

Types, Type Checking and Type Inference

Compiler Design

CSE 504

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Type Analysis

Is an operator applied to an “incompatible” operand?

Type checking:

- **Static:** Check for type compatibility at compile time
- **Dynamic:** Check for type compatibility at run time

Type analysis phase also used to resolve fields in a structure:

Example: `list.element`

Type Checking vs. Type Inference

- A **Type Checker** only verifies that the given declarations are consistent with their use.
Examples: type checkers for Pascal, C.
- A **Type Inference** system generates consistent type declarations from information implicit in the program.
Examples: Type inference in SML, Scheme.
Given $y = 3.1415 * x * x$, we can **infer** that y is a float.

Why Static Type Checking?

- Catch errors at compile time instead of run time.
- Determine which operators to apply.
Example: In $x + y$, “+” is integer addition if x and y are both integers.
- Recognize when to convert from one representation to another (**Type Coercion**).
Example: In $x + y$, if x is a float while y is an integer, convert y to a float value before adding.

Type Checking: An Example

```
 $E \longrightarrow \text{int\_const} \quad \{ E.type = \text{int}; \}$   
 $E \longrightarrow \text{float\_const} \quad \{ E.type = \text{float}; \}$   
 $E \longrightarrow E_1 + E_2 \quad \{$   
    if  $E_1.type == E_2.type == \text{int}$   
         $E.type = \text{int};$   
    else  
         $E.type = \text{float};$   
    }
```

Type Checking: Another Example

```
E  →  int_const    { E.type = int; }
E  →  float_const { E.type = float; }
E  →  id           { E.type = sym_lookup(id.entry, type); }
E  →  E1 + E2   {
                               if (E1.type ∉ {int, float}) OR
                                   (E2.type ∉ {int, float})
                                       E.type = error;
                               else if E1.type == E2.type == int
                                       E.type = int;
                               else
                                       E.type = float;
                               }
```

Types

- Base types: atomic types with no internal structure.
Examples: `int`, `char`.
- Structured types: Types that combine (collect together) elements of other types.
 - Arrays:
Characterized by **dimensions**, **index range** in each dimension, and type of elements.
 - Records: (structs and unions)
Characterized by **fields** in the record and their types.

Type Expressions

Language to define types.

Type → int | float | char ...
|
| void
| error
| name
| array(*Type*)
| record((name, *Type*)*)
| pointer(*Type*)
| tuple((*Type*)*)
| arrow(*Type*, *Type*)

Examples of Type Expressions

- `float xform[3][3];`
`xform` \in `array(array(float))`
- `char *string;`
`string` \in `pointer(char)`
- `struct list { int element; struct list *next; } l;`
`list` \equiv `record((element, int), (next, pointer(list)))`
`l` \in `list`
- `int max(int, int);`
`max` \in `arrow(tuple(int, int), int)`

Type Checking with Type Expressions

$$\begin{aligned} E &\longrightarrow E_1 [E_2] && \{ \text{if } E_1.type == \text{array}(\mathbf{T}) \text{ AND} \\ & && \quad E_2.type == \text{int} \\ & && \quad E.type = \mathbf{T} \\ & && \text{else} \\ & && \quad E.type = \text{error} \} \\ E &\longrightarrow * E_1 && \{ \text{if } E_1.type == \text{pointer}(\mathbf{T}) \\ & && \quad E.type = \mathbf{T} \\ & && \text{else} \\ & && \quad E.type = \text{error} \} \\ E &\longrightarrow \& E_1 && \{ E.type = \text{pointer}(E_1.type) \} \end{aligned}$$

Functions and Operators

Functions and Operators have *Arrow* types.

- $\text{max}: \text{int} \times \text{int} \longrightarrow \text{int}$
- $\text{sort}: \text{numlist} \longrightarrow \text{numlist}$

Functions and operators are *applied* to operands.

- $\text{max}(x, y):$

$$\begin{aligned} \text{max} & : \text{int} \times \text{int} \longrightarrow \text{int} \\ x & : \text{int} \\ y & : \text{int} \\ (x, y) & : \text{int} \times \text{int} \\ \text{max}(x, y) & : \text{int} \end{aligned}$$

Function Application

$$E \longrightarrow E_1 E_2 \quad \left\{ \begin{array}{l} \text{if } E_1.type \equiv \text{arrow}(\mathbf{S}, \mathbf{T}) \text{ AND} \\ E_2.type \equiv \mathbf{S} \\ E.type = \mathbf{T} \end{array} \right.$$

else

$$E.type = \text{error} \}$$
$$E \longrightarrow (E_1, E_2) \quad \{ E.type = \text{tuple}(E_1.type, E_2.type) \}$$

Type Equivalence

When are two types “equal”?

```
type Vector = array [1..10] of real;  
type Weights = array [1..10] of real;
```

```
var x, y: Vector;  
    z: Weight;
```

- **Name Equivalence:** When they have the same name.
x and y have same type, but z has different type.
- **Structural Equivalence:** When they have the same structure.
x, y and z have same type.

Structural Equivalence

$S \equiv T$ iff:

- S and T are the same **basic type**;
- $S = \text{array}(S_1)$, $T = \text{array}(T_1)$, and $S_1 \equiv T_1$.
- $S = \text{pointer}(S_1)$, $T = \text{pointer}(T_1)$, and $S_1 \equiv T_1$.
- $S = \text{tuple}(S_1, S_2)$, $T = \text{tuple}(T_1, T_2)$, and $S_1 \equiv T_1$ and $S_2 \equiv T_2$.
- $S = \text{arrow}(S_1, S_2)$, $T = \text{arrow}(T_1, T_2)$, and $S_1 \equiv T_1$ and $S_2 \equiv T_2$.

Subtyping

Object-oriented languages permit subtyping.

```
class Rectangle {
    private int x,y;
    int area() { ... }
}
class Square extends Rectangle {
    ...
}
```

Square is a subclass of Rectangle.

Since all methods on Rectangle are inherited by Square (unless explicitly overridden)

Square is a subtype of Rectangle.

Inheritance

```
class Circle {  
    float x, y; // center  
    float r; // radius  
    float area() {  
        return 3.1415 * r * r;  
    }  
}
```

```
class ColoredCircle extends Circle {  
    Color c;  
}
```

```
class Test{  
    static main() {  
        ColoredCircle t;  
        ... t.area() ...  
    }  
}
```


Resolving Names

What entity is represented by `t.area()`?
(assume no overloading)

- Determine the type of `t`.
`t` has to be of type `user(c)`.
- If `c` has a method of name `area`, we are done.
Otherwise, if the superclass of `c` has a method of name `area`, we are done.
Otherwise, if the superclass of superclass of `c`...
 - ⇒ Determine the least superclass of class `c` that has a method with name `area`.

Overloading

```
class Rectangle {
    int x,y; // top lh corner
    int l, w; // length and width

    Rectangle move() {
        x = x + 5;    y = y + 5;
        return this;
    }

    Rectangle move(int dx, int dy) {
        x = x + dx;    y = y + dy;
        return this;
    }
}
```

Resolving Overloaded Names

What entity is represented by `move` in `r.move(3, 10)`?

- Determine the type of `r`.
`r` has to be of type `user(c)`.
- Determine the nearest superclass of class `c` that has a method with name `move`

such that `move` is a method that takes two `int` parameters.

Structural Subtyping

$S \subseteq T$ iff:

- S and T are the same **basic type**.
- $S = \text{user}(type_1)$, $T = \text{user}(type_2)$ and $type_1 \subseteq type_2$.
- $S = \text{array}(S_1)$, $T = \text{array}(T_1)$, and $S_1 \subseteq T_1$;
- $S = \text{pointer}(S_1)$, $T = \text{pointer}(T_1)$, and $S_1 \subseteq T_1$;
- $S = \text{tuple}(S_1, S_2)$, $T = \text{tuple}(T_1, T_2)$, and $S_1 \subseteq T_1$ and $S_2 \subseteq T_2$;
- $S = \text{arrow}(S_1, S_2)$, $T = \text{arrow}(T_1, T_2)$, and $S_1 \supseteq T_1$ and $S_2 \subseteq T_2$.

Inheritance and Overloading

What entity is represented by f in $E.f(a_1, a_2, \dots, a_n)$?

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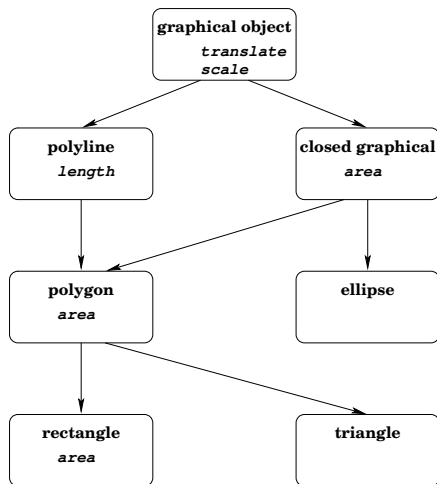
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- If there are multiple methods in a superclass of c , say f_1, f_2, \dots, f_n with signatures T_1, T_2, \dots, T_n respectively,
- ... select f_i such that T_i is the (unique) greatest type such that $T_i \subseteq T$.

Inheritance: Another Example



Abstract objects and Concrete Representations

Abstract classes declare methods, but do not define them.

Example:

- `closed_graphical` declares “area” method, but cannot define the method.
- The different “area” methods are defined when the object’s representations are concrete: in `rectangle`, `ellipse`, etc.

When “area” method is applied to an object of class `closed_graphical`, we method to be called is the one defined in `rectangle`, `triangle`, `ellipse`, etc.

... which can be resolved only at run-time!

Types in OO Languages: The Whole Story

Decaf implements a small part of the type system for an OO language.

- **Subtype rule:** Wherever an object of type t is required (as a parameter of a method, return value, or rhs of assignments), object of any subtype s of t can be used.

Types in OO Languages: The Whole Story (contd.)

- **Method Selection rule:** If class B inherits from class A and overwrites method `m`, then for any B object `b`, method `m` of B must be used, even if `b` is used as an A object.

| | |
|--|--|
| <pre>class A { int m() { ... } }</pre> | <pre>class B extends A { int m() { ... } }</pre> |
|--|--|

```
class C{  
    int f(B b) {  
        A a;  
  
        a = b;  
        ... a.m() ...  
    }  
}
```

Types in OO Languages: The Whole Story (contd.)

- **Dynamic Binding rule:** A method of object *obj*, which can be potentially overwritten in a subclass has to be bound **dynamically** if the compiler cannot determine the runtime type of *obj*.