CSE 373 Analysis of Algorithms
Fall 2016
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LEC11: DEPTH-FIRST SEARCH (169-184)

Lecture slide courtesy of Prof. Steven Skiena
Prove that in a breadth-first search on a undirected graph $G$, every edge in $G$ is either a tree edge or a cross edge, where a cross edge $(x; y)$ is an edge where $x$ is neither is an ancestor or descendent of $y$. 

Lecture slide courtesy of Prof. Steven Skiena
BFS VS DFS

- The difference between BFS and DFS results is in the order in which they explore vertices.
- This order depends completely upon the container data structure used to store the *discovered but not processed* vertices (The Todo-list),
Queue allows the BFS to explore the oldest unexplored vertices first.

- Thus our explorations radiate out slowly from the starting vertex.

Stack allows the DFS to explore the vertices by lurching along a path, visiting a new neighbor if one is available, and backing up only when we are surrounded by previously discovered vertices.

- Thus, our explorations quickly wander away from our starting point.
DFS has a neat recursive implementation which eliminates the need to explicitly use a stack.

By maintaining a notion of traversal time for each vertex.

- Our time clock ticks each time we enter or exit any vertex.
- Keep track of the entry and exit times for each vertex.
DFS PSEUDO CODE

DFS(G, u)

state[u] = “discovered”
process vertex u if desired
entry[u] = time  /* time is global variable */
time = time + 1
for each v ∈ Adj[u] do
    process edge (u, v) if desired
    if state[v] = “undiscovered” then
        p[v] = u
        DFS(G, v)
state[u] = “processed”
exit[u] = time
time[u] = time  /* time is global variable */
The beauty of implementing dfs recursively is that recursion eliminates the need to keep an explicit stack:

dfs(graph *g, int v)
{
    edgenode *p; /* temporary pointer */
    int y; /* successor vertex */

    if (finished) return; /* allow for search termination */

    discovered[v] = TRUE;
    time = time + 1;
    entry_time[v] = time;

    process_vertex_early(v);
p = g->edges[v];
while (p != NULL) {
  y = p->y;
  if (discovered[y] == FALSE) {
    parent[y] = v;
    process_edge(v,y);
    dfs(g,y);
  }
  else if ((!processed[y]) || (g->directed))
    process_edge(v,y);
  if (finished) return;
  p = p->next;
}
process_vertex_late(v);
time = time + 1;
extitme[v] = time;
processed[v] = TRUE;
In a DFS of an undirected graph, we assign a direction to each edge, from the vertex which discover it:

- Tree edges
- Back edges

Undirected graph

Depth-first search tree
EDGE CLASSIFICATION FOR DFS

- Every edge is either:

  - Tree Edges
  - Forward Edge
  - Back Edge
  - Cross Edges

*Figure 5.14: Possible edge cases for BFS/DFS traversal*

- On any particular DFS or BFS of a directed or undirected graph, each edge gets classified as one of the above.
USEFUL PROPERTIES OF TIME INTERVALS

Who is an ancestor?

+ Suppose that \( x \) is an ancestor of \( y \) in the DFS tree.
+ Time interval of \( y \) must be properly nested within ancestor \( x \).
  - we must enter \( x \) before \( y \),
  - we must exit \( y \) before we exit \( x \)

How many descendants?

+ Half the time difference between the exit and entry times for \( v \) tells us how many descendants \( v \) has in the DFS tree.
  - Clock ticks in entering & exiting (2 times)
SUMMARY OF DFS PROPERTIES

- Entry and Exit times in several applications of BFS,
  + EX> topological sorting & biconnected/strongly-connected components.

- DFS partitions the edges of an undirected graph into exactly two classes: tree edges and back edges.
  + Tree edges discover new vertices, and are those encoded in the parent relation.
  + Back edges are those whose other endpoint is an ancestor of the vertex being expanded, so they point back into the tree.
APPLICATIONS OF DEPTH-FIRST SEARCH

- Application of DFS is surprisingly subtle, however meaning that its correctness requires getting details right.
- The correctness of a DFS-based algorithm depends upon specifics of exactly when we process the edges and vertices.
  + We can process vertex \( v \) either before we have traversed any of the outgoing edges from \( v \) \((\text{process_vertex_early}())\) or
  + After we have finished processing all of them \((\text{process_vertex_late}())\).
In undirected graphs, each edge \((x, y)\) sits in the adjacency lists of vertex \(x\) and \(y\).

- there are **two potential times to process each edge** \((x, y)\), namely when exploring \(x\) and when exploring \(y\).

Edge-specific processing happened the first time and take different action the second time we see an edge.

- EX> The labeling of edges (as tree edges or back edges) occurs during the first time the edge is explored
How can we tell if we have previously traversed the edge from $y$?

- If vertex $y$ is undiscovered: $(x, y)$ becomes a tree edge so this must be the first time visiting the edge $(x, y)$.
- If $y$ has not been completely processed: we explored the edge $(y, x)$ when we explored $y$ this must be the second time visiting $(x, y)$.
- If $y$ is an ancestor of $x$ thus in a discovered state: this must be our first traversal unless $y$ is the immediate ancestor of $x$—i.e. $(y, x)$ is a tree edge.
  - testing if $y == \text{parent}[x]$. 
Back edges are the key to finding a cycle in an undirected graph.

Any back edge going from \( x \) to an ancestor \( y \) creates a cycle with the path in the tree from \( y \) to \( x \).

```c
process_edge(int x, int y)
{
    if (parent[x] != y) { /* found back edge! */
        printf("Cycle from %d to %d:",y,x);
        find_path(y,x,parent);
        printf("\n\n");
        printf("\n\n");
        finished = TRUE; /* so that we finish after first cycle */
    }
}
```
DFS APPLICATION 2: ARTICULATION VERTICES

- **articulation vertex** or **cut-node**: a single vertex whose deletion disconnects a connected component of the graph.

- Any graph that contains an articulation vertex is inherently fragile, because deleting that single vertex causes a loss of connectivity between other nodes.
FINDING ARTICULATION VERTICES

- Brute force method $O(n(m+n))$:
  - just delete each vertex to do a DFS or BFS on the remaining graph to see if it is connected.

- Better method $O(n+m)$:
  - In a DFS tree, a vertex $v$ (other than the root) is an articulation vertex iff $v$ is not a leaf and some subtree of $v$ has no back edge incident until a proper ancestor of $v$. 
When traversing undirected graphs, every edge is either in the depth-first search tree or a back edge to an ancestor in the tree.

- Suppose we encountered a “forward edge” \((x, y)\) directed toward a descendant vertex. In this case, we would have discovered \((x, y)\) while exploring \(y\), making it a back edge.
- Suppose we encounter a “cross edge” \((x, y)\), linking two unrelated vertices.

For directed graphs, depth-first search labelings can take all four labels.
int edge_classification(int x, int y) {
    if (parent[y] == x)
        return(TREE);
    if (discovered[y] && !processed[y])
        return(BACK);
    if (processed[y] && (entry time[y]<entry time[x]))
        return(FORWARD);
    if (processed[y] && (entry time[y]>entry time[x]))
        return(CROSS);
    printf("Warning: unclassified edge (%d,%d)",x,y);
}

Figure 5.14: Possible edge cases for BFS/DFS traversal
A directed acyclic graph (DAG) has no directed cycles.

A topological sort of a graph is an ordering on the vertices so that all edges go from left to right. DAGs (and only DAGs) has at least one topological sort (here G; A;B; C; F;E;D).
Applications of Topological Sorting

- Topological sorting is often useful in scheduling jobs in their proper sequence.
- In general, we can use it to order things given precedence constraints.
- Example: Dressing schedule from CLR.
A directed graph is a DAG if and only if no back edges are encountered during a depth-first search.

Labeling each of the vertices in the reverse order that they are marked *processed* finds a topological sort of a DAG.

Why?

Consider what happens to each directed edge \( \{x,y\} \) as we encounter it during the exploration of vertex \( x \):
CASE ANALYSIS

- If y is currently *undiscovered*, then we then start a DFS of y before we can continue with x. Thus y is marked *processed* before x is, and x appears before y in the topological order, as it must.

- If y is *discovered* but not *processed*, then \{x,y\} is a back edge, which is forbidden in a DAG.

- If y is *processed*, then it will have been so labeled before x. Therefore, x appears before y in the topological order, as it must.
process_vertex_late(int v)
{
    push(&sorted,v);
}

process_edge(int x, int y)
{
    int class; /* edge class */
    class = edge_classification(x,y);
    if (class == BACK)
        printf("Warning: directed cycle found, not a DAG\n");
}
```c
void topsort(graph *g)
{
    int i;    /* counter */
    init_stack(&sorted);

    for (i=1; i<=g->nvertices; i++)
        if (discovered[i] == FALSE)
            dfs(g, i);

    print_stack(&sorted);  /* report topological order */
}
```

We push each vertex on a stack as soon as we have evaluated all outgoing edges. The top vertex on the stack always has no incoming edges from any vertex on the stack. Repeatedly popping them off yields a topological ordering.
A directed graph is strongly connected iff there is a directed path between any two vertices.

The **strongly connected components** of a graph is a partition of the vertices into subsets (maximal) such that each subset is strongly connected.

Observe that no vertex can be in two maximal components, so it is a partition.
There is an elegant, linear time algorithm to find the strongly connected components of a directed graph using DFS.

![strongly-connected components](image)

![associated DFS tree](image)
Depth-first search uses essentially the same idea as backtracking.
Both involve exhaustively searching all possibilities by advancing if it is possible, and backing up as soon as there is no unexplored possibility for further advancement.
Both are most easily understood as recursive algorithms.
strong_components(graph *g) {
    int i; /* counter */
    for (i=1; i<=(g->nvertices); i++) {
        low[i] = i;
        scc[i] = -1;
    }
    components_found = 0;
    init_stack(&active);
    initialize_search(&g);

    for (i=1; i<=(g->nvertices); i++)
        if (discovered[i] == FALSE) {
            dfs(g,i);
        }
}
int low[MAXV+1]; /* oldest vertex surely in component of v */
int scc[MAXV+1]; /* strong component number for each vertex */

process_edge(int x, int y)
{
    int class; /* edge class */
    class = edge_classification(x,y);
    if (class == BACK) {
        if (entry_time[y] < entry_time[ low[x] ] )
            low[x] = y;
    }
    if (class == CROSS) {
        if (scc[y] == -1) /* component not yet assigned */
            if (entry_time[y] < entry_time[ low[x] ] )
                low[x] = y;
    }
}
process_vertex_early(int v) { push(&active,v); }
process_vertex_late(int v)
{
    if (low[v] == v) /* edge (parent[v],v) cuts off scc */
        pop_component(v);

    if (entry_time[low[v]] < entry_time[low[parent[v]]])
        low[parent[v]] = low[v];
}

pop_component(int v)
{
    int t; /* vertex placeholder */
    components_found = components_found + 1;
    scc[v] = components_found;
    while ((t = pop(&active)) != v) {
        scc[t] = components_found;
    }
}