.suffixmax, x.total, \ell.sum, r.sum \\ & \ell.suffixmax + r.prefixmax) \end{array}
```

return x

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(\log n) \rangle$ 



Node x for the entire array



Node x for the entire array



Node x for the entire array



# Solutions $\rightarrow$ Kadane's algorithm

- 1. Iterate through the array. For each number, add it to the sum we are building.
- 2. If sum is smaller than the element value, we know it isn't worth keeping, so throw it away.
- 3. Update max (max subarray sum) every time we find a new maximum.

```
KADANEALGORITHM(A[1 \dots n])max \leftarrow A[1]; sum \leftarrow A[1]for i \leftarrow 2 to n do// If sum is negative, throw it away. Otherwise, keep adding to it.sum \leftarrow Max(A[i], sum + A[i])max \leftarrow Max(max, sum)return max
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(1) \rangle$ 

## Solutions $\rightarrow$ Kadane's algorithm



Algorithm	Time	Space
Brute force	$\Theta\left(n^3\right)$	$\Theta(1)$
Optimized brute force	$\Theta\left(n^2\right)$	$\Theta(1)$
Divide-and-conquer	$\Theta\left(n\log n\right)$	$\Theta\left(\log n\right)$
Improved divide-and-conquer	$\Theta\left(n ight)$	$\Theta\left(\log n\right)$
Kadane's algorithm	$\Theta\left(n ight)$	$\Theta(1)$

# Loop in a Linked List (HOME)

# Problem

- You are given a singly linked list that may contain a loop. Your task is to detect the presence of a loop in the linked list, and if there exists a loop, then find the node where the loop begins (intersection node), and calculate the length of the cycle.
- Input: A singly linked list
- **Output:** The following information should be returned:
  - Detection of loop: True if a loop is detected, false otherwise.
  - Intersection node: If a loop is detected, return the node where the loop begins. If there is no loop, return null.
  - Length of the cycle: If a loop is detected, return the length of the cycle. If there is no loop, return 0.

# Problem



Output: (true, node 5, 5)

- Step 1. Create and initialize variables: *curr*: pointer to current node *prev*: pointer to the previous node *currd*: distance of the *curr* pointer from *head* (distance is measured in the number of nodes) *prevd*: distance of the *prev* pointer from *head*
- Step 2. Repeat until the end of SLL is reached or *currd* < *prevd* Move *curr* and *prev* pointers one node at a time Update *currd* and *prevd* distances
- Step 3. If curr reaches null, there is no loop
- Step 4. If currd < prevd, there is a loop with: Intersection node = curr Loop length = prevd - currd + 1

# Solutions $\rightarrow$ Storing length



```
// Step 1. Create and initialize variables
curr \leftarrow head; prev \leftarrow head; currd \leftarrow 1; prevd \leftarrow 0
// Step 2. Move curr and prev pointers by one unit until end of SLL is reached
    or curr pointer is at a smaller distance than that of prev pointer from head
while curr \neq null and currd > prevd do
  prev \leftarrow curr
                                                                 // previous pointer
  prevd \leftarrow currd
                                                    // distance to previous pointer
  curr \leftarrow curr next
                                                                  // current pointer
  currd \leftarrow \text{DISTANCE}(head, curr)
                                                    // distance to current pointer
 // Step 3. If curr = null, there is no loop
if curr = null then return (false, null, null)
// Step 4. If curr \neq null, there is a loop starting at node curr with a length
    of prevd - currd + 1
else return (true, curr, prevd - currd + 1)
```

#### Distance(first, last)

// Find the number of nodes between *first* and *last* pointers  $count \leftarrow 1$ ;  $current \leftarrow first$ while  $current \neq last$  do |  $count \leftarrow count + 1$ ;  $current \leftarrow current.next$ return count

$$\langle \mathsf{Time, Space} \rangle = \left\langle \mathcal{O}\left(n^2\right), \mathcal{O}\left(1\right) \right\rangle$$

# Solutions $\rightarrow$ Storing length



# Solutions $\rightarrow$ Storing length



- Use a hash map to keep track nodes visited.
- Iterate through the linked list to check if node is present in the hash map.
- If found, there exists a loop else add node and its position to the hash map.
- The intersection node is identified as the first node already present in the hash map.
- As we're already storing node positions {node number : position} in the hash map, the length of the loop equals the difference between the current node count and the value of the first repeated node in the hash map.

```
LOOPINALINKEDLIST(head)
Create a hash map H
count \leftarrow 0: curr \leftarrow head
// Traverse the singly linked list using the curr pointer
while curr \neq null do
   // If curr node exists in the hash map, there is a loop
  if H.Contains(curr) then
     looplength \leftarrow (count - H[curr])
     return (true, curr, looplength)
   // If curr node is visited for the first time, add it to the map
  H.Add(curr, count)
  count \leftarrow count + 1; curr \leftarrow curr.next
// If the end of the linked list is reached, there is no loop
return (false, null, null)
```

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(n) \,, \mathcal{O}(n) \rangle$ 

# Solutions $\rightarrow$ Hashing



# Solutions $\rightarrow$ Hashing



- Step 1. Use two pointers to scan the linked list: *tortoise*: slow pointer moves one node at a time *hare*: fast pointer moves two nodes at a time
- Step 2. Compare *tortoise* and *hare* each time
- Step 3. If the end of the list is reached, then there is no loop
- Step 4. If *tortoise* = *hare*, then there is a loop. Now compute:

looplength: count the list length starting from and ending at tortoise

*intersection*: start *tortoise* from *head* and *hare* from *looplength* distance from *head*; advance both pointers one node

at a time until they meet; this node is the intersection node

```
LOOPINALINKEDLIST(head)
// Step 1. tortoise and hare are slow and fast pointers, respectively
tortoise \leftarrow head: hare \leftarrow head
// Step 2. Scan the linked list and compare tortoise and hare
while hare \neq null and hare.next \neq null do
  tortoise \leftarrow tortoise.next
  hare \leftarrow hare.next.next
  if tortoise = hare then break
// Step 3. If end of list is reached, there is no loop
if hare = null or hare.next = null then
  return (false, null, null)
// Step 4. If tortoise = hare, there is a loop
looplength \leftarrow LOOPLENGTH(tortoise)
intersection \leftarrow \text{INTERSECTION}(head, looplength)
return (true, intersection, looplength)
```

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}\left(n\right), \mathcal{O}\left(1\right) \rangle$ 

```
LOOPLENGTH(curr)
```

```
\begin{array}{l} looplength \leftarrow 1; \ loop \leftarrow curr.next \\ \textbf{while} \ loop \neq curr \ \textbf{do} \\ | \ loop \leftarrow loop.next \\ | \ looplength \leftarrow looplength + 1 \end{array}
```

```
return \ looplength
```

INTERSECTION(head, looplength)

```
\begin{array}{l} \textit{tortoise} \leftarrow \textit{head}; \textit{hare} \leftarrow \textit{head} \\ \textit{// hare starts from looplength distance from head} \\ \textbf{while } \textit{looplength} > 0 \textit{ do} \\ \textit{hare} \leftarrow \textit{hare.next} \\ \textit{looplength} \leftarrow \textit{looplength} - 1 \\ \textit{// Advance both pointers and compare until match} \\ \textbf{while } \textit{tortoise} \neq \textit{hare do} \\ \textit{hare} \leftarrow \textit{hare.next} \\ \textit{tortoise} \leftarrow \textit{tortoise.next} \\ \textit{// Meeting node is the intersection node} \\ \textbf{return } \textit{tortoise} \end{array}
```

#### Solutions $\rightarrow$ Slow and fast pointers



#### Solutions $\rightarrow$ Slow and fast pointers



This algorithm is identical to the previous algorithm, except that

• We check in each of the two steps of *hare* if it meets *tortoise*, to avoid *hare* jumping the *tortoise* 

# Solutions $\rightarrow$ Slow and fast pointers alternative

```
LOOPINALINKEDLIST(head)
```

```
// Step 1. tortoise and hare are slow and fast pointers, respectively
tortoise \leftarrow head: hare \leftarrow head
// Step 2. Scan the linked list and compare tortoise and hare
while hare \neq null and hare.next \neq null do
  tortoise \leftarrow tortoise.next
  hare \leftarrow hare.next
  if tortoise = hare then break
  hare \leftarrow hare.next
  if tortoise = hare then break
 // Step 3. If the end of the list is reached, there is no loop
if hare = null or hare.next = null then
  return (false, null, null)
// Step 4. If tortoise = hare, there is a loop
looplength \leftarrow LOOPLENGTH(tortoise)
intersection \leftarrow \text{INTERSECTION}(head, looplength)
return (true, intersection, looplength)
```

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}\left(n
ight), \mathcal{O}\left(1
ight) \rangle$ 

- Step 1. Use two pointers to scan the linked list: *tortoise*: slow pointer transports directly to fast pointer position *hare*: fast pointer moves *steps* nodes at a time where, *steps* is initially 2
- Step 2. Compare *tortoise* and *hare* for each step of *hare* until *steps* Increase *steps* to  $\mathcal{F}(steps)$  (Brent used  $\mathcal{F}(x) = 2x$ ) *tortoise* transports directly to *hare* position
- Step 3. If the end of the list is reached, then there is no loop
- Step 4. If *tortoise* = *hare*, then there is a loop. Now compute *looplength* and *intersection* as before

# Solutions $\rightarrow$ Brent's algorithm

```
LOOPINALINKEDLIST(head)
// Step 1. tortoise and hare are slow and fast pointers, respectively
tortoise \leftarrow head; hare \leftarrow head; steps \leftarrow 1
// Step 2. Scan the linked list and compare tortoise and hare. Advance
    hare by \mathcal{F}(steps) at a time and tortoise to hare position.
while true do
  for i \leftarrow 1 to steps do
     if hare = null then break
     hare \leftarrow hare.next
     if hare = tortoise then break
  if hare = null or hare = tortoise then break
  tortoise \leftarrow hare
                                              // transport tortoise to hare
  steps \leftarrow \mathcal{F}(steps)
                                                             // update steps
// Step 3. If the end of the list is reached, there is no loop
if hare = null then return (false, null, null)
// Step 4. If hare = tortoise, there is a loop
looplength \leftarrow LOOPLENGTH(tortoise)
intersection \leftarrow \text{INTERSECTION}(head, looplength)
return (true, intersection, looplength)
```

 $\left<\mathsf{Time, Space}\right> = \left<\mathcal{O}\left(n\right), \mathcal{O}\left(1\right)\right>$
## Solutions $\rightarrow$ Brent's algorithm



## Solutions $\rightarrow$ Brent's algorithm



## Solutions $\rightarrow$ Brent's algorithm



Algorithm	Time	Extra space
Storing length	$\mathcal{O}\left(n^2\right)$	$\mathcal{O}\left(1 ight)$
Hashing	$\mathcal{O}\left(n ight)$	$\mathcal{O}\left(n ight)$
Slow-fast pointers	$\mathcal{O}\left(n ight)$	$\mathcal{O}\left(1 ight)$
Slow-fast pointers alternative	$\mathcal{O}\left(n ight)$	$\mathcal{O}\left(1 ight)$
Brent's algorithm	$\mathcal{O}\left(n ight)$	$\mathcal{O}\left(1 ight)$

# Y-shaped Linked List (HOME)

• There are two singly linked lists of sizes *m* and *n*, respectively. Due to some error, the two linked lists are connected in Y-shape. Design an efficient algorithm to determine the point of intersection of the two lists given their head nodes i.e., *head1* and *head2*.

# $\textbf{Solutions} \rightarrow \textbf{Brute force}$

- 1. Run two nested loops. One loop for list 1 and another for list 2.
- 2. If the two pointers match then that is the intersection node. Else return null.

```
YSHAPEDLINKEDLIST-BRUTEFORCE(head1, head2)
pointer1 \leftarrow head1
// Outer loop for nodes in list 1
while pointer1 \neq null do
  pointer2 \leftarrow head2
   // Inner loop for nodes in list 2
  while pointer2 \neq null do
      // First time the two pointers are the same is the intersection
     if pointer1 = pointer2 then
        return pointer1
     pointer2 \leftarrow pointer2.next()
  pointer1 \leftarrow pointer1.next()
return null
```

$$\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(mn), \Theta(1) \rangle$$

## Solutions $\rightarrow$ Two stacks

- 1. Store all nodes of list 1 in stack 1 and list 2 in stack 2  $\,$
- 2. Pop the same node pointers from both stacks until the pointers are different
- 3. The last same node reference is the intersecting node

YSHAPEDLINKEDLIST-TWOSTACKS(*head*1, *head*2)

```
Create two stacks S_1 and S_2

ptr1 \leftarrow head1; ptr2 \leftarrow head2; result \leftarrow null

// Store all nodes of list 1 in stack 1 and list 2 in stack 2

while ptr1 \neq null do { S_1.Push(ptr1); ptr1 \leftarrow ptr1.next }

while ptr2 \neq null do { S_2.Push(ptr2); ptr2 \leftarrow ptr2.next }

// If the two stack tops are different then there is no intersection

if S_1.Top() \neq S_2.Top() then return null
```

// Keep popping the same node references from the two stacks, the last node reference that is same is the intersection node while  $S_1$  is not empty and  $S_2$  is not empty and  $S_1.Top() = S_2.Top()$  do  $| \{ result \leftarrow S_1.Pop(); S_2.Pop() \}$ 

// Return the intersecting node return result

$$\left< \mathsf{Time, Space} \right> = \left< \Theta \left( m + n \right), \Theta \left( m + n \right) \right>$$

# $\textbf{Solutions} \rightarrow \textbf{Hashset}$

- 1. Store every node reference of list 1 in a hashset
- 2. Scan each node reference of list 2 and check if it exists in the hashset

```
YSHAPEDLINKEDLIST-HASHSET(head1, head2)
pointer1 \leftarrow head1; pointer2 \leftarrow head2
Create a hashset H to store node references
// Store every node reference of list 1 in a hashset
while pointer1 \neq null do
  H.Add(pointer1)
  pointer1 \leftarrow pointer1.next()
 // Scan each node pointer of list 2 and check if it exists in the hashset
while pointer2 \neq null do
  if H.ContainsKey(pointer2) then
     return pointer2
  pointer2 \leftarrow pointer2.next()
return null
```

$$\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(m+n), \Theta(m) \rangle$$

# $\textbf{Solutions} \rightarrow \textbf{Difference count}$

- 1. Find the difference diff in the lengths of the lists. This is the length of the bottom portion of Y.
- 2. Advance the pointer of the longer list by diff
- 3. Now move pointers of both longer and shorter one node at a time until there the intersection node is found. Else return null

YShapedLinkedList-DifferenceCount(head1, head2)

// Find the difference in the lengths of the lists. Determine which list is longer and set the longer and shorter lists accordingly

 $m \leftarrow \text{COMPUTELENGTH}(head1); n \leftarrow \text{COMPUTELENGTH}(head2)$ 

if m > n then  $\{ diff \leftarrow m - n; longer \leftarrow head1; shorter \leftarrow head2 \}$ 

else {  $diff \leftarrow n - m$ ;  $longer \leftarrow head2$ ;  $shorter \leftarrow head1$  }

// Advance the pointer of the longer list by the difference in lengths for  $i \leftarrow 1$  to diff do  $longer \leftarrow longer.next()$ 

// Iterate through both lists until the pointers meet at the merge point
while longer ≠ shorter do
| longer ← longer.next(); shorter ← shorter.next()
return longer

$$\left< \mathsf{Time, Space} \right> = \left< \Theta \left( m + n \right), \Theta \left( 1 \right) \right>$$

- 1. Traverse the first linked list, count the elements, and make a circular linked list. Remember the last node so that we can break the circle later on.
- 2. Transformed problem: Finding the loop in the second linked list.
- Since we already know the length of the loop (size of the first linked list), we can traverse those many nodes in the second list. Then, start another pointer from the beginning of the second list and traverse until they are equal, which is the required intersection point.
- 4. Remove the circular structure from the linked list.

# Solutions $\rightarrow$ Loop in a linked list

Length of the first list = length of the loop = 8 pointer1 (at  $C_3$ ) is 8 steps ahead of pointer2 (at  $B_1$ )



## Solutions $\rightarrow$ Loop in a linked list



# Solutions $\rightarrow$ Loop in a linked list

```
YSHAPEDLINKEDLIST-LOOPINALINKEDLIST(head1, head2)
pointer1 \leftarrow head1; pointer2 \leftarrow head2; lastnode \leftarrow null
// Traverse the first linked list and make it circular
length1 \leftarrow 0
while pointer1.next \neq null do
  pointer1 \leftarrow pointer1.next; length1 \leftarrow length1 + 1
lastnode \leftarrow pointer1; pointer1.next \leftarrow head1
// Set one of the pointers ahead
pointer1 \leftarrow head2
while length1 > 0 do
  pointer1 \leftarrow pointer1.next; length1 \leftarrow length1 - 1
// Traverse until they are equal, which is the intersection point
while pointer1 \neq pointer2 do
  pointer1 \leftarrow pointer1.next; pointer2 \leftarrow pointer2.next
// Remove the circular structure from the linked list
lastnode.next \leftarrow null
return pointer1
```

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta \left( m + n \right), \Theta \left( 1 \right) \rangle$$

Let

- $\boldsymbol{X} = \mathsf{length}$  of the first list until the intersection point
- Y = length of the second list until the intersection point
- Z = length from intersection node (inclusive) to the last node
- 1. Traverse the second list and find length  $L_2$
- 2. Traverse the first list and reverse it and find length  $L_1$
- 3. Traverse the new second list and find length  $L_3$
- 4. We have system of 3 equations and 3 unknowns. Solve:

$$X + Z = L_1;$$
  $Y + Z = L_2;$   $X + Y = L_3$ 

5. We get:

$$X = \frac{1}{2} \cdot (L_1 + L_3 - L_2); \qquad Y = \frac{1}{2} \cdot (L_2 + L_3 - L_1); \qquad Z = \frac{1}{2} \cdot (L_1 + L_2 - L_3)$$

- 6. Find the intersection node by traversing from the new second list by Y steps
- 7. Reverse the first linked list (if required)

#### Solutions $\rightarrow$ System of linear equations



#### Solutions $\rightarrow$ System of linear equations



## Solutions $\rightarrow$ System of linear equations

YSHAPEDLINKEDLIST-LINEAREQUATIONS(head1, head2) // Compute the length of the second and first linked lists  $L_1 \leftarrow \text{GetLinkedListLength}(head1)$  $L_2 \leftarrow \text{GetLinkedListLength}(head2)$ // Reverse first linked list and compute  $L_3$  $reversedhead1 \leftarrow \text{ReverseLinkedList}(head1)$  $L_3 \leftarrow \text{GetLinkedListLength}(head2)$ // Solve the equations for X, Y, and Z  $X = \frac{1}{2} \cdot (L_1 + L_3 - L_2); Y = \frac{1}{2} \cdot (L_2 + L_3 - L_1); Z = \frac{1}{2} \cdot (L_1 + L_2 - L_3)$ // Traverse the second linked list to the intersection point and return answer  $\leftarrow$  head2 for  $i \leftarrow 1$  to Y do answer  $\leftarrow$  answer.next // Restore first linked list by reversing it again  $head1 \leftarrow \text{ReverseLinkedList}(reversedhead1)$ return answer

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta(m+n), \Theta(1) \rangle$$

```
GETLINKEDLISTLENGTH(head)
L \leftarrow 0; pointer \leftarrow head
while pointer \neq null do
   L \leftarrow L + 1; pointer \leftarrow pointer.next
return L
REVERSELINKEDLIST(head)
current \leftarrow head; previous \leftarrow null; nextcurrent \leftarrow null
// Iterate through the list and reverse pointers
while current \neq null do
  next current \leftarrow current.next
  current.next \leftarrow previous
  previous \leftarrow current
  current \leftarrow next current
return previous
```

- 1. Scan list 1 using *pointer*1. Scan list 2 using *pointer*2.
- 2. If pointer1 reaches list 1 end, then start from list 2. If pointer2 reaches list 2 end, then start from list 1.
- 3. At any moment, when the two node references are same, it is the intersection node. Else, return *null*.

```
YSHAPEDLINKEDLIST-TWOPOINTERS(head1, head2)
pointer1 \leftarrow head1; pointer2 \leftarrow head2
// If one of the lists is empty, then there is no intersection node
if pointer1 = null or pointer = null then return null
// Traverse the lists until the intersection node is found
while pointer1 \neq pointer2 do
  pointer1 \leftarrow pointer1.next(); pointer2 \leftarrow pointer2.next()
  if pointer1 = pointer2 then return pointer1
   // If a pointer reaches its list end, then start from other list
  if pointer1 = null then pointer1 \leftarrow head2
  if pointer2 = null then pointer2 \leftarrow head1
return pointer1
```

$$\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}\left(m+n\right), \Theta\left(1\right) \rangle$$







Algorithm	Time	Extra Space
Brute force	$\mathcal{O}\left(mn ight)$	$\Theta(1)$
Two stacks	$\Theta\left(m+n\right)$	$\Theta\left(m+n\right)$
Hashset	$\mathcal{O}\left(m+n\right)$	$\Theta\left(m ight)$
Difference count	$\Theta\left(m+n\right)$	$\Theta(1)$
Loop in a linked list	$\Theta\left(m+n\right)$	$\Theta(1)$
Linear equations	$\Theta\left(m+n\right)$	$\Theta(1)$
Two pointers	$\mathcal{O}\left(m+n\right)$	$\Theta(1)$

#### Search Sorted Matrix (HOME)

- Search if an element k exists in a  $m\times n$  sorted matrix  $A[1\ldots m,1\ldots n].$
- If the element k exists, then return the location (i.e., row and column) of one cell whose value is k
- Input: Sorted matrix A of size  $m \times n$ Output: Location where k exists, -1 otherwise.

SearchInSortedMatrix $(A[1 \dots m, 1 \dots n], k)$ 

```
 \begin{array}{c|c} \text{for } i \leftarrow 1 \text{ to } m \text{ do} \\ | & \text{for } j \leftarrow 1 \text{ to } n \text{ do} \\ | & \text{if } A[i,j] = k \text{ then} \\ | & | & \text{return } (i,j) \\ \text{return } -1 \end{array}
```

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}\left(mn\right), \Theta\left(1\right) \rangle$ 

#### Core idea

- Step 1. Select the mid element
- Step 2. We get 3 cases:
  - Case 0: mid element = k
  - Case 1: mid element > k
  - Case 2: mid element < k
- Step 3. Eliminate a quadrant in Cases 1 and 2 and recurse

# $\textbf{Solutions} \rightarrow \textbf{D\&C}$

• Case 1: mid element > kSuppose mid element = 50 and k = 30



k can't be in quadrant IV Search for k in quadrants I, II, and III

# $\textbf{Solutions} \rightarrow \textbf{D\&C}$

• Case 2: mid element < kSuppose mid element = 50 and k = 70



k can't be in quadrant I Search for k in quadrants II, III, and IV

# Solutions $\rightarrow$ D&C

SEARCHINSORTEDMATRIX $(A[1 \dots m, 1 \dots n], k)$ return  $D\&C(A[1 \dots m, 1 \dots n], k)$  $D\&C(A[r_{\ell}\ldots r_{h}, c_{\ell}\ldots c_{h}], k)$ if  $r_{\ell} > r_h$  or  $c_{\ell} > c_h$  then return -1 $r_m \leftarrow (r_\ell + r_h)/2; c_m \leftarrow (c_\ell + c_h)/2$ if  $A[r_m, c_m] = k$  then return  $(r_m, c_m)$ // In this case, element is definitely not in the fourth quadrant else if  $A[r_m, c_m] > k$  then return  $D\&C(A[r_{\ell}...r_m-1,c_{\ell}...c_m-1],k)$  or // first quadrant  $D\&C(A[r_{\ell}...r_{m-1}, c_m...c_h], k)$  or // second quadrant  $D\&C(A[r_m ..., r_h, c_{\ell} ..., c_m - 1], k)$  or // third guadrant // In this case, element is definitely not in the first quadrant else if  $A[r_m, c_m] < k$  then return  $D\&C(A[r_{\ell}...r_{m}, c_{m} + 1...c_{h}], k)$  or // second guadrant  $D\&C(A[r_{m+1}...r_h, c_{\ell}...c_m], k)$  or // third quadrant  $D\&C(A[r_m + 1...r_h, c_m + 1...c_h], k)$  or // fourth quadrant  $\langle \mathsf{Time, Space} \rangle = \left\langle \mathcal{O}\left(\min(m, n)^{\log_2 3}\right), \mathcal{O}\left(\log\max(m, n)\right) \right\rangle$ 

#### Core idea

- Step 1. Select the mid-row
- Step 2. Do a binary search in the mid-row for the largest index *index* such that the array element at that index is not greater than k
- Step 3. We get 3 cases:
  - Case 1: there is no such index
  - Case 2: element (at index) = k
  - Case 3: element (at index) < k
- Step 4. Do the following:
  - Case 1: search the upper rectangle recursively
  - Case 2: return the location
  - Case 3: search the second and third regions recursively

In Cases 1 and 3, we eliminate at least half of the elements

# Solutions $\rightarrow$ D&C improved

• Case 1: there is no index

i.e., suppose the first element in the mid row is  $70,\,$  which is greater than k=50



k can't be in the lower half Search for k in the upper half Area of lower half is > 50%

# Solutions $\rightarrow$ D&C improved

• Case 3: element < k

Suppose element = 30, next element = 70, and k = 50



 $\frac{k}{k}$  can't be in regions I and IV Search for k in regions II and III

Combined area of regions I and IV is >50%

k = 10

Binary search row

1	4	7	11	15
2	5	8	12	19
3	6	9	16	22
10	13	14	17	24
11	21	23	26	30

k not found, 9 is max element < k, 16 is min element > k

1	4	7	11	15
2	5	8	12	19
3	6	9	16	22
10	13	14	17	24
11	21	23	26	30

Eliminating red zones, Recursively searching white top-right and bottom-left sub-matrices

1	4	7	11	15
2	5	8	12	19
3	6	9	16	22
10	13	14	17	24
11	21	23	26	30

# Solutions $\rightarrow$ D&C improved

SEARCHINSORTEDMATRIX $(A[1 \dots m, 1 \dots n], k)$ return D&C-IMPROVED $(A[1 \dots m, 1 \dots n], k)$ D&C-IMPROVED $(A[r_{\ell} \dots r_h, c_{\ell} \dots c_h], k)$ if  $c_{\ell} > c_h$  or  $r_{\ell} > r_h$  then return -1// Binary search returns the largest index j in  $[c_{\ell} \dots c_h]$  for which  $A[r_m, j] \leq k$ . If no such index exists, it returns -1 $r_m \leftarrow (r_\ell + r_h)/2$  $j \leftarrow \text{BINARYSEARCH}(A[r_m, c_\ell \dots c_h])$ if j = -1 then return D&C-IMPROVED $(A[r_{\ell} \dots r_m - 1, c_{\ell} \dots c_h], k)$  // upper half else if  $A[r_m, j] = k$  then return  $(r_m, j)$ else if  $A[r_m, j] < k$  then return D&C-IMPROVED $(A[r_{\ell} \dots r_m - 1, j + 1 \dots c_h], k)$  or // region II D&C-IMPROVED $(A[r_m + 1 \dots r_h, c_{\ell} \dots j], k)$ // region III

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(m \log n), \mathcal{O}(\log m) \rangle$
k = 8

# columns < # rows, so binary search on each column

j						j						j						j	
-10	-7	-4	-2	1	-10	-7	-4	-2	1	-10	-7	-4	-2	1	-10	-7	-4	-2	1
-8	-5	-3	-1	3	-8	-5	-3	-1	3	-8	-5	-3	-1	3	-8	-5	-3	-1	3
-5	-3	-2	0	5	-5	-3	-2	0	5	-5	-3	-2	0	5	-5	-3	-2	0	5
-2	-1	1	3	6	-2	-1	1	3	6	-2	-1	1	3	6	-2	-1	1	3	6
0	2	4	5	7	0	2	4	5	7	0	2	4	5	7	0	2	4	5	7
3	4	7	8	9	3	4	7	8	9	3	4	7	8	9	3	4	7	8	9
5	6	9	10	11	5	6	9	10	11	5	6	9	10	11	5	6	9	10	11
10	12	15	17	20	10	12	15	17	20	10	12	15	17	20	10	12	15	17	20

Element found!

• Perform a binary search for k in each row or column

```
SEARCHINSORTEDMATRIX(A[1 \dots m, 1 \dots n], k)
// #rows < #columns
if m < n then
   for i \leftarrow 1 to m do
   j \leftarrow \text{BINARYSEARCH}(A[i, 1 \dots n], k)
  if j \neq -1 then return (i, j)
// #columns < #rows</pre>
else
   for i \leftarrow 1 to n do
    | j \leftarrow \text{BINARYSEARCH}(A[1 \dots m, j], k) 
if j \neq -1 then return (i, j)
return -1
```

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(\min(m, n) \log \max(m, n)), \Theta(1) \rangle$ 

#### Core idea

- Step 1. Select the top-right element
- Step 2. We get 2 cases:
  - Case 0: element = k
  - Case 1: element > k
  - Case 2: element < k
- Step 3.
  - If Case 1, select the left element, and repeat Step 2 If Case 2, select the down element, and repeat Step 2

```
SEARCHINSORTEDMATRIX(A[1 \dots m, 1 \dots n], k)
// Start from the top right element
row \leftarrow 1: col \leftarrow n
while row \leq m and col > 1 do
  if A[row, col] = k then
     return (row, col)
   // In this case, go left as column col (down elements) can't have k
  else if k < A[row, col] then
  | col \leftarrow col - 1
   // In this case, go down as row row (left elements) can't have k
  else if k > A[row, col] then
     row \leftarrow row + 1
return -1
```

$$\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(m+n), \Theta(1) \rangle$$

#### Solutions $\rightarrow$ Decrease-and-conquer

$$k = 10$$
  
Starting from top right

1	4	7	11	15					
2	5	8	12	19					
3	6	9	16	22					
10	13	14	17	24					
11 21 23 26 30									
V									
Element found!									

- Can we start from any corner?
- No!
- We can start from
  - top-right (and go left or down)
  - bottom-left (and go up or right)
- We cannot start from
  - top-left (and go right or down)
  - bottom-right (and go left or up)
- Why can't we start from top-left or bottom-right?

Algorithm	Time	Space		
Linear search	$\mathcal{O}\left(mn ight)$	$\Theta(1)$		
D&C	$\mathcal{O}\left(\min(m,n)^{\log 3} ight)$	$\mathcal{O}\left(\log\max(m,n)\right)$		
Improved D&C	$\mathcal{O}\left(m\log n ight)$	$\mathcal{O}\left(\log m ight)$		
Binary search	$\mathcal{O}\left(\min(m,n)\log\max(m,n)\right)$	$\Theta(1)$		
Decrease-and-conquer	$\mathcal{O}\left(m+n ight)$	$\Theta(1)$		

#### First Missing Positive HOME

- Given an array A[1...n] of unique integers, design an efficient approach to find the smallest missing natural number.
- Input: [2, -9, 5, 11, 1, -10, 7]Output: 3
- Extension: What if we allow duplicates or repetitions?

# Solutions $\rightarrow$ Brute force 1

- 1. Check if i is missing in the array A[1...n] for  $i \in [1...n]$
- 2. Stop and return the smallest such i, otherwise return n+1

```
FIRSTMISSINGPOSITIVE-BRUTEFORCE1(A[1...n])
// Check if the any natural number from 1 to n is missing
for i \leftarrow 1 to n do
  imissing \leftarrow true
   // Iterate over the array to check if the natural number exists
  for i \leftarrow 1 to n do
      // If i is found then break
     if i = A[j] then
        imissing \leftarrow false
        break
   // Missing value found
  if imissing = true then
     return i
return n+1
```

$$\langle \mathsf{Time, Space} \rangle = \left\langle \mathcal{O}\left(n^2\right), \Theta\left(1\right) \right\rangle$$

- 1. Create an empty sorted set S to add all natural numbers from array
- 2. Check if i is missing in the array  $A[1 \dots n]$  for  $i \in [1 \dots n]$
- 3. Stop and return the smallest such i, otherwise return n+1

```
      FIRSTMISSINGPOSITIVE-BRUTEFORCE2(A[1...n])

      // Create a sorted set to store the natural numbers

      Create an empty sorted set S using a balanced search tree

      for i \leftarrow 1 to n do

      if A[i] > 0 then

      | S.Add(A[i])

      // Find the first missing natural number from A[1...n] using S

      for i \leftarrow 1 to n do

      if S does not contain i then

      | return i

      return n + 1
```

$$\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(n \log n), \mathcal{O}(n) \rangle$$

## $\textbf{Solutions} \rightarrow \textbf{Scan}$

- 1. Sort the input array in-place to skip non-natural numbers
- 2. Check if i is missing in the array  $A[1 \dots n]$  for  $i \in [1 \dots n]$
- 3. Stop and return the smallest such i, otherwise return n+1

```
FIRSTMISSINGPOSITIVE-SCAN(A[1...n])
```

```
// Sort the array in-place

SORT(A[1...n])

// Skip negative numbers and zero from the array

index \leftarrow 1

while A[index] < 1 do index \leftarrow index + 1

i \leftarrow 1

// Find the missing natural number from the sorted input array

for j \leftarrow index to n do

| if A[j] = i then i \leftarrow i + 1

else if A[j] > i then

return i
```

$$\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(n \log n), \Theta(1) \rangle$$

- 1. Use  $i \in [1 \dots n]$  of the same array to mark the presence of the numbers
- 2. If A[i] is a natural number and  $i \leq n$ , swap & place it in A[A[i]]
- 3. Stop and return smallest i where  $A[i] \neq i$ , otherwise return n+1

```
      FIRSTMISSINGPOSITIVE-INPLACEHASHING(A[1 \dots n])

      // Swap natural number A[i] to A[i]th index if A[i] \in [1 \dots n]

      for i \leftarrow 1 to n do

      while A[i] \geq 1 and A[i] \leq n and A[i] \neq A[A[i]] do

      | Swap(A[i], A[A[i]])

      // Find the first natural number that is not A[i] \neq i in A[1 \dots n]

      for i \leftarrow 1 to n do

      if A[i] \neq i then

      | return i

      return n + 1
```

```
\langle \mathsf{Time, Space} \rangle = \langle \Theta \left( n \right), \Theta \left( 1 \right) \rangle
```



### Solutions $\rightarrow$ In-place hashing



## Solutions $\rightarrow$ Hash table

- 1. Insert all the array numbers in a hashtable H
- 2. Find the first natural number i that is not present in H

```
      FIRSTMISSINGPOSITIVE-HASHTABLE(A[1 \dots n])

      // Create a HashTable to store the natural numbers

      Create a HashTable H

      for i \leftarrow 1 to n do H[A[i]] \leftarrow true

      // Find the first missing natural number from A[1 \dots n] using H

      for i \leftarrow 1 to n + 1 do

      if H does not contain i then

      + return i
```

$$\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O}(n), \mathcal{O}(n) \rangle$$

This Solution Might Not Always Work. Why?

Algorithm	Time	Space
Brute Force 1	$\mathcal{O}\left(n^{2} ight)$	$\Theta(1)$
Brute Force 2	$\mathcal{O}\left(n\log n\right)$	$\mathcal{O}\left(n ight)$
Scan	$\mathcal{O}\left(n\log n\right)$	$\Theta(1)$
In-Place Hashing	$\Theta\left(n ight)$	$\Theta(1)$
In-Place Hashing & Partition	$\Theta\left(n ight)$	$\Theta(1)$

## Celebrity Problem (HOME)

# Problem

- The knowledge of n guests in a party is represented by a binary matrix  $M[1 \dots n, 1 \dots n]$ , where M[i, j] = 1 means that person i knows person j. Given this binary matrix, find a celebrity if there exists a celebrity, where, a celebrity is a person who is known by everyone and doesn't know anyone.
- If there are multiple celebrities, return any one celebrity. (Prove that there cannot be more than one celebrity) If there are no celebrities, return -1.
- Input:



Output: 2

## Core idea (take-home lesson)



## $\textbf{Solutions} \rightarrow \textbf{Brute force}$

- 1. We iterate over each person and check if they are a celebrity.
- The inner for loop determines whether a person is a celebrity by verifying if they are known by everyone and don't know anyone.

```
FINDCELEBRITY-BRUTEFORCE(M[1 \dots n, 1 \dots n])
for i \leftarrow 1 to n do
  iscelebrity \leftarrow true
                                            // assume person i is a celebrity
  for j \leftarrow 1 to n do
     // Skip self
     if i = j then continue
     // Check if person i knows j or if person j doesn't know i
     if M[i, j] = 1 or M[j, i] = 0 then
        iscelebrity \leftarrow false
        break
  if iscelebrity then
     return i
return -1
```

$$\langle \mathsf{Time, Space} \rangle = \left\langle \mathcal{O}\left(n^2\right), \Theta\left(1\right) \right\rangle$$

- Indegree of person i is the number of people who know i
- *Outdegree* of person *i* is the number of people *i* knows
- We calculate the indegree and outdegree for each person based on their relationships in M.
- Next, we iterate through the guests to find the celebrity, i.e., a person who has an *indegree* of n-1 (knows everyone except self) and an *outdegree* of 0 (is not known by anyone).

FINDCELEBRITY( $M[1 \dots n, 1 \dots n]$ ) // Step 1. Calculate *outdegree* and *indegree* of each node  $outdegree[1 \dots n] \leftarrow [0 \dots 0]; indegree[1 \dots n] \leftarrow [0 \dots 0]$ for  $i \leftarrow 1$  to n do for  $j \leftarrow 1$  to n do // As i knows j, increment outdegree of i and indegree of jif M[i, j] = 1 then  $outdegree[i] \leftarrow outdegree[i] + 1$  $indegree[j] \leftarrow indegree[j] + 1$ // Step 2. Finding the celebrity for  $i \leftarrow 1$  to n do if outdegree[i] = 0 and indegree[i] = n - 1 then return i // celebrity found return -1

$$\langle \mathsf{Time, Space} 
angle = \left\langle \Theta\left(n^2\right), \Theta\left(n\right) \right\rangle$$

## $\textbf{Solutions} \rightarrow \textbf{Graph}$



- The algorithm recursively finds a potential celebrity in the first n-1 elements of the matrix M.
- It checks the base case to return 1 when *n* is 1, indicating that the only person is the celebrity.
- If no celebrity is found in the first n-1 person, it considers n as the potential celebrity.
- It checks if the potential celebrity knows person n-1. If yes, n-1 is the celebrity.
- If the potential celebrity doesn't know person n-1, the previously found celebrity(id) is the celebrity.
- The wrapper function ensures that the potential celebrity is a real celebrity based on the matrix M.

```
FINDCELEBRITY(M[1 \dots n, 1 \dots n])
// Step 1. Find the celebrity candidate
candidate \leftarrow FINDPOTENTIALCELEBRITY(M, n)
if candidate = -1 then
  return -1
                                                       // no celebrity found
// Step 2. Check if the candidate is a celebrity
outdegree \leftarrow 0; indegree \leftarrow 0
for i \leftarrow 1 to n do
  if i \neq candidate then
     outdegree \leftarrow outdegree + M[candidate, i]
     indegree \leftarrow indegree + M[i, candidate]
if outdegree = 0 and indegree = n - 1 then
  return candidate
return -1
                                                       // no celebrity found
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(n) \rangle$ 

```
FINDPOTENTIALCELEBRITY(M[1 \dots n, 1 \dots n], m)if m = 0 then return -1// Recursively find celebrity in the first m - 1 personscandidate \leftarrow FINDPOTENTIALCELEBRITY(M, m - 1)// If there is no candidate in the first m - 1 people, m is the new candidateif candidate = -1 then return m// If candidate knows m person, then m is the new candidateif M[candidate, m] = 1 then return m// If m knows candidate, then candidate is the new candidateif M[m, candidate] = 1 then return candidatereturn -1
```

## $\textbf{Solutions} \rightarrow \textbf{Recursion}$

FINDPOTENTIALCELEBRITY(M, 4)M0 1 0 FINDPOTENTIALCELEBRITY(M, 3)0 0 0 0 0 1 0 0 'FINDPOTENTIALCELEBRITY(M, 2)1 1 0 0 'FINDPOTENTIALCELEBRITY(M, 1)N = 4'FINDPOTENTIALCELEBRITY(M, 0)Base case Exiting with -1candidate = -1, so exiting with m = 1candidate  $\neq -1$ M[candidate, m] = M[1, 2] = 1, so exiting with m = 2 $candidate \neq -1$  $M[candidate, m] = M[2, 3] \neq 1$ , so checking ahead M[m, candidate] = M[3, 2] = 1, so exiting with m = 2candidate  $\neq -1$  $M[candidate, m] = M[2, 4] \neq 1$ , so checking ahead M[m, candidate] = M[4, 2] = 1, so exiting with m = 2Potential celebrity is 2

- We use a stack to eliminate potential non-celebrities.
- We compare pairs of individuals to determine which one cannot be a celebrity and pushes the other back into the stack.
- After processing all pairs, one person remains in the stack.
- Check if this person is known to everyone and doesn't know anyone to identify the celebrity.

## Solutions $\rightarrow$ Elimination technique

```
FINDCELEBRITY(M[1 \dots n, 1 \dots n])
// Step 1. Find a potential celebrity
Create a stack S \leftarrow [] to store all potential celebrities
for i \leftarrow 1 to n do S.Push(i)
while Stack S has greater than 1 element do
  i \leftarrow S.\mathsf{Pop}(); j \leftarrow S.\mathsf{Pop}()
                                                             // pop 2 elements
   // Check if i knows j, and push the potential celebrity to stack
  if M[i, j] = 1 then S.Push(j)
  else S.Push(i)
candidate \leftarrow S.\mathsf{Pop}()
// Step 2. Check if the candidate is a celebrity
for i \leftarrow 1 to n do
  if i \neq candidate then
     if M[i, candidate] = 0 then return -1
     if M[candidate, i] = 1 then return -1
return candidate
```

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(n) \rangle$$

## Solutions $\rightarrow$ Elimination technique



- We iterate through the people, starting with the first person r.
- Check if *r* knows the *i*<sup>th</sup> person and updates the diagonal elements accordingly.
- After processing, it checks if any person can be a celebrity by verifying if they are known by everyone and don't know anyone.
- If a potential celebrity is found, return it; otherwise, -1 is returned if no celebrity is found.

## Solutions $\rightarrow$ Efficient elimination technique

```
FINDCELEBRITY(M[1 \dots n, 1 \dots n])
// Step 1. Find the celebrity candidate
r \leftarrow 1
for i \leftarrow 2 to n do
   if M[r, i] = 1 then
     M[r,r] \leftarrow \star
                                                             // r can't be a celebrity
     r \leftarrow i
                                                                     // update r to i
   else
     M[i,i] \leftarrow \star
                                                             // i can't be a celebrity
// The single candidate will have its diagonal cell as 0
candidate \leftarrow 1
while candidate < n do
   if M[candidate, candidate] = 0 then break
// Step 2. Check if the candidate is really the celebrity
for i \leftarrow 1 to n do
   if i \neq candidate then
      if M[i, candidate] = 0 then return -1
      if M[candidate, i] = 1 then return -1
return candidate
```

 $\langle \text{Time, Space} \rangle = \langle \Theta(n), \Theta(1) \rangle$ Assumption: The input matrix M can be updated

#### Solutions $\rightarrow$ Efficient elimination technique



- Initialize two pointers, i at 1 (person 1) and j at n (person n).
- Iteratively check if person *j* knows person *i*. If so, decrement *j*; otherwise, increment *i*.
- Person pointed to by *i* is considered the celebrity candidate.
- Verify if the celebrity candidate is known by everyone and knows no one for every *i*.
- If the candidate satisfies these conditions, they are considered the celebrity, and their index is returned; otherwise, -1 is returned if no celebrity is found.

FINDCELEBRITY-TWOPOINTERS $(M[1 \dots n, 1 \dots n])$ // Step 1. Find the celebrity candidate  $i \leftarrow 1, j \leftarrow n$ while i < j do if M[j, i] = 1 then  $i \leftarrow i - 1$  // person j knows person i, so j can't be a celebrity else  $i \leftarrow i+1$  // person j doesn't know i, so i can't be a celebrity candidate  $\leftarrow i$ // person *i* is the celebrity candidate // Step 2. Check if the candidate is really the celebrity for  $j \leftarrow 1$  to n do if  $j \neq candidate$  then if M[j, candidate] = 0 or M[candidate, j] = 1 then return -1// candidate is not a celebrity return candidate // candidate is the celebrity

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n), \Theta(1) \rangle$
# Solutions $\rightarrow$ Two pointers (example 1)

1  $\mathbf{2}$ 3

4

5

		М			People	Pointers	Action
(	1 2 ) 1 ) 0	3 1 0	4 0 0	5 1 0	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 1 $j = 5$	Since $M[j, i] = M[5, 1] = 1$ j cannot be a celebrity. Hence, $j \leftarrow j - 1$ .
•	) 1 L 1 L 1	0 0 0	0 0 1	0 0 1	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 1 $j = 4$	Since $M[j, i] = M[4, 1] = 1$ j cannot be a celebrity. Hence, $j \leftarrow j - 1$ .
					$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 1 $j = 3$	Since $M[j, i] = M[3, 1] = 0$ <i>i</i> cannot be a celebrity. Hence, $i \leftarrow i + 1$ .
					$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 2 $j = 3$	Since $M[j, i] = M[3, 2 = 1, j$ cannot be a celebrity. Hence, $j \leftarrow j - 1$ .
					$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 2 $j = 2$	Since $i = j = 2$ i.e. $i \ge j$ , Potential celebrity is 2
					i = 2	turns out to n 2	be a celebrity,

1,

1,

0,

# Solutions $\rightarrow$ Two pointers (example 2)

Μ						People	Pointers	Action
1 2	1 0 0	2 1 0	3 1 0	4 0 0	5 1 0	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 1 $j = 5$	Since $M[j, i] = M[5, 1] = 0$ , i cannot be a celebrity. Hence, $i \leftarrow i + 1$ .
3 4 5	0 1 0	1 1 0	0 0 0	0 0 1	0 0 1	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 2 $j = 5$	Since $M[j, i] = M[5, 2] = 0$ , i cannot be a celebrity. Hence, $i \leftarrow i + 1$ .
						$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 3 $j = 5$	Since $M[j, i] = M[5, 3] = 0$ , i cannot be a celebrity. Hence, $i \leftarrow i + 1$ .
						$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 4 $j = 5$	Since $M[j, i] = M[5, 4] = 1$ , j cannot be a celebrity. Hence, $j \leftarrow j - 1$ .
						$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	i = 4 $j = 4$	Since $i = j = 4$ i.e. $i \ge j$ , Potential celebrity is 4
	i = 4 turns out to not be a celebrity, return $-1$							not be a celebrity,

Algorithm	Time	Space
Brute force	$\mathcal{O}\left(n^2\right)$	$\Theta(1)$
Graph	$\Theta\left(n^2\right)$	$\Theta\left(n ight)$
Recursion	$\Theta\left(n ight)$	$\Theta\left(n ight)$
Elimination	$\Theta\left(n ight)$	$\Theta\left(n ight)$
Efficient elimination	$\Theta\left(n ight)$	$\Theta(1)$
Two pointers	$\Theta\left(n ight)$	$\Theta(1)$

#### Random Permutation (HOME)

• Generate a random permutation of A[1, 2, ..., n]. A random permutation of A[1, 2, ..., n] is  $A[p_1, p_2, ..., p_n]$ , where  $[p_1, p_2, ..., p_n]$  is a random permutation of [1, 2, ..., n] with probability of occurring 1/n!.

## Solutions $\rightarrow$ Algorithm 1



```
RANDOM PERMUTATION (A[1 \dots n])
```

 $\begin{array}{l} \text{for } i \leftarrow 1 \text{ to } n-1 \text{ do} \\ x \leftarrow \text{RANDOM}([1 \dots n]) \\ y \leftarrow \text{RANDOM}([1 \dots n]) \\ \text{SWAP}(A[x], A[y]) \end{array}$ 

The algorithm is incorrect.

Counterexample:

- Suppose k = #iterations for which actual swap takes place total #permutations = n! total #outcomes  $= (n^2)^k$
- If #permutations does not divide #outcomes, then the output permutations are not equally likely
- For n = 3 and arbitrary natural number k, #permutations (3!) does not divide #outcomes  $((3^2)^k)$



```
RANDOM PERMUTATION (A[1 \dots n])
```

```
 \begin{array}{l} \text{for } i \leftarrow 1 \text{ to } n-1 \text{ do} \\ x \leftarrow i \\ y \leftarrow \text{RANDOM}([1 \dots n]) \\ \text{SWAP}(A[x], A[y]) \end{array}
```

The algorithm is incorrect.

Counterexample:

- Suppose k = #iterations for which actual swap takes place total #permutations = n! total #outcomes  $= n^k$
- If #permutations does not divide #outcomes, then the output permutations are not equally likely
- For n = 3 and arbitrary natural number k, #permutations (3!) does not divide #outcomes (n<sup>k</sup>)

RANDOM PERMUTATION  $(A[1 \dots n])$ 

 $\begin{array}{l} \text{for } i \leftarrow 1 \text{ to } n-1 \text{ do} \\ x \leftarrow i \\ y \leftarrow \text{RANDOM}([i+1 \dots n]) \\ \text{SWAP}(A[x], A[y]) \end{array}$ 

```
RANDOM PERMUTATION (A[1 \dots n])
```

```
 \begin{array}{l} \text{for } i \leftarrow 1 \text{ to } n-1 \text{ do} \\ x \leftarrow i \\ y \leftarrow \text{RANDOM}([i+1 \dots n]) \\ \text{SWAP}(A[x], A[y]) \end{array}
```

The algorithm is incorrect.

Counterexample:

- total #permutations = n! total #outcomes = (n - 1)!
- If #permutations does not divide #outcomes, then the output permutations are not equally likely
- For any natural number n > 1, #permutations (n!) does not divide #outcomes ((n - 1)!)

 RANDOMPERMUTATION(A[1...n])

 Choose a random hash function for the hash table H

 for  $i \leftarrow 1$  to n do

 H.Add(A[i]) // add the element even if the key exists

 for  $i \leftarrow 1$  to n do

  $A[i] \leftarrow i$ th element in hash table H

 $\begin{array}{l} \textbf{RANDOMPERMUTATION}(A[1 \dots n]) \\ \hline \textbf{for } i \leftarrow n \ \textbf{downto} \ 2 \ \textbf{do} \\ \mid x \leftarrow \textbf{RANDOM}([1 \dots i]) \\ \hline \textbf{for } j \leftarrow x + 1 \ \textbf{downto} \ i \ \textbf{do} \\ \mid A[j-1] \leftarrow A[j] \\ A[i] \leftarrow A[x] \end{array}$ 

The algorithm is correct.

Proof:

• We want to prove that probability of producing random permutation is 1/n!

Probability 
$$= \frac{1}{n} \times \frac{1}{n-1} \times \cdots \times \frac{1}{2} = \frac{1}{n!}$$

RANDOM PERMUTATION (A[1...n])

```
for i \leftarrow 1 to n - 1 do

x \leftarrow i

y \leftarrow \text{RANDOM}([i \dots n])

SWAP(A[x], A[y])
```

#### can also be written as

RANDOM PERMUTATION  $(A[1 \dots n])$ 

 $\begin{array}{l} \text{for } i \leftarrow n \text{ downto } 2 \text{ do} \\ x \leftarrow i \\ y \leftarrow \text{RANDOM}([1 \dots i]) \\ \text{SWAP}(A[x], A[y]) \end{array}$ 

The algorithm is correct.

RANDOM PERMUTATION (A[1...n])

for  $i \leftarrow n$  downto 2 do  $x \leftarrow i$  $y \leftarrow \text{RANDOM}([1 \dots i])$ SWAP(A[x], A[y])

Proof:

- Let X = [1, 2, ..., n] and  $Y = [p_1, p_2, ..., p_n]$  We want to prove that probability of producing Y from X is 1/n!

$$P(Y) = P(Y[1] = p_1, Y[2] = p_2, \dots, Y[n] = p_n)$$
  
=  $P(Y[n] = p_n)$   
 $\times P(Y[n-1] = p_{n-1} | Y[n] = p_n)$   
 $\times P(Y[n-2] = p_{n-2} | Y[n] = p_n, Y[n-1] = p_{n-1})$   
 $\times \dots$   
 $\times P(Y[1] = p_1 | Y[n] = p_n, Y[n-1] = p_{n-1}, \dots, Y[2] = p_2)$   
=  $\frac{1}{n} \times \frac{1}{n-1} \times \dots \times \frac{1}{1} = \frac{1}{n!}$ 

#### Count Distinct Pairs (HOME)

• Given an array of unique integers  $A[1 \dots n]$  and a positive integer k, count all distinct pairs with differences equal to k.

• Input: 
$$[8, 5, 1, 4, 2]$$
,  $k = 3$   
Output: 3  $(4 - 1 = 5 - 2 = 8 - 5)$ 

- Input: [8, 12, 16, 4, 0, 20], k = 4Output: 5 (20 - 16 = 16 - 12 = 12 - 8 = 8 - 4 = 4 - 0)
- Input: [1, 1, 1, 1, 2, 2, 2, 2], k = 1Input has duplicates, so this type of input is not allowed

 $\bullet$  Consider every pair of elements and increment count if the difference equals k

 $\begin{array}{c} \text{CountPairs-BruteForce}(A[1 \dots n],k) \\ \hline count \leftarrow 0 \\ \text{for } i \leftarrow 1 \text{ to } n-1 \text{ do} \\ | \text{ for } j \leftarrow i+1 \text{ to } n \text{ do} \\ | \text{ if absolute}(A[i] - A[j]) = k \text{ then} \\ | count \leftarrow count + 1 \\ \hline \text{return } count \end{array}$ 

$$\langle \mathsf{Time, Space} 
angle = \left\langle \Theta\left(n^2\right), \Theta\left(1\right) \right\rangle$$

- 1. Sort the array, initialize count to 0
- 2. For each element A[i] for  $i \in [1 \dots n-1]$ , search for A[i] + k in the remaining array  $A[i+1 \dots n]$  using binary search
- 3. Each time A[i] + k is found, increment *count* by 1

```
COUNTING PAIRS-BINARY SEARCH(A[1...n], k)

SORT(A[1...n])

count \leftarrow 0

for i \leftarrow 1 to n - 1 do

// Check if A[i] + k in A[i + 1...n] using binary search

if BINARY SEARCH(A[i + 1...n], A[i] + k) \neq -1 then

| count \leftarrow count + 1

return count
```

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta(n \log n), \Theta(1) \rangle$$

- 1. Add all elements of the array to the HashTable  ${\cal H}$
- 2. For each element A[i] for  $i \in [1 \dots n]$ , search for A[i] + k and A[i] k in H and increment *count* on finding a match
- 3. Return count/2

```
COUNTINGPAIRS-HASHING(A[1...n],k)Create an empty HashTable Hfor i \leftarrow 1 to n do H.Add(A[i])count \leftarrow 0for i \leftarrow 1 to n dofor i \leftarrow 1 to n dofor i \leftarrow 1 to n doif H.Contains(A[i] + k) then count \leftarrow count + 1if H.Contains(A[i] - k) then count \leftarrow count + 1return count/2
```

$$\langle \mathsf{Time, Space} 
angle = \langle \Theta\left(n
ight)^{*}, \mathcal{O}\left(n
ight) 
angle$$

# Solutions $\rightarrow$ Sorting + two pointers

- 1. Sort  $A[1 \dots n],$  initialize two pointers low and high to 1
- 2. Calculate the difference diff = A[high] A[low]. While  $high \le n$ 
  - If diff = k, increment low, high, and count
  - If diff > k, increment low
  - If diff < k, increment high

```
CountingPairs-TwoPointers(A[1...n], k)
```

```
\begin{split} &\operatorname{SORT}(A[1 \dots n]) \\ &\operatorname{count} \leftarrow 0; \ low \leftarrow 1; \ high \leftarrow 1 \\ &\operatorname{while} \ high \leq n \ \operatorname{do} \\ & | \ diff = A[high] - A[low] \\ & \operatorname{if} \ diff = k \ \operatorname{then} \\ & | \ \ count \leftarrow count + 1; \ low \leftarrow low + 1; \ high \leftarrow high + 1 \\ & \operatorname{else} \ \operatorname{if} \ diff > k \ \operatorname{then} \ \ high \leftarrow high + 1 \\ & \operatorname{else} \ \operatorname{if} \ diff > k \ \operatorname{then} \ \ high \leftarrow high + 1 \\ & \operatorname{else} \ \operatorname{if} \ diff > k \ \operatorname{then} \ \ high \leftarrow high + 1 \\ & \operatorname{else} \ \operatorname{if} \ diff > k \ \operatorname{then} \ \ high \leftarrow high + 1 \end{split}
```

$$\langle \mathsf{Time, Space} \rangle = \langle \Theta(n \log n), \Theta(1) \rangle$$

#### Solutions $\rightarrow$ Sorting + two pointers



Algorithm	Time	Space
Brute force	$\Theta\left(n^2\right)$	$\Theta(1)$
Sorting + Binary Search	$\Theta\left(n\log n\right)$	$\Theta(1)$
Hashing	$\Theta\left(n ight)^{*}$	$\mathcal{O}\left(n ight)$
Sorting + Two Pointers	$\Theta\left(n\log n\right)$	$\Theta(1)$

Solve the problem when there are duplicates in the array.

### Maximum and Minimum (HOME)

- Given an array, find the maximum and minimum elements in the array.
- We consider the number of array element comparisons for measuring time.
- Input: A = [4, 2, 0, -2, 20, 9, 2]Output: [20, -2]

• Traverse the array and compare each element with *max* and *min*.

 $\begin{array}{l} & \textbf{BRUTEFORCE}(A[1 \dots n]) \\ & max \leftarrow A[1]; \ min \leftarrow A[1] \\ & \textbf{for } i \leftarrow 2 \ \textbf{to} \ n \ \textbf{do} \\ & | \ \textbf{if } A[i] > max \ \textbf{then} \ max \leftarrow A[i] \\ & | \ \textbf{else if } A[i] < min \ \textbf{then} \ min \leftarrow A[i] \\ & | \ \textbf{return} \ (max, min) \end{array}$ 

$$\langle \mathsf{Time, Space} \rangle = \langle 2n - 2, \Theta(1) \rangle$$

## Solutions $\rightarrow$ Increment by two

• Pick elements in pairs, the smaller element amongst the two becomes a candidate for *min* and the larger element for *max*.

INCREMENTBYTWO $(A[1 \dots n])$ 

```
if n is odd then \{ max \leftarrow A[1], min \leftarrow A[1], i \leftarrow 2 \}
else
   if A[1] < A[2] then { max \leftarrow A[2]; min \leftarrow A[1] }
   else { max \leftarrow A[1]; min \leftarrow A[2] }
   i \leftarrow 3
while i < n do
   if A[i] < A[i+1] then
      if A[i] < min then min \leftarrow A[i]
      if A[i+1] > max then max \leftarrow A[i+1]
   else
     if A[i] > max then max \leftarrow A[i]
     if A[i+1] < min then min \leftarrow A[i+1]
   i \leftarrow i+2
return (max, min)
```

$$\langle \text{Time, Space} \rangle = \left\langle \frac{3}{2} \left( n - 1 - \boxed{n \text{ is even}} \right), \Theta(1) \right\rangle$$

- 1. Divide the problem into two equal size sub-problems.
- 2. Recursively find the max and min of left and right parts.
- 3. Compare the max of both halves to get the overall max, and the min of both halves to get the overall min.

## $\textbf{Solutions} \rightarrow \textbf{Divide-and-conquer}$

```
DIVIDEANDCONQUER(A[low \dots high])
size \leftarrow high - low + 1
if size = 1 then \{max \leftarrow A[low]; min \leftarrow A[low]\}
else if size = 2 then
  if A[low] < A[high] then \{max \leftarrow A[high]; min \leftarrow A[low]\}
  else { max \leftarrow A[low]; min \leftarrow A[high] }
else
  mid \leftarrow |(low + high)/2|
   (\ell max, \ell min) \leftarrow \text{DIVIDEANDCONQUER}(A[low ... mid))
   (rmax, rmin) \leftarrow \text{DIVIDEANDCONQUER}(A[mid + 1...high])
  if \ell max > rmax then max \leftarrow \ell max
  else max \leftarrow rmax
   if \ell min < rmin then min \leftarrow \ell min
  else min \leftarrow rmin
return (max, min)
```

$$T(n) = \begin{cases} n-1 & \text{if } n = 1 \text{ or } 2, \\ 2T(n/2) + 2 & \text{if } n > 2. \end{cases}$$
  
$$\langle \text{Time, Space} \rangle = \left\langle \frac{3n}{2} - 2, \Theta(\log n) \right\rangle$$

Algorithm	Time	Space
Brute force	2n - 2	$\Theta(1)$
Increment by two	$\frac{3}{2}\left(n-1-\boxed{n \text{ is even}}\right)$	$\Theta\left(1 ight)$
Divide-and-conquer	$\frac{3n}{2} - 2$	$\Theta\left(\log n\right)$

# Sorting Algorithms (HOME)

- Design an efficient algorithm to sort a given array  $A[1 \dots n]$ .
- Input: [80, 30, 90, 50, 40, 20, 100]
   Output: [20, 30, 40, 50, 80, 90, 100]
- Input: [23, 15, 40, 15, 10]Output: [10, 15, 15, 23, 40]

 PermutationSort(A[1...n])

 while true do

 RANDOMPERMUTE(A[1...n])

 if IsSorted(A[1...n]) then

 | break

 RANDOMPERMUTE(A[1...n])

 for  $i \leftarrow 1$  to n - 1 do

 |  $A[i] \leftarrow SWAP(A[i], A[RANDOM(i...n)])$ 

 $\langle \mathsf{Time, Space} \rangle = \langle \mathcal{O} \left( \infty \right), \Theta \left( 1 \right) \rangle$ 

## $\textbf{Solutions} \rightarrow \textbf{Slow sort}$

- 1. Divide the subarray into two halves.
- 2. Sort the first half recursively.
- 3. Sort the second half recursively.
- 4. Swap the last elements of the two halves if they are out of order.
- 5. Sort the subarray except the last element recursively.

```
SLOWSORT(A[low ... high])
if i > j then return
// Sort the two halves recursively
mid \leftarrow (low + high)/2
SLOWSORT(A[low ... mid])
SLOWSORT(A[mid + 1...high])
// The largest element of the subarray should go to its correct position
if A[high] < A[mid] then
  Swap(A[high], A[mid])
// Sort the remaining subarray
SLOWSORT(A[low ... high - 1])
```

$$\langle \mathsf{Time, Space} \rangle = \left\langle \mathcal{O}\left(n^{\frac{\log_2 n}{2}}\right), \Theta\left(n\right) \right\rangle$$

## $\textbf{Solutions} \rightarrow \textbf{Pancake sort}$

- 1. Suppose the index of the maximum element in A[1...n] is maximum.
- 2. Reverse  $A[1 \dots maxindex]$  to move the largest element in the array to index 1.
- 3. Reverse  $A[1 \dots n]$  to move the largest element to A[n].
- 4. Recursively sort  $A[1 \dots n-1]$ .

```
PANCAKESORT(A[1 \dots n])
// The ith iteration finds the ith largest element
for i \leftarrow n downto 2 do
   // Step 1. Find the index of the \max(A[1...i])
  maxindex \leftarrow 1
  for i \leftarrow 2 to i do
     if A[j] > A[maxindex] then
     maxindex \leftarrow j
   // Step 2. Move max(A[1...maxindex]) to index 1
   \operatorname{Reverse}(A[1 \dots maxindex])
   // Step 3. Move A[1] to its correct position
   \operatorname{Reverse}(A[1 \dots i])
```

$$\left< \mathsf{Time, Space} \right> = \left< \mathcal{O}\left( n^2 \right), \Theta\left( 1 
ight) \right>$$

#### Solutions $\rightarrow$ Pancake sort



6	8	7	7	9
8	6	7	7	9
7	7	6	8	9

7	7	6	8	9
7	7	6	8	9
6	7	7	8	9

6	7	7	8	9
7	6	7	8	9
6	7	7	8	9

i = 5; maxindex = 2Reverse  $A[1 \dots maxindex]$ Reverse  $A[1 \dots i]$ 

i = 4; maxindex = 2 Reverse  $A[1 \dots maxindex]$ Reverse  $A[1 \dots i]$ 

i = 3; maxindex = 1Reverse  $A[1 \dots maxindex]$ Reverse  $A[1 \dots i]$ 

i = 2; maxindex = 2Reverse  $A[1 \dots maxindex]$ Reverse  $A[1 \dots i]$
## Solutions $\rightarrow$ Stooge sort

- 1. If the start element is greater than the end element, swap them.
- 2. If there are three or more elements in the array:
  - 1. Recursively sort the first 2/3rd of the array
  - 2. Recursively sort the last 2/3rd of the array
  - 3. Recursively sort the first 2/3rd of the array

```
STOOGESORT(A[\ell \dots h])
```

```
\begin{array}{l} size \leftarrow h - \ell + 1 \\ \textbf{if} \ (A[\ell] > A[h]) \ \textbf{then} \\ | \ SWAP(A[\ell], A[h]) \\ \textbf{if} \ (size > 2) \ \textbf{then} \\ | \ third \leftarrow size/3 \\ STOOGESORT(A[\ell \dots h - third]) \\ STOOGESORT(A[\ell \dots h - third]) \\ STOOGESORT(A[\ell \dots h - third]) \end{array}
```

$$\langle \mathsf{Time, Space} 
angle = \left\langle \Theta\left(n^{\log_{1.5}3}
ight), \Theta\left(\log n
ight) 
ight
angle$$

#### Solutions $\rightarrow$ Stooge sort



The original array

First (2/3)rd of the array

Sort the first (2/3)rd of the array

Last (2/3)rd of the array

Sort the last (2/3)rd of the array

First (2/3)rd of the array

Sort the first (2/3)rd of the array

The original array is sorted

## Solutions $\rightarrow$ Counting sort

#### Assumption

- Items are natural numbers with maximum value k.
- 1. Create an array for indices in the range  $\left[0,k\right]$
- 2. Distribute items to these indices to compute item frequences
- 3. Compute the cumulative frequencies of items for indices in the range  $\left[0,k\right]$
- 4. Find the sorted array

$$A \ \boxed{2} \ \boxed{5} \ \boxed{3} \ \boxed{0} \ \boxed{2} \ \boxed{3} \ \boxed{0} \ \boxed{3}$$

Unsorted array 
$$A[1..n]$$

$$C \ \boxed{2} \ 0 \ \boxed{2} \ \boxed{3} \ 0 \ \boxed{1}$$

$$C \ \boxed{2} \ \boxed{2} \ \boxed{4} \ \boxed{7} \ \boxed{7} \ \boxed{8}$$

Frequencies array C[0..k]

Cumulative frequencies array C[0..k]

Sorted array B[1..n]

#### Solutions $\rightarrow$ Counting sort

CountingSort( $A[1 \dots n]$ )

 $k \leftarrow \max(A[1 \dots n])$ Create new array  $B[1 \dots n]$ Create new array  $C[0 \dots k]$  and initialize it to 0 // Find the frequencies of items // After this step, C[i] will contain #elements equal to i for  $j \leftarrow 1$  to n do  $| C[A[j]] \leftarrow C[A[j]] + 1$ // Find the cumulative frequencies of items // After this step, C[i] will contain #elements less than or equal to i for  $i \leftarrow 1$  to k do  $| C[i] \leftarrow C[i] + C[i-1]$ // Get the sorted array in B for  $i \leftarrow n$  downto 1 do  $B[C[A[j]] \leftarrow A[j]$  $C[A[j]] \leftarrow C[A[j]] - 1$ // Copy the sorted array to Afor  $j \leftarrow 1$  to n do  $A[j] \leftarrow B[j]$ 

#### Solutions $\rightarrow$ Counting sort



- This algorithm counts the number of occurrences of each element in the input sequence and then uses that information to construct the sorted output. It is often used when the range of input elements is known in advance.
- The algorithm works by distributing the input elements into a number of bins/buckets based on their values and then collecting from the bins in order, resulting in a sorted output
- This algorithm is typically used for sorting a large number of elements with a small range of possible values

#### Solutions $\rightarrow$ Counting sort variant

```
COUNTINGSORT VARIANT (A[1...n])
(max, min) \leftarrow MAXMIN(A[1...n])
size \leftarrow max - min + 1
                                                    // size of range [min, max]
Create an array B[1 \dots size] \leftarrow [0 \dots 0]
// Distribute array A elements to buckets in B
for i \leftarrow 1 to n do
i \leftarrow A[j] - min + 1; B[i] \leftarrow B[i] + 1
// Construct the sorted array A based on the bucket array
index \leftarrow 1
for i \leftarrow 1 to size do
  while B[i] > 0 do
      A[index] \leftarrow i + min - 1
     index \leftarrow index + 1
      B[i] \leftarrow B[i] - 1
```

Let  $\#buckets = \max(A[1 \dots n]) - \min(A[1 \dots n])$  $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n + \#buckets), \Theta(\#buckets) \rangle$ 

# Solutions $\rightarrow$ Counting sort variant

A	5	7	9	3	5	3	4	5		
B	2	1	3	0	1	0	1			
В	2	1	3	0	1	0	1		index=1 , $i=1$	$B \  \  0 \  \  0 \  \  1 \  \  0 \  \  1 \  \  0 \  \  1 \  \  0 \  \  1 \  \  0 \  \  1 \  \  0 \  \  1 \  \  0 \  \  1 \  \  0 \  \  1 \  \  0 \  \  1 \  \  0 \  \  1 \  \  0 \  \  0 \  \  0 \  \  0 \  \  0 \  \ $
A	3								A[index] = i + min - 1	$A \ 3 \ 3 \ 4 \ 5 \ 5 \ 5 \ A[index] = i + min - 1$
В	1	1	3	0	1	0	1	ļ	B[i]	$B \ 0 \ 0 \ 0 \ 0 \ 1 \ 0 \ 1 \ B[i]$
В	1	1	3	0	1	0	1		index=2 , $i=1$	$B \ 0 \ 0 \ 0 \ 0 \ 1 \ 0 \ 1 \qquad index = 4 \ , \ i = 4$
A	3	3							A[index] = i + min - 1	A 3 3 4 5 5 5
В	0	1	3	0	1	0	1		B[i]	B 0 0 0 0 1 0 1
B	0	1	3	0	1	0	1		index = 3, $i = 2$	$B \ 0 \ 0 \ 0 \ 0 \ 1 \ 0 \ 1 \qquad index = 7 \ , \ i = 5$
A	3	3	4						A[index] = i + min - 1	$A \ 3 \ 3 \ 4 \ 5 \ 5 \ 5 \ 7 \qquad A[index] = i + min - 1$
B	0	0	3	0	1	0	1		B[i]	B 0 0 0 0 0 1 B[i]
,										
В	0	0	3	0	1	0	1		index=4 , $i=3$	$B \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 1 \qquad index = 8 \ , \ i = 6$
A	3	3	4	5					A[index] = i + min - 1	A 3 3 4 5 5 5 7
B	0	0	2	0	1	0	1		B[i]	$B \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 1$
,	_		_			_	-	,		
В	0	0	2	0	1	0	1		index = 5, $i = 3$	$B \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 1 \qquad index = 8 \ , \ i = 7$
A	3	3	4	5	5				A[index] = i + min - 1	$A \ 3 \ 3 \ 4 \ 5 \ 5 \ 5 \ 7 \ 9 \qquad A[index] = i + min - 1$
B	0	0	1	0	1	0	1		B[i]	B 0 0 0 0 0 0 0 0 0 B[i]

#### $\textbf{Solutions} \rightarrow \textbf{Radix sort}$

- 1. Sort the numbers based on digits at unit's place
- 2. Sort the numbers based on digits at ten's place
- 3. Sort the numbers based on digits at hundred's place
- 4. Continue the process until you cover all decimal digits
- 5. By the end, the entire array will be sorted



```
\operatorname{RadixSort}(A[1 \dots n])
max \leftarrow \mathsf{Max}(A[1 \dots n]); exp \leftarrow 1
// Sort the array for each digit
while exp < max do
   C[0\ldots 9] \leftarrow [0\ldots 0]; B[1\ldots n] \leftarrow [0\ldots 0]
    // Find the cumulative frequencies of items
   for i \leftarrow 1 to n do
       { index \leftarrow \left|\frac{A[i]}{exp}\right| \mod 10; C[index] \leftarrow C[index] + 1 }
   for i \leftarrow 1 to 9 do C[i] \leftarrow C[i] + C[i-1]
    // Populate output using count array
   for i \leftarrow n downto 1 do
       index \leftarrow \left|\frac{A[i]}{am}\right| \mod 10
       B[C[index]] \leftarrow A[i]
      C[index] \leftarrow C[index] - 1
   A[1 \dots n] \leftarrow B[1 \dots n]; exp \leftarrow exp \times 10
```

 $\langle \mathsf{Time, Space} \rangle = \langle \Theta(n \log n), \Theta(n) \rangle$ 

• Sort numbers based on the digits at unit's place

${A}$	35	29	45	57	- 83	39	43	36	7	20	355	A[6] = 355	A	329	43	57	83	<u> 89</u>	43	6	72	20	355	A[3] = 839
C	1	1	1	1	1	2	3	4	4	6		C[5] = 2	C	0 1	1	1	1	1	2	4	4	6		C[9] = 6
B			35	55								B[2] = 355	В	720	- 38	55	43	36					839	B[6] = 839
C	1	1	1	1	1	1	3	4	4	6		C[5]	C	0 1	1	1	1	1	2	4	4	5		C[9]
											,													
A	35	29	45	57	83	39	43	36	-7	20	355	A[5] = 720	A	329	4	57	83	39	43	6	72	20	355	A[2] = 457
C	1	1	1	1	1	1	3	4	4	6		C[0] = 1	C	0 1	1	1	1	1	2	4	4	5		C[7] = 4
B	75	20	35	55								B[1] = 720	В	720	- 38	55	43	86	45	7			839	B[4] = 457
C	0	1	1	1	1	1	3	4	4	6		C[0]	C	0 1	1	1	1	1	2	3	4	5		C[7]
A	35	29	45	57	- 83	39	43	36	7	20	355	A[4] = 436	A	329	4	57	-83	39	43	6	72	20	355	A[1] = 329
C	0	1	1	1	1	1	3	4	4	6		C[6] = 3	C	0 1	1	1	1	1	2	3	4	5		C[9] = 5
B	75	20	35	55	43	36						B[3] = 436	В	720	- 38	55	43	36	45	7	32	9	839	B[5] = 329
C	0	1	1	1	1	1	2	4	4	6		C[6]	C	0 1	1	1	1	1	2	3	4	4		C[9]

#### $\textbf{Solutions} \rightarrow \textbf{Radix sort}$

- Sort numbers based on the digits at ten's place
- B from the previous iteration will be the A for this iteration.

A	720	355	436	457	329	839	A[6] = 839	A	720	355	436	457	329	839	A[3] = 436
C	0 0	2 4	4 6	6 6	6 6		C[3] = 4	C	0 0	1 3	4 5	6 6	6 6		C[3] = 3
B				839			B[4] = 839	B		329	436	839		457	B[3] = 436
C	0 0	2 3	4 6	6 6	6 6		C[3]	C	0 0	1 2	4 5	6 6	6 6		C[3]
A	720	355	436	457	329	839	A[5] = 329	A	720	355	436	457	329	839	A[2] = 355
C	0 0	2 3	4 6	6 6	6 6		C[2] = 1	C	0 0	1 2	4 5	6 6	6 6		C[5] = 5
B		329		839			B[1] = 329	B		329	436	839	355	457	B[5] = 355
C	0 0	1 3	4 6	6 6	6 6		C[2]	C	0 0	1 2	4 4	6 6	6 6		C[5]
A	720	355	436	457	329	839	A[4] = 457	A	720	355	436	457	329	839	A[1] = 720
C	0 0	1 3	4 6	6 6	6 6		C[5] = 6	C	0 0	1 2	4 4	6 6	6 6		C[2] = 1
B		329		839		457	B[6] = 457	B	720	329	436	839	355	457	B[1] = 720
C	0 0	1 3	4 5	6 6	6 6		C[5]	C	0 0	0 2	4 4	6 6	6 6		C[2]

#### $\textbf{Solutions} \rightarrow \textbf{Radix sort}$

- Sort numbers based on the digits at hundred's place
- B from the previous iteration will be the A for this iteration.

A	720	329	436	839	355	457	A[6] = 457	A	720	329	436	839	355	457	A[3] = 436
C	0 0	0 2	4 4	4 5	6 6		C[4] = 4	C	0 0	0 1	3 4	4 5	5 6		C[4] = 3
B				457			B[4] = 457	B		355	436	457		839	B[3] = 436
C	0 0	0 2	3 4	4 5	6 6		C[4]	C	0 0	0 1	2 4	4 5	5 6		C[4]
${}^{A}$	720	329	436	839	355	457	A[5] = 355	A	720	329	436	839	355	457	A[2] = 329
C	0 0	0 2	3 4	4 5	6 6		C[3] = 2	C	0 0	0 1	2 4	4 5	5 6		C[3] = 1
B		355		457			B[2] = 355	B	329	355	436	457		839	B[1] = 329
C	0 0	0 1	3 4	4 5	6 6		C[3]	C	0 0	0 0	2 4	4 5	5 6		C[3]
A	720	329	436	839	355	457	A[4] = 839	A	720	329	436	839	355	457	A[1] = 720
C	0 0	0 1	3 4	4 5	6 6		C[8] = 6	C	0 0	0 0	2 4	4 5	5 6		C[7] = 5
B		355		457		839	B[6] = 839	B	329	355	436	457	720	839	B[5] = 720
C	0 0	0 1	3 4	4 5	56		C[8]	C	0 0	0 0	2 4	6 4	5 6		C[7]

#### $\textbf{Solutions} \rightarrow \textbf{Bitonic sort}$



#### $\textbf{Solutions} \rightarrow \textbf{Bitonic sort}$



#### • Invoke BITONICSORT $(A[1 \dots n], ascending)$

```
\begin{array}{l} & \text{BITONICSORT}(A[\ell \dots h], order) \\ & size \leftarrow h - \ell + 1 \\ & \text{if } size > 1 \text{ then} \\ & m \leftarrow (\ell + h)/2 \\ & \text{BITONICSORT}(A[\ell \dots m], ascending) \\ & \text{BITONICSORT}(A[m + 1 \dots h], descending) \\ & \text{BITONICMERGE}(A[\ell \dots h], order) \end{array}
```

#### Solutions $\rightarrow$ Bitonic sort

```
BITONICMERGE(A[\ell \dots h], order)
```

```
COMPARE & SWAP (A[\ell \dots h], order)
```

$$\langle \mathsf{Time, Space} \rangle = \left\langle \Theta\left(n \log^2 n\right), \Theta\left(n\right) \right\rangle$$

$$\begin{split} T(n) &= \begin{cases} \Theta\left(1\right) & \text{if } n = 1, \\ 2T(n/2) + T^{\mathsf{merge}}(n/2) & \text{if } n > 1. \end{cases} \\ T^{\mathsf{merge}}(n) &= \begin{cases} \Theta\left(1\right) & \text{if } n = 1, \\ 2T^{\mathsf{merge}}(n/2) + \Theta\left(n\right) & \text{if } n > 1. \end{cases} \end{split}$$

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