

CSE216 Programming Abstractions

Data Abstractions

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Overview: 3 Elements of Data

- The 3 elements of data
 - Primitive data
 - Compound data
 - Data abstraction

- Like 3 elements of programming
 - Primitive expression
 - Means of combination
 - Means of abstraction

Overview: Primitive Data

- Integers

- -1, 0, 1, 2, ...

```
# 1;;  
- : int = 1
```

- Floats

- -1.0, 0, 1.0, 3.141592, ...

```
# 1.0;;  
- : float = 1.
```

- Boolean

- true, false

```
# true;;  
- : bool = true
```

- Character

- 'a', 'b', 'c',

```
# 'a';;  
- : char = 'a'
```

- String

- "hello world"

```
# "hello";;  
- : string = "hello"
```

Overview: Compound Data

- Compound data
 - A way to **glue** data together
 - **Closure** property: can glue combined data objects again
 - Needs a way to **access individual components**
 - Compound data can increase the **modularity** of programs

Overview: Compound Data

- E.g.) Rational number with two integers
 - **Without** compound data: needs to manage sets of two integer variables

```
# let num1 = 1 in let den1 = 2 in
  let num2 = 3 in let den2 = 4 in
    let num3 = add_rat_num(num1, den1, num2, den2) in
      let den3 = add_rat_den(num1, den1, num2, den2) in ...
```

- **Combine num** and **den** into **rat**

```
# let rat1 = make_rat(1,2) in
  let rat2 = make_rat(3,4) in
    let rat3 = add_rat(rat1, rat2) in ...
```

Overview: Data Abstraction

- **Data abstraction** means isolating
 - how data objects are **represented** from
 - how data objects are **used**
- E.g.)

```
let example () =  
  let ( + ) = arith "add" in  
  let ( - ) = arith "sub" in  
  let ( * ) = arith "mul" in  
  let ( / ) = arith "div" in  
  let a = complex 2. 3. in  
  let b = polar 1. 3.14 in  
  (a + b) * a / b
```

 - **a** is a complex number in the **rectangular form**
 - **b** is a complex number in the **polar form**
 - However, we can **use** them the **same** way without **distinguishing** their **implementations**

Primitive Data

- OCaml Basic types

Type	Comments
int	31-bit signed int on 32-bit processors, 63-bit signed int on 64-bit processors
float	IEEE double-precision floating point
bool	A boolean
char	An 8-bit char
string	A string
unit	Like void in C

Compound Data: Tuples

- Tuple

- Ordered collection of values that can be of different type

- E.g.)

```
# (1, "hello", true);;
```

```
- : int * string * bool = (1, "hello", true)
```

```
# (1, ("hello", true));;
```

```
- : int * (string * bool) = (1, ("hello", true))
```


Compound Data: Tuples

- **Pattern matching** to **access** components

```
# let (x, y) = (1, ("hello", true));  
val x : int = 1  
val y : string * bool = ("hello", true)
```

```
# let (x, (y, z)) = (1, ("hello", true));  
val x : int = 1  
val y : string = "hello"  
val z : bool = true
```

```
# let (_, (y, _)) = (1, ("hello", true));  
val y : string = "hello"
```

Building Rational Numbers

- Example: building rational numbers
 - Assume that the **constructor** and **selectors** are available as
 - `make_rat` `n` `d`,
 - `num` `x`, `den` `x`

```
let add_rat x y =  
  make_rat ((num x) * (den y) + (num y) * (den x))  
           ((den x) * (den y));;
```

```
let sub_rat x y =  
  make_rat ((num x) * (den y) - (num y) * (den x))  
           ((den x) * (den y));;
```

Building Rational Numbers

```
let mul_rat x y =  
  make_rat ((num x) * (num y)) ((den x) * (den y));;
```

```
let div_rat x y =  
  make_rat ((num x) * (den y)) ((den x) * (num y));;
```

```
let equal_rat x y =  
  (num x) * (den y) = (den x) * (num y);;
```

```
let print_rat x =  
  Printf.printf "%d/%d\n" (num x) (den x);;
```

Building Rational Numbers

- Representing rational numbers **as a pair**
 - Implementing **pair** using a **tuple**: constructor and accessors

```
let pair a b = (a, b) ;;  
let first x = let (a, _) = x in a ;;  
let second x = let (_, b) = x in b ;;
```

- The constructor and accessors for rational numbers

```
let make_rat n d = pair n d ;;  
let num x = first x ;;  
let den x = second x ;;
```

```
print_rat (sub_rat (make_rat 1 2)  
                 (make_rat 1 3)) ;;
```

Building Rational Numbers

- Reduce rational numbers to their lowest terms
 - Divide n and d by their gcd in make_rat

```
let make_rat n d =  
  let rec gcd x y =  
    if x > y      then gcd (x - y) y  
    else if x < y then gcd (y - x) x  
    else x in  
  let g = gcd n d in  
  pair (n/g) (d/g);;
```

```
print_rat (sub_rat (make_rat 1 2)  
                  (make_rat 1 3));;
```

- Because of the **data abstraction**, this change does not affect other parts of the program

Building Rational Numbers

- Implementing **pair** using a **function**

```
let pair a b = fun z -> if z then a else b;;  
let first x = x true in;;  
let second x = x false in;;
```

```
print_rat (sub_rat (make_rat 1 2)  
                (make_rat 1 3));;
```

- Again, because of the **data abstraction**, this change does not affect any other parts of the program

What is Meant by Data

- We can think of **data** as
 - Some collection of **selectors** and **constructors**, and
 - **Conditions** that these procedures must satisfy
- E.g.) pairs of rational number
 - Constructor: **pair**
 - Selectors: **first**, **second**
 - Conditions: if x is a **pair** of a and b , then **first** x is a and **second** x is b

What is Meant by Data

- E.g.) Representing **pair**

```
let pair a b = (a, b)
let first  (a, _) = a
let second (_, b) = b
```

uncurried function:
pattern matching
at parameters

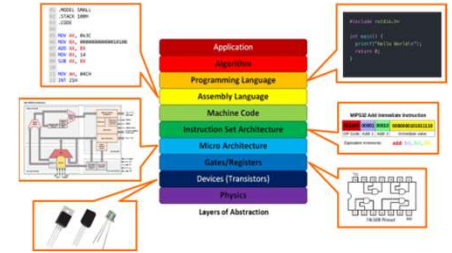
```
let pair a b z =
    if z then a
    else b
let first  x = x true
let second x = x false
```

- Both representations have the same **constructor**, **selectors**, and the **condition**

Abstraction Barriers

- Abstraction barriers
 - Isolate different levels of a system
 - The **barrier** at each level
 - Separates the **program above** that **uses** the data
 - From the **program below** that **implements** the data abstraction
 - Procedures at each level are **interfaces** that define the abstraction barriers

Abstraction Barriers



Programs that use rational numbers

Rational numbers in problem domain

```
add_rat sub_rat ...
```

Rational numbers as numerators and denominators

```
make_rat num den
```

Rational numbers as pairs

```
pair first second
```

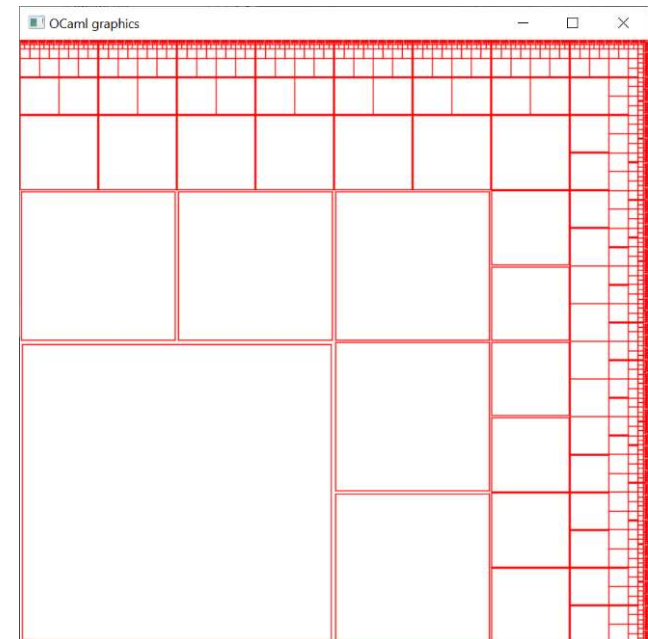
Pairs as tuples

```
(a, b) let (a, b) = x
```

However tuples are implemented

Example: A Picture Language

- Demonstrates the power of
 - Data abstraction
 - High order procedures
 - Closure property
 - Results of an operation can be used for the same operation



Install Graphics Package

- Run the following commands in Ubuntu
 - `sudo apt install pkg-config` (may not necessary)
 - `opam init`
 - `opam update`
 - `opam install graphics`

Install Graphics Package

- Copy `graphics.cmi` and `graphics.cma` to your local directory
 - `opam config list graphics`
 - Find where the graphics library is installed
 - Look for `graphics:lib` or `library directory for this package`
 - Copy `graphics.cmi` and `graphics.cma` from the library to your local directory
 - E.g.:
 - `cp ~/.opam/default/lib/graphics/graphics.cmi .`
 - `cp ~/.opam/default/lib/graphics/graphics.cma .`

Test Graphics

- Run the following commands from your ocaml top level

```
ykwon4@youngbox2: /mnt/c/ × + v
ykwon4@youngbox2: /mnt/c/Users/young/Documents/Share/CSE216/OCaml/Recitation$ ocaml
OCaml version 4.13.1

# #load "graphics.cma";;
# open Graphics;;
# open_graph " 500x500";;
- : unit = ()
# lineto 300 300;;
- : unit = ()
# close_graph ();;
- : unit = ()
# |
```

Install X11 Server

- You may need to install X11 server
 - Windows: install `xming` from <https://sourceforge.net/projects/xming/>
 - WSL: may need to add `export DISPLAY=127.0.0.1:0` to `.bashrc` file
- Mac: install `XQuartz`

To Use Graphics in Cygwin

- Check if Graphics package is installed

```
$ opam list
# Packages matching: installed
# Name                # Installed      # Synopsis
base-bigarray         base
...
graphics            5.1.1          The OCaml graphics library
ocaml                  4.11.1          The OCaml compiler (virtual package)
...
```

- Install Graphics package if it is not installed

```
$ opam install graphics
```

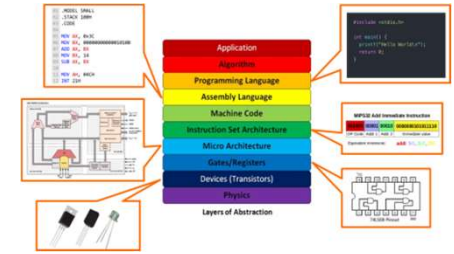
- Run Ocaml with -I (include) option

```
$ ocaml -I $(ocamlfind query graphics)
```

- If ocamlfind is not installed, install it using

```
$ opam install ocamlfind
```


Picture Language: Abstraction Barriers



Programs that use transforms

Complex transform operations on painter

`right_split, up_split, corner_split...`

Simple transform operations on painter

`tf_painter, flip, scale, translate, rotate`

Frames as a tuple of vectors

`new_frame, frame_to_globalcoord_map`

2D vectors as tuples

`add, sub, prod, smul`

However tuples are implemented

A Picture Language

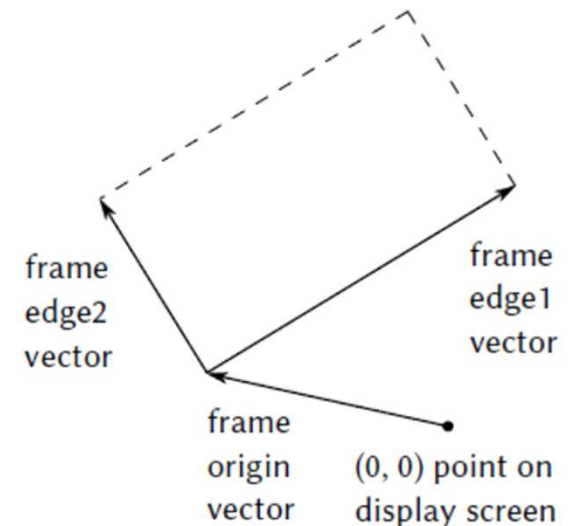
- Key elements

- Painter

- A function that takes a frame and **draws on the frame**

- Frame

- Decides where and how the painter draws image
 - A tuple of **o**, **u**, and **v** vectors in the **global coordinate**
 - **o**: origin vector,
 - **u**: edge1 vector, **v**: edge2 vector



A Picture Language

- Key elements

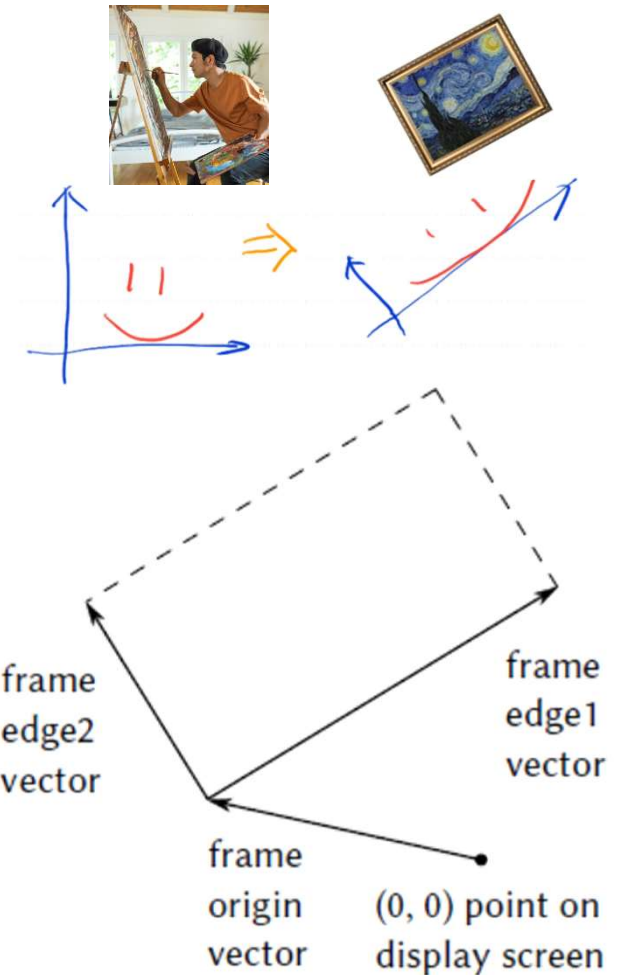
- Mapping

- Frame coordinate \rightarrow screen coordinate

- $p \rightarrow o + p.x * u + p.y * v$

- Painter draws on the frame

- We transform the frames



A Picture Language

- Programs that use transforms
- Complex transform operations on painter
- right_split, up_split, corner_split...
- Simple transform operations on painter
- tf_painter, flip, scale, translate, rotate
- Frames as a tuple of vectors
- new_frame, frame_to_globalcoord_map
- 2D vectors as tuples
- add, sub, prod, smul
- However tuples are implemented

■ Vector 2d

(*vector 2d-----
*)

(*add, sub*)

let add (x1, y1) (x2, y2) = (x1 +. x2, y1 +. y2)

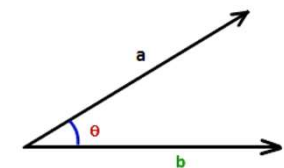
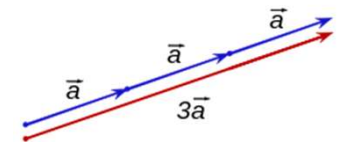
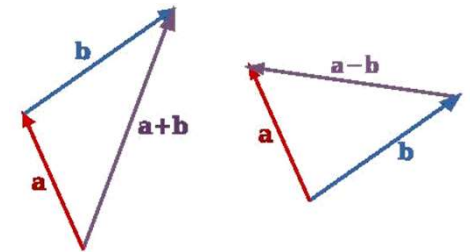
let sub (x1, y1) (x2, y2) = (x1 -. x2, y1 -. y2)

(*scalar multiplication*)

let smul s (x, y) = (s *. x, s *. y)

(*inner product*)

let prod (x1, y1) (x2, y2) = x1 *. x2 +. y1 *. y2



$$a \cdot b = |a| |b| \cos \theta$$

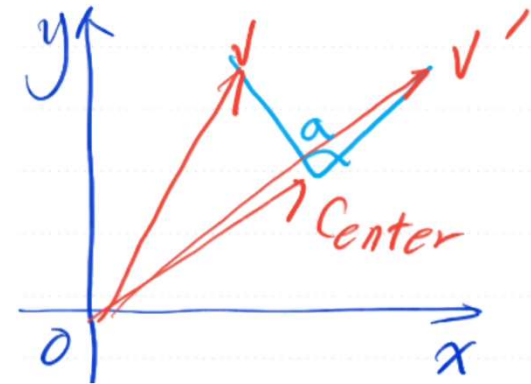
A Picture Language

■ Vector 2d

```
let pi = acos (- 1.)  
let deg2rad deg = deg /. 180. *. pi  
let rad2deg rad = rad /. pi *. 180.
```

*(*rotate v a degree from center*)*

```
let rot a center v =  
  let cv = sub v center in  
  let cosx = cos (deg2rad a) in  
  let sinx = sin (deg2rad a) in  
  let x = prod (cosx, -. sinx) cv in  
  let y = prod (sinx, cosx) cv in  
  add (x, y) center
```



Frame and Coordinate Mapping

- Programs that use transforms
- Complex transform operations on painter
- right_split, up_split, corner_split...
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```
(*frame  
*)
```

```
let new_frame o u v = (o, u, v)
```

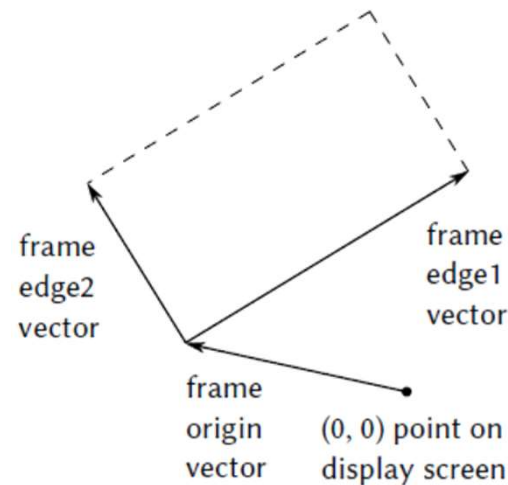
```
let frame_g = new_frame (0.,0.) (1.,0.) (0.,1.)
```

```
(*convert (x,y) in frame coord to global coord*)
```

```
let frame_to_global_coord_map frame =
```

```
let (o, u, v) = frame in
```

```
fun (x, y) -> add o (add (smul x u) (smul y v))
```



Base Painter



*(*base painter-----
draw a box of a nearly entire frame
)

```
let base_painter =  
  let scale a s = truncate (a *. float s) in  
  let move_to (x, y) = scale x (size_x ()) |> fun sx ->  
    scale y (size_y ()) |> fun sy ->  
    moveto sx sy in  
  let line_to (x, y) = scale x (size_x ()) |> fun sx ->  
    scale y (size_y ()) |> fun sy ->  
    lineto sx sy in  
  
  fun frame ->  
    let map = frame_to_global_coord_map frame in  
    let b = 0.99 in  
    let a = 1. -. b in  
    set_color red;  
    move_to (map (a, a));  
    line_to (map (a, b));  
    line_to (map (b, b));  
    line_to (map (b, a));  
    line_to (map (a, a))
```

Returns a **painter**, a function that takes a **frame** and **draws on it**

Sequence Operator:
append next expr
if prev expr is ()

Simple Transform Painters

- Programs that use transforms
- Complex transform operations on painter
 - right_split, up_split, corner_split...
- Simple transform operations on painter
 - tf_painter, flip, scale, translate, rotate
- Frames as a tuple of vectors
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(*simple transform on painters-----*)

(*tf_painter make painter draw on the local coordinate system of o, x, y w.r.t. frame i.e. paint on the new frame of o, x, y w.r.t. frame*)

```
let tf_painter painter o x y =  
  fun frame ->
```

```
    let map = frame_to_global_coord_map frame in  
    let (go, gu, gv) = (map o, map x, map y) in
```

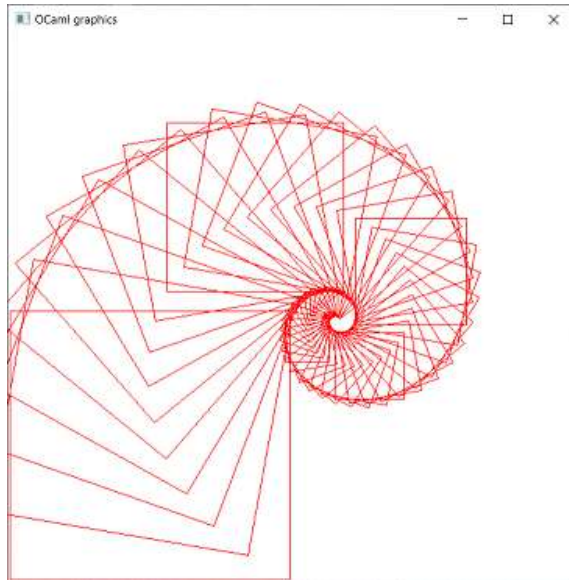
```
      (*make the frame for o, x, y local coord. sys.*)  
      painter (new_frame go (sub gu go) (sub gv go))
```

Closure property:
tf_painter returns a painter. It takes a frame and draws on it

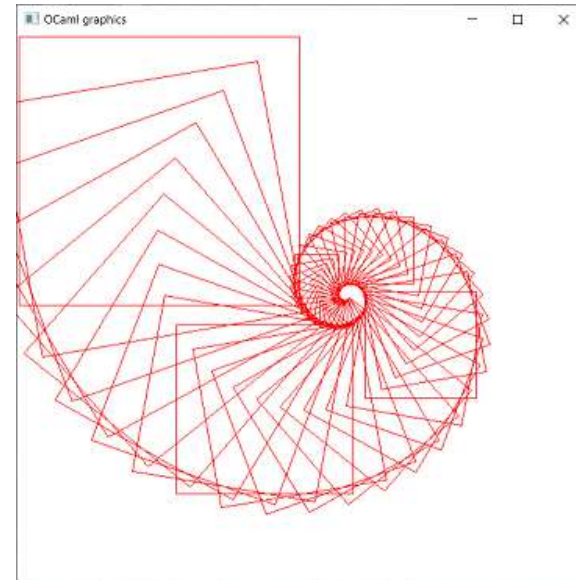


Simple Transform Painters

```
let flip_ver painter =  
  tf_painter painter (0.,1.) (1.,1.) (0.,0.)  
  (*      ^o      ^x      ^y      *)
```

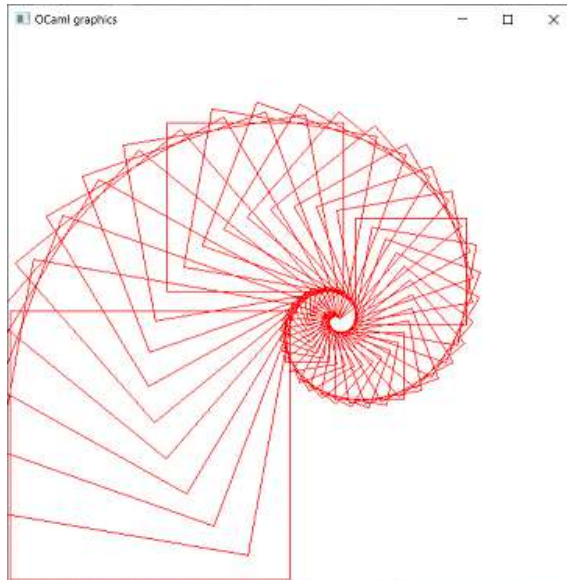


=>

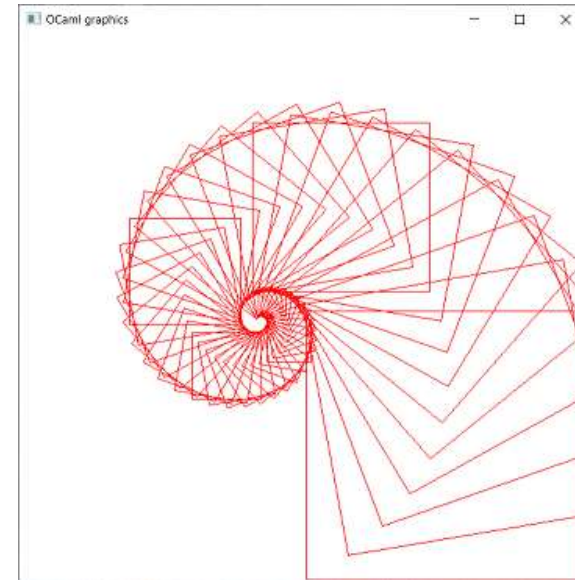


Simple Transform Painters

```
let flip_hor painter =  
  tfPainter painter (1.,0.) (0.,0.) (1.,1.)  
  (*      ^o      ^x      ^y      *)
```



=>



Simple Transform Painters

```
let scale sx sy painter =  
  tf_painter painter (0., 0.) (sx, 0.) (0., sy)
```

```
let translate tx ty painter =  
  tf_painter painter (tx, ty) (1. +. tx, 0. +. ty)  
                                (0. +. tx, 1. +. ty)
```

```
let rotate a center painter =  
  let r = rot a center in  
  tf_painter painter (r (0., 0.)) (r (1., 0.)) (r (0., 1.))
```

```
let rotate90 painter = rotate 90. (0.5, 0.5) painter
```

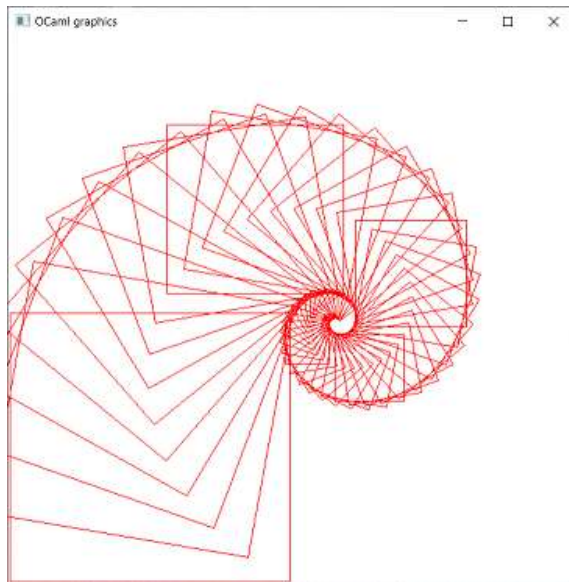
```
let rotate180 painter = rotate 180. (0.5, 0.5) painter
```

```
let rotate270 painter = rotate 270. (0.5, 0.5) painter
```

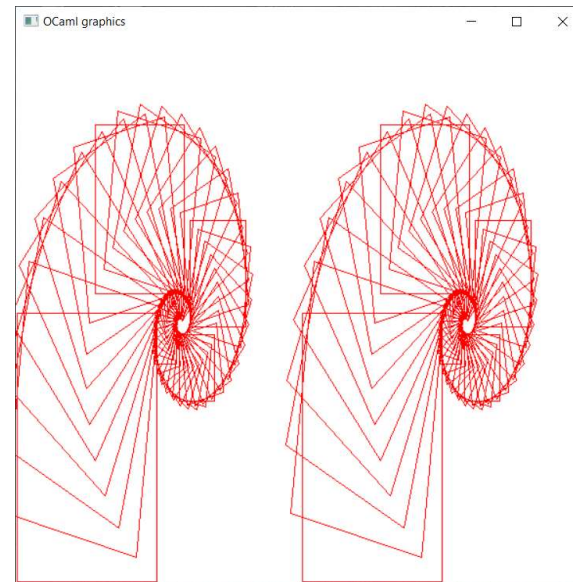
Simple Transform Painters

```
let beside painter_l painter_r =  
  let paint_left  = tfPainter painter_l (0.,0.) (0.5,0.) (0.,1.) in  
  let paint_right = tfPainter painter_r (0.5,0.) (1.,0.) (0.5,1.) in  
  fun frame ->  
    paint_left frame;  
    paint_right frame
```

Closure property: beside returns a painter. It takes a frame and draws on it

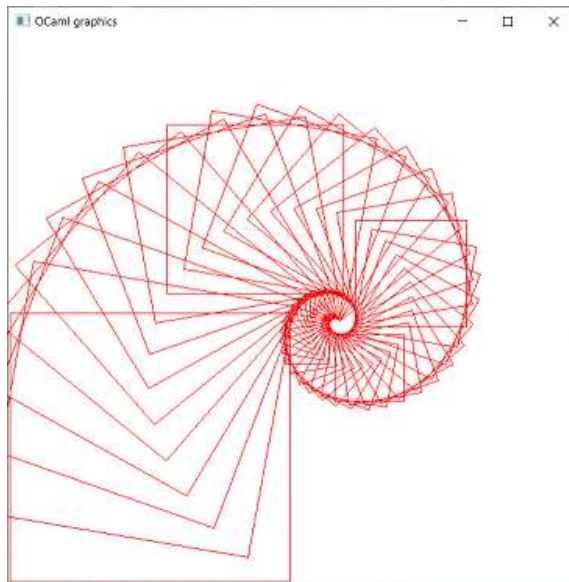


=>

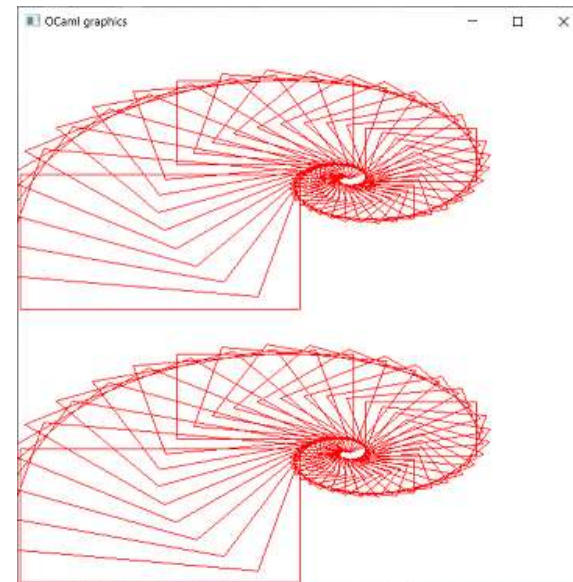


Simple Transform Painters

```
let below painter_t painter_b =  
  let paint_top      = tf_painter painter_t (0.,0.5) (1.,0.5) (0.,1.) in  
  let paint_bottom  = tf_painter painter_b (0.,0.)  (1.,0.)  (0.,0.5) in  
  fun frame ->  
    paint_top      frame;  
    paint_bottom  frame
```



=>

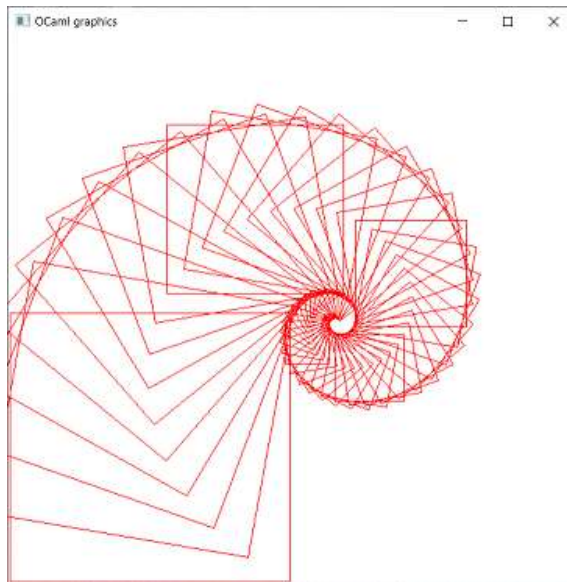


Complex Transform Painters

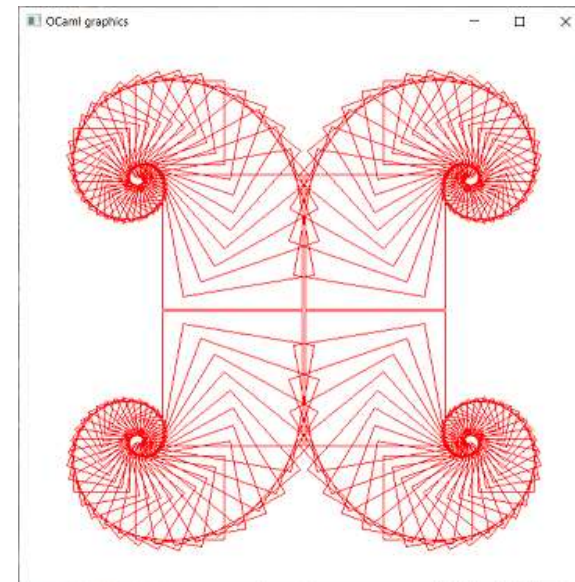
- Programs that use transforms
- Complex transform operations on painter
 - right_split, up_split, corner_split
- Simple transform operations on painter
 - tf_painter, flip, scale, translate, rotate
- Frames as a tuple of vectors
 - new_frame, frame_to_globalcoord_map
- 2D vectors as tuples
 - add, sub, prod, smul
- However tuples are implemented

(*complex transform on painters-----*)

```
let flipped_pairs painter =  
  let painter2 = beside (flip_hor painter) painter in  
  below painter2 (flip_ver painter2)
```



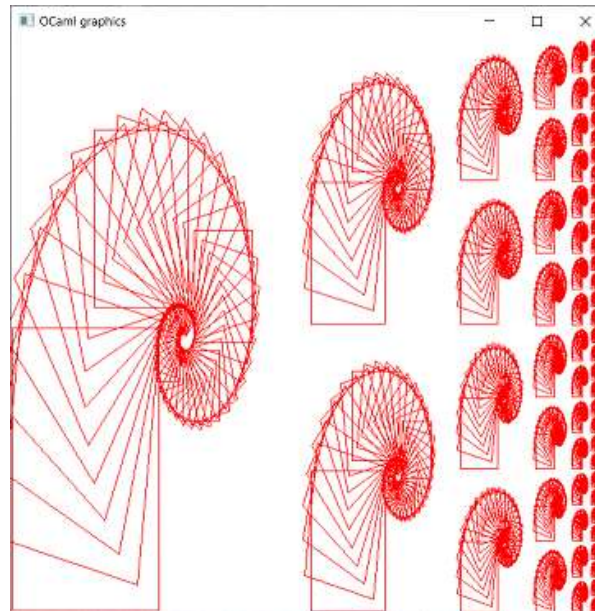
=>



Complex Transform Painters

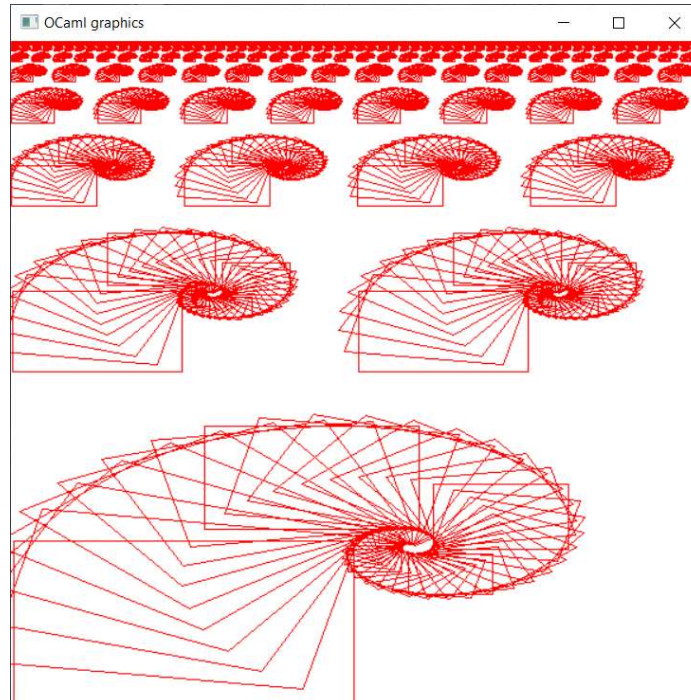
```
let rec right_split painter n =  
  if n = 0 then painter  
  else  
    let smaller = right_split painter (n-1) in  
    beside painter (below smaller smaller)
```

right_split returns a painter: it takes a frame and draws on it



Complex Transform Painters

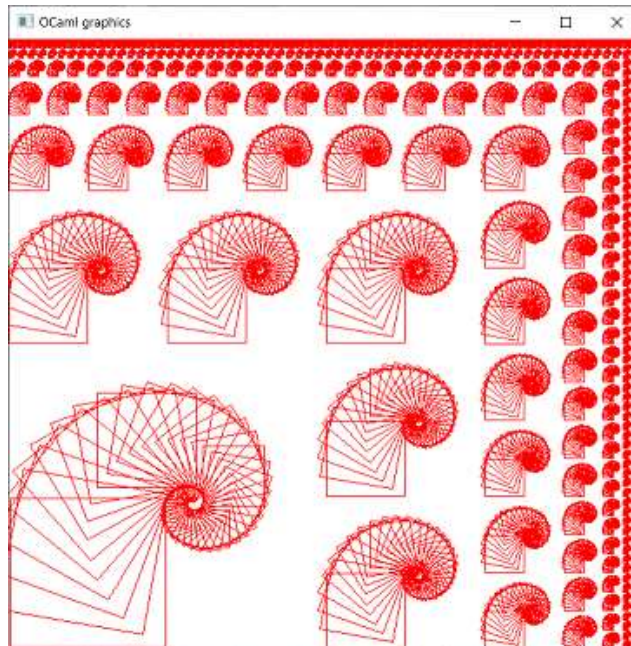
```
let rec up_split painter n =  
  if n = 0 then painter  
  else  
    let smaller = up_split painter (n-1) in  
    below (beside smaller smaller) painter
```



Complex transform on painter

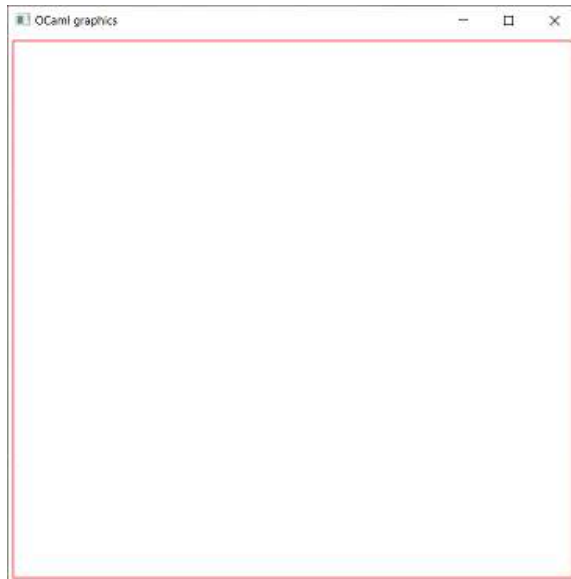
```
let rec corner_split painter n =  
  if n = 0 then painter  
  else  
    let up          = up_split    painter (n-1) in  
    let right       = right_split painter (n-1) in  
    let top_left    = beside     up up      in  
    let bottom_right = below     right right in  
    let corner      = corner_split painter (n-1) in  
    beside (below top_left painter)  
          (below corner bottom_right)
```

Without **up up** or **right right**, the pictures look squeezed.

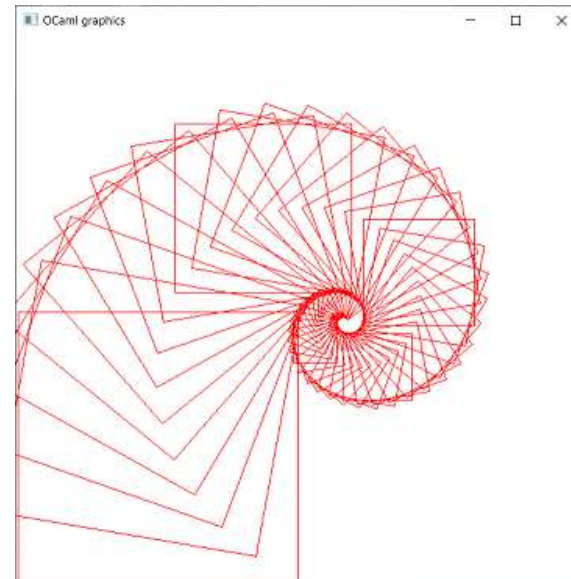


Complex Transform Painters

```
let rec rot_scale painter n =  
  if n = 0 then painter  
  else  
    let rs = painter |> scale 0.95 0.95  
                    |> rotate (-10.) (0.7, 0.3)  
                    |> fun p -> rot_scale p (n-1) in  
    fun frame ->  
      painter frame;  
      rs frame
```



⇒

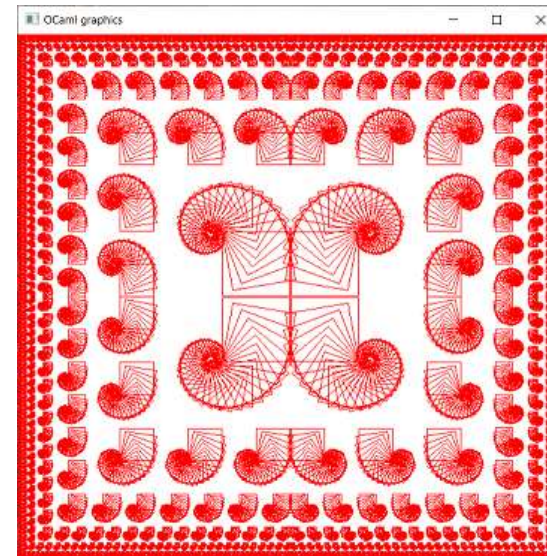
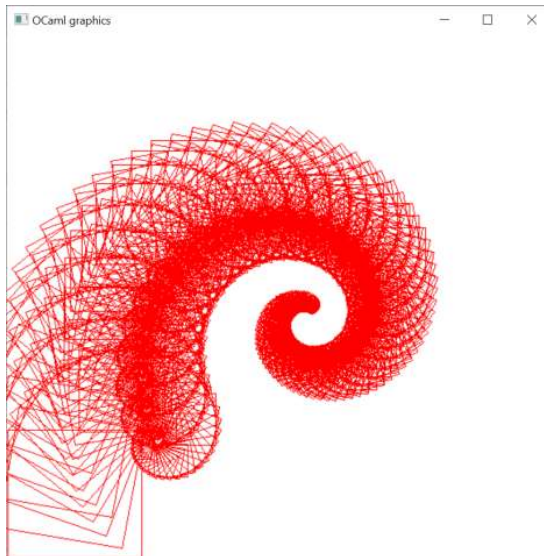


Drawing on a window

- Programs that use transforms
- Complex transform operations on painter
 - right_split, up_split, corner_split...
- Simple transform operations on painter
 - tf_painter, flip, scale, translate, rotate
- Frames as a tuple of vectors
 - new_frame, frame_to_globalcoord_map
- 2D vectors as tuples
 - add, sub, prod, smul
- However tuples are implemented

```
(*draw-----  
*)  
let draw painter frame =  
  open_graph "600x600";  
  clear_graph ();  
  painter frame;  
  (*close_graph ();*)  
  ()
```

This space is not a mistake



A Picture Language: Overall Program

```
#load "graphics.cma";;  
open Graphics;;
```

Load Graphics module

```
(*vector 2d*)  
(*frame*)  
(*base painter*)  
(*simple transform on painter*)  
(*complex transform on painter*)  
(*draw*)
```

After `open`, you can use `lineto` instead of `Graphics.lineto`

```
let rs = rot_scale (scale 0.5 0.5 base_painter) 50  
let p1 = base_painter  
let p2 = flip_ver rs  
let p3 = flip_hor rs  
let p4 = beside rs rs  
let p5 = below rs rs  
let p6 = flipped_pairs rs  
let p7 = right_split rs 8  
let p8 = up_split rs 8  
let p9 = corner_split rs 8  
let pa = rot_scale (scale 0.5 0.5 rs) 50  
let _ = draw p9 frame_g
```

Compound Data: Lists

- List

- Any number of items of the same type
- Tuple: fixed number of possibly different types
- E.g.)

```
# [1; 2; 3];;  
- : int list = [1; 2; 3]
```

```
# ["hello"; "world"];;  
- : string list = ["hello"; "world"]
```

```
# [1, 2, 3];; (*semicolons vs commas*)  
- : (int * int * int) list = [(1, 2, 3)]
```

Compound Data: Lists

- Constructing lists with `::`

```
# 1::2::3::[];; (* two list constructors: [] and :: *)  
- : int list = [1; 2; 3]
```

```
# 1::(2::(3::[]));;  
- : int list = [1; 2; 3]
```

```
# [1;2;3] @ [4;5;6];; (* list concatenation *)  
- : int list = [1; 2; 3; 4; 5; 6]
```

```
# [];;  
- : 'a list = []
```

Compound Data: Lists

- Use **pattern matching** to extract components
 - Two list constructors: `[]` and `::`

```
let rec sum l =  
  match l with  
  | [] -> 0  
  | hd :: tl -> hd + sum tl  
sum [1;2;3];;
```

```
- : int = 6
```

```
let rec sum = function  
  | [] -> 0  
  | hd :: tl -> hd + sum tl
```

function is equivalent to
<param> match <param> with

Compound Data: Lists

- Mapping over list
 - Apply a transform to each element in a list and generate the list of results

```
let rec map f l =  
  match l with  
  | [] -> []  
  | hd :: tl -> (f hd) :: map f tl;;
```

```
val map : ('a -> 'b) -> 'a list -> 'b list = <fun>
```

```
let _ = map (fun x -> x * x) [1; 2; 3];;
```

```
- : int list = [1; 4; 9]
```


Compound Data: Lists

- Filter

- Apply a predicate function to each element in a list and generate a filtered list

```
let rec filter f l =  
  match l with  
  | [] -> []  
  | hd :: tl -> if f hd  
                 then hd :: filter f tl  
                 else filter f tl  
let _ = filter ((fun x -> x mod 2 = 0)) [1; 2; 3; 4; 5]  
  
- : int list = [2; 4]
```

Compound Data: Lists

- Function composition by `|>` operator

```
let sum_of_odd_squares l =  
  l |> filter (fun x -> x mod 2 = 1)  
    |> map (fun x -> x * x)  
    |> sum
```

```
let _ = sum_of_odd_squares [1;2;3;4;5;6;7;8;9;10];;  
- : int = 165
```

Compound Data: Records

- Records
 - Similar to tuples
 - Individual fields are named
- Defining new data type

```
# type point2d = { x : float; y : float };;  
type point2d = { x : float; y : float; }
```

```
# let p = { x = 3.; y = -4. };;  
val p : point2d = {x = 3.; y = -4.}
```

■ Accessing data

function parameter

```
let mag1 { x = _x; y = _y } = (*pattern matching*)  
  sqrt (_x ** 2. +. _y ** 2.)
```

```
let mag2 { x; y } = (*field punning*)  
  sqrt (x ** 2. +. y ** 2.)
```

omitting param. names
when they are equal to
field names

```
let mag3 p = (*dot notation*)  
  sqrt (p.x ** 2. +. p.y ** 2.)
```

```
let mag = mag3
```

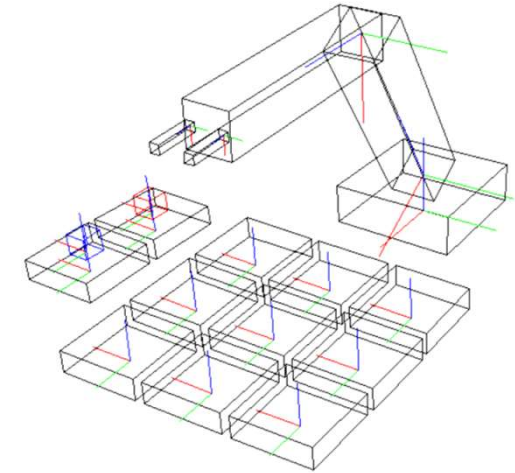
```
let dist p q = (*distance between p and q*)  
  mag { x = p.x -. q.x; y = p.y -. q.y }
```

```
let p = { x = 3.; y = -4. }
```

```
let q = { x = 4.; y = -5. }
```

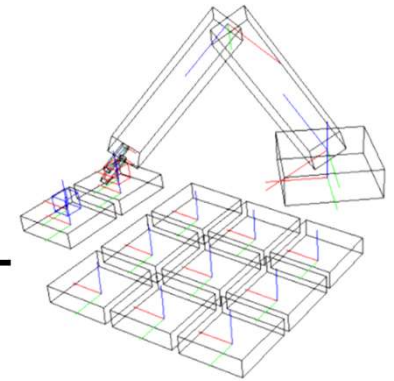
```
let _ = dist p q  
- : float = 1.4142135623730951
```

Assignment 3



- Implement a Tic-Tac-Toe game
 - Download [robot.zip](#)
 - Implement all **TODO** parts
 - After finishing the assignment, you should be able to play the Tic-Tac-Toe game with the robot
 - Upload [basis.ml](#), [board.ml](#), [command.ml](#), [drawer.ml](#), [pose.ml](#), [vector.ml](#) in a **single zip file** to Brightspace
- Due date: 4/4/2024

Abstraction Barriers



Game Plays the game

winner, next_mark, game, ...

Command moves robots

move_to_pose, pick, drop, mark , ...

Drawer draws a robot and a board w.r.t. a basis

draw_box, draw_robot, draw_arm1, ...

Pose pose of a robot

get_pose, chg_pose, find_pose, ...

Basis as a tuple of vectors

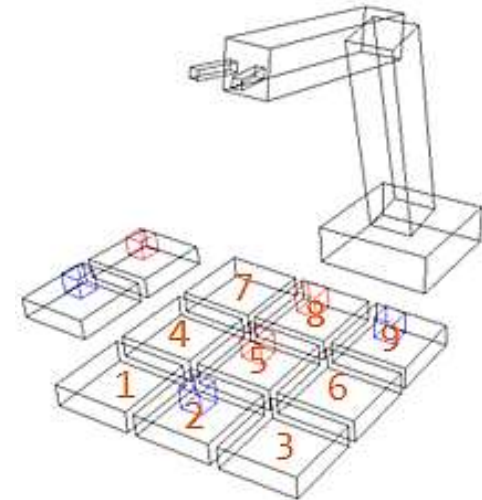
scale, translate, rot, v2g, b2g, ...

3D vectors as tuples

add, sub, prod, smul, ...

Assignment 3

- To play Tic-Tac-Toe
 - Press the **number keys** (1 ~ 9) to put a mark at the position
 - Press **q** to quit
- The robot should mark on the position, where
 - it will **win** the game if the position is marked by the robot
 - it will **lose** the game if the position is marked by the other
 - Otherwise, mark **any empty position**



```
(*app.ml*)
```

```
...
```

```
#use "globals.ml"  
#use "vector.ml"  
#use "basis.ml"  
#use "board.ml"  
#use "pose.ml"  
#use "drawer.ml"  
#use "command.ml"  
#use "game.ml"
```



Abstraction levels

You can test each file by uncommenting
test codes

```
let app () =
```

```
...
```

```
  (*camera basis*)
```

```
  let b_camera = (b_rotx (-60.) (b_rotz (-210.) gb_basis)) in
```

```
  (*initial pose*)
```

```
  let ipose = (90., 30., 60., 0., mark_n) in
```

```
  (*initial board*)
```

```
  let iboard = [ mark_n; mark_n; mark_n;  
                 mark_n; mark_n; mark_n;  
                 mark_n; mark_n; mark_n;  
                 mark_o (*9*); mark_x (*10*)] in
```

```
  Graphics.open_graph " 800x800";
```

```
  Graphics.auto_synchronize false;
```

```
  game b_camera (ipose, iboard) |> print_result;
```

```
  Graphics.auto_synchronize true
```

```
let _ = app ()
```



```
(*drawer.ml*)
```

```
(*convert b w.r.t. basis to the global coordinate*)
```

```
let b2g_basis b basis =
```

```
...
```

```
let draw_arm1 pose =
```

```
  let s      = 0.9 in
```

```
  let v_ta2 = (0.0,0.0,0.56) in
```

```
  fun basis ->
```

```
    let b_a2      = gb_basis (*b_a2: basis for arm 2*)
```

```
      (*TODO: rotate gb_basis by arm2 angle of pose around y axis*)
```

```
      (*TODO: scale the result by 0.5*)
```

```
      (*TODO: translate the result by v_ta2*)
```

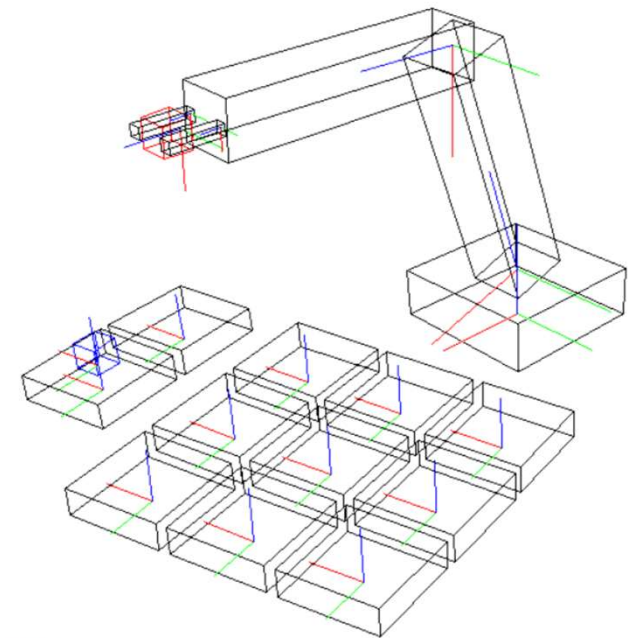
```
      (*TODO: convert the result in basis coord to global coord*)
```

```
|> b_rot y (get_pose pose "arm2")
```

```
|> b_scale 0.5
```

```
|> b_translate v_ta2
```

```
|> fun b -> b2g_basis b basis in
```



These are not in your assignment file

```
(*draw arm2 in b_a2 basis*)
```

```
draw_arm2 pose b_a2;
```

```
(*draw arm1*)
```

```
draw_box (0.12/.s) (0.12/.s) (0.5/.s) Graphics.black basis
```

(*pose.ml*)

```
type pose = float * float * float * float * float;;
```

(*find the angle of joints to get to x y z*)

```
let find_pose (x, y, z) =
```

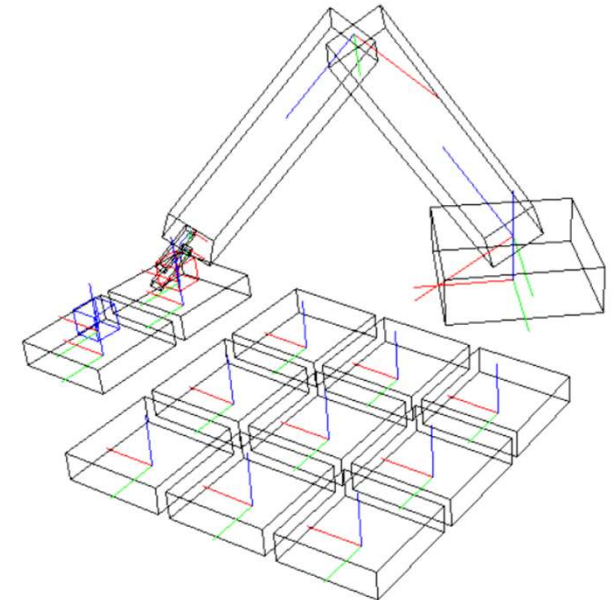
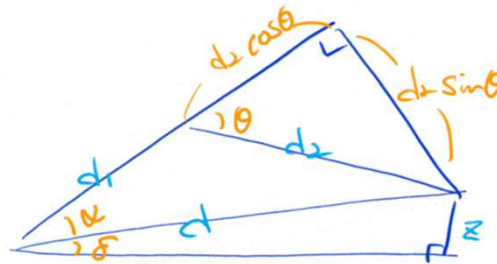
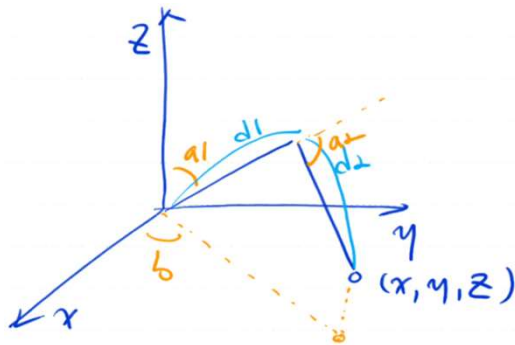
```
  fun f m ->
```

```
    (*TODO: find b, a1, and a2 and return the pose (b, a1, a2, f, m)
```

```
      b: angle (deg) of base measured from x axis (use atan2),
```

```
      a1: angle (deg) of arm1 measured from z axis
```

```
      a2: angle (deg) of arm2 measured from arm1 ... *)
```



$$d = \sqrt{x^2 + y^2 + z^2}$$
$$(d_1 + d_2 \cos \theta)^2 + (d_2 \sin \theta)^2 = d^2$$
$$\sin \alpha = d_2 \sin \theta / d$$
$$\sin \delta = z / d$$
$$\tan b = \frac{y}{x}$$

```
(*command.ml*)
```

```
(*move from pose to target_pose*)
```

```
let moveto_pose b_camera (pose, board) target_pose =  
  let db = (get_pose target_pose "base") -. (get_pose pose "base") in  
  let da1 = (get_pose target_pose "arm1") -. (get_pose pose "arm1") in  
  let da2 = (get_pose target_pose "arm2") -. (get_pose pose "arm2") in  
  let df = (get_pose target_pose "finger") -. (get_pose pose "finger") in
```

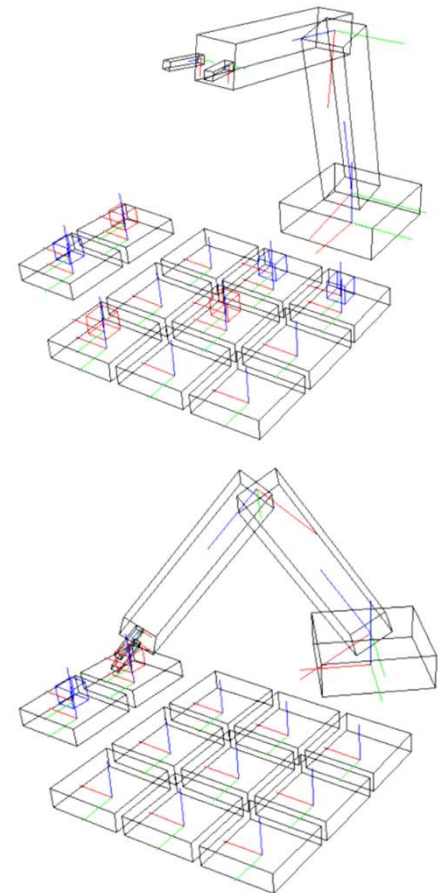
```
(*move the joint <ang> angle in <step> steps  
  e.g. rotate arm1 30 deg in 5 steps  
      => rotate arm1 5 times 6 deg each
```

```
*)
```

```
let rot_joint pose joint ang step =  
  (*TODO: implement this method  
  - on each step, draw the robot and the board  
  - wait for 50ms by calling Thread.delay 0.05  
  - after rotating step times, return the final pose  
  *)
```

```
(*move the joints in base, arm1, arm2, and finger order*)
```

```
let p = pose  
  |> fun p -> rot_joint p "base" db 5  
  |> fun p -> rot_joint p "arm1" da1 5  
  |> fun p -> rot_joint p "arm2" da2 5  
  |> fun p -> rot_joint p "finger" df 3 in  
(p, board)
```



```
(*command.mL*)
```

```
(*put mark at dst*)
```

```
let mark b_camera (pose, board) mrk dst =  
  let src = if mrk = mark_o then 9 else 10 in  
  let f = get_pose pose "finger" in  
  let m = get_pose pose "mark" in
```

```
  (*TODO: 1) find b, a1, and a2 for dst_pose and src_pose  
           using find_pose, mark_pos then  
          2) pass two params for the fun returned by find_pose
```

```
*)
```

```
let dst_pose = in (*robot's pose for the dst-th mark with finger is f, mark is mrk*)  
let src_pose = in (*robot's pose for the src-th mark with finger is 0, mark is m*)
```

```
(*moveto_pose with the first param applied*)
```

```
let.mvp = moveto_pose b_camera in
```

```
(*TODO: 1. move to pose src_pose (use.mvp)  
          2. pick the mark at src (use pick)  
          3. lift (use.mvp and lift_pose)  
          4. move to pose dst_pose (use.mvp)  
          5. drop the mark at dst (use drop)  
          6. lift (use.mvp and lift_pose)  
          7. return the resulting pose and the board*)
```

