

# Viewing Transformation

- World coordinate system
- Object (model) coordinate system
- In OpenGL: modelview matrix
  - modelview matrix is constructed in two steps
  - from ocs (mcs) to wcs
  - from wcs to vcs
- Viewing coordinate system
- A common way to define the camera position and orientation
  - eye position
  - a reference point
  - an up vector

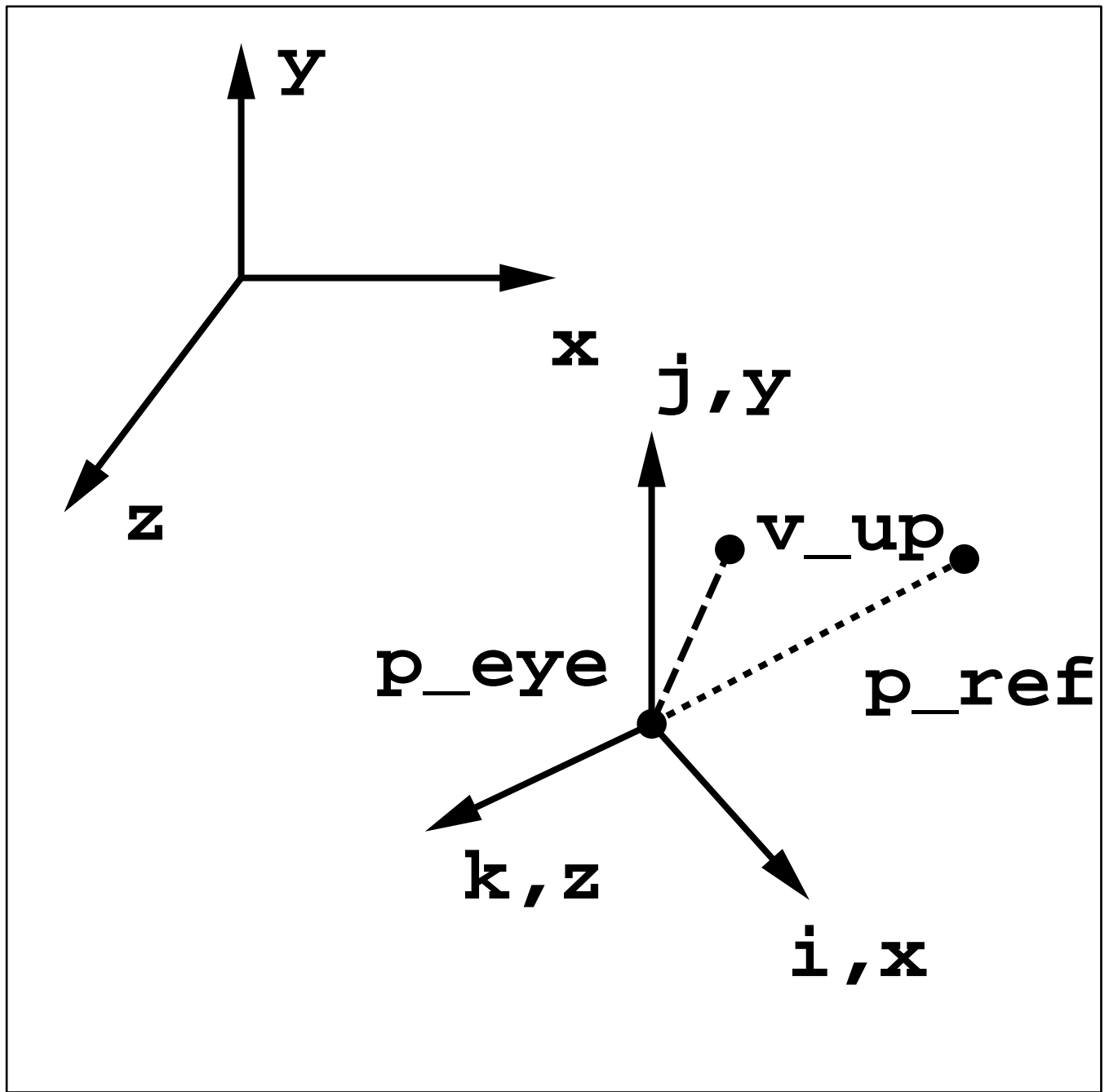
$$\mathbf{k} = \frac{\mathbf{p}_{eye} - \mathbf{p}_{ref}}{|\mathbf{p}_{eye} - \mathbf{p}_{ref}|}$$

$$\mathbf{I} = \mathbf{v}_{up} \times \mathbf{k}$$

$$\mathbf{i} = \frac{\mathbf{I}}{|\mathbf{I}|}$$

$$\mathbf{j} = \mathbf{k} \times \mathbf{i}$$

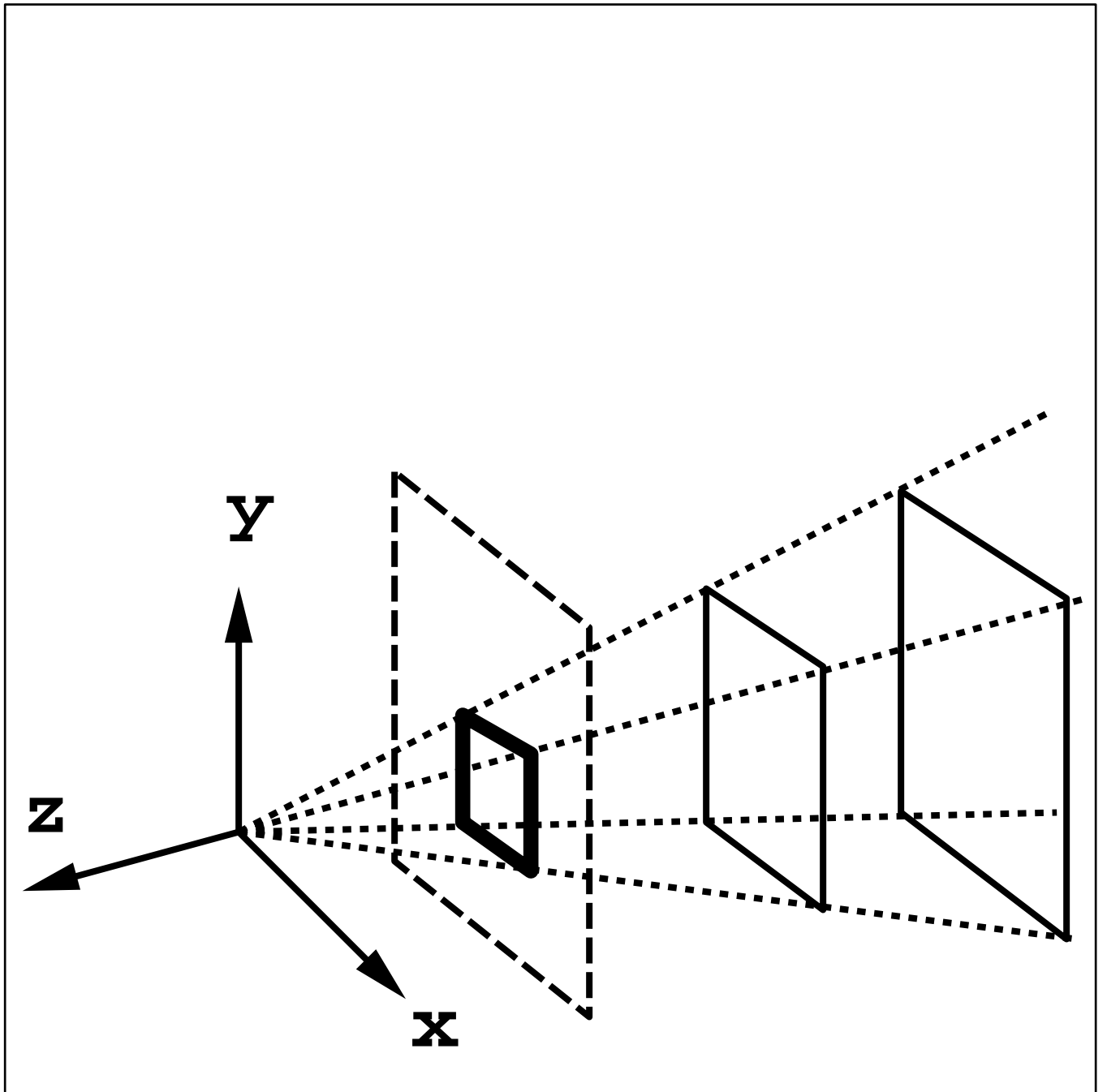
# Viewing Coordinate System



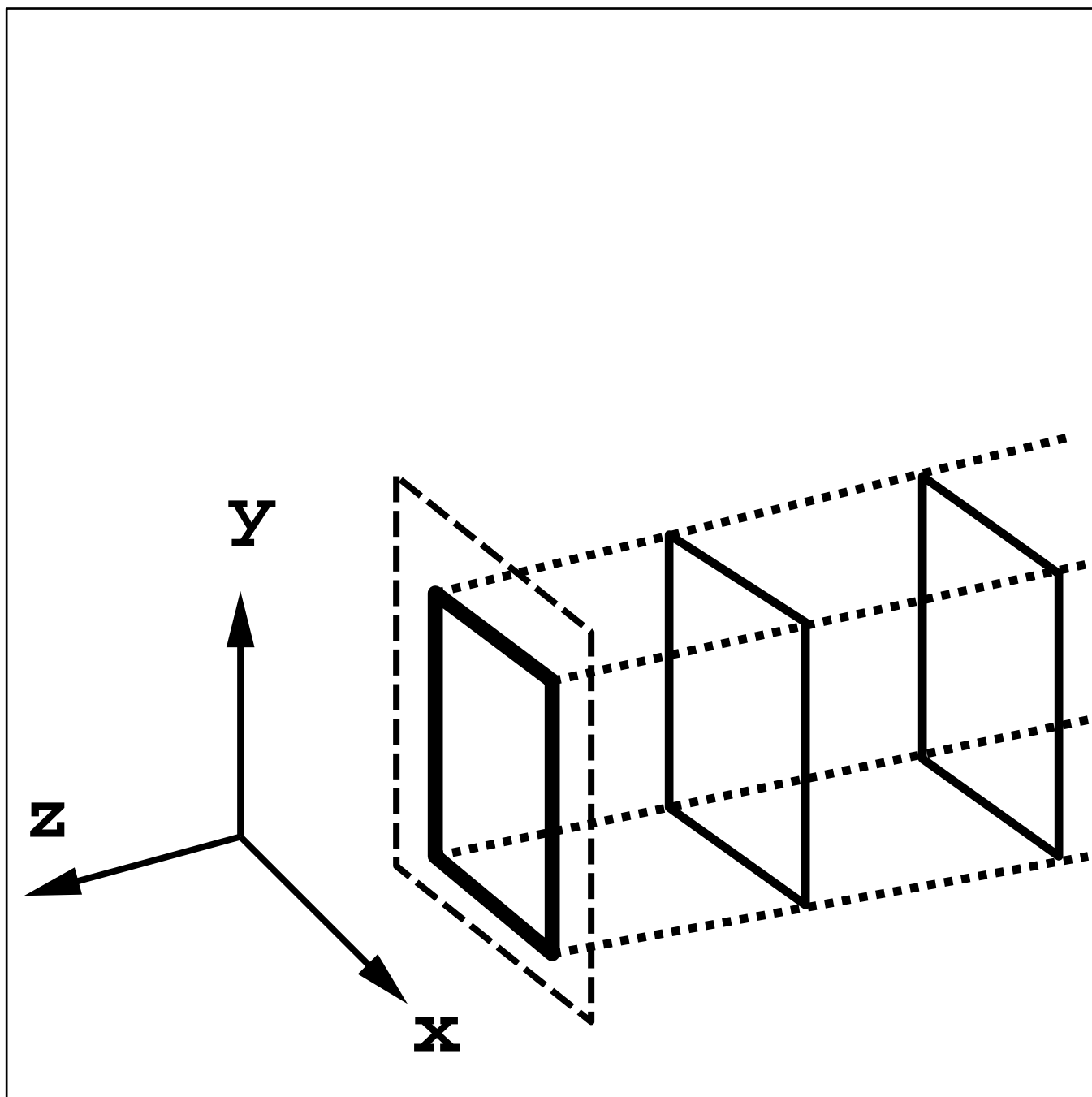
# Viewing Volume

- Frustum
- Clip object which will not project on the image plane
- Restricting the domain of  $z$  for visibility calculation
- A perspective viewing volume
  - image plane
  - $x = \text{left}$
  - $y = \text{right}$
  - $y = \text{top}$
  - $y = \text{bottom}$
  - $z = - \text{near}$
  - $z = - \text{far}$

# Viewing Volume



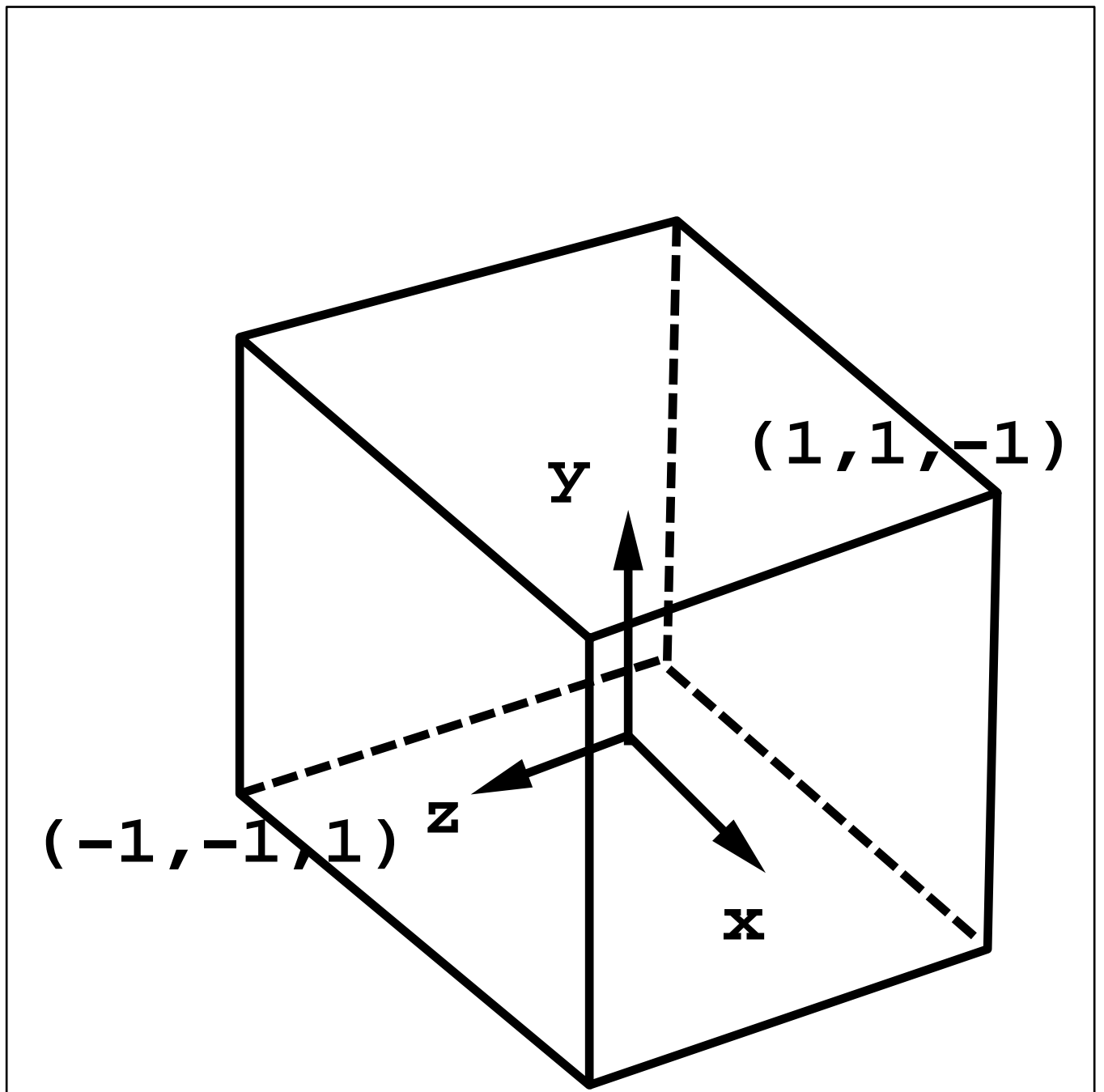
# Orthographic View Volume



# Orthographic View

- $x = \text{left}$
- $x = \text{right}$
- $y = \text{top}$
- $y = \text{bottom}$
- $z = - \text{near}$
- $z = - \text{far}$

# Normalized View Volume





# Projection Transformation

- From view volumes into canonical view volumes
- For orthographic projection  
(Scaling, translation)
- Clipping operations can be carried out after we map the existing view volume into “canonical or normalized view volume”
- This is because clipping operations are much simplified
- In OpenGL, normalized view volume is a cube of size 2 centered at origin !
- z-coordinates are retained for use in visibility calculations
- For perspective projection  
It is very complicated, deformation is involved!

# 3D Clipping

- Why 3D clipping
- Why not clipping in NDCS ?
- The transformation from VCS to NDCS is non-linear due to the division operation
- View volume clipping
- 2D algorithms can be generalized to 3D
  - Cohen-Sutherland line-clipping
  - Sutherland-Hodgeman algorithm
- Plane equations