

ADVANCED GRAPHICS: ROTATION, 3D, AND SCALING

ISE 108: INTRODUCTION TO PROGRAMMING
STONY BROOK UNIVERSITY

LIST OF TOPICS

- Rotation
- Translation: Moving the origin
- Working in Three Dimensions
- Scaling
- Creating your own polygons
- Grouping transformations

ROTATION AND TRANSLATION

ROTATION

- Use `rotate ()` to rotate (spin) a shape
- rotation is clockwise
- `rotate ()` takes one argument: an angle (in radians)
 - Use the `radians ()` command to translate degrees into radians (2π radians = 360°)
 - ex. `rotate(radians(45)) ;`

ROTATION: THE CATCH

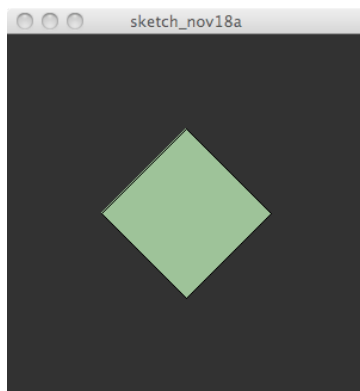
- Rotation moves a shape around the origin
- The origin (coordinates (0, 0)) defaults to the top-left corner of the window
 - This means that rotated objects “swing down” instead of spinning around their center
- Solution: move the origin!

TRANSLATION

- Translation shifts the origin from the top left corner to a different location
- Use the `translate()` function to determine the new position of the origin
 - `translate()` takes an x-offset and a y-offset
 - ex. `translate(50, 0)` moves origin 50 px right
- Note: this changes where every shape is drawn!
- The origin resets to the top left when `draw()` restarts

TRANSLATION AND ROTATION

```
size(300, 300);  
background(50);  
fill(150, 200, 150);  
  
translate(150, 150);  
rotate(radians(45));  
rect(-50, -50, 100, 100);
```



Note: the new origin is at the center of the shape!

WORKING IN 3D

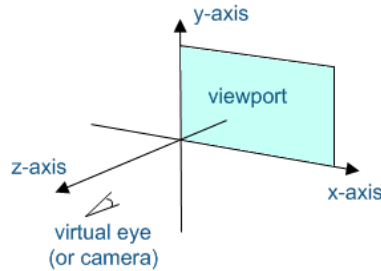
ADDING A THIRD DIMENSION

- The third dimension runs along the Z axis
 - +Z: out of the screen
 - -Z: into the screen

- To make a 3D sketch, we add an extra argument to `size()`:

`size(width, height, P3D);`

- “P3D”: use Processing’s 3D renderer



TRANSLATION IN 3D

- Translate also accommodates three dimensions
- Just add a third argument to `translate()`:
 - `translate(50, 100, -30)` shifts the origin 50 pixels right, 100 pixels down, and 30 pixels “away”
- NOTE: 3D translation doesn’t look different from 2D unless we also rotate the sketch!

ROTATION IN 3D

- We can rotate a shape around all three axes
 - By default, shapes rotate around the Z axis (which points out of the screen)
- Use `rotateX()`, `rotateY()`, and `rotateZ()` to specify which axis to rotate around
 - `rotateZ()` is identical to `rotate()`

3D SHAPES

- Processing provides two built-in 3D shapes
 - Box — a 3D rectangle
 - Syntax: `box(width, height, depth)`
 - Sphere — a 3D circle/ellipse
 - Syntax: `sphere(radius)`
 - Use `noStroke()` to turn off the “facets” / lines between the pieces that make up the sphere

Image credit: <http://polymathprogrammer.com/2008/09/01/cartesian-coordinates-and-transformation-matrices/>

STACKING TRANSFORMATIONS

COMBINING ROTATIONS

- Suppose that we want to rotate two shapes independently of one another
- Problem: `rotate()` and `translate()` are relative to the window's previous coordinates
 - Calling `rotate()` again causes the second object to rotate around the first, not the origin
- To solve this, we need to “reset” the window's state between rotations, to start “fresh”

WELCOME TO THE MATRIX

- Processing uses a matrix (a table of numbers) to store information about the coordinate system
 - Every rotation/translation updates the matrix
- We can save and restore the state of the matrix at any point
 - This lets us “undo” one transformation before we apply the next

BRIEF INTERLUDE: STACKS



- A stack stores data in Last-In, First-Out order
- Push: add a new item to the top of the stack
- Pop: remove the item at the top of the stack
- Processing uses a stack to save copies of the coordinate matrix

Image source: http://static.dezeen.com/uploads/2008/04/shay_alkalay_stack_1800mm_o.jpg

REPEATING HISTORY...

- To prevent one transformation from affecting the rest, we need to reset the coordinate matrix after working with each shape
- General strategy:
 1. Save current state of matrix
 2. Perform translation/rotation operations
 3. Restore the old version of the matrix
 4. Repeat steps 1–3 for the next shape

MATRIX OPERATIONS

- Use `pushMatrix()` to save the current state of the coordinate matrix
- Use `popMatrix()` to restore the coordinate matrix to its last saved state
- You must have an equal number of `pushMatrix()` and `popMatrix()` operations
- The stack has an unlimited storage capacity

SCALING AND POLYGONS

SCALING IMAGES

- Use the `scale()` function to change the size of any objects onscreen
- `scale()` takes a floating-point argument representing the percentage to scale by
 - 1.0 = 100%, 3.0 = 300%, 0.5 = 50%, etc.
- Use two or three arguments to scale by different amounts in those directions/dimensions
 - e.g., `scale(1.0, 2.0, 3.0)` stretches an object 200% vertically and 300% in depth

DRAWING YOUR OWN SHAPES

- Processing allows us to create our own polygons
- Use the `vertex()` command to set one point
 - `vertex()` takes x, y, and (optional) z coordinates
- Start the definition by calling `beginShape()`
- End with a call to `endShape()`
 - use `endShape(CLOSE)` to join the first and last vertices

SIMPLE POLYGON EXAMPLE

- Drawing a square using `vertex()`:

```
beginShape();  
vertex(50, 50);    // top left  
vertex(150, 50);   // top right  
vertex(150, 150);  // lower right  
vertex(50, 150);   // lower left  
endShape(CLOSE);
```

ADVANCED POLYGON TRICKS

- Use `curveVertex()` instead of `vertex()` to join points with curved lines
- `beginShape()` can take an optional “mode” argument
 - This argument affects how vertices are connected
- Modes: `TRIANGLES`, `TRIANGLE_FAN`, `TRIANGLE_STRIP`, `QUADS`, `QUAD_STRIP`, `POINTS`, `LINES`

see http://processing.org/reference/beginShape_.html

POLYGON MODES

- Supplying an argument to `beginShape()` tells Processing how to treat the vertices it gets
 - “`TRIANGLES`” / “`QUADS`”: Every group of 3 or 4 vertex points make up a triangle/quadrangle
 - Adding “`_STRIP`”: triangles/quadrangles are connected by intermediate shapes
 - `TRIANGLE_FAN`: triangles are positioned around a central point (a common vertex)