Problem 1: number of all-pairs shortest paths

$$d_{ij}^0 = \ell(v_i, v_j) \quad \text{if} \quad (v_i, v_j) \in E$$

$$h_{ij}^0 = \begin{cases} 1 & \text{if } i = j \\ \infty & \text{otherwise} \end{cases}$$

$$d_{ij}^k = \infty \quad \text{if} \quad (v_i, v_j) \notin E^k$$

$$h_{ij}^k = \begin{cases} \infty & \text{if } i = j \\ 1 & \text{otherwise} \end{cases}$$

$$d_{ij}^k = \min\{d_{ij}^{k-1}, d_{ik}^{k-1} + d_{kj}^{k-1}\} \quad \text{if } k > 0$$

$$h_{ij}^k = \begin{cases} h_{ij}^{k-1} & \text{if } i = j \\ n_{ij}^{k-1} n_{ij}^{k-1} + n_{ik}^{k-1} n_{kj}^{k-1} & \text{otherwise} \end{cases}$$

$$d_{ij}^k < d_{ij}^{k-1} + \sum_{k=1}^{M} d_{ik}^k + d_{kj}^k$$
Algorithm

for $i \leq 1$ to $n$ do
  for $j \leq 1$ to $n$ do
    if $i = j$ then $d_{ij} = 0$; $n_{ij} = 1$
    else if $(v_i, v_j) \in E$ then
      $d_{ij} = \ell(v_i, v_j)$, $n_{ij} = 1$
  $O(n^2)$
  $d_{ij} \rightarrow \infty$, $n_{ij} = 0$
  end do
  $O(n)$
end do

for $k = 1$ to $n$ do
  for $i \leq 1$ to $n$ do
    for $j \leq 1$ to $n$ do
      $d_{ij} = d_{ik} + d_{kj}$
      if $d_{ij} = d_{ik} + d_{kj}$ then

&
Problem 2; Dynamic Tables

Scenario

- Have a table—maybe a hash table.
- Don’t know in advance how many objects will be stored in it.
- When it fills, must reallocate with a larger size, copying all objects into the new, larger table.
- When it gets sufficiently small, might want to reallocate with a smaller size.

Details of table organization not important.

Goals

1. $O(1)$ amortized time per operation.
2. Unused space always $\leq$ constant fraction of allocated space.

Load factor $\alpha = \frac{num}{size}$, where $num = \#$ items stored, $size = \text{allocated size}$.

If $size = 0$, then $num = 0$. Call $\alpha = 1$.

Never allow $\alpha > 1$.

Keep $\alpha > \text{a constant fraction} \Rightarrow \text{goal (2)}$. 
Table expansion

Consider only insertion.

- When the table becomes full, double its size and reinsert all existing items.
- Guarantees that $\alpha \geq 1/2$.
- Each time we actually insert an item into the table, it’s an elementary insertion.

**TABLE-INSERT**($T, x$)

```
if $T.size == 0$
    allocate $T.table$ with 1 slot
    $T.size = 1$
if $T.num == T.size$ // expand?
    allocate new-table with $2 \cdot T.size$ slots
    insert all items in $T.table$ into new-table // $T.num$ elem insertions
    free $T.table$
    $T.table = new-table$
    $T.size = 2 \cdot T.size$
insert $x$ into $T.table$ // 1 elem insertion
$T.num = T.num + 1$
```

Initially, $T.num = T.size = 0$. 
**Running time**

Charge 1 per elementary insertion. Count only elementary insertions, since all other costs together are constant per call.

\[ c_i = \text{actual cost of } i\text{th operation} \]

- If not full, \( c_i = 1 \).
- If full, have \( i - 1 \) items in the table at the start of the \( i\)th operation. Have to copy all \( i - 1 \) existing items, then insert \( i\)th item \( \Rightarrow c_i = i \).

\( n \) operations \( \Rightarrow c_i = O(n) \Rightarrow O(n^2) \) time for \( n \) operations.

Of course, we don’t always expand:

\[
c_i = \begin{cases} 
  \frac{i}{\log_2 i} & \text{if } i - 1 \text{ is exact power of } 2 \\
  1 & \text{otherwise}
\end{cases}
\]

Total cost:

\[
\sum_{i=1}^{n} c_i 
\]

\[
\leq n + \sum_{j=0}^{\lfloor \log_2 n \rfloor} 2^j
\]

\[
= n + 2^{\lfloor \log_2 n \rfloor + 1} - 1
\]

\[
= n + \frac{2^{\lfloor \log_2 n \rfloor + 1} - 1}{2 - 1}
\]

\[
< n + 2n
\]

\[
= 3n
\]

Therefore, aggregate analysis says amortized cost per operation = \( \frac{3n}{n} = \Theta(1) \).

**Accounting method**

Charge $3 per insertion of \( x \).

- $1 pays for \( x \)'s insertion.
- $1 pays for \( x \) to be moved in the future.
- $1 pays for some other item to be moved.

Suppose we’ve just expanded, \( \overline{\text{size}} = m \) before next expansion, \( \overline{\text{size}} = 2m \) after next expansion.

- Assume that the expansion used up all the credit, so that there’s no credit stored after the expansion.
- Will expand again after another \( m \) insertions.
Assume that the expansion used up all the credit, so that there's no credit stored after the expansion.

- Will expand again after another \( m \) insertions.
- Each insertion will put $1 on one of the \( m \) items that were in the table just after expansion and will put $1 on the item inserted.
- Have $2m$ of credit by next expansion, when there are \( 2m \) items to move. Just enough to pay for the expansion, with no credit left over!
Potential method

\[ \Phi(T) = 2 \cdot T.num - T.size \]

- Initially, \( num = size = 0 \Rightarrow \Phi = 0 \).
- Just after expansion, \( size = 2 \cdot num \Rightarrow \Phi = 0 \).
- Just before expansion, \( size = num \Rightarrow \Phi = num \Rightarrow \) have enough potential to pay for moving all items.
- Need \( \Phi \geq 0 \), always.

Always have

\[
\begin{align*}
\text{size} & \geq \text{num} \geq \text{size}/2 \Rightarrow \\
2 \cdot \text{num} & \geq \text{size} \Rightarrow \\
\Phi & \geq 0 .
\end{align*}
\]

Amortized cost of \( i \) th operation

\( num_i = num \) after \( i \) th operation,

\( size_i = size \) after \( i \) th operation,

\( \Phi_i = \Phi \) after \( i \) th operation.

- If no expansion

\[
\begin{align*}
\text{size}_{i+1} & = \text{size}_{i} \\
2 \cdot \text{num}_i & = 2 \cdot \text{num}_{i-1} + 1 \\
\text{c}_i & = 1 .
\end{align*}
\]

Then we have

\[
\begin{align*}
\hat{c}_i & = c_i + \Phi_i - \Phi_{i-1} \\
& = 1 + (2 \cdot \text{num}_i - \text{size}_i) - (2 \cdot \text{num}_{i-1} - \text{size}_{i-1}) \\
& = 1 + (2 \cdot \text{num}_i - \text{size}_i) - (2(\text{num}_{i-1} - 1) - \text{size}_{i-1}) \\
& = 1 + 2 \\
& = 3
\end{align*}
\]
• If expansion:
  \[
  \text{size}_i = 2 \cdot \text{size}_{i-1},
  \]
  \[
  \text{size}_{i-1} = \text{num}_{i-1} = \text{num}_i - 1,
  \]
  \[
  c_i = \text{num}_{i-1} + 1 = \text{num}_i.
  \]

  Then we have
  \[
  \hat{c}_i = c_i + \Phi_i + \Phi_{i-1}
  \]
  \[
  = \text{num}_i + (2 \cdot \text{num}_i - \text{size}_i) - (2 \cdot \text{num}_{i-1} - \text{size}_{i-1})
  \]
  \[
  = \text{num}_i + (2 \cdot \text{num}_i - 2(\text{num}_i - 1)) - (2(\text{num}_i - 1) - (\text{num}_i - 1))
  \]
  \[
  = \text{num}_i + 2 - (\text{num}_i - 1)
  \]
  \[
  = 3.
  \]
Expansion and contraction

When $\alpha$ drops too low, contract the table.

- Allocate a new, smaller one.
- Copy all items.

Still want

- $\alpha$ bounded from below by a constant.
- amortized cost per operation = $O(1)$.

Measure cost in terms of elementary insertions and deletions.

“Obvious strategy”

- Double size when inserting into a full table (when $\alpha = 1$, so that after insertion $\alpha$ would become $> 1$).
- Halve size when deletion would make table less than half full (when $\alpha = 1/2$, so that after deletion $\alpha$ would become $< 1/2$).
- Then always have $1/2 \leq \alpha \leq 1$.
- Suppose we fill table.
  Then insert $\Rightarrow$ double
  2 deletes $\Rightarrow$ halve
  2 inserts $\Rightarrow$ double
  2 deletes $\Rightarrow$ halve
  ... 

Not performing enough operations after expansion or contraction to pay for the next one.
Simple solution

- Double as before: when inserting with $\alpha = 1 \Rightarrow$ after doubling, $\alpha = 1/2$.
- Halve size when deleting with $\alpha = 1/4 \Rightarrow$ after halving, $\alpha = 1/2$.
- Thus, immediately after either expansion or contraction, have $\alpha = 1/2$.
- Always have $1/4 \leq \alpha \leq 1$.

Intuition

- Want to make sure that we perform enough operations between consecutive expansions/contractions to pay for the change in table size.
- Need to delete half the items before contraction.
- Need to double half the items before expansion.
- Either way, number of operations between expansions/contractions is at least a constant fraction of number of items copied.

$$
\Phi(T) = \begin{cases} 
2 \cdot T.num - T.size & \text{if } \alpha \geq 1/2, \\
T.size/2 - T.num & \text{if } \alpha < 1/2.
\end{cases}
$$

$T$ empty $\Rightarrow \Phi = 0$.

$\alpha \geq 1/2 \Rightarrow num \geq size/2 \Rightarrow 2 \cdot num \geq size \Rightarrow \Phi \geq 0$.

$\alpha < 1/2 \Rightarrow num < size/2 \Rightarrow \Phi \geq 0$. 
3. CLRS 21.3-4: Suppose that we wish to add the UNION-FIND operation PRINT-SET.x/, which is given a node x and prints all the members of x’s set, in any order. Show how we can add just a single attribute to each node in a disjoint-set forest so that PRINT-SET.x/ takes time linear in the number of members of x’s set and the asymptotic running times of the other operations are unchanged. Assume that we can print each member of the set in O(1) time.

Maintain a circular, singly linked list of the nodes of each set.
To print, just follow the list until you get back to node x, printing each member of the list.
The only other operations that change are FIND, which sets x.next = x, and LINK, which exchanges the pointers x.next and y.next.
Problem 4

D(v) = product of
D(v) from root to
leaf l = salary of
D(v) x w x base-salary

search(numb)

V & root

while v is not a leaf do
for each child u of v do
    D(cw) & D(cw) x D(v)
end for

D(v) += 1

end while

return (v)