

AVL Trees

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Objectives

- To know what an *AVL tree* is
- To understand how to *rebalance* a tree using the *LL rotation*, *LR rotation*, *RR rotation*, and *RL rotation*
- To know how to design the **AVLTree** class
- To *insert* elements into an AVL tree
- To implement node *rebalancing*
- To *delete* elements from an AVL tree
- To implement and test the **AVLTree** class
- To analyze the *complexity* of search, insert, and delete operations in AVL trees

Why AVL Trees?

- The search, insertion, and deletion time for a binary search tree is dependent on the **height of the tree**
 - In the worst case, the height is $n - 1$, so worse time complexity is $O(n)$
- If a tree is *perfectly balanced*, i.e., a **complete binary tree**, its height is $\log n$ (e.g., sorting heaps)
 - So, search, insertion, and deletion time would be $O(\log n)$
- **Can we maintain a perfectly balanced tree?**
 - Yes, but it will be costly to do so
 - The compromise is to maintain a *well-balanced tree*, i.e., the heights of two subtrees for every node are about the same

What are AVL Trees?

- *AVL trees* are well-balanced binary search trees were invented by two Russian computer scientists: **Georgy Adelson-Velsky** and **Evgenii Landis** in 1962 at the Institute for Theoretical and Experimental Physics in Moscow
- In an AVL tree, the difference between the heights of two subtrees **for every node** is 0 or 1
 - Can be proved that the **maximum height** of an AVL tree is $O(\log n)$



Adelson-Velsky (left) also developed Kaissa, the first computer chess champion (1974)



Evgenii Mikhailevich Landis

Balance Factor/Left-Heavy/Right-Heavy

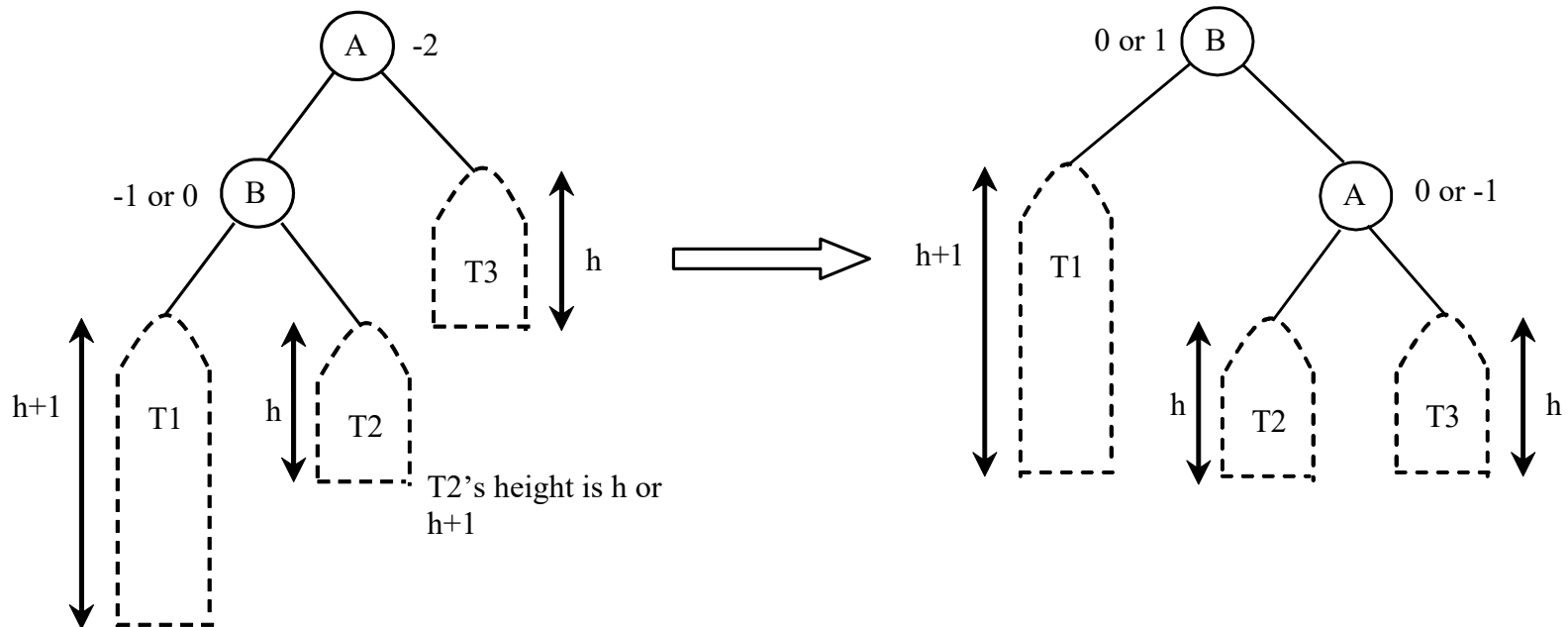
- The process for inserting or deleting an element in an AVL tree is the same as in a regular binary search tree
 - The difference is that you may have to *rebalance* the tree after an insertion or deletion operation
- The *balance factor* of a node is the height of its right subtree minus the height of its left subtree
- A node is said to be *balanced* if its balance factor is -1, 0, or 1
 - A node is said to be *left-heavy* if its balance factor is -1
 - A node is said to be *right-heavy* if its balance factor is +1

Balancing Trees

- If a node is **not balanced** (i.e., its balance factor is not -1, 0, or 1) after an insertion or deletion operation, you need to rebalance it:
 - The process of rebalancing a node is called a *rotation*
- There are four possible rotations:
 - *LL rotation (left-heavy left-heavy rotation)*
 - *RR rotation (right-heavy right-heavy rotation)*
 - *LR rotation (left-heavy right-heavy rotation)*
 - *RL rotation (right-heavy left-heavy rotation)*

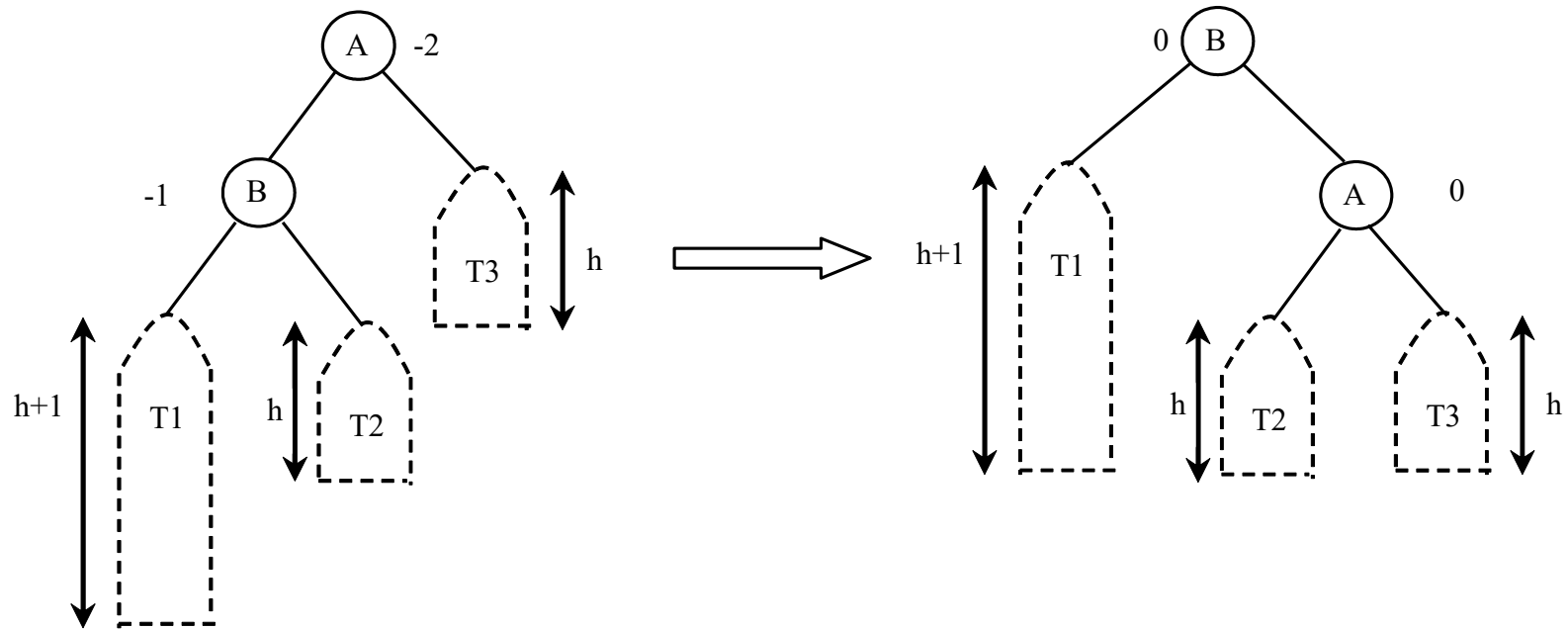
LL imbalance and LL rotation

- **LL Rotation:** An *left-heavy, left-heavy imbalance* occurs at a node **A** if **A** has a balance factor **-2 (left-heavy)** and its left child **B** has a balance factor **-1 (left-heavy)** or **0**
 - This type of imbalance can be fixed by performing a single **right rotation** at **A**:



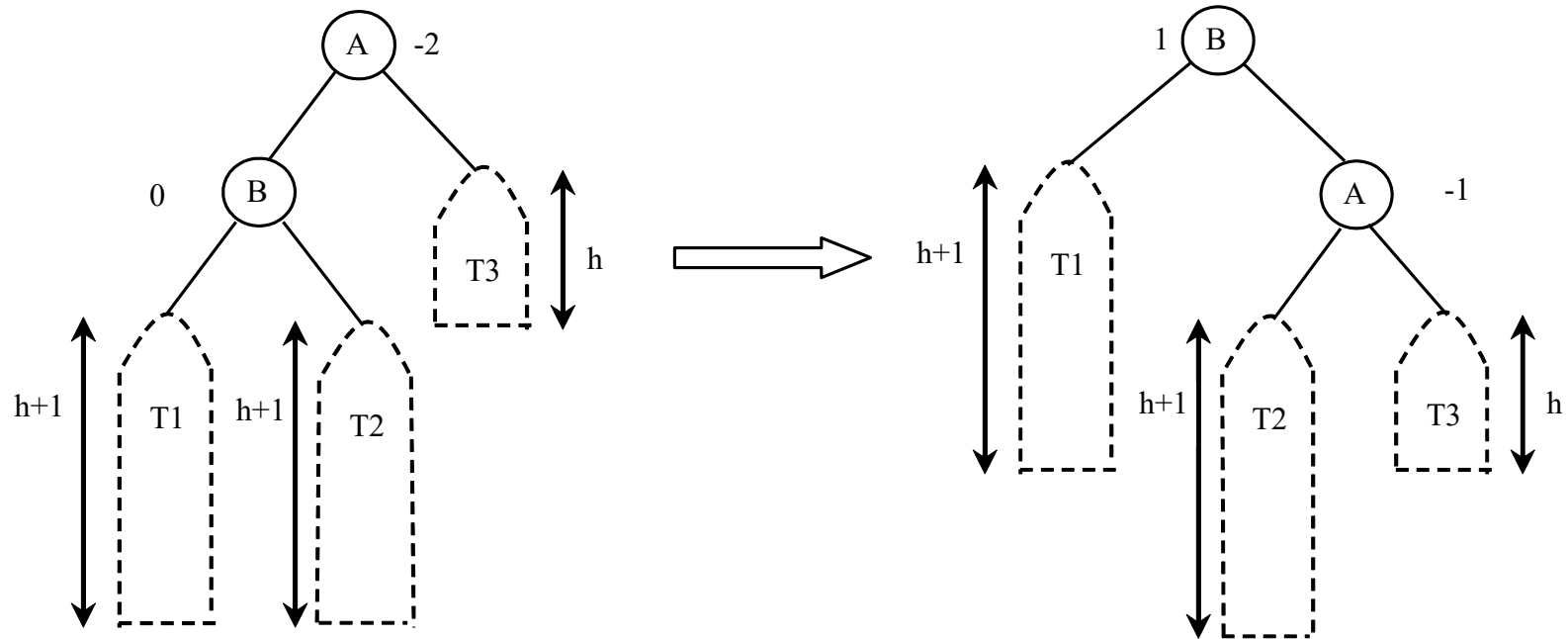
LL imbalance and LL rotation

- **LL case 1:** If the left child **B** has a balance factor **-1**



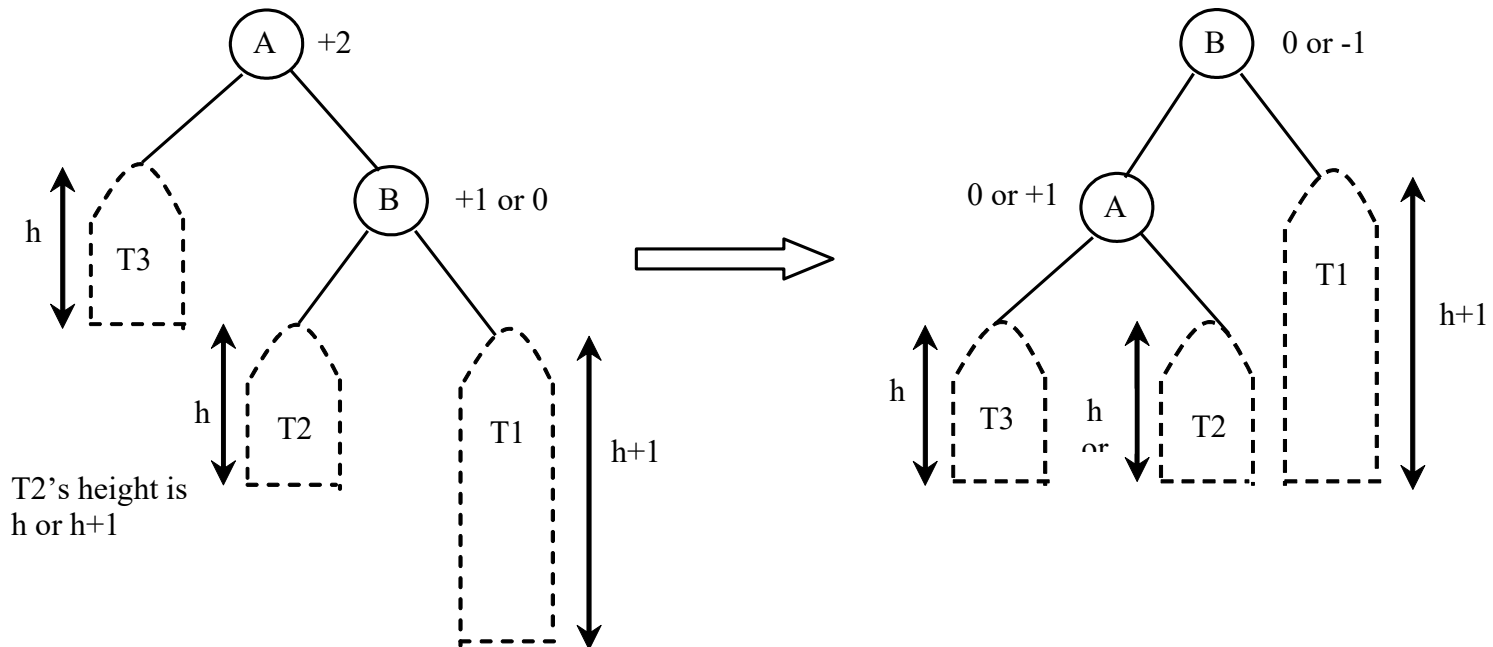
LL imbalance and LL rotation

- **LL case 2:** If the left child **B** has a balance factor of **0**



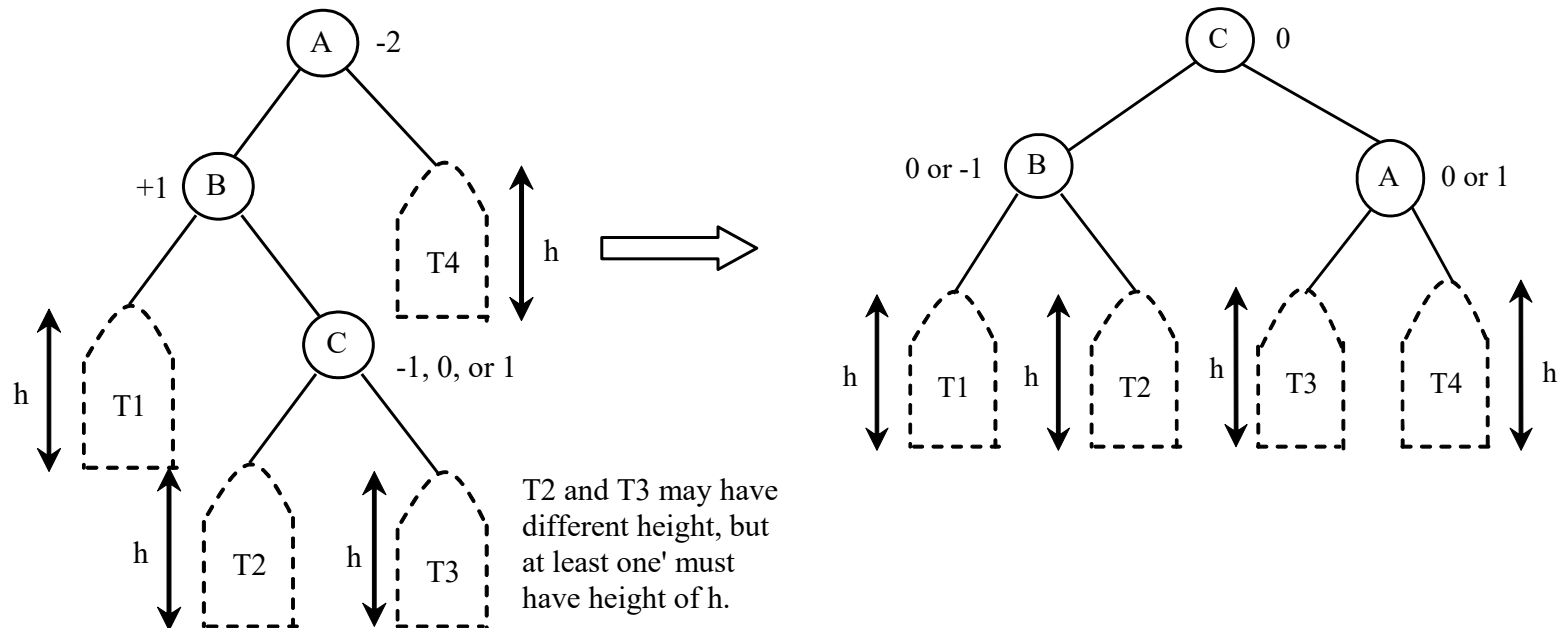
RR imbalance and RR rotation

- **RR Rotation:** An *RR imbalance* occurs at a node **A** if **A** has a balance factor **+2 (right-heavy)** and a right child **B** has a balance factor **+1 (right-heavy)** or **0**
 - This type of imbalance can be fixed by performing a single **left rotation** at **A**:



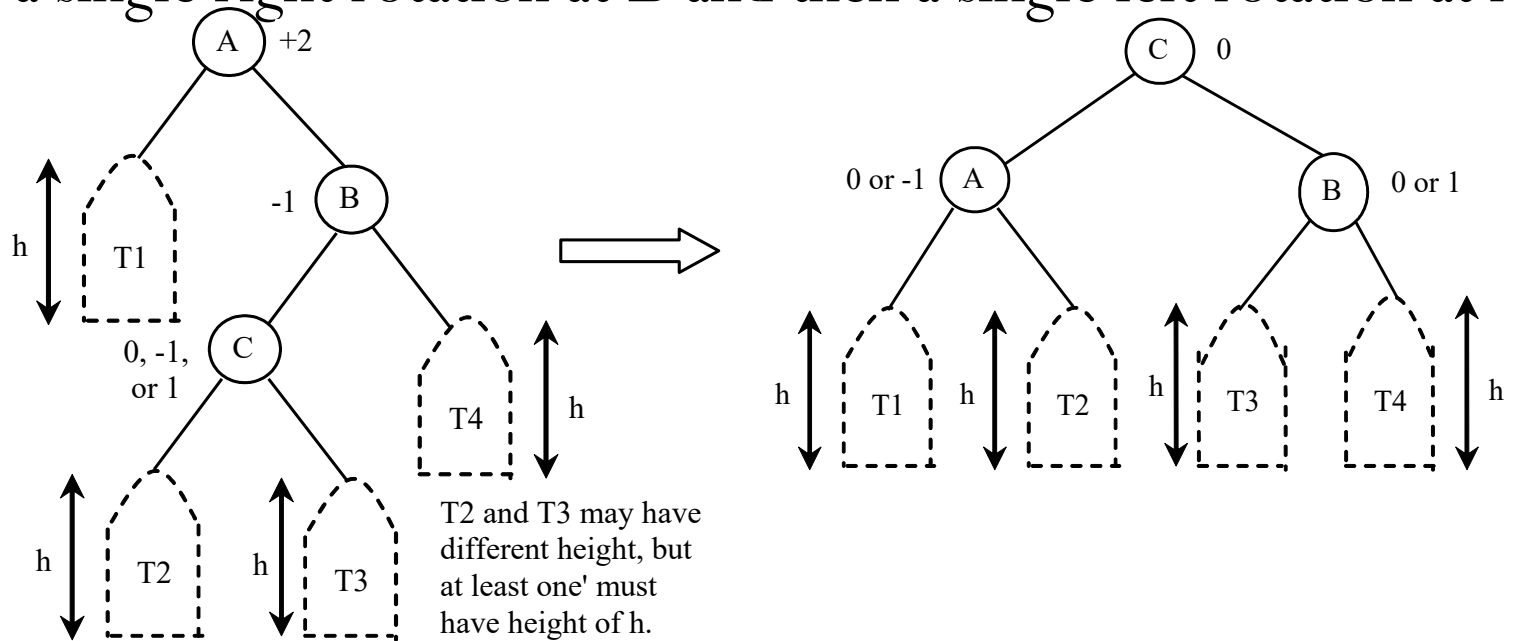
LR imbalance and LR rotation

- **LR Rotation:** An **LR imbalance** occurs at a node **A** if **A** has a balance factor **-2 (left-heavy)** and a left child **B** has a balance factor **+1 (right-heavy)**
 - Assume **B**'s right child is **C**
 - This type of imbalance can be fixed by performing a double rotation: first a single left rotation at **B** and then a single right rotation at **A**

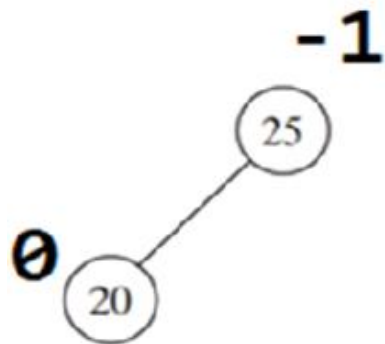


RL imbalance and RL rotation

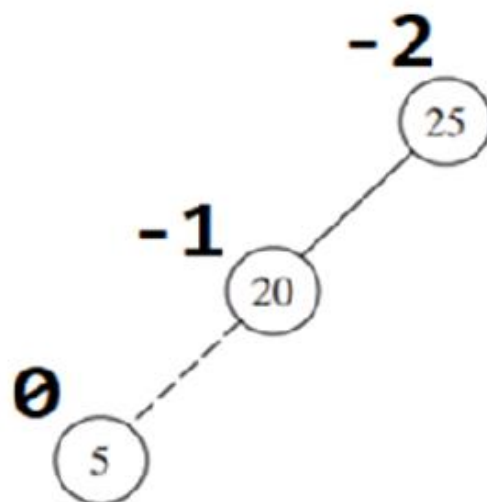
- **RL Rotation:** An **RL imbalance** occurs at a node **A** if **A** has a balance factor **+2 (right-heavy)** and a right child **B** has a balance factor **-1 (left-heavy)**
 - Assume B's left child is C
 - This type of imbalance can be fixed by performing a double rotation: first a single right rotation at **B** and then a single left rotation at **A**



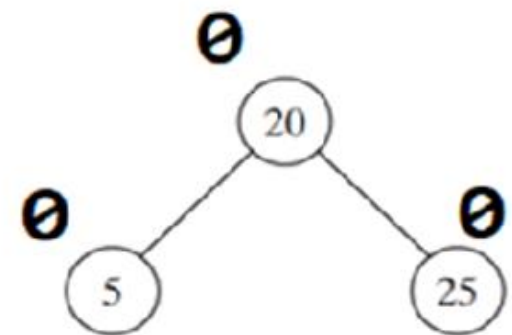
Insert 25, 20



Insert 5

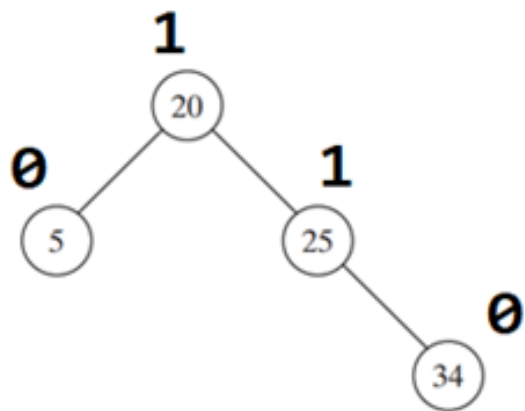


Need LL rotation
at node 25

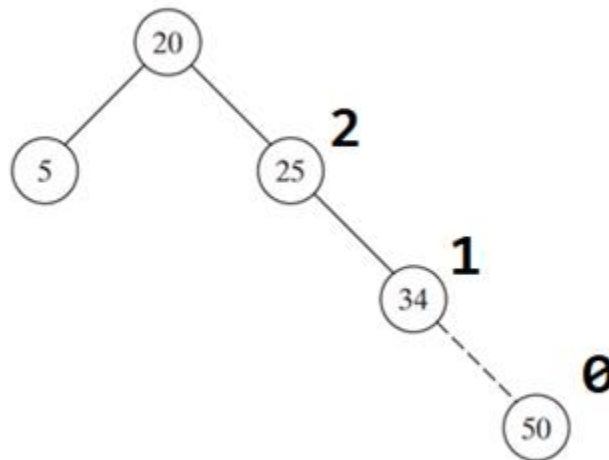


Balanced

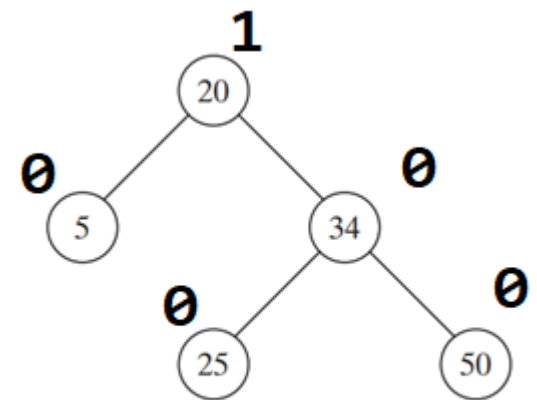
Insert 34



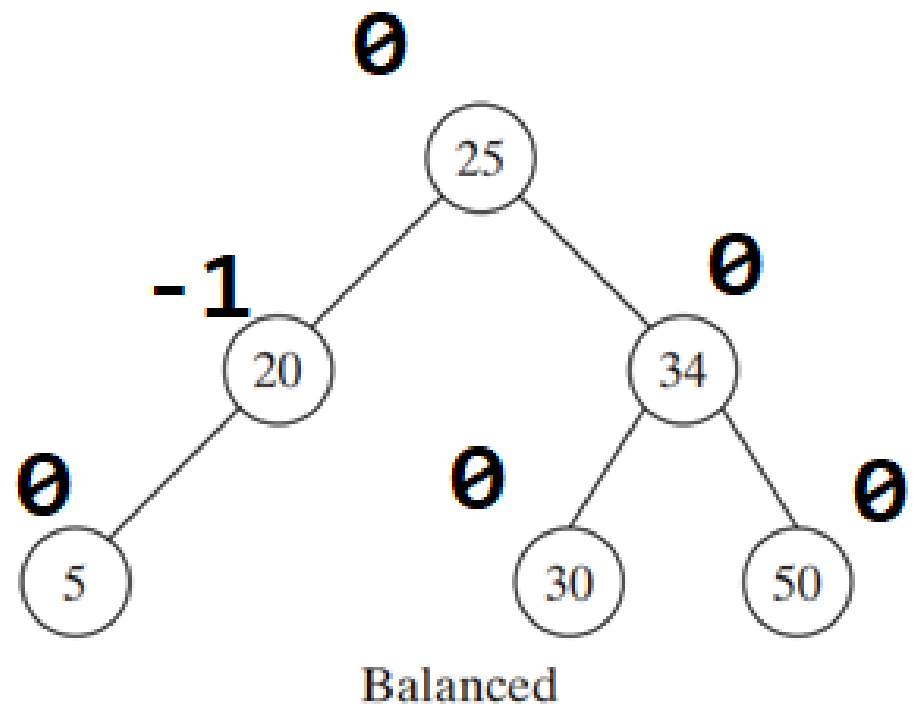
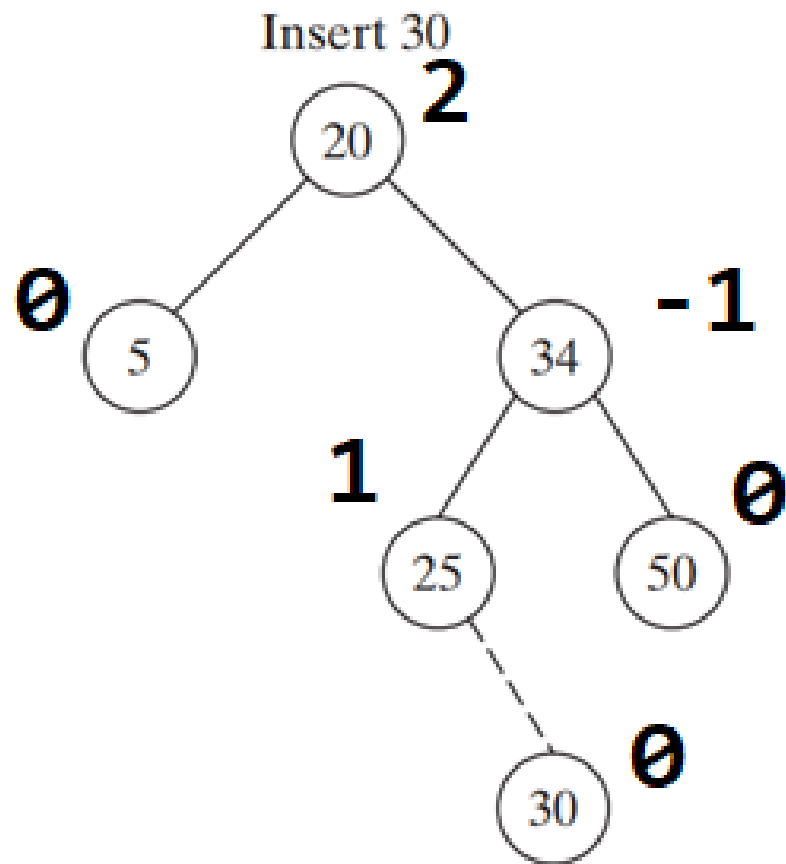
Insert 50



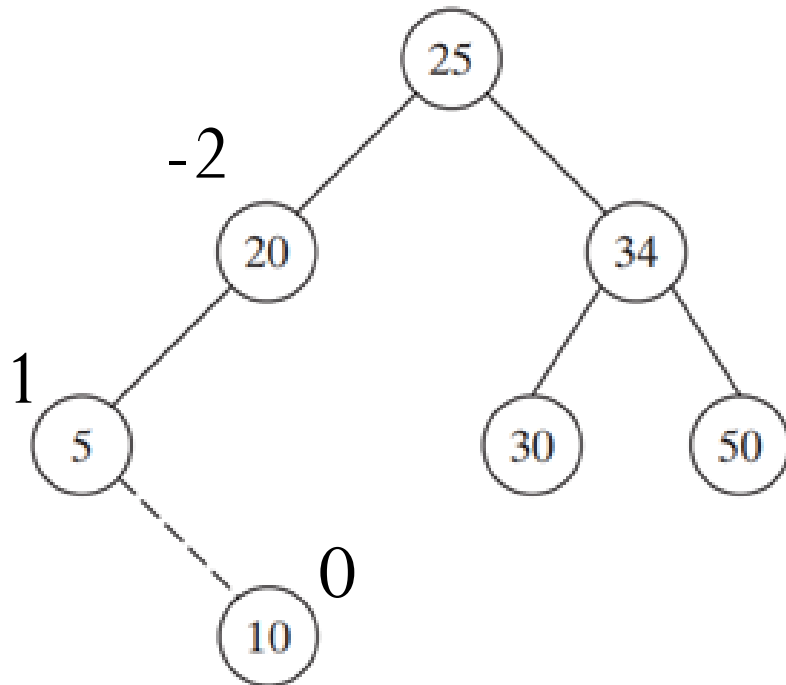
Need RR rotation
at node 25



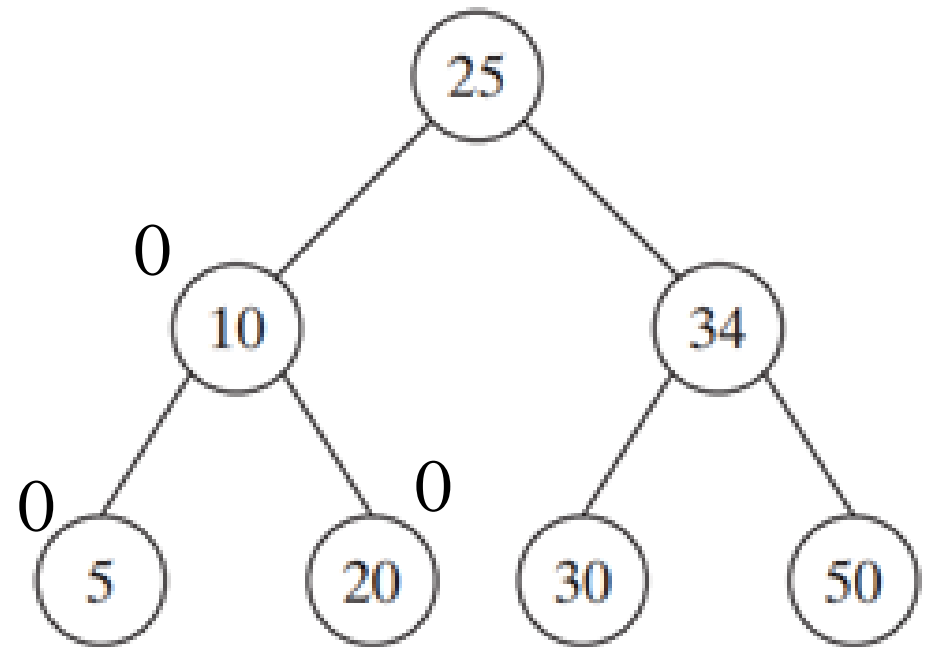
Balanced



Insert 10

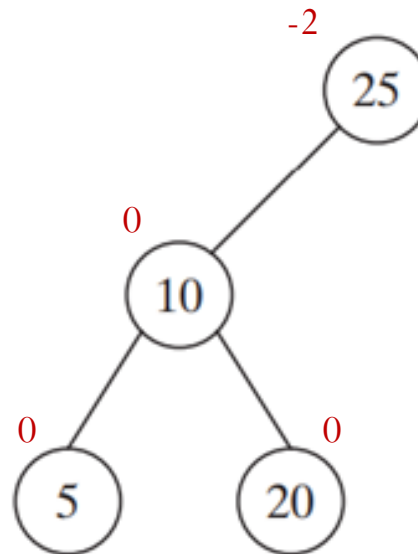
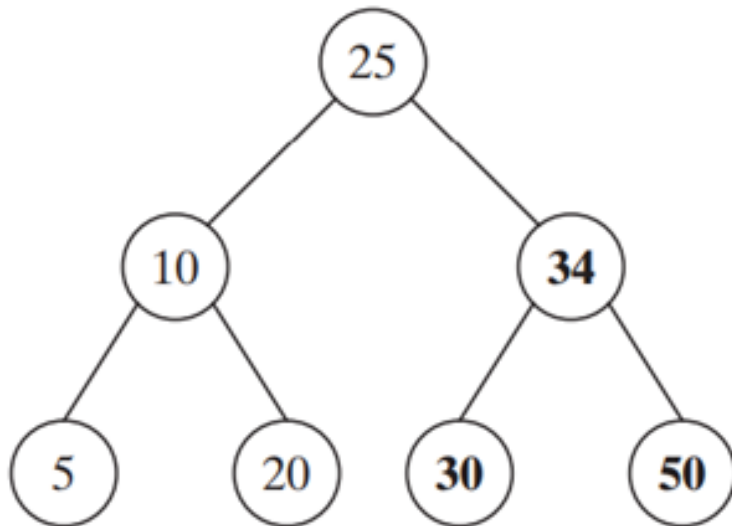


LR rotation at
node 20

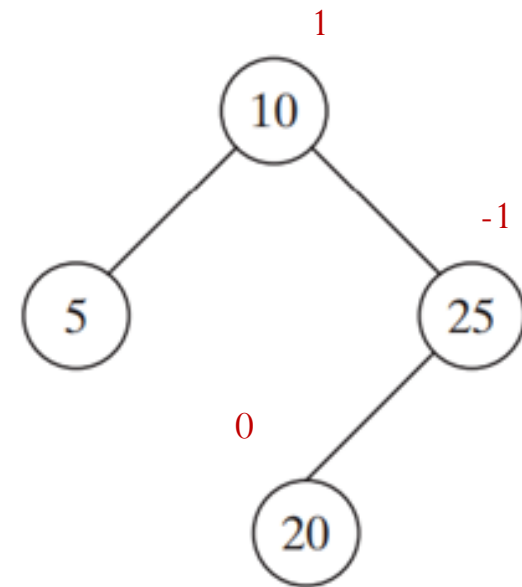


Balanced

Delete 34, 30, 50

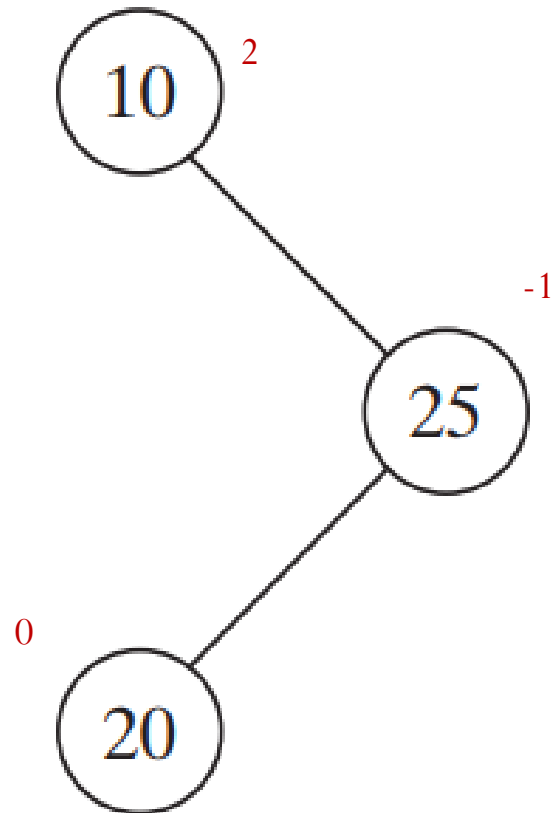


LL rotation
at node 25

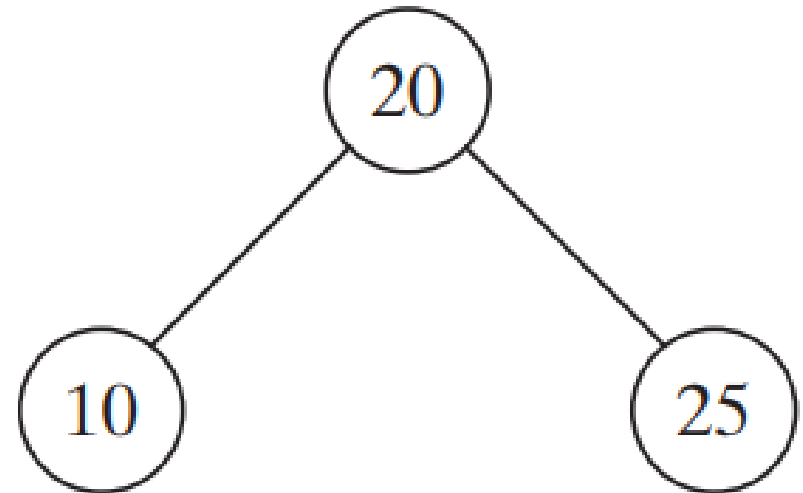


Balanced

After 5 is deleted



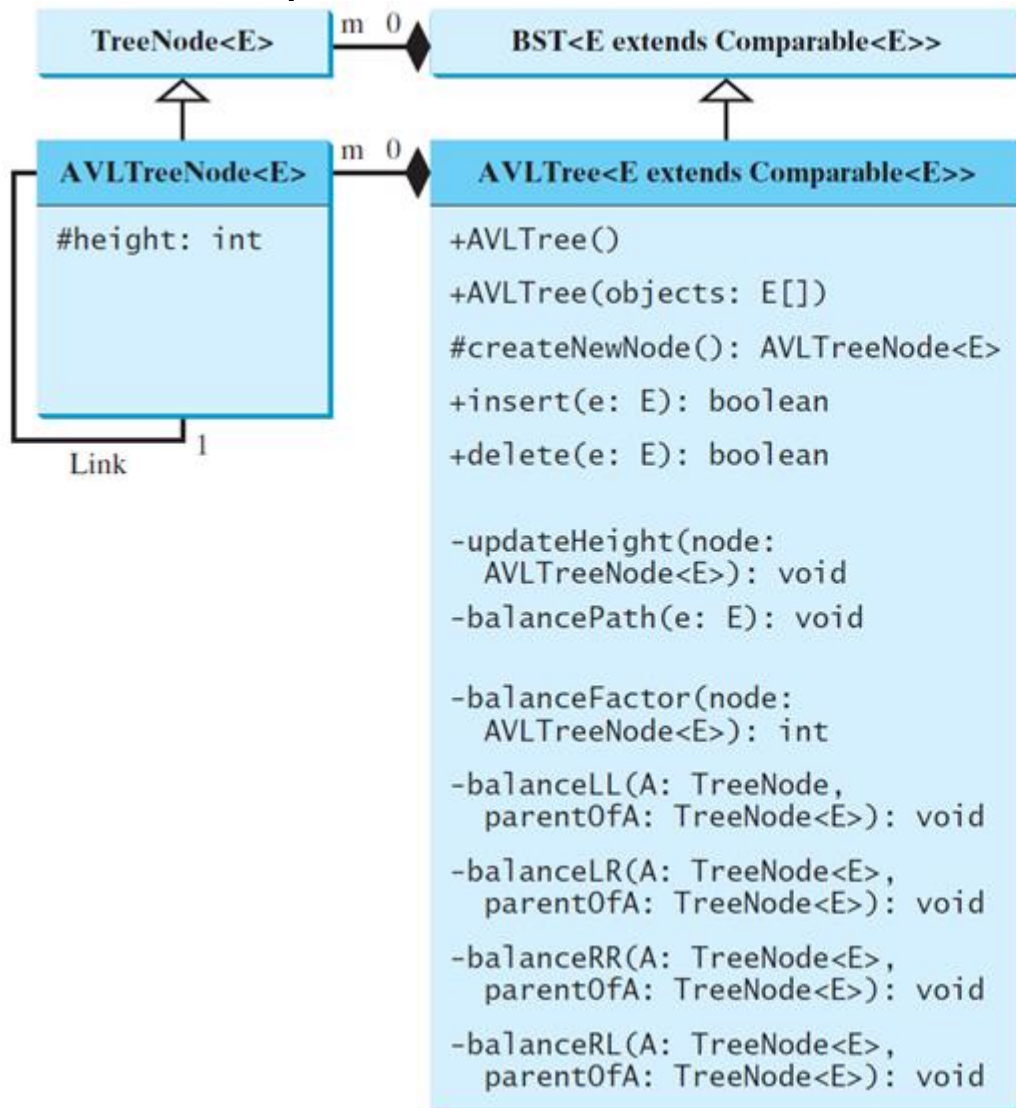
RL rotation at 10



Balanced

Designing Classes for AVL Trees

- An AVL is a binary search tree, so we can define the **AVLTree** class to extend the **BST** class



Creates an empty AVL tree.

Creates an AVL tree from an array of objects.

Overrides this method to create an **AVLTreeNode**.

Returns true if the element is added successfully.

Returns true if the element is removed from the tree successfully.

Resets the height of the specified node.

Balances the nodes in the path from the node for the element to the root if needed.

Returns the balance factor of the node.

Performs LL balance.

Performs LR balance.

Performs RR balance.

Performs RL balance.

```

public class AVLTree<E extends Comparable<E>> extends BST<E> {
    /** AVLTreeNode is TreeNode plus height */
    protected static class AVLTreeNode<E extends Comparable<E>>
        extends BST.TreeNode<E> {
        protected int height = 0; // New data field
        public AVLTreeNode(E o) {
            super(o);
        }
    }

    @Override /** Override createNewNode to create an AVLTreeNode */
    protected AVLTreeNode<E> createNewNode(E e) {
        return new AVLTreeNode<E>(e);
    }

    /** Create a default AVL tree */
    public AVLTree() {
    }

    /** Create an AVL tree from an array of objects */
    public AVLTree(E[] objects) {
        super(objects);
    }
}

```

```
@Override /** Insert an element and rebalance if necessary */
public boolean insert(E e) {
    boolean successful = super.insert(e);
    if (!successful)
        return false; // e is already in the tree
    else {
        balancePath(e); // Balance from e to the root if necessary
    }
    return true; // e is inserted
}
```

```

/** Balance the nodes in the path from the specified
 * node to the root if necessary
 */
private void balancePath(E e) {
    java.util.ArrayList<TreeNode<E>> path = path(e); // from root to e
    for (int i = path.size() - 1; i >= 0; i--) {
        AVLTreeNode<E> A = (AVLTreeNode<E>) (path.get(i));
        updateHeight(A);
        AVLTreeNode<E> parentOfA = (A == root) ? null :
            (AVLTreeNode<E>) (path.get(i - 1));
        switch(balanceFactor(A)) {
            case -2:
                if (balanceFactor((AVLTreeNode<E>)A.left) <= 0) {
                    balanceLL(A, parentOfA); // Perform LL rotation
                } else {
                    balanceLR(A, parentOfA); // Perform LR rotation
                }
                break;
            case +2:
                if (balanceFactor((AVLTreeNode<E>)A.right) >= 0) {
                    balanceRR(A, parentOfA); // Perform RR rotation
                } else {
                    balanceRL(A, parentOfA); // Perform RL rotation
                }
            }
        }
    }
}

```

```

/** Update the height of a specified node */
private void updateHeight(AVLTreeNode<E> node) {
    if (node.left == null && node.right == null) // node is a leaf
        node.height = 0;
    else if (node.left == null) // node has no left subtree
        node.height = 1 + ((AVLTreeNode<E>) (node.right)).height;
    else if (node.right == null) // node has no right subtree
        node.height = 1 + ((AVLTreeNode<E>) (node.left)).height;
    else
        node.height = 1 +
            Math.max(((AVLTreeNode<E>) (node.right)).height,
                ((AVLTreeNode<E>) (node.left)).height);
}

```

```

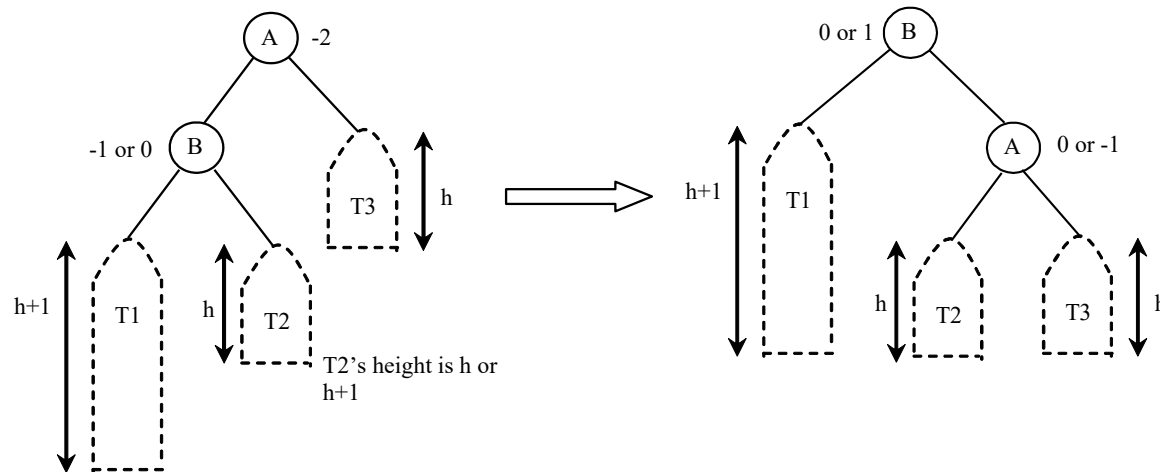
/** Return the balance factor of the node */
private int balanceFactor(AVLTreeNode<E> node) {
    if (node.right == null) // node has no right subtree
        return -node.height;
    else if (node.left == null) // node has no left subtree
        return +node.height;
    else
        return ((AVLTreeNode<E>) node.right).height -
            ((AVLTreeNode<E>) node.left).height;
}

```

```

/** Balance LL */
private void balanceLL(TreeNode<E> A, TreeNode<E> parentOfA) {
    TreeNode<E> B = A.left; // A is left-heavy and B is left-heavy
    if (A == root) {
        root = B;
    } else {
        if (parentOfA.left == A) {
            parentOfA.left = B;
        } else {
            parentOfA.right = B;
        }
    }
    A.left = B.right; // Make T2 the left subtree of A
    B.right = A; // Make A the left child of B
    updateHeight((AVLTreeNode<E>)A);
    updateHeight((AVLTreeNode<E>)B);
}

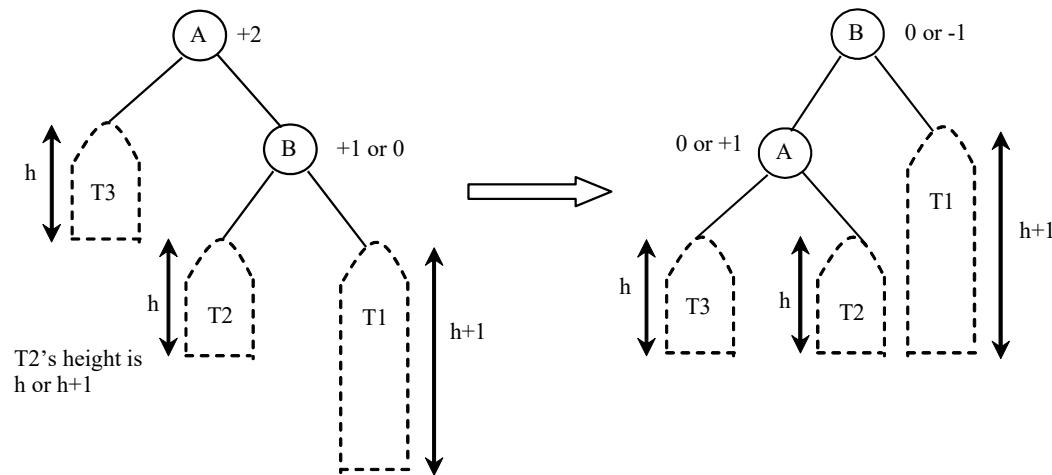
```




```

/** Balance RR */
private void balanceRR(TreeNode<E> A, TreeNode<E> parentOfA) {
    TreeNode<E> B = A.right; // A is right-heavy and B is right-heavy
    if (A == root) {
        root = B;
    } else {
        if (parentOfA.left == A) {
            parentOfA.left = B;
        } else {
            parentOfA.right = B;
        }
    }
    A.right = B.left; // Make T2 the right subtree of A
    B.left = A;
    updateHeight((AVLTreeNode<E>)A);
    updateHeight((AVLTreeNode<E>)B);
}

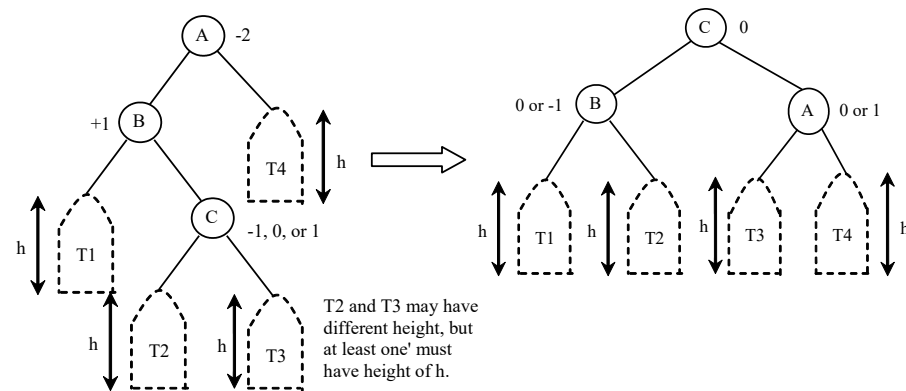
```



```

/** Balance LR */
private void balanceLR(TreeNode<E> A, TreeNode<E> parentOfA) {
    TreeNode<E> B = A.left; // we know that A is left-heavy
    TreeNode<E> C = B.right; // we know that B is right-heavy
    if (A == root) {
        root = C;
    } else {
        if (parentOfA.left == A) {
            parentOfA.left = C;
        } else {
            parentOfA.right = C;
        }
    }
    A.left = C.right; // Make T3 the left subtree of A
    B.right = C.left; // Make T2 the right subtree of B
    C.left = B;
    C.right = A;
    // Adjust heights
    updateHeight((AVLTreeNode<E>) A);
    updateHeight((AVLTreeNode<E>) B);
    updateHeight((AVLTreeNode<E>) C);
}

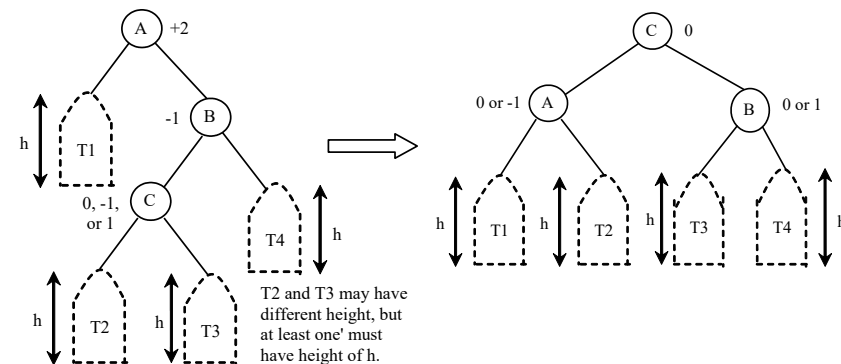
```



```

/** Balance RL */
private void balanceRL(TreeNode<E> A, TreeNode<E> parentOfA) {
    TreeNode<E> B = A.right; // we know that A is right-heavy
    TreeNode<E> C = B.left; // we know that B is left-heavy
    if (A == root) {
        root = C;
    } else {
        if (parentOfA.left == A) {
            parentOfA.left = C;
        } else {
            parentOfA.right = C;
        }
    }
    A.right = C.left; // Make T2 the right subtree of A
    B.left = C.right; // Make T3 the left subtree of B
    C.left = A;
    C.right = B;
    // Adjust heights
    updateHeight((AVLTreeNode<E>) A);
    updateHeight((AVLTreeNode<E>) B);
    updateHeight((AVLTreeNode<E>) C);
}

```



```

@Override /** Delete an element from the binary tree.
 * Return true if the element is deleted successfully
 * Return false if the element is not in the tree */
public boolean delete(E element) {
    if (root == null)
        return false; // Element is not in the tree
    // Locate the node to be deleted and also locate its parent node
    TreeNode<E> parent = null;
    TreeNode<E> current = root;
    while (current != null) {
        if (element.compareTo(current.element) < 0) {
            parent = current;
            current = current.left;
        } else if (element.compareTo(current.element) > 0) {
            parent = current;
            current = current.right;
        } else
            break; // Element is in the tree pointed by current
    }
    if (current == null)
        return false; // Element is not in the tree
    // Case 1: current has no left children
    if (current.left == null) {
        // Connect the parent with the right child of the current node
        if (parent == null) {
            root = current.right;
        }
    }
}

```

```

else {
    if (element.compareTo(parent.element) < 0)
        parent.left = current.right;
    else
        parent.right = current.right;
    // Balance the tree if necessary
    balancePath(parent.element);
}
} else {
    // Case 2: The current node has a left child
    // Locate the rightmost node in the left subtree of
    // the current node and also its parent
    TreeNode<E> parentOfRightMost = current;
    TreeNode<E> rightMost = current.left;
    while (rightMost.right != null) {
        parentOfRightMost = rightMost;
        rightMost = rightMost.right; // Keep going to the right
    }
    // Replace the element in current by the element in rightMost
    current.element = rightMost.element;
    // Eliminate rightmost node
    if (parentOfRightMost.right == rightMost)
        parentOfRightMost.right = rightMost.left;
    else
        // Special case: parentOfRightMost is current
        parentOfRightMost.left = rightMost.left;
}

```

```
    // Balance the tree if necessary  
    balancePath(parentOfRightMost.element);  
}  
size--;  
return true; // Element deleted  
}  
}
```

```

public class TestAVLTree {
    public static void main(String[] args) {
        // Create an AVL tree
        AVLTree<Integer> tree = new AVLTree<>(new Integer[]{25, 20, 5});
        System.out.print("After inserting 25, 20, 5:");
        printTree(tree);

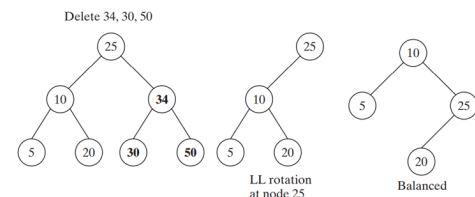
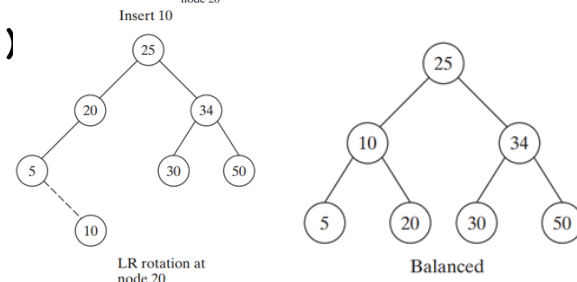
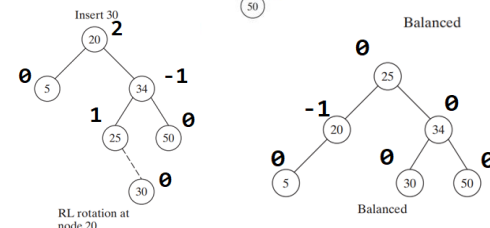
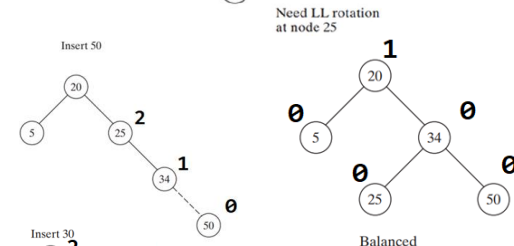
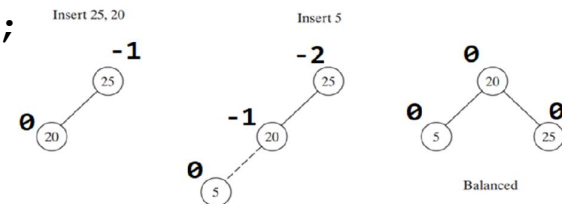
        tree.insert(34);
        tree.insert(50);
        System.out.print("\nAfter inserting 34, 50:");
        printTree(tree);

        tree.insert(30);
        System.out.print("\nAfter inserting 30");
        printTree(tree);

        tree.insert(10);
        System.out.print("\nAfter inserting 10");
        printTree(tree);

        tree.delete(34);
        tree.delete(30);
        tree.delete(50);
        System.out.print("\nAfter removing 34, 30, 50:");
        printTree(tree);
    }
}

```

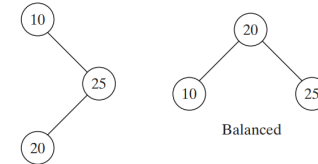


```

tree.delete(5);
System.out.print("\nAfter removing 5:");
printTree(tree);

```

After 5 is deleted



RL rotation at 10

```

System.out.print("\nTraverse the elements in the tree: ");
for (int e: tree) { // inorder: 10 20 25
    System.out.print(e + " ");
}
}

```

```

public static void printTree(BST tree) {
    // Traverse tree
    System.out.print("\nPreorder: ");
    tree.preorder();
    System.out.print("\nInorder (sorted): ");
    tree.inorder();
    System.out.print("\nPostorder: ");
    tree.postorder();
    System.out.print("\nThe number of nodes is " + tree.getSize());
    System.out.println();
}
}

```


After inserting 25, 20, 5:

Preorder: 20 5 25

Inorder (sorted): 5 20 25

Postorder: 5 25 20

The number of nodes is 3

After inserting 34, 50:

Preorder: 20 5 34 25 50

Inorder (sorted): 5 20 25 34 50

Postorder: 5 25 50 34 20

The number of nodes is 5

After inserting 30

Preorder: 25 20 5 34 30 50

Inorder (sorted): 5 20 25 30 34 50

Postorder: 5 20 30 50 34 25

The number of nodes is 6

After inserting 10

Preorder: 25 10 5 20 34 30 50

Inorder (sorted): 5 10 20 25 30 34 50

Postorder: 5 20 10 30 50 34 25

The number of nodes is 7

After removing 34, 30, 50:

Preorder: 10 5 25 20

Inorder (sorted): 5 10 20 25

Postorder: 5 20 25 10

The number of nodes is 4

After removing 5:

Preorder: 20 10 25

Inorder (sorted): 10 20 25

Postorder: 10 25 20

The number of nodes is 3

Traverse the elements in the tree:

10 20 25

AVL Tree Time Complexity Analysis

- Let $G(h)$ denote the minimum number of the nodes in an AVL tree with height h
 - $G(1) = 1$
 - $G(2) = 2$
 - The minimum number of nodes in an AVL tree with height $h > 2$ must have two minimum subtrees: one with height $h-1$ and the other with height $h-2$
 - Thus, $G(h) = G(h - 1) + G(h - 2) + 1$
 - A Fibonacci number at index i can be described using the recurrence relation: $F(i) = F(i - 1) + F(i - 2)$
 - Therefore, the function $G(h)$ is essentially the same as $F(i)$
 - It can be proven that $h < 1.4405 \log(n + 2) - 1.3277$ where n is the number of nodes in the tree
 - Hence, the height of an AVL tree is $O(\log n)$

AVL Tree Time Complexity Analysis

- The search, insert, and delete methods involve only the nodes along a single path in the tree
- The **updateHeight** and **balanceFactor** methods are executed in a constant time for each node in the path
- The **balancePath** method is executed in a constant time for a node in the path
- Thus, the time complexity for the search, insert, and delete methods is **$O(\log n)$**