

Introduction to the Discrete Fourier Transform



Lucas J. van Vliet
www.ph.tn.tudelft.nl/~lucas



TNW: Faculty of Applied Sciences
 IST: Imaging Science and technology
 PH: Pattern Recognition Group

Linear Shift Invariant System

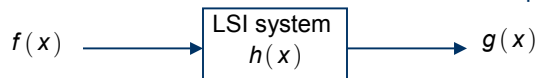


Pattern Recognition Group

A discrete image can be decomposed into a weighted field of equi-spaced impulses.

$$f(x) = \sum_{n=-\infty}^{+\infty} f(n) \delta(x - n)$$

impulse at position n
 amplitude at position n



$\delta(x)$ → $h(x)$ $h(x)$ = impulse response or Point Spread Function (PSF)

$a \delta(x)$ → linear → $a h(x)$

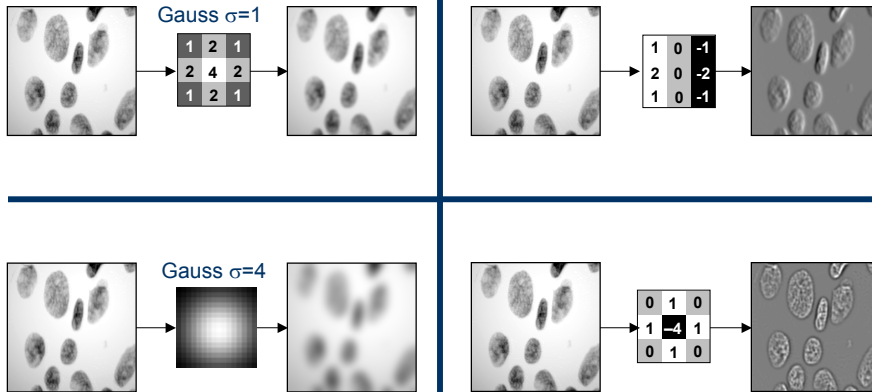
$\delta(x - n\Delta)$ → shift inv. → $h(x - n)$

$f(x) = \sum_{n=-\infty}^{+\infty} f(n\Delta) \delta(x - n\Delta)$ → superposition → $g(x) = \sum_{n=-\infty}^{+\infty} f(n) h(x - n) \equiv f(x) * h(x)$

Image g is the result of a **convolution** between image f and h

Convolution revisited

- Convolution: Replace the central pixel by a weighted sum of the gray-values inside an $n \times n$ neighborhood. Impulse response $h(x)$ is the filter.



Eigenfunction of LSI systems

- Eigenfunctions of LSI systems are complex exponentials $\varphi(x)$.

$$\varphi_\omega(x) = e^{j\omega x} = \cos \omega x + j \sin \omega x$$

$$\begin{aligned} \varphi_{\omega=1}(x) &= \cos x + j \sin x \\ \varphi_{\omega=2}(x) &= \cos 2x + j \sin 2x \\ \varphi_{\omega=3}(x) &= \cos 3x + j \sin 3x \end{aligned}$$

$$\varphi_\omega(x) \xrightarrow{\text{LSI system } h(x)} K \varphi_\omega(x) = \sum_{n=-\infty}^{+\infty} \varphi(n) h(x-n)$$

$$e^{j\omega x} \xrightarrow{\text{LSI system } h(x)} g(x) = \sum_{n=-\infty}^{+\infty} e^{j\omega n} h(x-n) = e^{j\omega x} \underbrace{\sum_{n=-\infty}^{+\infty} h(m) e^{-j\omega m}}_{H(\omega)}$$

$$= e^{j\omega x} H(\omega)$$

- An LSI system multiplies each eigenfunction $\exp(j\omega x)$ by its corresponding eigenvalue $H(\omega)$.
- The Fourier transform decomposes an image into a weighted set of complex exponentials of varying frequency ω : "The Fourier spectrum"
- The system function $H(\omega)$ is the Fourier Transform of $h(x)$

Convolution property

- A convolution between an image $f(x)$ and an impulse response $h(x)$ in space, corresponds to a multiplication of the Fourier spectra $F(\omega)$ and $H(\omega)$ in the Fourier domain.

$$f(x) \longrightarrow \boxed{\text{LSI system } h(x)} \longrightarrow f(x) * h(x) = \sum_{n=-\infty}^{+\infty} f(n\Delta)h(x - n\Delta)$$

$$\begin{aligned} \underline{F\{f(x) * h(x)\}} &= \sum_{x=-\infty}^{+\infty} \left[\sum_{n=-\infty}^{+\infty} f(n)h(x-n) \right] e^{-j\omega x} \\ &= \underbrace{\sum_{n=-\infty}^{+\infty} f(n)e^{-j\omega n}}_{F(\omega)} \underbrace{\sum_{x=-\infty}^{+\infty} h(m)e^{-j\omega m}}_{H(\omega)} \\ &= \underline{F(\omega)H(\omega)} \end{aligned}$$

Gaussian derivatives

- How to compute a derivative in digital space?

$$\boxed{f_x[x,y] \triangleq \frac{\partial}{\partial x} f[x,y] = ?}$$

- Introduce (Gaussian) scale

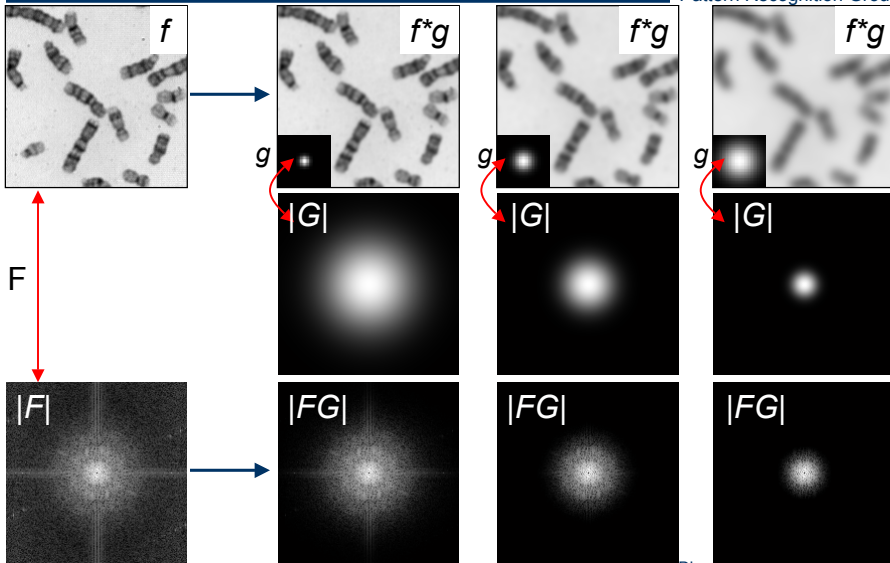
$$\begin{aligned} f^{(\sigma)}[x,y] &= f^{(0)}[x,y] \otimes g^{(\sigma)}[x,y] \\ f^{(\sigma=5)}[x,y] &= f^{(\sigma=3)}[x,y] \otimes g^{(\sigma=4)}[x,y] \end{aligned}$$

- Derivative at scale σ is computed by convolution of the discrete image $f[x,y]$ with discrete Gaussian derivative

$$\boxed{f_x^{(\sigma)}[x,y] = f^{(0)}[x,y] \otimes g_x^{(\sigma)}[x,y]}$$

- Note that the Gaussian function is known analytically, compute the derivative(s), and then sample to produce a discrete filter. The sampling of the Gaussian should be high enough, i.e. $\sigma > 0.9$ pixels

Fourier filters: Gaussian



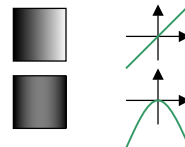
Gaussian derivative filters

- In continuous space: the derivative operator corresponds to multiplication of the Fourier spectrum with $j\omega$

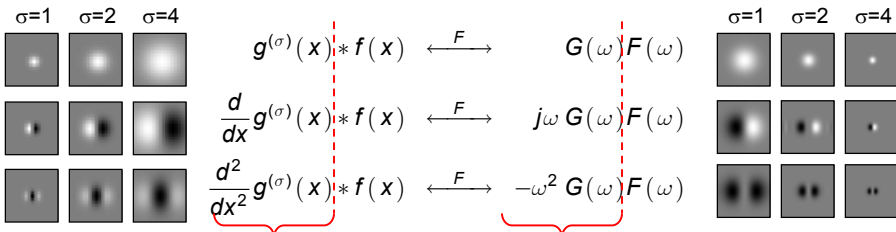
$$f(x) \xrightarrow{F} F(\omega)$$

$$\frac{d}{dx} f(x) \xrightarrow{F} j\omega F(\omega)$$

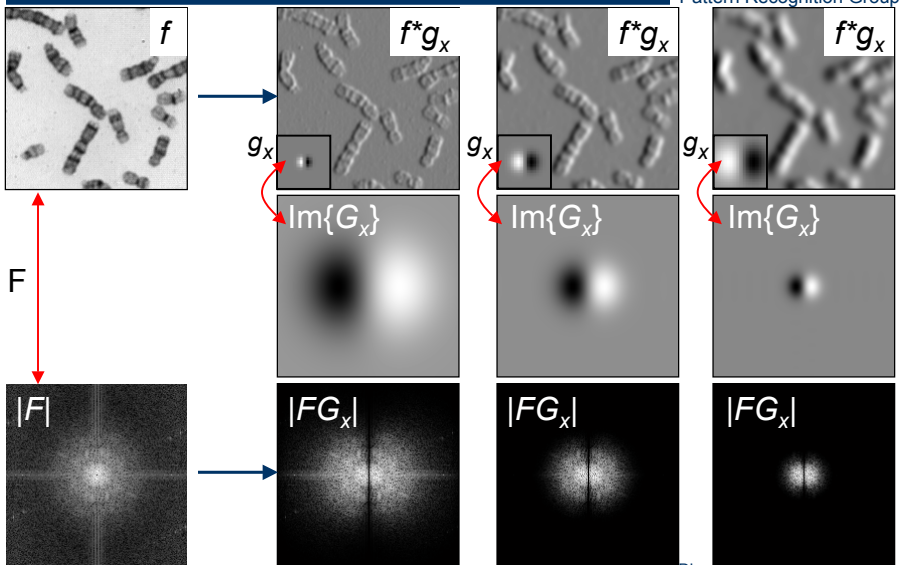
$$\frac{d^2}{dx^2} f(x) \xrightarrow{F} -\omega^2 F(\omega)$$



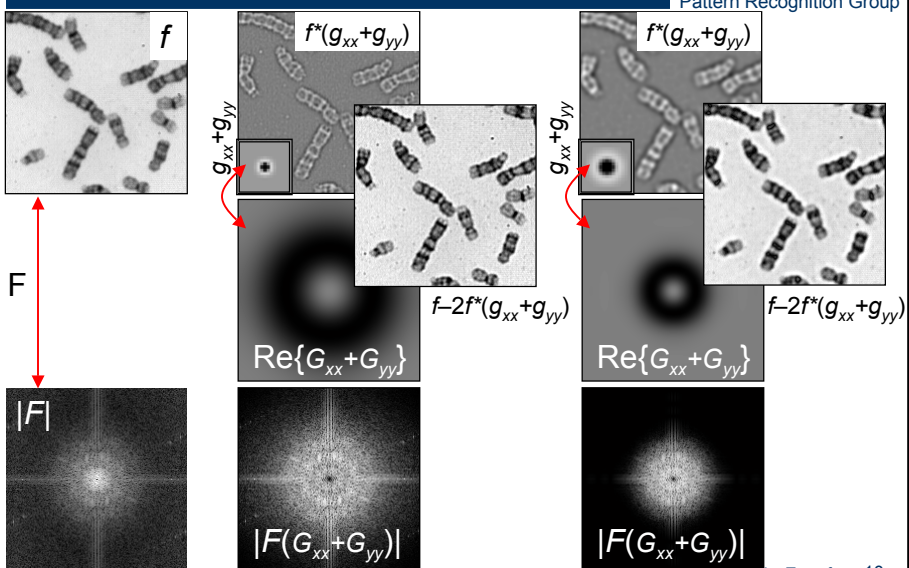
- In discrete space: combine the derivative operator with Gaussian smoothing



Fourier: Gaussian derivative



Fourier: Laplace & sharpening



Discrete Fourier Transform

- Each image can be decomposed in weighted sum of complex exponentials (sines and cosines) of frequency f and angle ϕ . (or two frequency components u and v)

image size $N \times N$

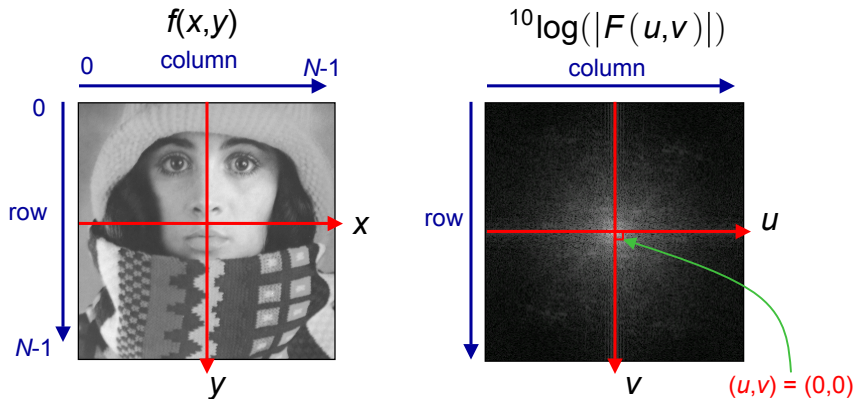
$$g(x,y) = \frac{1}{N} \sum_{u=0}^{N-1} \sum_{v=0}^{N-1} G(u,v) e^{j\frac{2\pi}{N}(ux+vy)}$$

$$G(u,v) = \frac{1}{N} \sum_{x=0}^{N-1} \sum_{y=0}^{N-1} g(x,y) e^{-j\frac{2\pi}{N}(ux+vy)}$$

- For real-valued images: $\text{Ev}\{g(x,y)\} \xrightarrow{F} \text{Re}\{G(u,v)\}$
 $\text{Od}\{g(x,y)\} \xrightarrow{F} j \text{Im}\{G(u,v)\}$

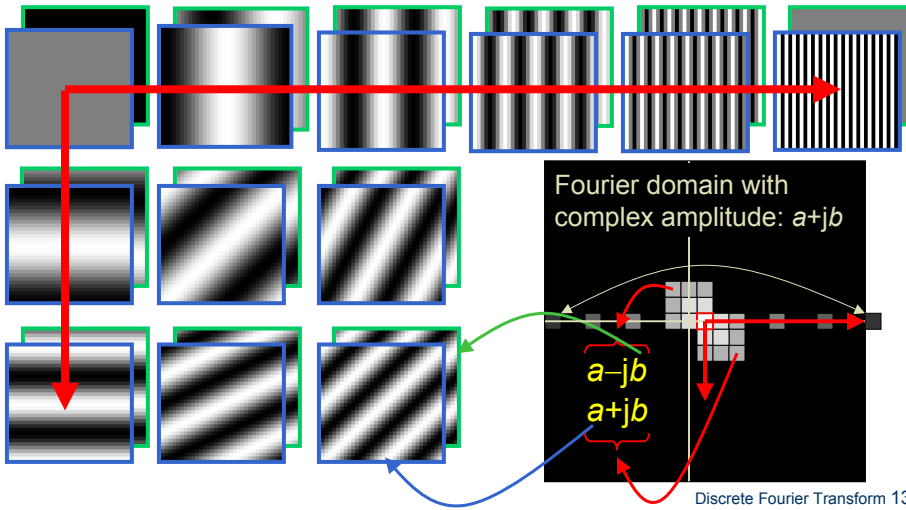
Fourier spectrum

- $F(u,v)$ is the complex amplitude of the eigenfunction $\exp(j(2\pi/N)(ux+vy))$
 Note that $\exp(j(2\pi/N)(ux+vy)) = \cos((2\pi/N)(ux+vy)) + j \sin((2\pi/N)(ux+vy))$
- Standard display is the logarithm of the magnitude: $\log(|F(u,v)|)$

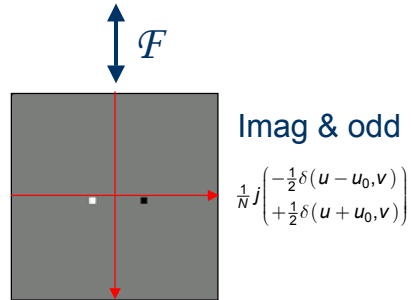
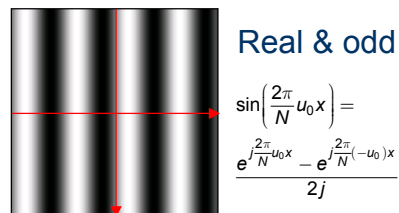
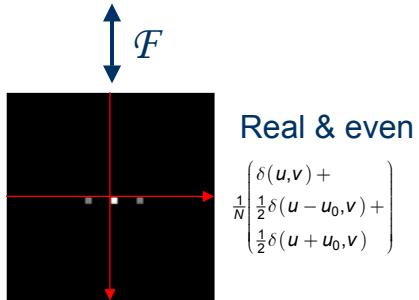
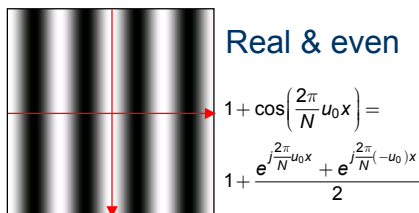


Getting used to Fourier (2)

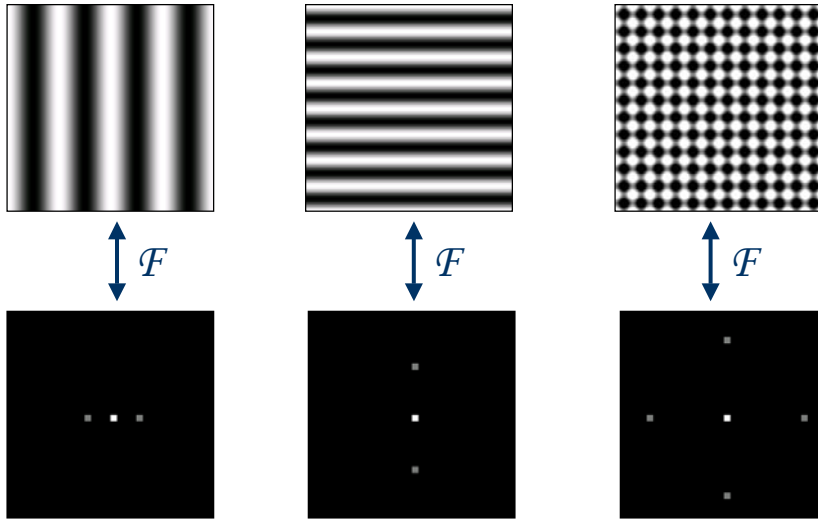
An image is a weighted sum of **cos (even)** and **sin (odd)** images.



Eigenfunctions: Even & Odd



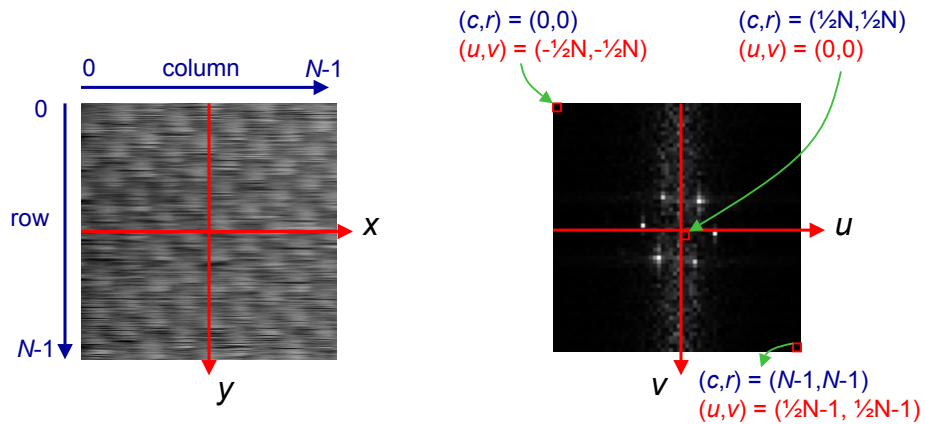
Orientation & frequency



Discrete Fourier Transform 15

Getting used to Fourier (1)

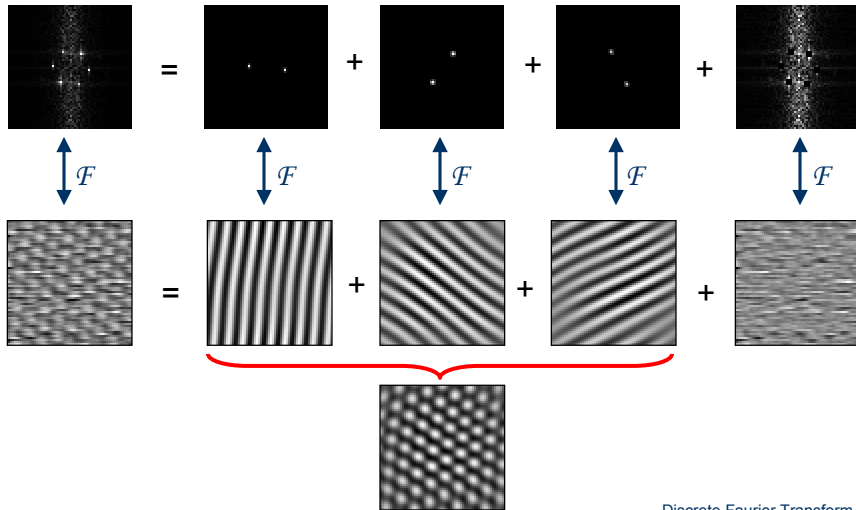
- Graphite surface by Scanning Tunneling Microscopy
- Atomic structure of graphite shows a hexagonal surface



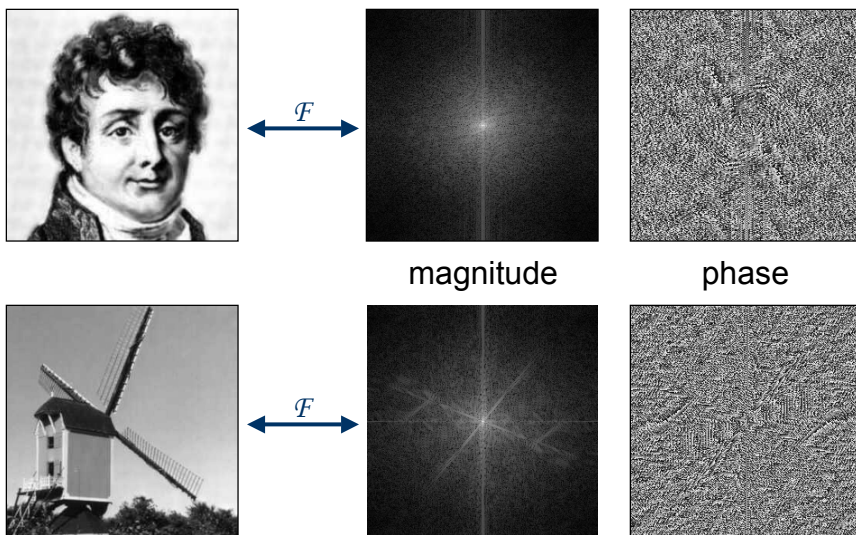
Discrete Fourier Transform 16

Superposition

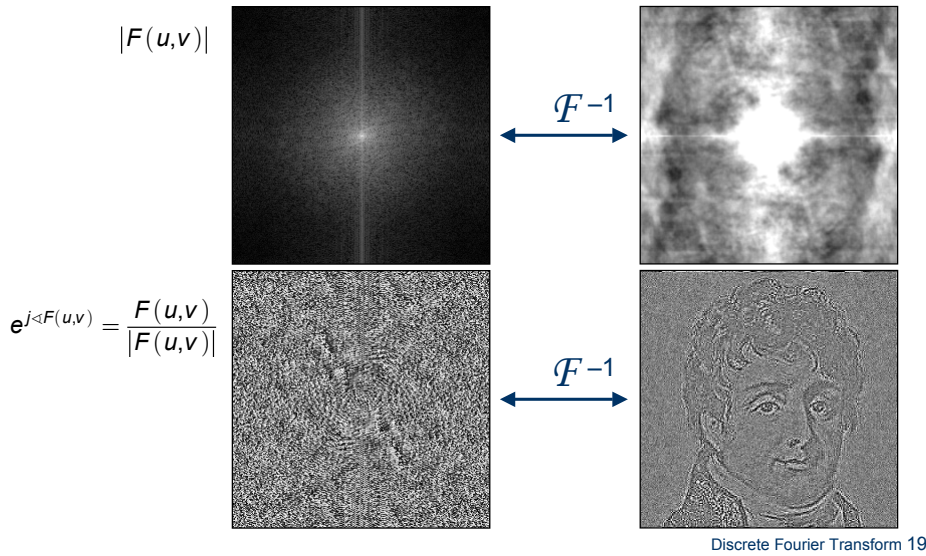
■ Fourier spectrum



Fourier transforms

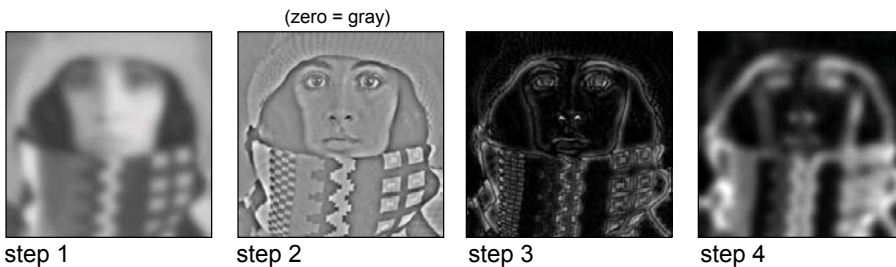
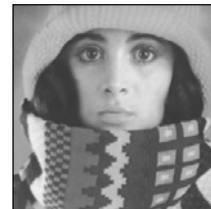


Magnitude & phase



Local variance filter: power

- *Recipe*: local variance filter (filter size = n)
 1. Compute the local mean (blurring filter of size n)
 2. Subtract the local mean.
 3. Compute the square of each pixel value
 4. Suppress the “double” response by local averaging (blurring filter of size n)
- Local variance is a measure for the local squared-contrast.



Scaling: local vs global

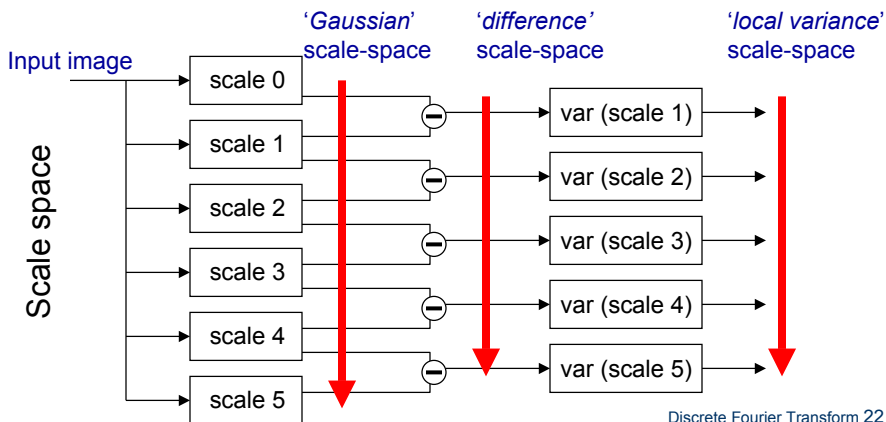
- Problem: Choosing the proper scale is an important, but tedious task.
 - Scale too small: Local characteristics are missed which yields an incomplete data description.
 - Scale too large: Confusion (mixing) of adjacent objects, lack of localization, and blindness for detail.
- Solution: Multi-scale analysis.
 - Analyze the image as function of scale: from fine detail to course “image-filling” objects.

$$g(x,y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}} \xleftrightarrow{F} G(u,v) = e^{-\frac{\left(\frac{2\pi}{N}u\right)^2 + \left(\frac{2\pi}{N}v\right)^2}{2}\sigma^2}$$

Multi-Scale

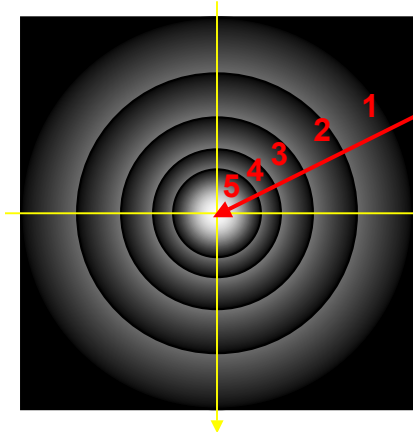
Series of images of increasing scale: Scale-space

- Sample the scales logarithmically using filters of $size = base^{scale}$
yields n scales per octave $base \in \{2^1, 2^{1/2}, 2^{1/3}, \dots, 2^{1/n}\}$



Scale-spaces

- Morphological scale-space: Use *openings (closings)*
- Gaussian scale-space: Use *Gaussian filters*

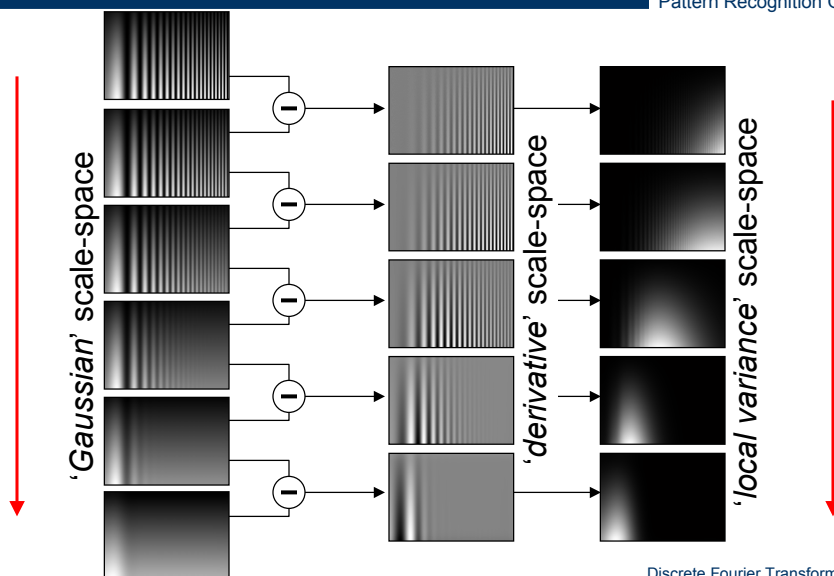


Increasing scales

Fourier domain with "footprints" of Gaussian filters of increasing scale

Filter size is inversely proportional to "footprint" in Fourier domain

Chirp example



Gaussian derivatives

$f^{(0)}[x,y]$



$f^{(1)}[x,y]$



$f^{(5)}[x,y]$



$f_x^{(0)}[x,y] = ?$

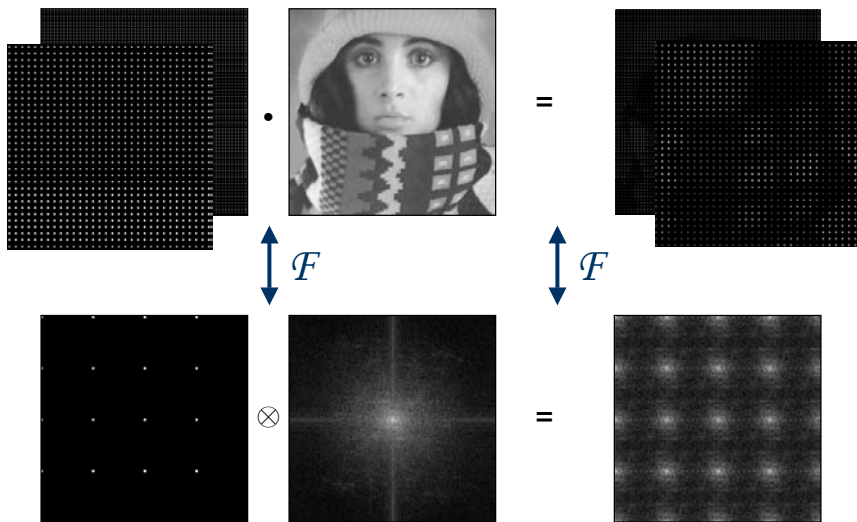
$f_x^{(1)}[x,y]$



$f_x^{(5)}[x,y]$



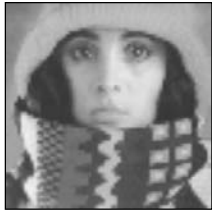
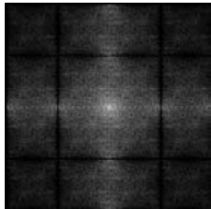
Sampling



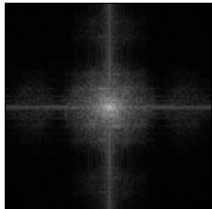
Interpolation



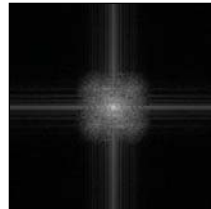
Zero-order hold
 \mathcal{F}



First-order hold
 \mathcal{F}



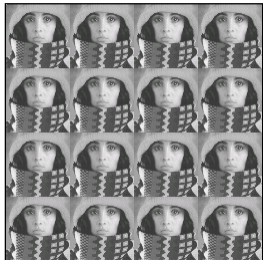
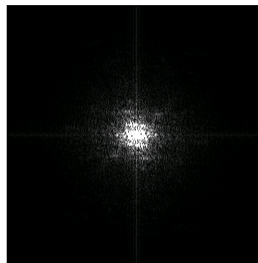
B-spline
 \mathcal{F}



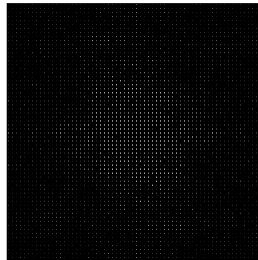
Periodic images



\mathcal{F}



\mathcal{F}



Periodic image
yields
Fourier spectrum
with impulses