

**CSE 590: Special Topics Course
(Supercomputing)**

**Lecture 6
(The Message Passing Interface)**

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Principles of Message-Passing Programming

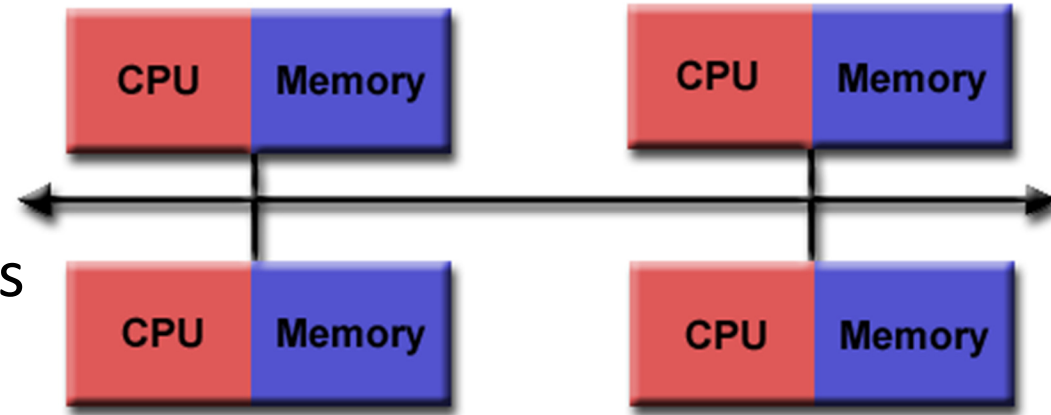
– One of the oldest and most widely used approaches for programming parallel computers

– Two key attributes

- Assumes a partitioned address space
- Supports only explicit parallelism

– Two immediate implications of partitioned address space

- Data must be explicitly partitioned and placed to appropriate partitions
- Each interaction (read-only and read/write) requires cooperation between two processes: process that has the data, and the one that wants to access the data



Source: Blaise Barney, LLNL

Structure of Message-Passing Programs

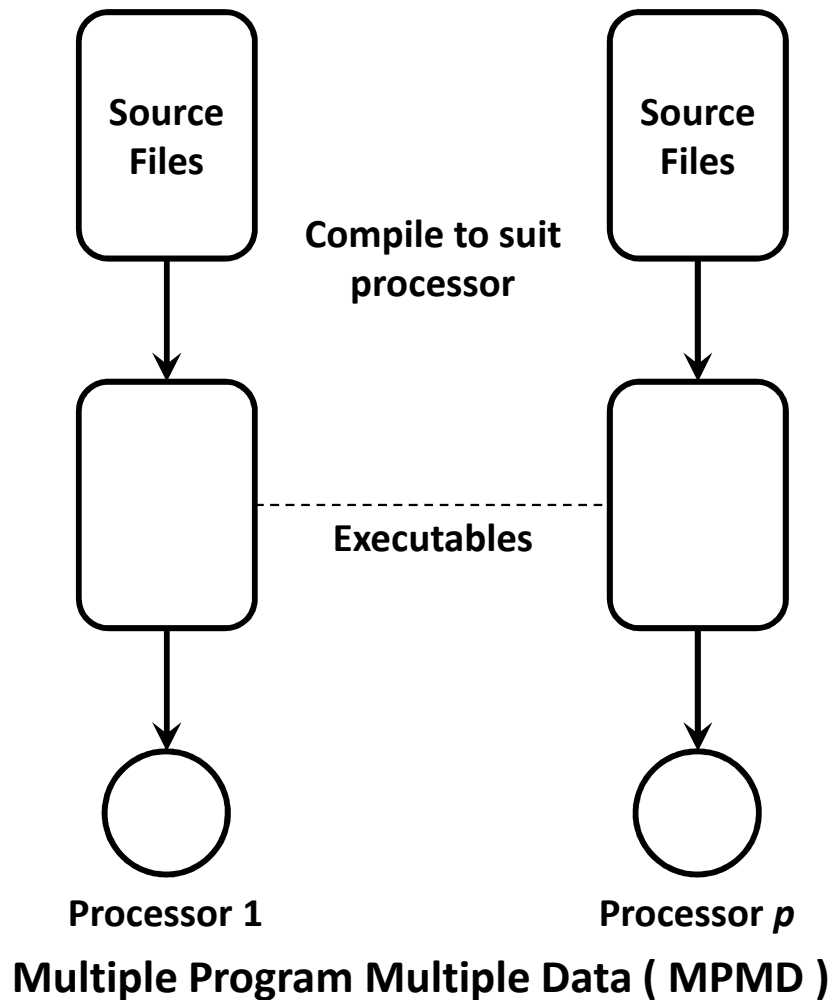
Asynchronous

- All concurrent tasks execute asynchronously
- Most general (can implement any parallel algorithm)
- Can be difficult to reason about
- Can have non-deterministic behavior due to races

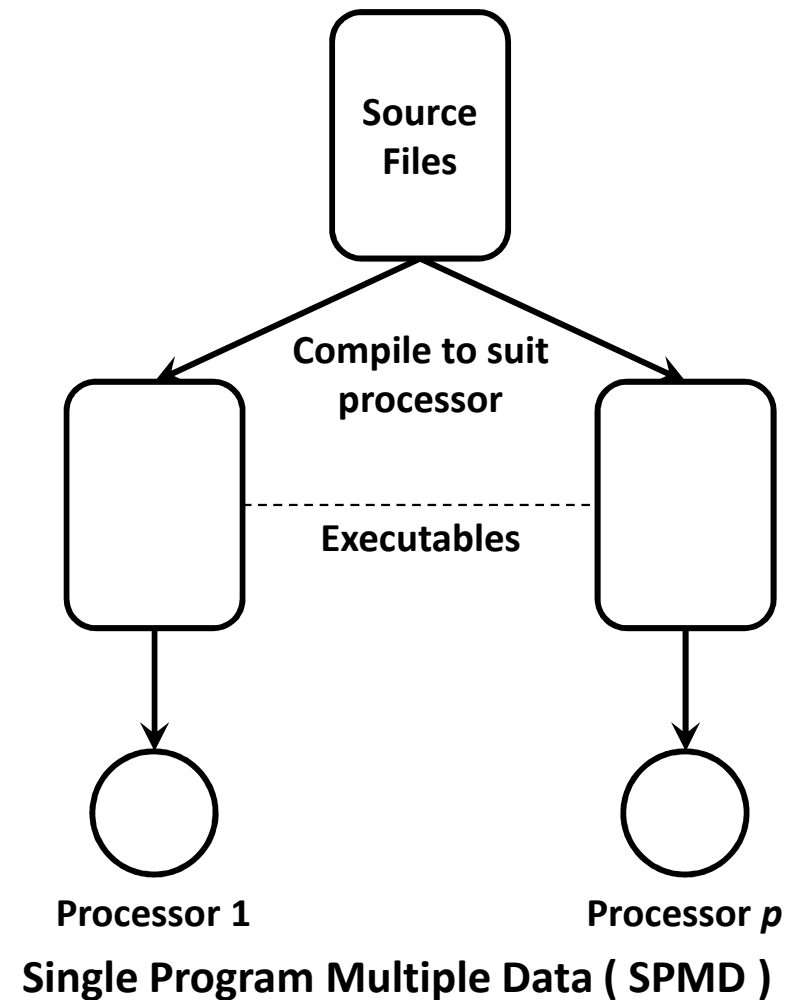
Loosly Synchronous

- A good compromise between synchronous and asynchronous
- Tasks or subset of tasks synchronize to interact
- Between the interactions tasks execute asynchronously
- Easy to reason about these programs

Structure of Message-Passing Programs



- Ultimate flexibility in parallel programming
- Unscalable



- Most message-passing programs
- Loosely synchronous or completely asynchronous

The Building Blocks: Send & Receive Operations

send(*&data*, *n*, *dest*):

Send *n* items pointed to by *&data* to a processor with id *dest*

receive(*&data*, *n*, *src*):

Receive *n* items from a processor with id *src* to location pointed to by *&data*

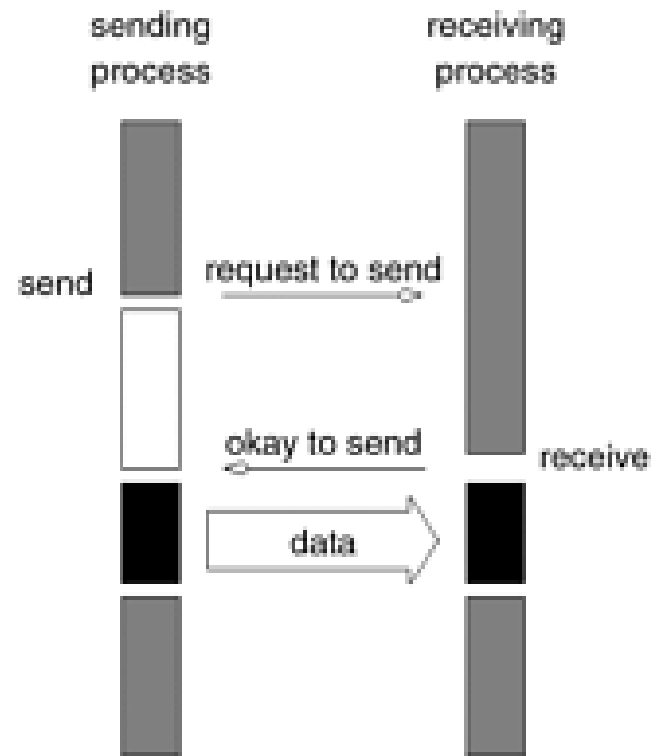
But wait! What P1 prints when P0 and P1 execute the following code?

```
1          P0                                P1
2
3          a = 100;                          receive(&a, 1, 0)
4          send(&a, 1, 1);                    printf("%d\n", a);
5          a=0;
```

Source: Grama et al., "Introduction to Parallel Computing", 2nd Edition

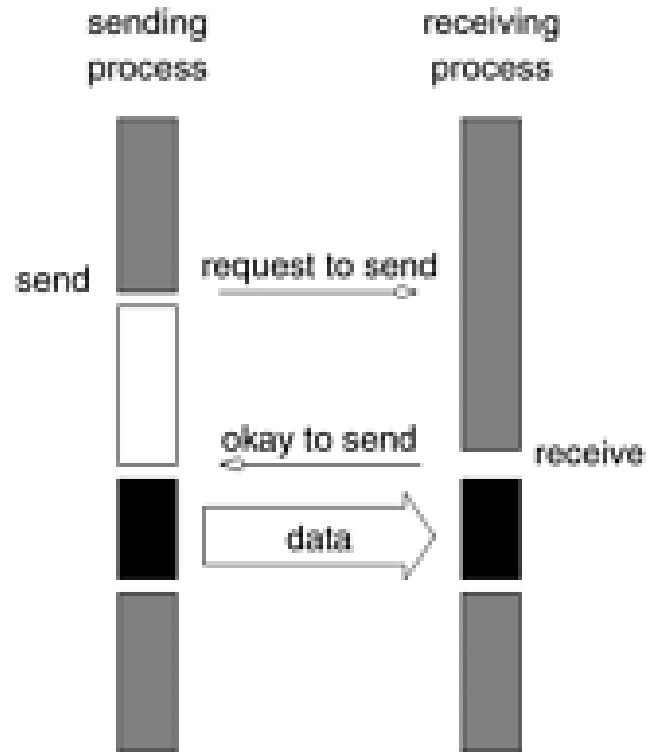
Blocking Non-Buffered Send / Receive

Sending operation waits until the matching receive operation is encountered at the receiving process, and data transfer is complete.



Blocking Non-Buffered Send / Receive

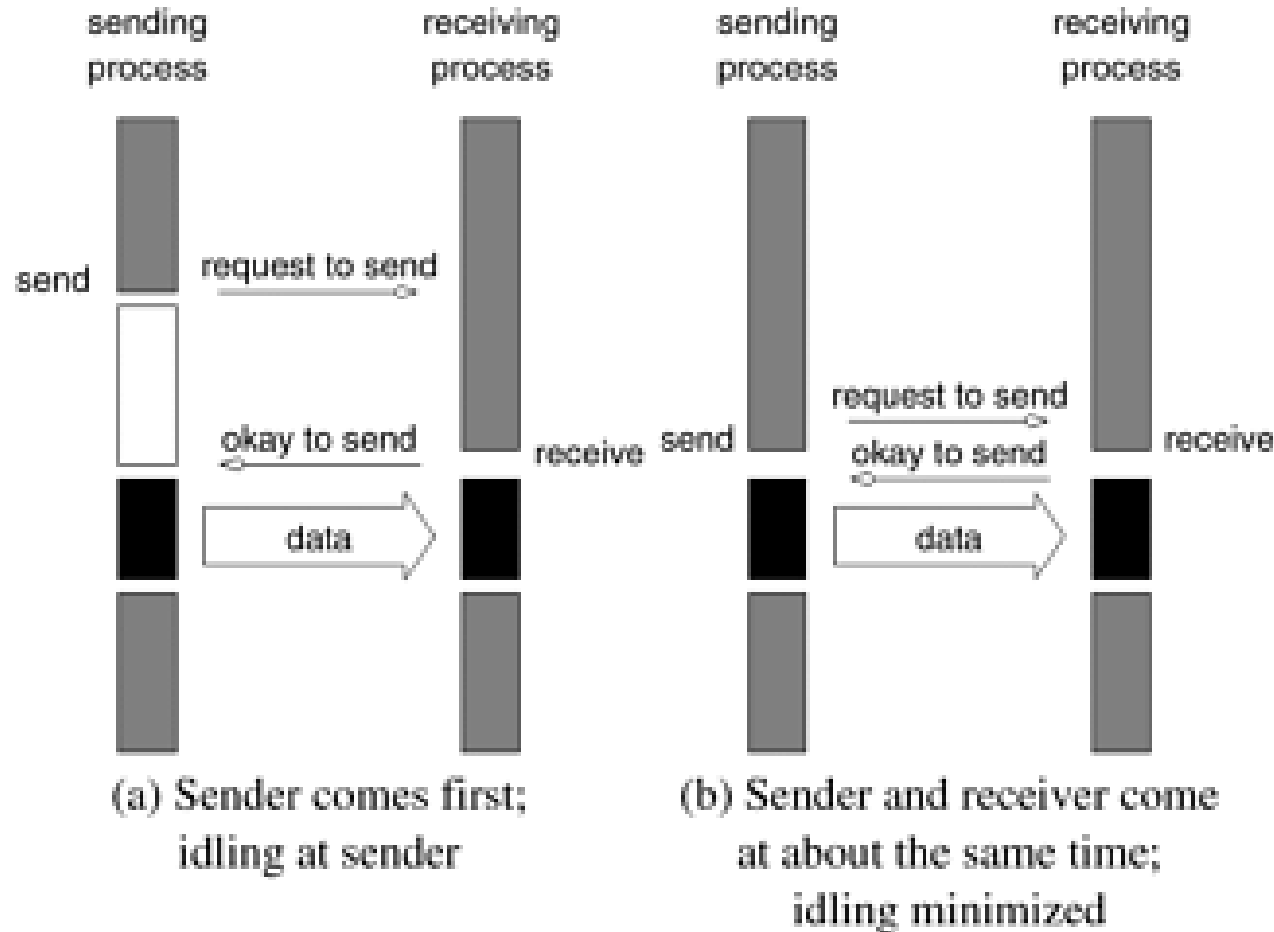
May lead to idling:



(a) Sender comes first;
idling at sender

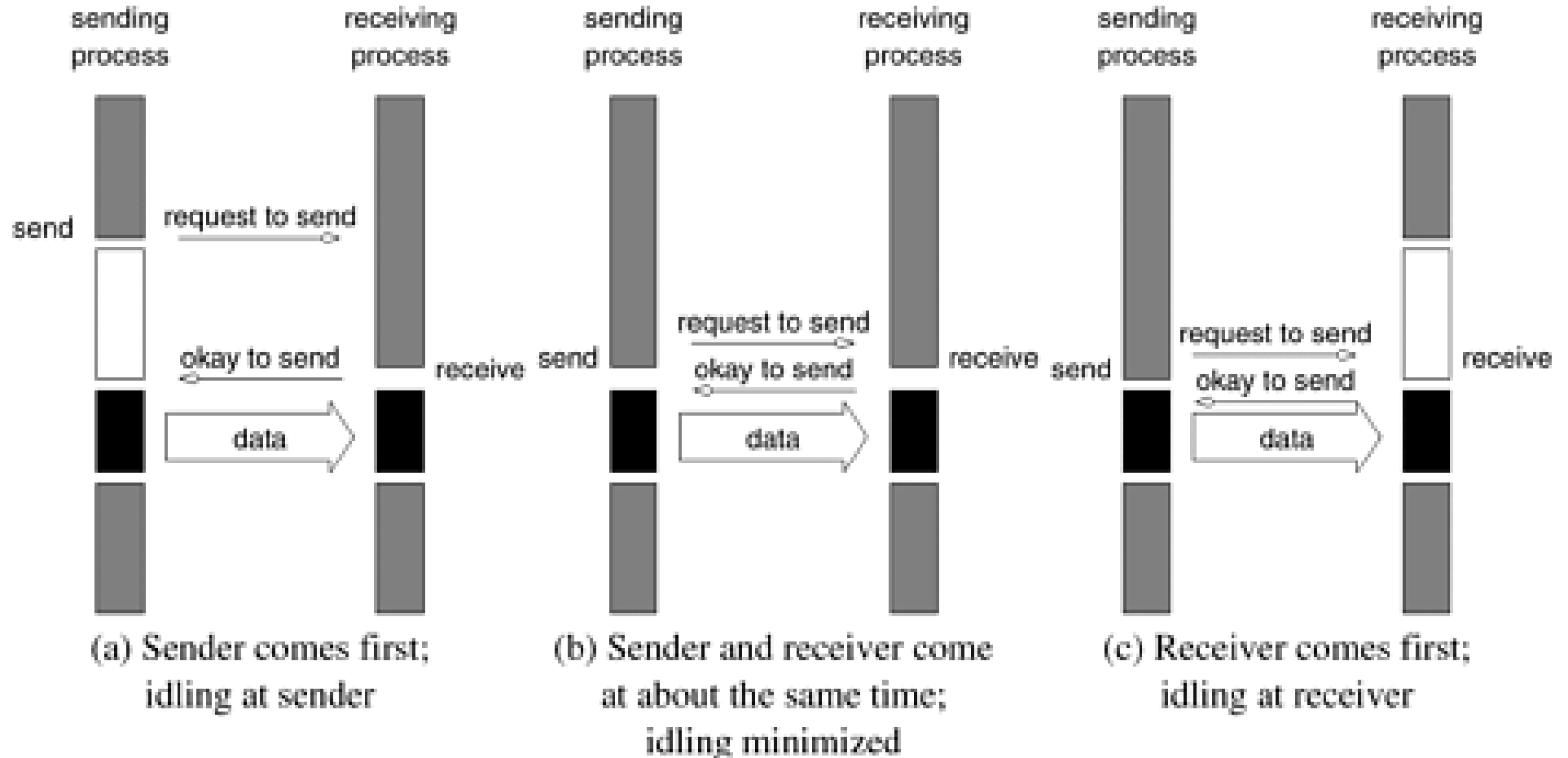
Blocking Non-Buffered Send / Receive

May lead to idling:



Blocking Non-Buffered Send / Receive

May lead to idling:



Source: Grama et al., "Introduction to Parallel Computing", 2nd Edition

Blocking Non-Buffered Send / Receive

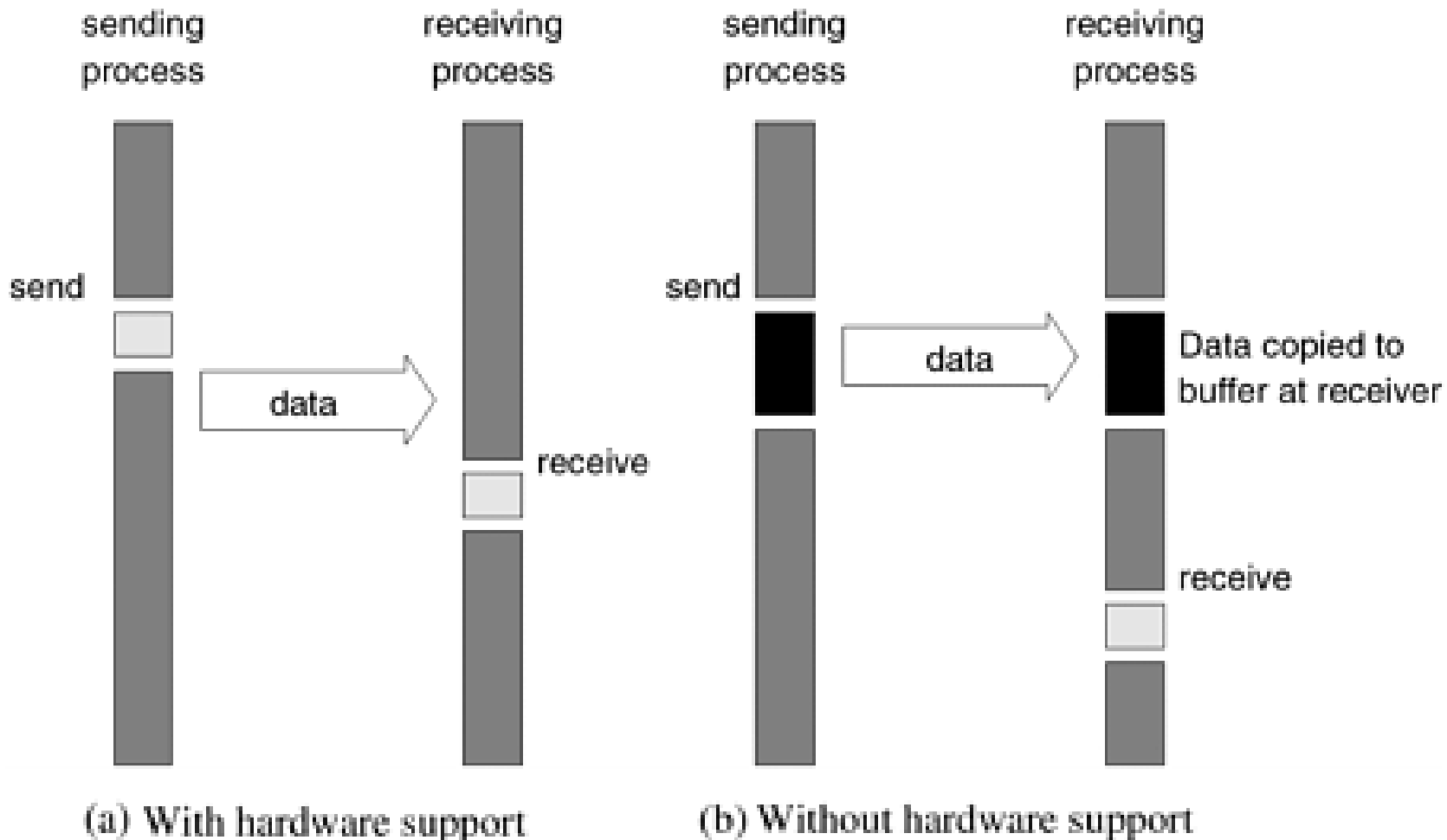
May lead to deadlocks:

```
1          P0          P1
2
3          send(&a, 1, 1);    send(&a, 1, 0);
4          receive(&b, 1, 1); receive(&b, 1, 0);
```

- The send at P0 waits for the matching receive at P1
- The send at P1 waits for the matching receive at P0

Blocking Buffered Send / Receive

- Sending operation waits until data is copied into a pre-allocated communication buffer at the sending process
- Data is first copied into a buffer at the receiving process as well, from where data is copied to the target location by the receiver



Blocking Buffered Send / Receive

Finite buffers lead to delays:

```
1      P0                                P1
2
3      for (i = 0; i < 1000; i++) {      for (i = 0; i < 1000; i++) {
4          produce_data(&a);              receive(&a, 1, 0);
5          send(&a, 1, 1);                consume_data(&a);
6      }                                  }
```

Source: Grama et al., "Introduction to Parallel Computing", 2nd Edition

- What happens if the sender's buffer can only hold 10 items?

Blocking Buffered Send / Receive

May still lead to deadlocks:

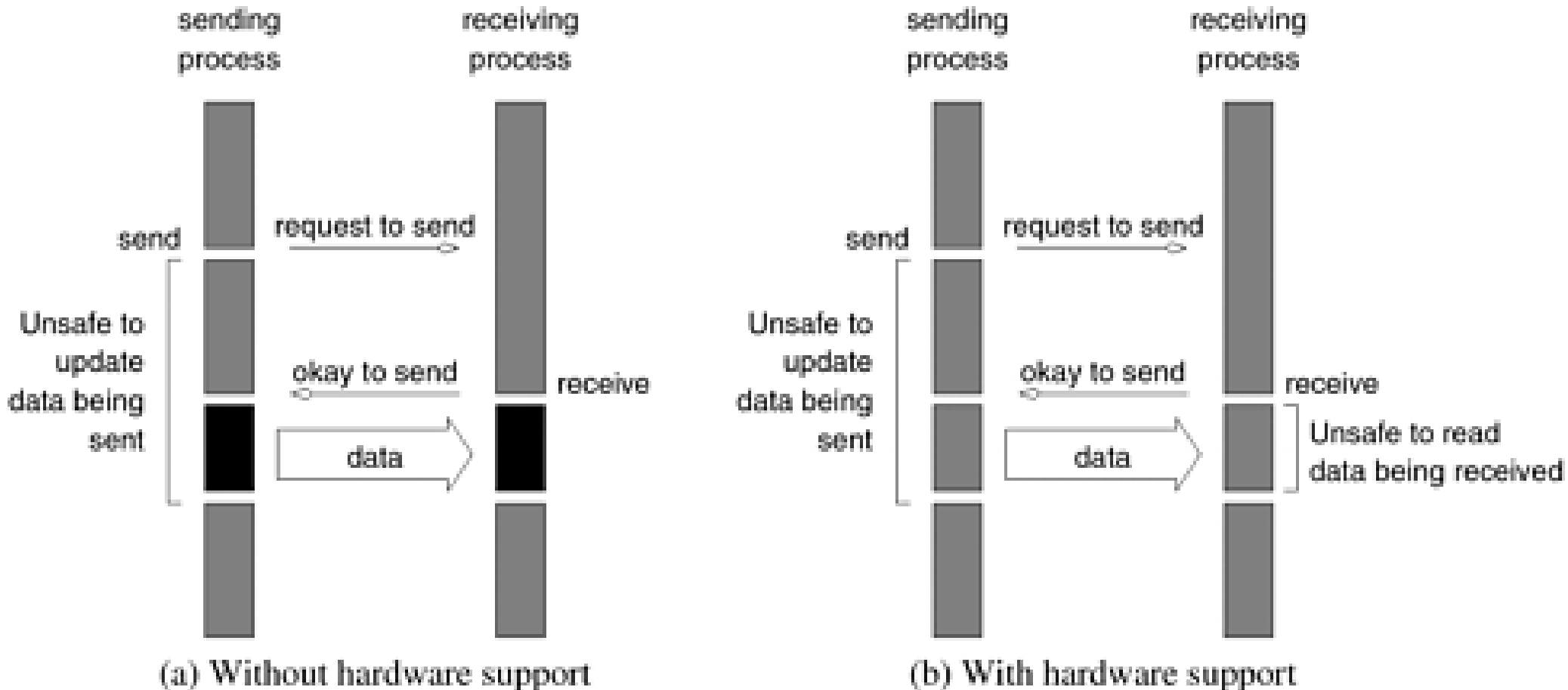
```
1          P0                                P1
2
3          receive(&a, 1, 1);                receive(&a, 1, 0);
4          send(&b, 1, 1);                    send(&b, 1, 0);
```

Source: Grama et al., "Introduction to Parallel Computing", 2nd Edition

- Blocks because the receive calls are always blocking in order to ensure consistency

Non-Blocking Non-Buffered Send / Receive

- Sending operation posts a pending message and returns
- When the corresponding receive is posted data transfer starts
- When data transfer is complete the *check-status* operation indicates that it is safe to touch the data



Non-Blocking Buffered Send / Receive

- Sending operation initiates a DMA (Direct Memory Access) operation and returns immediately
- Data becomes safe as soon as the DMA operation completes
- The receiver initiates a transfer from sender's buffer to receiver's target location
- Reduces the time during which the data is unsafe to touch

Possible Protocols for Send & Receive Operations

	Blocking Operations	Non-Blocking Operations
Buffered	<p>Sending process returns after data has been copied into communication buffer</p>	<p>Sending process returns after initiating DMA transfer to buffer. This operation may not be completed on return</p>
Non-Buffered	<p>Sending process blocks until matching receive operation has been encountered</p>	
	<p>Send and Receive semantics assured by corresponding operation</p>	<p>Programmer must explicitly ensure semantics by polling to verify completion</p>

Source: Grama et al.,
"Introduction to Parallel Computing",
2nd Edition

The Minimal Set of MPI Routines

- The MPI library contains over 125 routines
- But fully functional message-passing programs can be written using only the following 6 MPI routines

<code>MPI_Init</code>	Initializes MPI.
<code>MPI_Finalize</code>	Terminates MPI.
<code>MPI_Comm_size</code>	Determines the number of processes.
<code>MPI_Comm_rank</code>	Determines the label of the calling process.
<code>MPI_Send</code>	Sends a message.
<code>MPI_Recv</code>	Receives a message.

- All 6 functions return `MPI_SUCCESS` upon successful completion, otherwise return an implementation-defined error code
- All MPI routines, data-types and constants are prefixed by `MPI_`
- All of them are defined in `mpi.h` (for C/C++)

Starting and Terminating the MPI Library

```
1. #include < mpi.h >
2.
3. main( int argc, char *argv[ ] )
4. {
5.     MPI_Init( &argc, &argv );
6.     ... .. // do some work
7.     MPI_Finalize( );
8. }
```

- Both *MPI_Init* and *MPI_Finalize* must be called by all processes
- Command line should be processed only after *MPI_Init*
- No MPI function may be called after *MPI_Finalize*

Communicators

- A *communicator* defines the scope of a communication operation
- Each process included in the communicator has a rank associated with the communicator
- By default, all processes are included in a communicator called *MPI_COMM_WORLD*, and each process is given a unique rank between 0 and $p - 1$, where p is the number of processes
- Additional communicator can be created for groups of processes
- To get the size of a communicator:

```
int MPI_Comm_size( MPI_Comm comm, int *size )
```

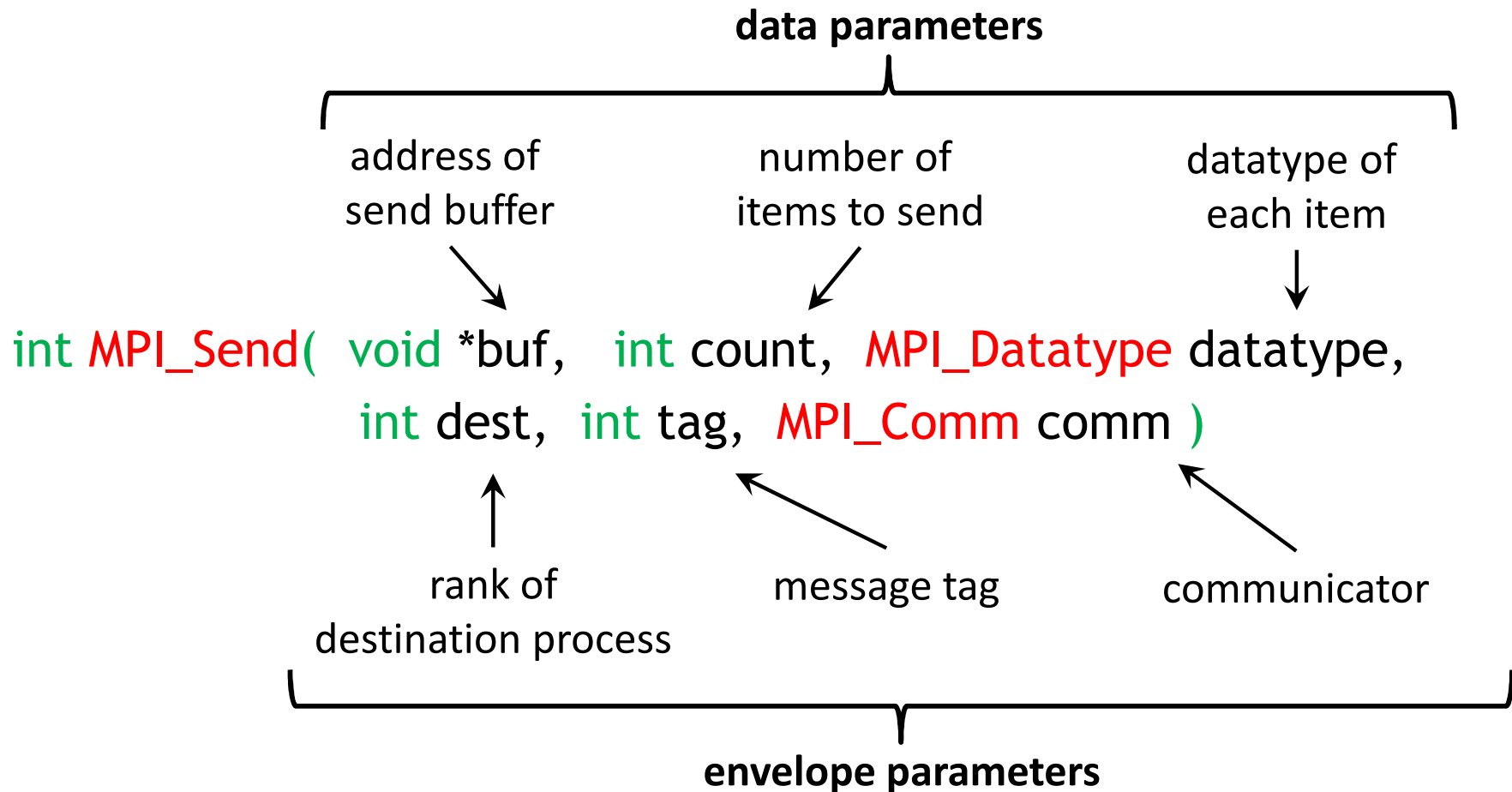
- To get the rank of a process associated with a communicator:

```
int MPI_Comm_rank( MPI_Comm comm, int *rank )
```

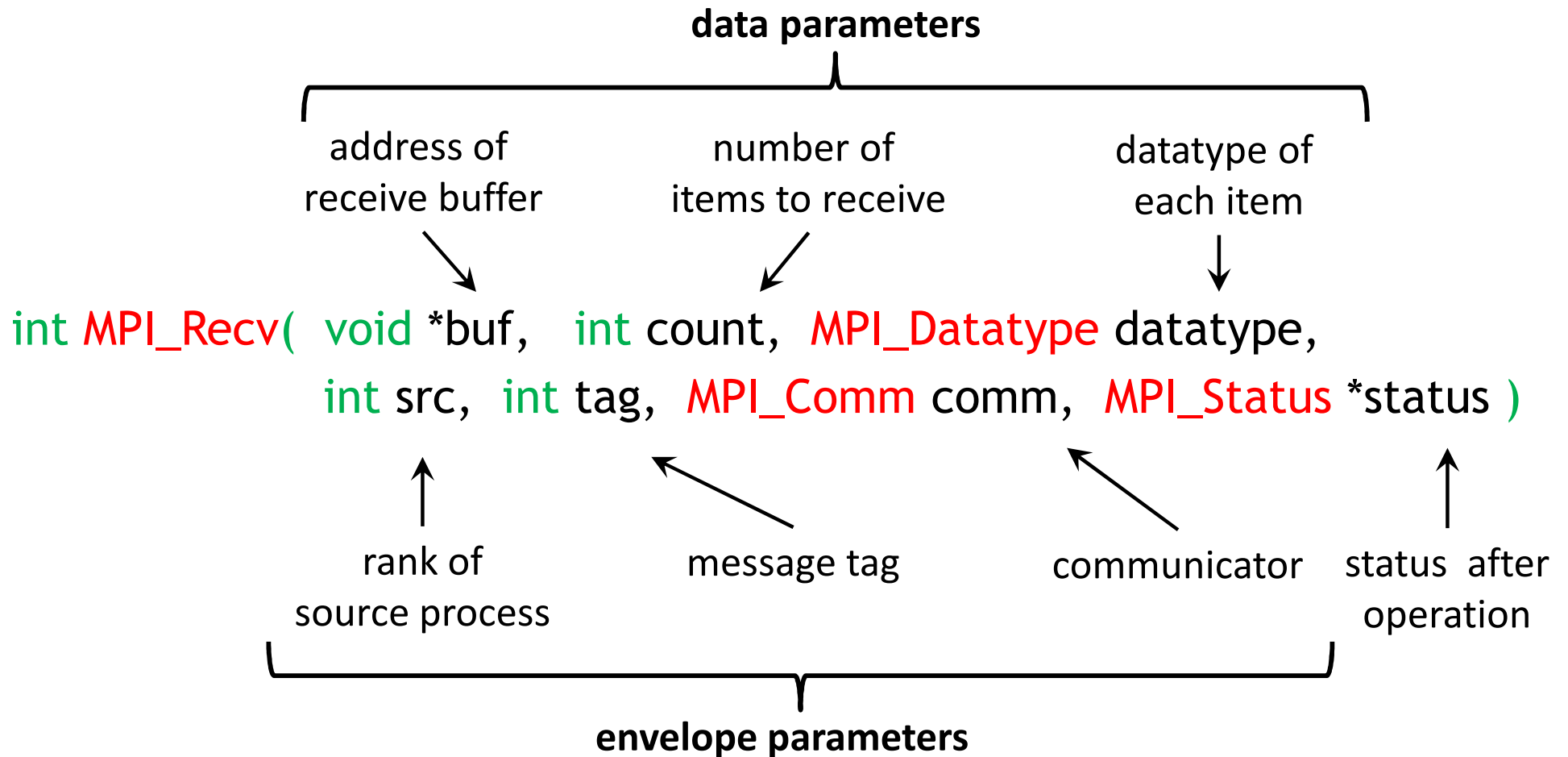
Communicators

```
1. #include < mpi.h >
2.
3. main( int argc, char *argv[ ] )
4. {
5.     int p, myrank;
6.     MPI_Init( &argc, &argv );
7.     MPI_Comm_size( MPI_COMM_WORLD, &p );
8.     MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
9.     printf( "This is process %d out of %d!\n", p, myrank );
10.    MPI_Finalize( );
11. }
```

MPI Standard Blocking Send Format



MPI Standard Blocking Receive Format



MPI Datatypes

MPI Datatype

MPI_CHAR

MPI_SHORT

MPI_INT

MPI_LONG

MPI_UNSIGNED_CHAR

MPI_UNSIGNED_SHORT

MPI_UNSIGNED

MPI_UNSIGNED_LONG

MPI_FLOAT

MPI_DOUBLE

MPI_LONG_DOUBLE

MPI_BYTE

MPI_PACKED

C Datatype

signed char

signed short int

signed int

signed long int

unsigned char

unsigned short int

unsigned int

unsigned long int

float

double

long double

Blocking Send/Receive between Two Processes

```
1. #include < mpi.h >
2.
3. main( int argc, char *argv[ ] )
4. {
5.     int myrank, v = 121;
6.     MPI_Status status;
7.     MPI_Init( &argc, &argv );
8.     MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
9.     if ( myrank == 0 ) {
10.         MPI_Send( &v, 1, MPI_INT, 1, MPI_ANY_TAG, MPI_COMM_WORLD );
11.         printf( "Process %d sent %d!\n", p, myrank, v );
12.     } else if ( myrank == 1 ) {
13.         MPI_Recv( &v, 1, MPI_INT, 1, MPI_ANY_TAG, MPI_COMM_WORLD , &status );
14.         printf( "Process %d received %d!\n", p, myrank, v );
15.     }
16.     MPI_Finalize( );
17. }
```


Non-Blocking Send / Receive

```
int MPI_Isend( void *buf, int count, MPI_Datatype datatype,  
              int dest, int tag, MPI_Comm comm, MPI_Request *req )
```

```
int MPI_Irecv( void *buf, int count, MPI_Datatype datatype,  
              int src, int tag, MPI_Comm comm, MPI_Request *req )
```

The MPI_Request object is used as an argument to the following two functions to identify the operation whose status we want to query or to wait for its completion.

```
int MPI_Test( MPI_Request *req, int *flag, MPI_Status *status )
```

- Returns *flag = 1, if the operation associated with *req has completed, otherwise returns *flag = 0

```
int MPI_Wait( MPI_Request *req, MPI_Status *status )
```

- Waits until the operation associated with *req completes

Non-Blocking Send and Blocking Receive

```
1. #include < mpi.h >
2.
3. main( int argc, char *argv[ ] )
4. {
5.     int myrank, v = 121;
6.     MPI_Status status;
7.     MPI_Request req;
8.     MPI_Init( &argc, &argv );
9.     MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
10.    if ( myrank == 0 ) {
11.        MPI_Isend( &v, 1, MPI_INT, 1, MPI_ANY_TAG, MPI_COMM_WORLD, &req );
12.        compute( );          /* but do not modify v */
13.        MPI_Wait( &req, &status );
14.    } else if ( myrank == 1 ) MPI_Recv( &v, 1, MPI_INT, 1, MPI_ANY_TAG, MPI_COMM_WORLD, &status );
15.    MPI_Finalize( );
16. }
```

Non-Blocking Send/Receive

```
1. #include < mpi.h >
2. main( int argc, char *argv[ ] )
3. {
4.     int myrank, v = 121;
5.     MPI_Status status;
6.     MPI_Request req;
7.     MPI_Init( &argc, &argv );
8.     MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
9.     if ( myrank == 0 ) {
10.         MPI_Isend( &v, 1, MPI_INT, 1, MPI_ANY_TAG, MPI_COMM_WORLD, &req );
11.         compute( );          /* but do not modify v */
12.         MPI_Wait( &req, &status );
13.     } else if ( myrank == 1 ) {
14.         MPI_Irecv( &v, 1, MPI_INT, 1, MPI_ANY_TAG, MPI_COMM_WORLD, &req );
15.         compute( );          /* but do not read or modify v */
16.         MPI_Wait( &req, &status );
17.     }
18.     MPI_Finalize( );
19. }
```

MPI Collective Communication & Computation Operations

Synchronization

- Barrier

Data Movement

- Broadcast
- Scatter
- Gather
- All-to-all

Global Computation

- Reduce
- Scan

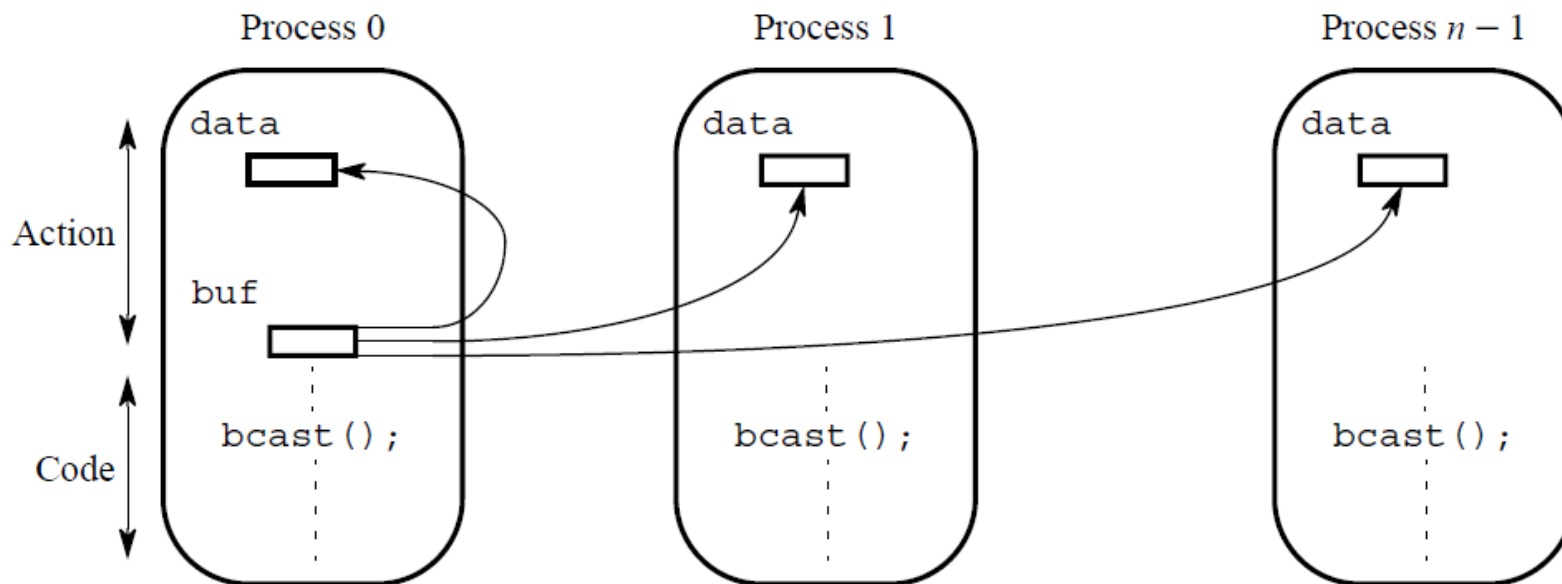
These routines must be called by all processes in the communication group

Barrier Synchronization

```
int MPI_Barrier( MPI_Comm comm )
```

Returns only after all processes in the communication group have called this function

Broadcast

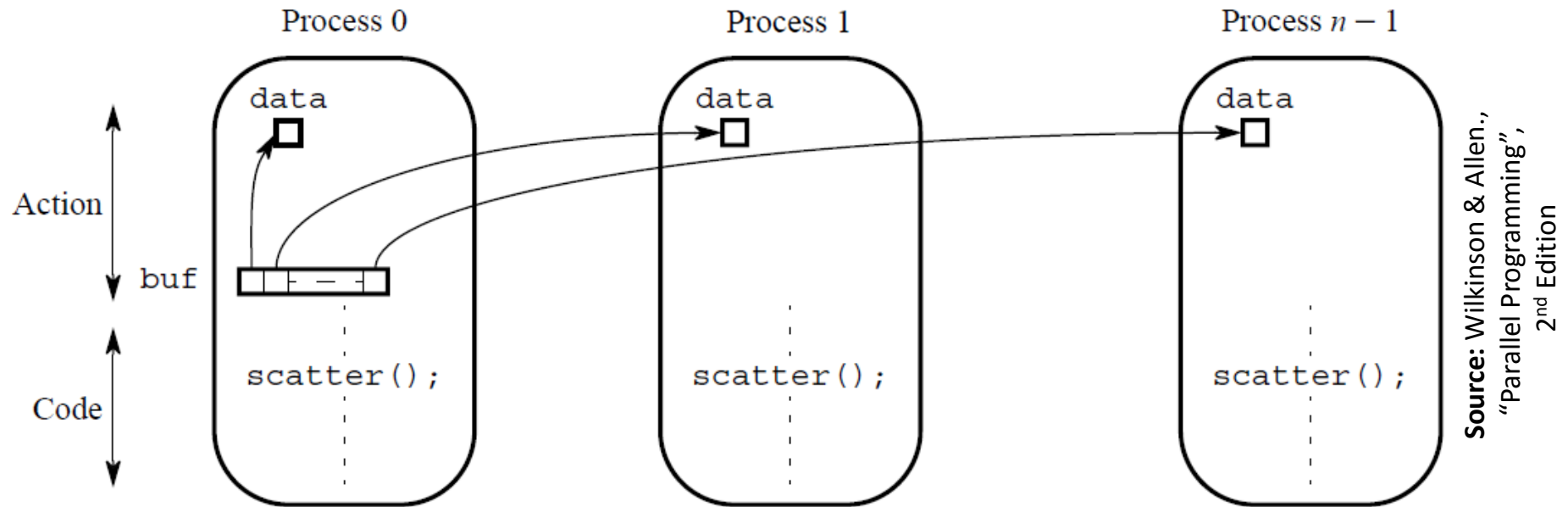


Source: Wilkinson & Allen,
"Parallel Programming",
2nd Edition

```
int MPI_Bcast( void *buf,  
              int count,  
              MPI_Datatype datatype,  
              int src,  
              MPI_Comm comm )
```

Sends the data stored in the buffer *buf* of process *src* to all the other processes in the group

Scatter

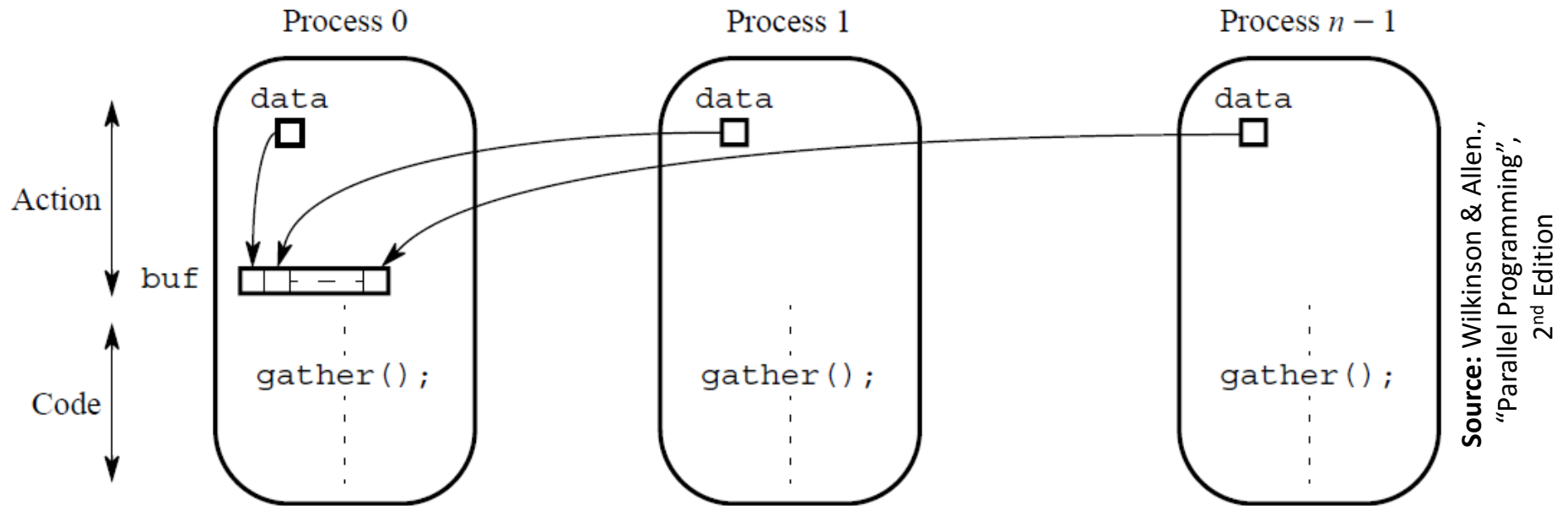


Source: Wilkinson & Allen.,
"Parallel Programming",
2nd Edition

```
int MPI_Scatter( void *sendbuf,  
               int sendcount,  
               MPI_Datatype sendtype,  
               void *recvbuf,  
               int recvcount,  
               MPI_Datatype recvtype,  
               int src,  
               MPI_Comm comm )
```

The *src* process sends a different part of *sendbuf* to each process, including itself. Process *i* receives *sendcount* contiguous elements starting from $i \times sendcount$. The received data are stored in *recvbuf*.

Gather



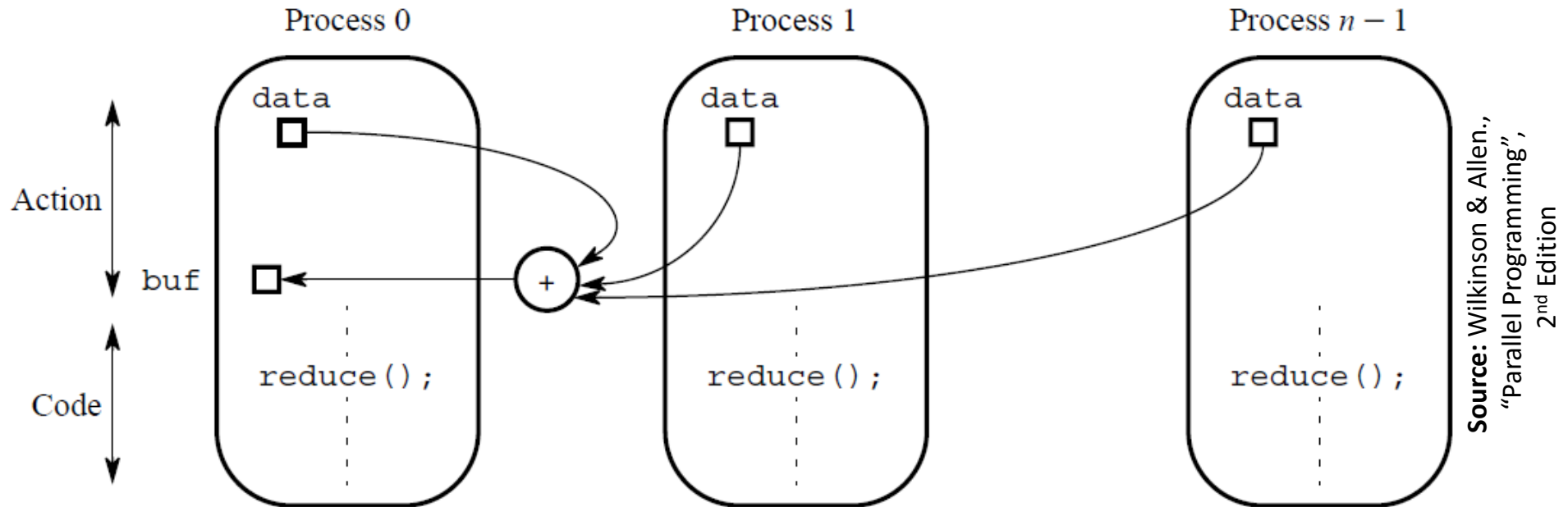
```
int MPI_Gather( void *sendbuf,  
               int sendcount,  
               MPI_Datatype sendtype,  
               void *recvbuf,  
               int recvcount,  
               MPI_Datatype recvtype,  
               int dest,  
               MPI_Comm comm )
```

The opposite of scatter.

Every process, including *dest* sends data stored in *sendbuf* to *dest*.

Data from process i occupy *sendcount* contiguous locations of *recvbuf* starting from $i \times \text{sendcount}$.

Reduce

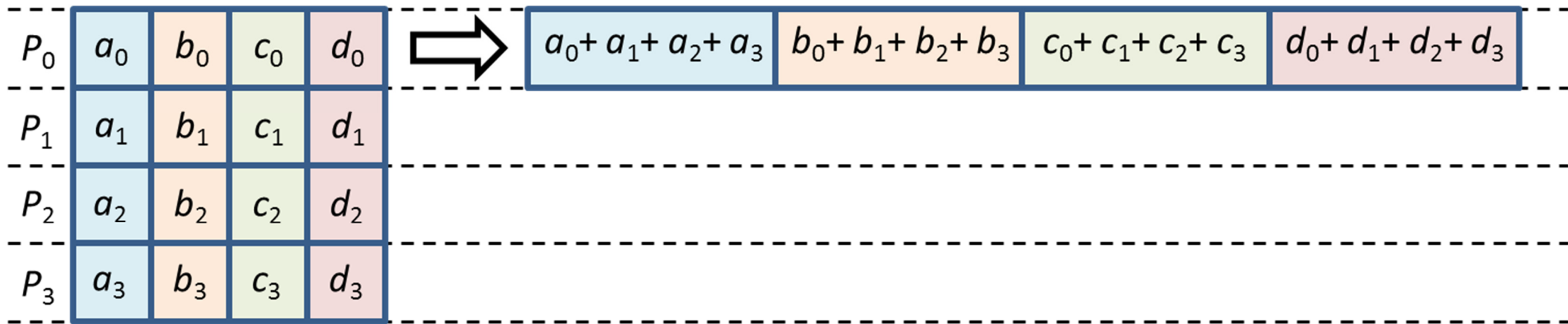


```
int MPI_Reduce( void *sendbuf,  
               void *recvbuf,  
               int count,  
               MPI_Datatype datatype,  
               MPI_Op op,  
               int dest,  
               MPI_Comm comm )
```

Combines the elements stored in *sendbuf* of each process using the operation *op*, and stores the combined values in *recvbuf* of the process with rank *dest*.

Reduce

`MPI_Reduce(vals, sums, 4, MPI_INT, MPI_SUM, 0, MPI_COMM_WORLD)`



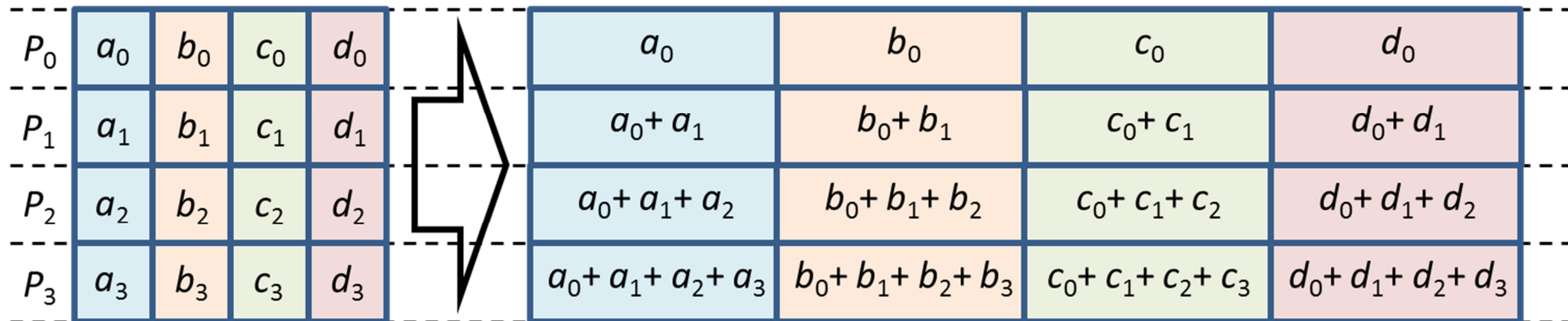
Predefined Reduction Operations

Operation	Meaning	Datatypes
<code>MPI_MAX</code>	Maximum	C integers and floating point
<code>MPI_MIN</code>	Minimum	C integers and floating point
<code>MPI_SUM</code>	Sum	C integers and floating point
<code>MPI_PROD</code>	Product	C integers and floating point
<code>MPI_LAND</code>	Logical AND	C integers
<code>MPI_BAND</code>	Bit-wise AND	C integers and byte
<code>MPI_LOR</code>	Logical OR	C integers
<code>MPI_BOR</code>	Bit-wise OR	C integers and byte
<code>MPI_LXOR</code>	Logical XOR	C integers
<code>MPI_BXOR</code>	Bit-wise XOR	C integers and byte
<code>MPI_MAXLOC</code>	max-min value-location	Data-pairs
<code>MPI_MINLOC</code>	min-min value-location	Data-pairs

Scan / Prefix

```
int MPI_Scan( void *sendbuf,  
             void *recvbuf,  
             int count,  
             MPI_Datatype datatype,  
             MPI_Op op,  
             MPI_Comm comm )
```

Performs a prefix reduction of the data stored in *sendbuf* at each process and returns the results in *recvbuf* of the process with rank *dest*.



```
MPI_Scan( vals, sums, 4, MPI_INT, MPI_SUM, MPI_COMM_WORLD )
```