Surface Quasi-Conformal Mapping by Solving Beltrami Equations

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Thank for the organizer and reviewers.

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Motivation

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Motivation

3D geometric data acquisition technology becomes mature.



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Our group has developed high speed 3D scanner, which can capture dynamic surfaces 180 frames per second.



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Motivation

Conformal geometry has been applied for studying surface deformation. The following image shows an isometric deformation, which is conformal.



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Quasi-Conformal Mapping

Motivation

In reality, most deformations are quasi-conformal.Same face with different expressions have different conformal moduli.



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Generalize computational algorithms for conformal mappings to quasi-conformal mappings.

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Definition (Conformal Atlas)

suppose *S* is a surface covered by a collection of open sets $\mathscr{A} = \{U_{\alpha}\}, S \subset \bigcup U_{\alpha}$. A chart is $(U_{\alpha}, \phi_{\alpha})$, where $\phi_{\alpha} : U_{\alpha} \to \mathbb{C}$ is a homeomorphism. The chart transition function $\phi_{\alpha\beta} : \phi_{\alpha}(U_{\alpha} \cap U_{\beta}) \to \phi_{\alpha}(U_{\alpha} \cap U_{\beta}), \phi_{\alpha\beta} = \phi_{\beta} \circ \phi_{\alpha}^{-1}$. If all transition functions are holomorphic, then the atlas \mathscr{A} is a conformal atlas.



Theorem (Riemann Surface)

Any metric surfaces can be covered by conformal atlas, such that each local coordinate system is isothermal.

Isothermal Coordinates

A surface Σ with a Riemannian metric **g**, a local coordinate system (u, v) is an isothermal coordinate system, if

$$\mathbf{g} = \mathbf{e}^{2\lambda(u,v)}(\mathbf{d}u^2 + \mathbf{d}v^2).$$



Definition (Conformal Map)

suppose S_1 and S_2 are two Riemann surfaces with conformal atlas $\{(U_{\alpha}, \phi_{\alpha})\}$ and $\{(V_{\beta}, \tau_{\beta}\}$ respectively, $f: S_1 \rightarrow S_2$ is a homeomorphism. If the local representation of f

$$\tau_{\beta} \circ f \circ \phi_{\alpha}^{-1} : \phi_{\alpha}(U_{\alpha}) \to \tau_{\beta}(V_{\beta})$$

is holomorphic, then *f* is a conformal map.



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Definition (Quasi-Conformal Map)

If f is a diffeomorphism, locally

 $df = f_z dz + f_{\bar{z}} d\bar{z}.$

Let Beltrami coefficient $\mu(z)$ be

$$\mu(z)=\frac{f_{\bar{z}}}{f_z}.$$

If $|\mu(z)| < \infty$, then *f* is a quasi-conformal map. $\mu(z) \equiv 0$ iff *f* is conformal.



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Property

A Conformal mapping maps infinitesimal circles to infinitesimal circles; a quasi-conformal mapping maps circles to ellipses.



Geometric Meaning

The argument of $\mu(z)$ is determined by the orientation of the ellipse; the norm of $\mu(z)$ is determined by the eccentric rate of the ellipse.



Beltrami Equation

Suppose $\Omega \subset \mathbb{C}$, given a complex valued measurable function $\mu(z): \Omega \to \mathbb{C}$, such that $\parallel \mu(z) \parallel_{\infty} < 1$ almost everywhere on Ω , then the Beltrami equation is

$$\bar{\partial}f(\boldsymbol{z}) = \mu(\boldsymbol{z})\partial f(\boldsymbol{z}),$$

where $f: \Omega \to \mathbb{C}$.

Theorem

Let μ be a measurable function in $\Omega \subset \mathbb{C}$ and suppose $\| \mu \|_{\infty} < 1$. Then there is a homeomorphic solution $g : \Omega \to \mathbb{C}$ to the Beltrami equation.

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Central Result

Suppose *S* is a topological surface, \mathscr{A}_1 and \mathscr{A}_2 are two conformal structures on *S*. Suppose the local complex parameters of (S, \mathscr{A}_1) and (S, \mathscr{A}_2) are *z* and *w*. The identity map is a quasi-conformal map, with Beltrami coefficient $\mu(z)$,

$$\frac{\partial w}{\partial \bar{z}} = \mu(z) \frac{\partial w}{\partial z}.$$

Then we construct another conformal atlas $\tilde{\mathscr{A}}_1$. For each chart $(U_{\alpha}, z_{\alpha}) \in \mathscr{A}_1$, convert it to $(U_{\alpha}, \tilde{z}_{\alpha})$, such that

$$d\tilde{z}_{\alpha} = dz_{\alpha} + \mu(z)d\bar{z}_{\alpha}.$$

Theorem

The atlas $\tilde{\mathscr{A}_1}$ is a conformal atlas. The Riemann surface $(S, \tilde{\mathscr{A}_1})$ is conformal equivalent to (S, \mathscr{A}_2) .

Converting quasi-conformal mappings to conformal mappings

Given a surface (S, \mathbf{g}) and Beltrami coefficient μ , $\|\mu\|_{\infty} < 1$, find a map $f : S \to \mathbb{C}$, such that $\bar{\partial} f = \mu \partial f$.

O Compute a conformal mapping $\phi : (S, \mathbf{g}) \to \mathbb{C}$, such that

$$\mathbf{g}=\mathbf{e}^{2\lambda(z)}dzd\bar{z}.$$

Construct a new metric

$$\tilde{\mathbf{g}} = |dz + \mu(z)d\bar{z}|^2$$

Sind a conformal map $f : (S, \tilde{g}) \to \mathbb{C}$, then f is the solution.

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Solveing Beltrami Equation

Given metric surfaces (S_1, \mathbf{g}_1) and (S_2, \mathbf{g}_2) , let z, w be isothermal coordinates of $S_1, S_2, w = \phi(z)$.

$$\mathbf{g}_1 = e^{2u_1} dz d\bar{z} \tag{1}$$
$$\mathbf{g}_2 = e^{2u_2} dw d\bar{w}. \tag{2}$$

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Then

- φ : (S₁, g₁) → (S₂, g₂), quasi-conformal with Beltrami coefficient μ.
- $\phi : (S_1, \phi^* \mathbf{g}_2) \rightarrow (S_2, \mathbf{g}_2)$ is isometric

•
$$\phi^* \mathbf{g}_2 = \mathbf{e}^{u_2} |dw|^2 = \mathbf{e}^{u_2} |dz + \mu d\bar{dz}|^2$$
.

• $\phi: (S_1, |dz + \mu d\bar{dz}|^2) \rightarrow (S_2, \mathbf{g}_2)$ is conformal.

Discrete Computational Method

Discrete Algorithm

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Generic Surface Model - Triangular Mesh

- Surfaces are represented as polyhedron triangular meshes.
- Isometric gluing of triangles in \mathbb{E}^2 .
- Isometric gluing of triangles in $\mathbb{H}^2, \mathbb{S}^2$.



Definition (Chain Space)

linear combination of splices

$$C_k = \{\sum_i \lambda_i \sigma_i^k | \lambda_i \in \mathbb{Z}\}$$

Definition (Boundary Operator on a simplex)

$$\partial_n[v_0, v_1, \cdots, v_n] = \sum_k (-1)^k [v_0, \cdots, v_{k-1}, v_{k+1}, \cdots, v_n]$$

Definition (Boundary Operator on a k-chain)

 $\partial_k: C_k \to C_{k-1}$

$$\partial_k \sum_i \lambda_i \sigma_i^k = \sum_i \lambda_i \partial_k \sigma_i^k.$$

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Definition (Homology Group)

linear combination of splices

$$H_k = \frac{Ker\partial_k}{Img\partial_{k+1}}$$

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Cochain Space

Definition (Cochain)

A k-form ω is a linear functional on C_k

$$\omega: C_k \to \mathbb{R}.$$

Definition (Cochain Space)

A k-cochain space C^k is the dual space of C_k

$$C^{k} = \{\omega | \omega \ k - form\}$$

Definition (Exterior Differentiation)

 $d_k: C^k \to C^{k+1}$ linear operator

$$(\mathbf{d}_k \omega)(\sigma) = \omega(\partial_k \sigma), \omega \in \mathbf{C}^k, \sigma \in \mathbf{C}_{k+1}.$$

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Definition (Cohomology Group)

$$H^k = \frac{Kerd_k}{Imgd_{k-1}}$$

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Definition (Edge Weight)

Given an edge $[v_i, v_j]$ adjacent to two faces $[v_i, v_j, v_k]$ and $[v_j, v_i, v_l]$, then the edge weight is defined as

$$w_{ij} = \cot \theta_{ij}^k + \cot \theta_{ji}^l.$$

Given an 1-form ω

$$\Delta \omega(\mathbf{v}_i) = \sum_j w_{ij} \omega([\mathbf{v}_i, \mathbf{v}_j]).$$

Definition (Harmonic 1-form)

Let ω be a 1-form, ω is harmonic if

$$\Delta \omega = 0.$$

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Theorem (Hodge)

All the harmonic 1-forms form a group, which is isomorphic to $H_1(M)$.

Harmonic 1-form

Each cohomologous class has a unique harmonic 1-form, which represents a vortex free, source-sink free flow field.

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Harmonic 1-form

Harmonic 1-form Basis



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Harmonic 1-form

Conjugate Harmonic 1-form



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Holomorphic 1-form Basis



Holomorphic 1-form Basis



Holomorphic 1-form - Global Conformal Parameterization



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Holomorphic 1-form - Global Conformal Parameterization



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Topological Annulus

- Compute an exact harmonic 1-form, and its conjugate harmonic 1-form.
- 2 Combine the two harmonic 1-forms to a holomorphic 1-form ω on the annulus, such that $Im(\int_{\gamma_{h}} \omega = 2\pi)$.
- Solution Choose a base point p. For any point $q \in S$, map it to

$$\phi(\boldsymbol{q}) = \exp(\int_{\boldsymbol{\rho}}^{\boldsymbol{q}} \omega).$$

This mapping maps the whole surface to a planar annulus conformally.

Algorithms

Topological Annulus



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Algorithms

Simply Connected Domains

By removing one point to convert it to a topological annulus.



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Algorithms

Multiply Connected Domains

Fill all the holes except two, map it to an annulus. Then we fill these two circles, and open another two holes. Iterate this procedure.



(1). D_1 is removed. (2). Conformal mapping for $S - D_1$. (3). D_1 is glued back.



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(1). D_2 is removed. (2). Conformal mapping for $S - D_2$. (3). D_2 is glued back followed by a Möbius transformation.



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(1). D_3 is removed. (2). Conformal mapping for $S - D_3$. (3). D_3 is glued back followed by a Möbius transformation.



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Table: Computational Time.

Figure	#Vertex	#Face	#Bnd	Iter	Time (sec)
Fig. 1(e)	80593	160054	1	1	102
Fig. 6(a)	80593	160054	1	1	73
Fig. 6(b)	80593	160054	1	1	110
Fig. 6(c)	80593	160054	1	1	105
Fig. 7(a)	80724	160054	2	1	78
Fig. 7(b)	80724	160054	2	1	110
Fig. 7(c)	80724	160054	2	1	112
Fig. 9(c)	15160	29974	4	2	156
Fig. 9(a)	15160	29974	4	2	160
Fig. 9(b)	15160	29974	4	2	156
Fig. 9(c)	15160	29974	4	2	157

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- Introduce a generic method for computing quasi-conformal mappings by solving Beltrami equations.
- Give algorithmic details for genus zero surfaces based on holomorphic 1-forms
- The method can be directly applied for surfaces with arbitrary topologies

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For more information, please email to gu@cs.sunysb.edu.



Thank you!

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