## CSE 541 - Logic in Computer Science

# Solutions for Selected Exercises on Temporal Logic

## Exercise 3.4.9

A CTL formula EFp is true for a state if p is true for that state already, wheras EX EFp need not be true if p is true for the present state.

A formula AGp is true for a state s if, and only if, p is true for the present state s and all states reachable from s, wheras AXAGp is true for s and if, and only if, it is true for all states reachable from s.

A formula E[pUq] is true for a state if q is true for that state already. The formula  $p \wedge EX E[pUq]$ , on the other hand, requires that (i) q be true in a future state, not including the present state, and (ii) p be true in all preceding states, including the present state.

#### Exercise 3.4.10

a.  $EF \phi$  and  $EG \phi$  are not equivalent.

Let  $\phi$  be p and  $\mathcal{M}$  be a transition system with

States:  $S = \{s_0, s_1\}$ Transitions:  $s_0 \rightarrow s_1, s_1 \rightarrow s_1$ Labels:  $L(s_0) = \{p\}, L(s_1) = \emptyset$ 

We have  $\mathcal{M}, s_0 \models EFp$  but  $\mathcal{M}, s_0 \not\models EGp$ .

- b.  $EF \phi \lor EF \psi$  and  $EF(\phi \lor \psi)$  are equivalent.
- c.  $AF \phi \lor AF \psi$  and  $AF(\phi \lor \psi)$  are not equivalent.

Take  $\phi = p$  and  $\psi = q$  and let  $\mathcal{M}$  be a transition system with

States:  $S = \{s_0, s_1, s_2\}$ Transitions:  $s_0 \rightarrow s_1, s_0 \rightarrow s_2, s_1 \rightarrow s_1, s_2 \rightarrow s_2$ Labels:  $L(s_0) = \emptyset, L(s_1) = \{p\} L(s_2) = \{q\}$ 

Then  $\mathcal{M}, s_0 \models AF(p \lor q)$  but  $\mathcal{M}, s_0 \not\models AFp \lor AFq$ .

- d.  $AF \neg \phi$  is equivalent to  $\neg EG \phi$ .
- e.  $EF \neg \phi$  and  $\neg AF \phi$  are not equivalent.

Take the same formula  $\phi = p$  and transition system  $\mathcal{M}$  as in 1(a). Then  $\mathcal{M}, s_0 \models EF \neg p$  and  $\mathcal{M}, s_0 \models AF p$  and hence  $\mathcal{M}, s_0 \not\models \neg AF p$ 

f.  $\psi = A[\phi_1 U A[\phi_2 U \phi_3]]$  and  $\psi' = A[A[\phi_1 U \phi_2]U \phi_3]$  are not equivalent. Take  $\phi_1 = p$ ,  $\phi_2 = q$ , and  $\phi_3 = r$ ; and let  $\mathcal{M}$  be a transition system with

> States:  $S = \{s_0, s_1\}$ Transitions:  $s_0 \rightarrow s_1, s_1 \rightarrow s_1$ Labels:  $L(s_0) = \{p\}, L(s_1) = \{r\}$

Then  $\mathcal{M}, s_0 \models A[p U A[q U r]]$  but  $\mathcal{M}, s_0 \not\models A[A[p U q] U r].$ 

Also, let  $\mathcal{M}'$  be a transition system with

States:  $S = \{s_0, s_1, s_2, s_3, s_4\}$ Transitions:  $s_0 \rightarrow s_1, s_1 \rightarrow s_2, s_2 \rightarrow s_3, s_3 \rightarrow s_4, s_4 \rightarrow s_4$ Labels:  $L(s_0) = L(s_2) = \{p\}, L(s_1) = L(s_3) = \{q\}, L(s_4) = \{r\}$ 

Then  $\mathcal{M}', s_0 \not\models A[p U A[q U r]]$  but  $\mathcal{M}', s_0 \models A[A[p U q] U r].$ 

- g.  $AG \phi \to EG \phi$  is equivalent to  $\top$ .
- h.  $EG \phi \to AG \phi$  is not equivalent to  $\top$ .

Let  $\mathcal{M}$  be a transition system with

States:  $S = \{s_0, s_1\}$ Transitions:  $s_0 \to s_0, s_0 \to s_1, s_1 \to s_1$ Labels:  $L(s_0) = \{p\}, L(s_1) = \emptyset$ 

Then  $\mathcal{M}, s_0 \not\models EG p \to AG p$ .

## Exercise 3.4.11.

- a.  $AG(\phi \wedge \psi) \equiv AG \phi \wedge AG \psi$
- b.  $EF \neg \phi \equiv \neg AG \phi$

**Exercise 3.4.13.** Let  $\mathcal{M}$  be a CTL model and s be a state of  $\mathcal{M}$ . Then

 $s \models \neg AX \phi$ iff  $s \not\models AX \phi$ iff not for all s' such that  $s \to s'$  we have  $s' \models \phi$ iff for some s' such that  $s \to s'$  we have  $s' \not\models \phi$ iff for some s' such that  $s \to s'$  we have  $s' \models \neg \phi$ iff  $s \models EX \neg \phi$ 

This proves that  $\neg AX \phi \equiv EX \neg \phi$ .

Exercise 3.5.1. We express informal statements as formulas.

a. Whenever p is followed by q (after finitely many steps), then the system enters an "interval" in which no r occurs until t.

If "finitely many steps" means "zero or more steps," we may use

$$AG(p \to AG(q \to A[\neg r U t])).$$

If zero steps are not admissible, we get

$$AG(p \to AX AG (q \to A[\neg r U t])).$$

b. Event p precedes s and t on all computation paths.

We express this via negation, that it is not the case that on some computation path p does not precede s and t:

$$\neg E[\neg p U ((s \lor t) \land \neg p)].$$

c. After p, q is never true (on all computation paths).

$$AG(p \to AX AG \neg q)$$

or

$$AG(p \to \neg EX \, EF \, q)$$

d. Between the events q and r, p is never true (on all computation paths).

$$[AG(q \to \neg EF(p \land EFr))] \land [AG(r \to \neg EF(p \land EFq))]$$

e. Transitions to states satisfying p occur at most twice (on all computation paths).

$$\neg(EX EF(p \land EX EF(p \land EX EF p)))$$

**Exercise 3.5.3.** Let  $\phi_1$  be the formula  $Fp \to Fq$ ,  $\phi_2$  be  $AFp \to AFq$ , and  $\phi_3$  be  $AG(p \to AFq)$ .

(a) Let  $\mathcal{M}$  be a transition system with

States:  $S = \{s\}$ Transitions:  $s \to s$ Labels:  $L(s) = \emptyset$  (or  $L(s) = \{q\}$ )

Then  $\mathcal{M}, s \not\models p$  and  $\mathcal{M}, s \not\models AFp$ , and consequently  $\mathcal{M}, s \models A[\phi_1] \land \phi_2 \land \phi_3$ .

(b) Let  $\mathcal{M}$  be a transition system and s be a state in  $\mathcal{M}$ . First observe that if  $Fp \to Fq$  is satisfied by all paths  $\pi$  starting at s and  $\mathcal{M}, s \models AFp$ , then  $\mathcal{M}, s \models AFq$ . In short, if  $\phi_1$  is satisfied by s, so is  $\phi_2$ . Thus,  $\phi_1$  can not be the only formula satisfied  $\mathcal{M}$ .

Secondly, if  $\mathcal{M}, s \models AG(p \rightarrow AFq)$ , then  $\mathcal{M}, s \models AFp \rightarrow AFq$ , and hence  $\phi_3$  can not be the only formula satisfied either.

Finally, if  $\mathcal{M}$  is a transition system with

States:  $S = \{s_0, s_1, s_2\}$ Transitions:  $s_0 \to s_1, s_0 \to s_2, s_1 \to s_1, s_2 \to s_2$ Labels:  $L(s_0) = L(s_1) = \emptyset$  and  $L(s_2) = \{p\}$ 

then  $\mathcal{M}, s \not\models AFp$  and, hence,  $\mathcal{M}, s_0 \models AFp \to AFq$ . On the other hand,  $s_0$  satisfies neither  $Fp \to Fq$  (because the path  $s_0 \to s_2 \to s_2 \cdots$  satisfies Fp but not Fq) nor  $AG(p \to AFq)$  (because  $s_0 \to s_2$  and  $s_2$  satisifies p but not AFq). Thus,  $s_0$  satisfies only  $\phi_2$  (but note that  $s_2$  does not satisfy  $\phi_2$ ). (c) Let  $\mathcal{M}$  be a transition system with

States:  $S = \{s\}$ Transitions:  $s \to s$ Labels:  $L(s) = \{p\}$ 

Then  $\mathcal{M}, s \models p$  and  $\mathcal{M}, s \models AFp$ , but  $\mathcal{M}, s \not\models AFq$ . Since there is only one computation path in this system, we may conclude that  $s_0$  satisfies none of the formulas  $A[\phi_1], \phi_2$ , and  $\phi_3$ .

**Exercise 3.5.4.** In terms of the order of occurrences of events p, s, and t, the formula  $AG(p \rightarrow AF(s \land AX(AFt)))$  expresses that event p is accompanied or followed by s, which in turn is followed by t.

Exercise 3.5.6.

- a. See remark 3.18 on pp. 219-220.
- b. AGFp and AGEFp are not equivalent.
  - Let  $\mathcal{M}$  be a transition system with

States:  $S = \{s_0, s_1\}$ Transitions:  $s_0 \to s_0, s_0 \to s_1, s_1 \to s_1$ Labels:  $L(s_0) = \emptyset, L(s_1) = \{p\}$ 

Then  $\mathcal{M}, s_0 \models AG EF p$  but  $\mathcal{M}, s_0 \not\models AG F p$ .

c.  $A[(pUr) \lor (qUr)]$  and  $A[(p \lor q)Ur]$  are not equivalent.

Let  $\mathcal{M}$  be a transition system with

States:  $S = \{s_0, s_1, s_2\}$ Transitions:  $s_0 \to s_1, s_1 \to s_2, s_2 \to s_2$ Labels:  $L(s_0) = \{p\}, L(s_1) = \{q\}, L(s_2) = \{r\}$ 

Then  $\mathcal{M}, s_0 \models A[(p \lor q)Ur]$  but  $\mathcal{M}, s_0 \not\models A[(pUr) \lor (qUr)].$ 

d.  $A[Xp \lor XXp]$  and  $AXp \lor AXAXp$  are not equivalent.

Let  $\mathcal{M}$  be a transition system with

States:  $S = \{s_0, s_1, s_2, s_3\}$ Transitions:  $s_0 \to s_1, s_0 \to s_2, s_1 \to s_2, s_2 \to s_3, s_3 \to s_3$ Labels:  $L(s_0) = L(s_2) = \emptyset, L(s_1) = L(s_3) = \{p\}$ 

Then  $\mathcal{M}, s_0 \models A[Xp \lor XXp]$  but  $\mathcal{M}, s_0 \not\models AXp \lor AXAXp$ .

e. E(GFp) and EGEFp are not equivalent.

Let  $\mathcal{M}$  be a transition system with

States:  $S = \{s_0, s_1, s_2\}$ Transitions:  $s_0 \rightarrow s_0, s_0 \rightarrow s_1, s_1 \rightarrow s_2, s_2 \rightarrow s_2$ Labels:  $L(s_0) = L(s_2) = \emptyset, L(s_1) = \{p\}$ 

Then  $\mathcal{M}, s_0 \models EG EF p$  but  $\mathcal{M}, s_0 \not\models E(GF p)$ .

## Exercise 3.5.8

- We first show that  $\neg q U (\neg p \land \neg q) \rightarrow \neg Gp$  is valid.
  - Suppose  $\pi \models \neg q U (\neg p \land \neg q)$ . Then  $\pi^i \models \neg p \land \neg q$ , for some *i*. But if  $\pi^i \models \neg p \land \neg q$ , then  $\pi^i \models \neg p$ , and hence  $\pi^i \not\models p$ . Consequently,  $\pi \not\models Gp$  and hence  $\pi \models \neg Gp$ . In sum, we may conclude that  $\pi \models \neg q U (\neg p \land \neg q) \rightarrow \neg Gp$ , for all paths  $\pi$ .

• We next show that  $(G \neg q \land F \neg p) \rightarrow \neg q U (\neg p \land \neg q)$  is valid.

Suppose  $\pi \models G \neg q \land F \neg p$ . Then  $\pi \models G \neg q$  and  $\pi \models F \neg p$ . The latter assertion implies that  $\pi^i \models \neg p$ , for some *i*. Since  $\pi \models G \neg q$  we obtain, in particular, that  $\pi^j \models \neg q$  for all *j* with  $j \leq i$ . Thus,  $\pi^i \models (\neg p \land \neg q)$ and  $\pi \models \neg q U (\neg p \land \neg q)$ . We conclude that  $\pi \models (G \neg q \land F \neg p) \rightarrow$  $\neg q U (\neg p \land \neg q)$ , for all paths  $\pi$ .

• Using the above facts and basic propositional and LTL equivalences we obtain:

$$\begin{aligned} &= \neg (p U q) \lor Gp) \\ &\equiv \neg (p U q) \land \neg Gp \\ &\equiv [(\neg q U (\neg p \land \neg q)) \lor \neg Fq] \land \neg Gp \\ &\equiv [(\neg q U (\neg p \land \neg q)) \land \neg Gp] \lor [\neg Fq \land \neg Gp] \\ &\equiv [(\neg q U (\neg p \land \neg q)) \land \neg Gp] \lor [G \neg q \land F \neg p] \\ &\equiv [\neg q U (\neg p \land \neg q)] \lor [G \neg q \land F \neg p] \\ &\equiv \neg q U (\neg p \land \neg q) \\ &\equiv \neg q U (\neg p \land \neg q) \end{aligned}$$

**Exercise 3.6.10**. The assertion  $s \models AG AF \phi$  means that  $\phi$  is true infinitely often along every path starting at s.

Let  $\pi$  be an arbitrary path

$$s = s_1 \rightarrow s_2 \rightarrow \cdots \rightarrow s_n \rightarrow \cdots$$

starting at s.

First note that by the semantics of AG, from  $s \models AG AF \phi$  we may infer that  $s_i \models AF \phi$ , for all  $i \ge 1$ . Thus, by the definition of AF, for each  $i \ge 1$ there exists an index j with  $i \le j$ , such that  $s_j \models \phi$ . Furthermore, whenever  $s_j \models \phi$  there exists an index k with j < k, such that  $s_k \models \phi$ . (The latter observation follows from the fact that  $s_{j+1} \models AF \phi$ .)

Based on these assertions, we can inductively define an infinite sequence  $k_1, k_2, \ldots$  such that  $k_i < k_{i+1}$  and  $s_{k_i} \models \phi$ , for all  $i \ge 1$ . In other words,  $\phi$  is true infinitely often along  $\pi$ .