

CSE 590: Special Topics Course (Supercomputing)

Lecture 6 (Analyzing Distributed Memory Algorithms)

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2D Heat Diffusion

Let $h_t(x, y)$ be the heat at point (x, y) at time t .

Heat Equation

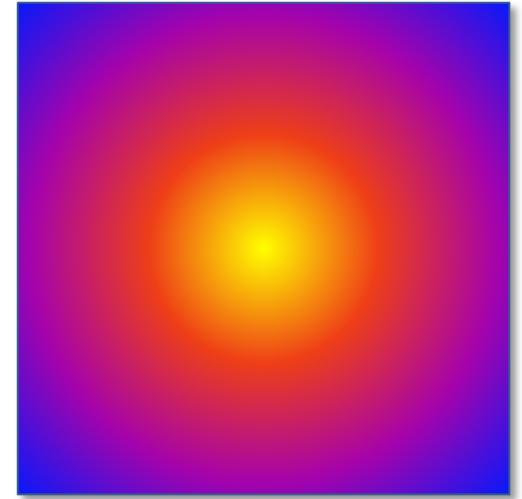
$$\frac{\partial h}{\partial t} = \alpha \left(\frac{\partial^2 h}{\partial x^2} + \frac{\partial^2 h}{\partial y^2} \right), \quad \alpha = \text{thermal diffusivity}$$

Update Equation (on a discrete grid)

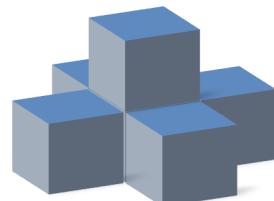
$$h_{t+1}(x, y) = h_t(x, y)$$

$$+ c_x(h_t(x + 1, y) - 2h_t(x, y) + h_t(x - 1, y))$$

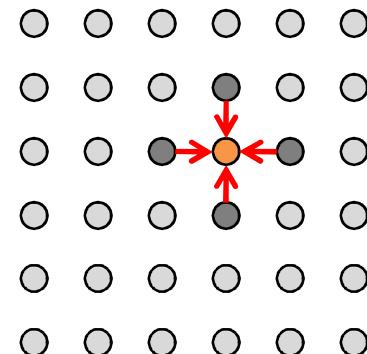
$$+ c_y(h_t(x, y + 1) - 2h_t(x, y) + h_t(x, y - 1))$$



2D 5-point Stencil



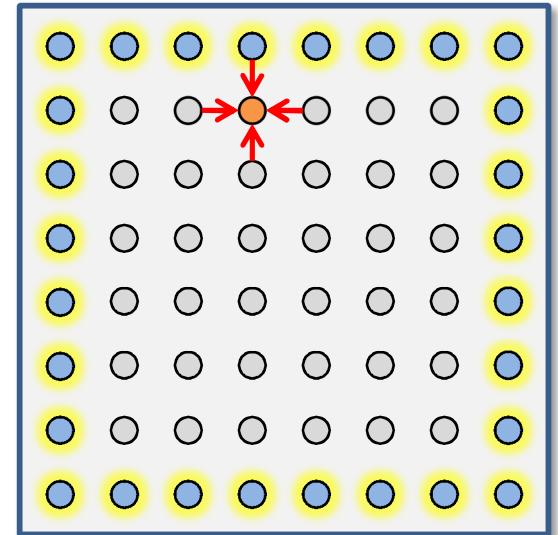
↑
time



Standard Serial Implementation

Implementation Tricks

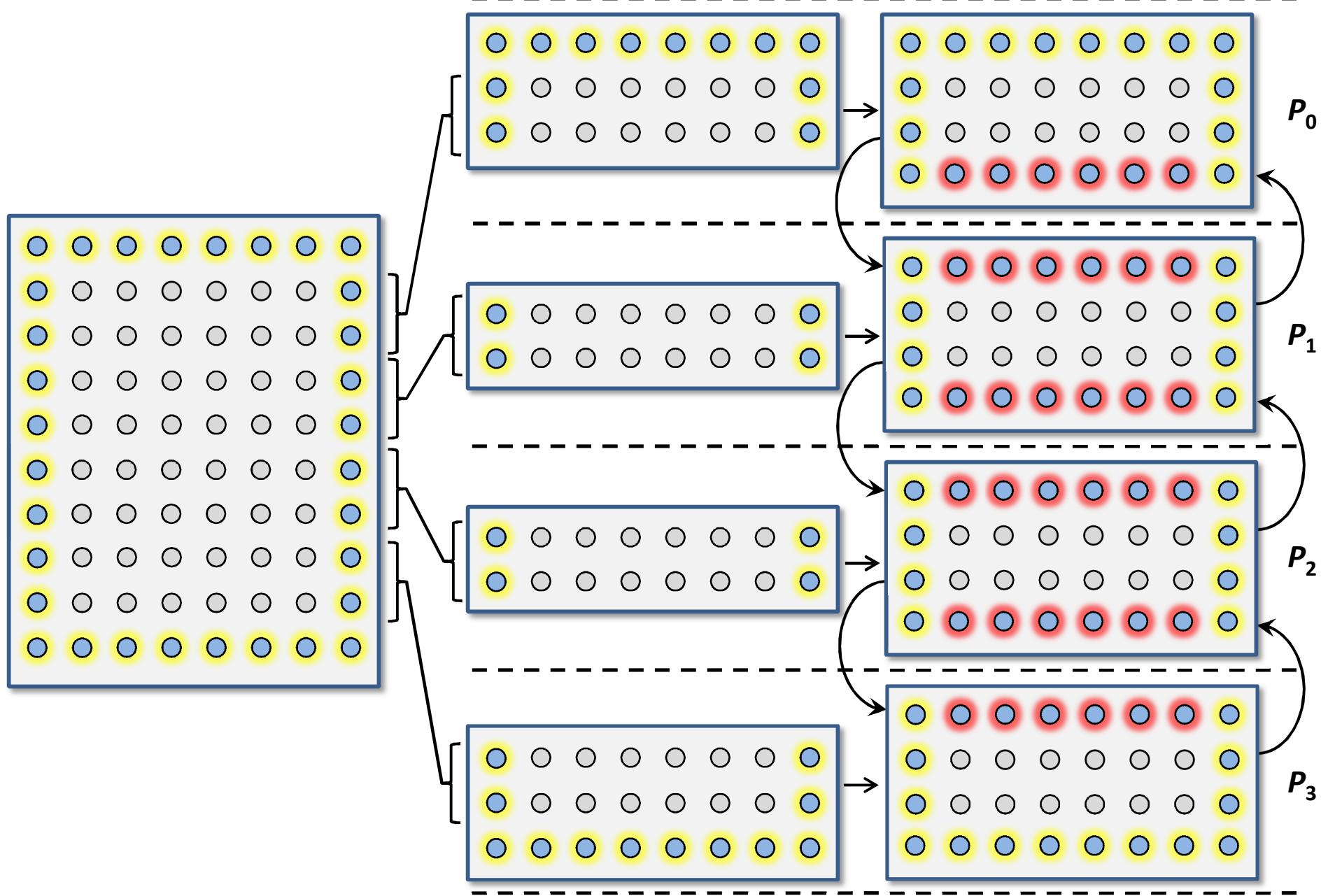
- Reuse storage for odd and even time steps
- Keep a halo of ghost cells around the array with boundary values



```
for ( int t = 0; t < T; ++t )
{
    for ( int x = 1; x <= X; ++x )
        for ( int y = 1; y <= Y; ++y )
            g[x][y] = h[x][y]
                + cx * ( h[x+1][y] - 2 * h[x][y] + h[x-1][y] )
                + cy * ( h[x][y+1] - 2 * h[x][y] + h[x][y-1] );

    for ( int x = 1; x <= X; ++x )
        for ( int y = 1; y <= Y; ++y )
            h[x][y] = g[x][y];
}
```

One Way of Parallelization



MPI Implementation of 2D Heat Diffusion

```
#define UPDATE( u, v ) ( h[u][v] + cx * ( h[u+1][v] - 2* h[u][v] + h[u-1][v] ) + cy * ( h[u][v+1] - 2* h[u][v] + h[u][v-1] ) )

...
...
...
MPI_FLOAT h[ XX + 2 ][ Y + 2 ], g[ XX + 2 ][ Y + 2 ];
MPI_Status stat;
MPI_Request sendreq[ 2 ], recvreq[ 2 ];

...
...
...
for ( int t = 0; t < T; ++t )
{
    if ( myrank < p - 1 ) { MPI_Isend( h[ XX ], Y, MPI_FLOAT, myrank + 1, 2 * t, MPI_COMM_WORLD , & sendreq[ 0 ] );
                            MPI_Irecv( h[ XX + 1 ], Y, MPI_FLOAT, myrank + 1, 2 * t + 1, MPI_COMM_WORLD , & recvreq[ 0 ] ); }

    if ( myrank > 0 )     { MPI_Isend( h[ 1 ], Y, MPI_FLOAT, myrank - 1, 2 * t + 1, MPI_COMM_WORLD , & sendreq[ 1 ] );
                            MPI_Irecv( h[ 0 ], Y, MPI_FLOAT, myrank - 1, 2 * t, MPI_COMM_WORLD , & recvreq[ 1 ] ); }

    for ( int x = 2; x < XX; ++x )
        for ( int y = 1; y <= Y ; ++y )
            g[x][y] = UPDATE( x, y );

    if ( myrank < p - 1 ) MPI_Wait( &recvreq[ 0 ], &stat );
    if ( myrank > 0 )     MPI_Wait( &recvreq[ 1 ], &stat );

    for ( int y = 1; y <= Y ; ++y ) { g[1][y] = UPDATE( 1, y ); g[XX][y] = UPDATE( XX, y ); }

    if ( myrank < p - 1 ) MPI_Wait( &sendreq[ 0 ], &stat );
    if ( myrank > 0 )     MPI_Wait( &sendreq[ 1 ], &stat );

    for ( int x = 1; x <= XX; ++x )
        for ( int y = 1; y <= Y ; ++y )
            h[x][y] = g[x][y];
}
```

MPI Implementation of 2D Heat Diffusion

```
#define UPDATE( u, v ) ( h[u][v] + cx * ( h[u+1][v] - 2* h[u][v] + h[u-1][v] ) + cy * ( h[u][v+1] - 2* h[u][v] + h[u][v-1] ) )  
... ... ...  
... ... ...  
MPI_FLOAT h[ XX + 2 ][ Y + 2 ], g[ XX + 2 ][ Y + 2 ];  
MPI_Status stat;  
MPI_Request sendreq[ 2 ], recvreq[ 2 ];  
... ... ...  
... ... ...  
for ( int t = 0; t < T; ++t )  
{  
    if ( myrank < p - 1 ) { MPI_Isend( h[ XX ], Y, MPI_FLOAT, myrank + 1, 2 * t, MPI_COMM_WORLD , & sendreq[ 0 ] );  
                           MPI_Irecv( h[ XX + 1 ], Y, MPI_FLOAT, myrank + 1, 2 * t + 1, MPI_COMM_WORLD , & recvreq[ 0 ] ); }  
  
    if ( myrank > 0 ) { MPI_Isend( h[ 1 ], Y, MPI_FLOAT, myrank - 1, 2 * t + 1, MPI_COMM_WORLD , & sendreq[ 1 ] );  
                         MPI_Irecv( h[ 0 ], Y, MPI_FLOAT, myrank - 1, 2 * t, MPI_COMM_WORLD , & recvreq[ 1 ] ); }  
  
    for ( int x = 2; x < XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            g[x][y] = UPDATE( x, y );  
  
    if ( myrank < p - 1 ) MPI_Wait( &recvreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &recvreq[ 1 ], &stat );  
  
    for ( int y = 1; y <= Y ; ++y ) { g[1][y] = UPDATE( 1, y ); g[XX][y] = UPDATE( XX, y ); }  
  
    if ( myrank < p - 1 ) MPI_Wait( &sendreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &sendreq[ 1 ], &stat );  
  
    for ( int x = 1; x <= XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            h[x][y] = g[x][y];  
}
```

leave enough space
for ghost cells

MPI Implementation of 2D Heat Diffusion

```
#define UPDATE( u, v ) ( h[u][v] + cx * ( h[u+1][v] - 2* h[u][v] + h[u-1][v] ) + cy * ( h[u][v+1] - 2* h[u][v] + h[u][v-1] ) )  
... ... ...  
... ... ...  
MPI_FLOAT h[ XX + 2 ][ Y + 2 ], g[ XX + 2 ][ Y + 2 ];  
MPI_Status stat;  
MPI_Request sendreq[ 2 ], recvreq[ 2 ];  
... ... ...  
... ... ...  
for ( int t = 0; t < T; ++t )  
{  
    if ( myrank < p - 1 ) { MPI_Isend( h[ XX ], Y, MPI_FLOAT, myrank + 1, 2 * t, MPI_COMM_WORLD , & sendreq[ 0 ] );  
                           MPI_Irecv( h[ XX + 1 ], Y, MPI_FLOAT, myrank + 1, 2 * t + 1, MPI_COMM_WORLD , & recvreq[ 0 ] ); }  
  
    if ( myrank > 0 ) { MPI_Isend( h[ 1 ], Y, MPI_FLOAT, myrank - 1, 2 * t + 1, MPI_COMM_WORLD , & sendreq[ 1 ] );  
                           MPI_Irecv( h[ 0 ], Y, MPI_FLOAT, myrank - 1, 2 * t, MPI_COMM_WORLD , & recvreq[ 1 ] ); }  
  
    for ( int x = 2; x < XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            g[x][y] = UPDATE( x, y );  
  
    if ( myrank < p - 1 ) MPI_Wait( &recvreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &recvreq[ 1 ], &stat );  
  
    for ( int y = 1; y <= Y ; ++y ) { g[1][y] = UPDATE( 1, y ); g[XX][y] = UPDATE( XX, y ); }  
  
    if ( myrank < p - 1 ) MPI_Wait( &sendreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &sendreq[ 1 ], &stat );  
  
    for ( int x = 1; x <= XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            h[x][y] = g[x][y];  
}
```

downward send and upward receive

MPI Implementation of 2D Heat Diffusion

```
#define UPDATE( u, v ) ( h[u][v] + cx * ( h[u+1][v] - 2* h[u][v] + h[u-1][v] ) + cy * ( h[u][v+1] - 2* h[u][v] + h[u][v-1] ) )  
... ... ...  
... ... ...  
MPI_FLOAT h[ XX + 2 ][ Y + 2 ], g[ XX + 2 ][ Y + 2 ];  
MPI_Status stat;  
MPI_Request sendreq[ 2 ], recvreq[ 2 ];  
... ... ...  
... ... ...  
for ( int t = 0; t < T; ++t )  
{  
    if ( myrank < p - 1 ) { MPI_Isend( h[ XX ], Y, MPI_FLOAT, myrank + 1, 2 * t, MPI_COMM_WORLD , & sendreq[ 0 ] );  
        MPI_Irecv( h[ XX + 1 ], Y, MPI_FLOAT, myrank + 1, 2 * t + 1, MPI_COMM_WORLD , & recvreq[ 0 ] ); }  
  
    if ( myrank > 0 ) { MPI_Isend( h[ 1 ], Y, MPI_FLOAT, myrank - 1, 2 * t + 1, MPI_COMM_WORLD , & sendreq[ 1 ] );  
        MPI_Irecv( h[ 0 ], Y, MPI_FLOAT, myrank - 1, 2 * t, MPI_COMM_WORLD , & recvreq[ 1 ] ); }  
  
    for ( int x = 2; x < XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            g[x][y] = UPDATE( x, y );  
  
    if ( myrank < p - 1 ) MPI_Wait( &recvreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &recvreq[ 1 ], &stat );  
  
    for ( int y = 1; y <= Y ; ++y ) { g[1][y] = UPDATE( 1, y ); g[XX][y] = UPDATE( XX, y ); }  
  
    if ( myrank < p - 1 ) MPI_Wait( &sendreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &sendreq[ 1 ], &stat );  
  
    for ( int x = 1; x <= XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            h[x][y] = g[x][y];  
}
```

upward send and
downward receive

MPI Implementation of 2D Heat Diffusion

```
#define UPDATE( u, v ) ( h[u][v] + cx * ( h[u+1][v] - 2* h[u][v] + h[u-1][v] ) + cy * ( h[u][v+1] - 2* h[u][v] + h[u][v-1] ) )  
... ... ...  
... ... ...  
MPI_FLOAT h[ XX + 2 ][ Y + 2 ], g[ XX + 2 ][ Y + 2 ];  
MPI_Status stat;  
MPI_Request sendreq[ 2 ], recvreq[ 2 ];  
... ... ...  
... ... ...  
for ( int t = 0; t < T; ++t )  
{  
    if ( myrank < p - 1 ) { MPI_Isend( h[ XX ], Y, MPI_FLOAT, myrank + 1, 2 * t, MPI_COMM_WORLD , & sendreq[ 0 ] );  
                           MPI_Irecv( h[ XX + 1 ], Y, MPI_FLOAT, myrank + 1, 2 * t + 1, MPI_COMM_WORLD , & recvreq[ 0 ] ); }  
  
    if ( myrank > 0 ) { MPI_Isend( h[ 1 ], Y, MPI_FLOAT, myrank - 1, 2 * t + 1, MPI_COMM_WORLD , & sendreq[ 1 ] );  
                        MPI_Irecv( h[ 0 ], Y, MPI_FLOAT, myrank - 1, 2 * t, MPI_COMM_WORLD , & recvreq[ 1 ] ); }  
  
    for ( int x = 2; x < XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            g[x][y] = UPDATE( x, y );  
  
    if ( myrank < p - 1 ) MPI_Wait( &recvreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &recvreq[ 1 ], &stat );  
  
    for ( int y = 1; y <= Y ; ++y ) { g[1][y] = UPDATE( 1, y ); g[XX][y] = UPDATE( XX, y ); }  
  
    if ( myrank < p - 1 ) MPI_Wait( &sendreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &sendreq[ 1 ], &stat );  
  
    for ( int x = 1; x <= XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            h[x][y] = g[x][y];  
}
```

in addition to the ghost rows exclude
the two outermost interior rows

MPI Implementation of 2D Heat Diffusion

```
#define UPDATE( u, v ) ( h[u][v] + cx * ( h[u+1][v] - 2* h[u][v] + h[u-1][v] ) + cy * ( h[u][v+1] - 2* h[u][v] + h[u][v-1] ) )  
... ... ...  
... ... ...  
MPI_FLOAT h[ XX + 2 ][ Y + 2 ], g[ XX + 2 ][ Y + 2 ];  
MPI_Status stat;  
MPI_Request sendreq[ 2 ], recvreq[ 2 ];  
... ... ...  
... ... ...  
for ( int t = 0; t < T; ++t )  
{  
    if ( myrank < p - 1 ) { MPI_Isend( h[ XX ], Y, MPI_FLOAT, myrank + 1, 2 * t, MPI_COMM_WORLD , & sendreq[ 0 ] );  
                           MPI_Irecv( h[ XX + 1 ], Y, MPI_FLOAT, myrank + 1, 2 * t + 1, MPI_COMM_WORLD , & recvreq[ 0 ] ); }  
  
    if ( myrank > 0 ) { MPI_Isend( h[ 1 ], Y, MPI_FLOAT, myrank - 1, 2 * t + 1, MPI_COMM_WORLD , & sendreq[ 1 ] );  
                        MPI_Irecv( h[ 0 ], Y, MPI_FLOAT, myrank - 1, 2 * t, MPI_COMM_WORLD , & recvreq[ 1 ] ); }  
  
    for ( int x = 2; x < XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            g[x][y] = UPDATE( x, y );  
  
    if ( myrank < p - 1 ) MPI_Wait( &recvreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &recvreq[ 1 ], &stat );  
  
    for ( int y = 1; y <= Y ; ++y ) { g[1][y] = UPDATE( 1, y ); g[XX][y] = UPDATE( XX, y ); }  
  
    if ( myrank < p - 1 ) MPI_Wait( &sendreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &sendreq[ 1 ], &stat );  
  
    for ( int x = 1; x <= XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            h[x][y] = g[x][y];  
}
```

wait until data is received
for the ghost rows

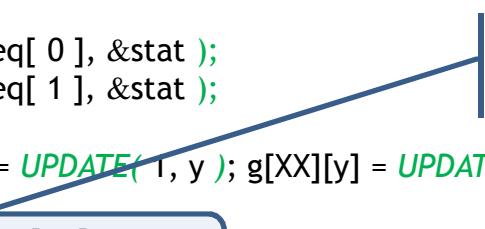
MPI Implementation of 2D Heat Diffusion

```
#define UPDATE( u, v ) ( h[u][v] + cx * ( h[u+1][v] - 2* h[u][v] + h[u-1][v] ) + cy * ( h[u][v+1] - 2* h[u][v] + h[u][v-1] ) )  
... ... ...  
... ... ...  
MPI_FLOAT h[ XX + 2 ][ Y + 2 ], g[ XX + 2 ][ Y + 2 ];  
MPI_Status stat;  
MPI_Request sendreq[ 2 ], recvreq[ 2 ];  
... ... ...  
... ... ...  
for ( int t = 0; t < T; ++t )  
{  
    if ( myrank < p - 1 ) { MPI_Isend( h[ XX ], Y, MPI_FLOAT, myrank + 1, 2 * t, MPI_COMM_WORLD , & sendreq[ 0 ] );  
                           MPI_Irecv( h[ XX + 1 ], Y, MPI_FLOAT, myrank + 1, 2 * t + 1, MPI_COMM_WORLD , & recvreq[ 0 ] ); }  
  
    if ( myrank > 0 ) { MPI_Isend( h[ 1 ], Y, MPI_FLOAT, myrank - 1, 2 * t + 1, MPI_COMM_WORLD , & sendreq[ 1 ] );  
                         MPI_Irecv( h[ 0 ], Y, MPI_FLOAT, myrank - 1, 2 * t, MPI_COMM_WORLD , & recvreq[ 1 ] ); }  
  
    for ( int x = 2; x < XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            g[x][y] = UPDATE( x, y );  
  
    if ( myrank < p - 1 ) MPI_Wait( &recvreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &recvreq[ 1 ], &stat );  
  
    for ( int y = 1; y <= Y ; ++y ) { g[1][y] = UPDATE( 1, y ); g[XX][y] = UPDATE( XX, y ); }  
  
    if ( myrank < p - 1 ) MPI_Wait( &sendreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &sendreq[ 1 ], &stat );  
  
    for ( int x = 1; x <= XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            h[x][y] = g[x][y];  
}
```

update the two outermost interior rows

MPI Implementation of 2D Heat Diffusion

```
#define UPDATE( u, v ) ( h[u][v] + cx * ( h[u+1][v] - 2* h[u][v] + h[u-1][v] ) + cy * ( h[u][v+1] - 2* h[u][v] + h[u][v-1] ) )  
... ... ...  
... ... ...  
MPI_FLOAT h[ XX + 2 ][ Y + 2 ], g[ XX + 2 ][ Y + 2 ];  
MPI_Status stat;  
MPI_Request sendreq[ 2 ], recvreq[ 2 ];  
... ... ...  
... ... ...  
for ( int t = 0; t < T; ++t )  
{  
    if ( myrank < p - 1 ) { MPI_Isend( h[ XX ], Y, MPI_FLOAT, myrank + 1, 2 * t, MPI_COMM_WORLD , & sendreq[ 0 ] );  
                           MPI_Irecv( h[ XX + 1 ], Y, MPI_FLOAT, myrank + 1, 2 * t + 1, MPI_COMM_WORLD , & recvreq[ 0 ] ); }  
  
    if ( myrank > 0 ) { MPI_Isend( h[ 1 ], Y, MPI_FLOAT, myrank - 1, 2 * t + 1, MPI_COMM_WORLD , & sendreq[ 1 ] );  
                         MPI_Irecv( h[ 0 ], Y, MPI_FLOAT, myrank - 1, 2 * t, MPI_COMM_WORLD , & recvreq[ 1 ] ); }  
  
    for ( int x = 2; x < XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            g[x][y] = UPDATE( x, y );  
  
    if ( myrank < p - 1 ) MPI_Wait( &recvreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &recvreq[ 1 ], &stat );  
  
    for ( int y = 1; y <= Y ; ++y ) { g[1][y] = UPDATE( 1, y ); g[XX][y] = UPDATE( XX, y ); }  
  
    if ( myrank < p - 1 ) MPI_Wait( &sendreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &sendreq[ 1 ], &stat );  
  
    for ( int x = 1; x <= XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            h[x][y] = g[x][y];  
}
```



wait until sending data is complete
so that h can be overwritten

MPI Implementation of 2D Heat Diffusion

```
#define UPDATE( u, v ) ( h[u][v] + cx * ( h[u+1][v] - 2* h[u][v] + h[u-1][v] ) + cy * ( h[u][v+1] - 2* h[u][v] + h[u][v-1] ) )  
... ... ...  
... ... ...  
MPI_FLOAT h[ XX + 2 ][ Y + 2 ], g[ XX + 2 ][ Y + 2 ];  
MPI_Status stat;  
MPI_Request sendreq[ 2 ], recvreq[ 2 ];  
... ... ...  
... ... ...  
for ( int t = 0; t < T; ++t )  
{  
    if ( myrank < p - 1 ) { MPI_Isend( h[ XX ], Y, MPI_FLOAT, myrank + 1, 2 * t, MPI_COMM_WORLD , & sendreq[ 0 ] );  
                           MPI_Irecv( h[ XX + 1 ], Y, MPI_FLOAT, myrank + 1, 2 * t + 1, MPI_COMM_WORLD , & recvreq[ 0 ] ); }  
  
    if ( myrank > 0 ) { MPI_Isend( h[ 1 ], Y, MPI_FLOAT, myrank - 1, 2 * t + 1, MPI_COMM_WORLD , & sendreq[ 1 ] );  
                         MPI_Irecv( h[ 0 ], Y, MPI_FLOAT, myrank - 1, 2 * t, MPI_COMM_WORLD , & recvreq[ 1 ] ); }  
  
    for ( int x = 2; x < XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            g[x][y] = UPDATE( x, y );  
  
    if ( myrank < p - 1 ) MPI_Wait( &recvreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &recvreq[ 1 ], &stat );  
  
    for ( int y = 1; y <= Y ; ++y ) { g[1][y] = UPDATE( 1, y ); g[XX][y] = UPDATE( XX, y ); }  
  
    if ( myrank < p - 1 ) MPI_Wait( &sendreq[ 0 ], &stat );  
    if ( myrank > 0 ) MPI_Wait( &sendreq[ 1 ], &stat );  
  
    for ( int x = 1; x <= XX; ++x )  
        for ( int y = 1; y <= Y ; ++y )  
            h[x][y] = g[x][y];  
}
```

now overwrite h

Analysis of the MPI Implementation of Heat Diffusion

Let the dimension of the 2D grid be $n_X \times n_Y$, and suppose we execute n_T time steps. Let p be the number of processors, and suppose the grid is decomposed along X direction.

The computation cost in each time step is clearly $\frac{n_X n_Y}{p}$. Hence, the total computation cost, $t_{comp} = \frac{n_T n_X n_Y}{p}$.

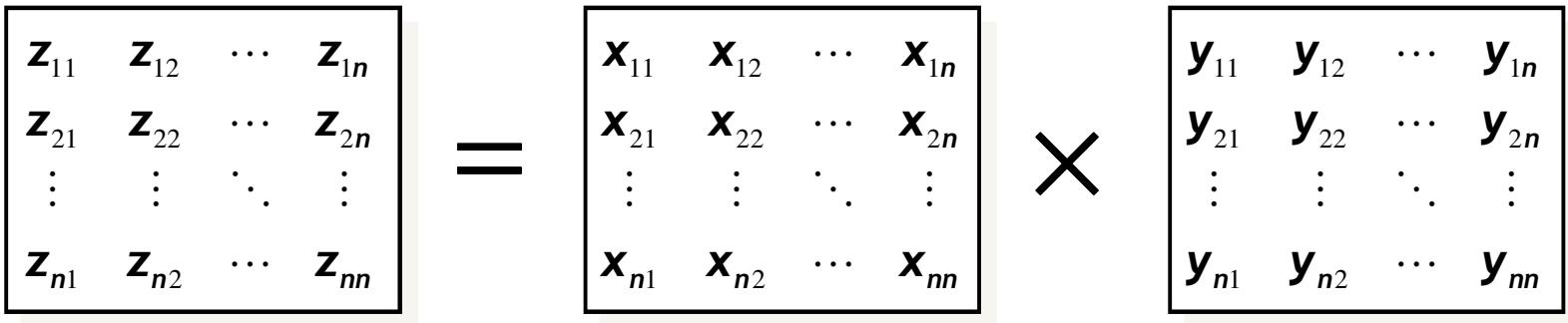
All processors except processors 0 and $p - 1$ send two rows and receive two rows each in every time step. Processors 0 and $p - 1$ send and receive only one row each. Hence, the total communication cost, $t_{comm} = 4n_T(t_s + n_Y t_w)$, where t_s is the startup time of a message and t_w is the per-word transfer time.

Thus $T_p = t_{comp} + t_{comm} = \frac{n_T n_X n_Y}{p} + 4n_T(t_s + n_Y t_w)$,

and $T_1 = n_T n_X n_Y$.

Naïve Matrix Multiplication

$$z_{ij} = \sum_{k=1}^n x_{ik} y_{kj}$$



Iter-MM(X, Y, Z, n)

1. *for* $i \leftarrow 1$ *to* n *do*
2. *for* $j \leftarrow 1$ *to* n *do*
3. *for* $k \leftarrow 1$ *to* n *do*
4. $z_{ij} \leftarrow z_{ij} + x_{ik} \times y_{kj}$

Naïve Matrix Multiplication

$$z_{ij} = \sum_{k=1}^n x_{ik} y_{kj}$$

$$\begin{matrix} z_{11} & z_{12} & \cdots & z_{1n} \\ z_{21} & z_{22} & \cdots & z_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ z_{n1} & z_{n2} & \cdots & z_{nn} \end{matrix} = \begin{matrix} x_{11} & x_{12} & \cdots & x_{1n} \\ x_{21} & x_{22} & \cdots & x_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \cdots & x_{nn} \end{matrix} \times \begin{matrix} y_{11} & y_{12} & \cdots & y_{1n} \\ y_{21} & y_{22} & \cdots & y_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y_{n1} & y_{n2} & \cdots & y_{nn} \end{matrix}$$

Suppose we have $p = n \times n$ processors, and processor P_{ij} is responsible for computing z_{ij} .

One master processor initially holds both X and Y , and sends all x_{ik} and y_{kj} for $k = 1, 2, \dots, n$ to each processor P_{ij} . One-to-all Broadcast is a bad idea as each processor requires a different part of the input.

Each P_{ij} computes z_{ij} and sends back to master.

Thus $t_{comp} = 2n$, and $t_{comm} = n^2(t_s + 2nt_w) + n^2(t_s + t_w)$.

Hence, $T_p = t_{comp} + t_{comm} = 2n + n^2(2t_s + t_w + 2nt_w)$.

Total work, $T_1 = 2n^3$.

Naïve Matrix Multiplication

$$z_{ij} = \sum_{k=1}^n x_{ik} y_{kj}$$

z_{11}	z_{12}	\cdots	z_{1n}
z_{21}	z_{22}	\cdots	z_{2n}
\vdots	\vdots	\ddots	\vdots
z_{n1}	z_{n2}	\cdots	z_{nn}

=

x_{11}	x_{12}	\cdots	x_{1n}
x_{21}	x_{22}	\cdots	x_{2n}
\vdots	\vdots	\ddots	\vdots
x_{n1}	x_{n2}	\cdots	x_{nn}

×

y_{11}	y_{12}	\cdots	y_{1n}
y_{21}	y_{22}	\cdots	y_{2n}
\vdots	\vdots	\ddots	\vdots
y_{n1}	y_{n2}	\cdots	y_{nn}

Observe that row i of X will be required by all $P_{i,j}$, $1 \leq j \leq n$. So that row can be broadcast to the group $\{P_{i,1}, P_{i,2}, \dots, P_{i,n}\}$ of size n .

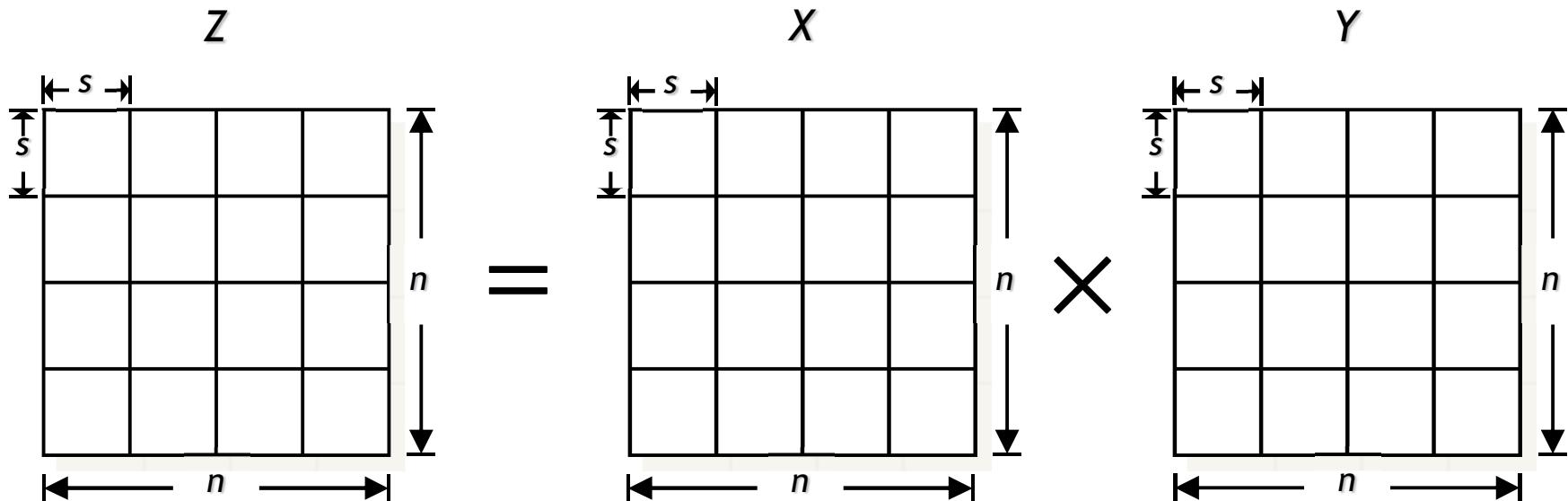
Similarly, for other rows of X , and all columns of Y .

The communication complexity of broadcasting m units of data to a group of size n is $(t_s + mt_w) \log n$.

As before, each P_{ij} computes z_{ij} and sends back to master.

Hence, $t_{comm} = 2n(t_s + nt_w) \log n + n^2(t_s + t_w)$.

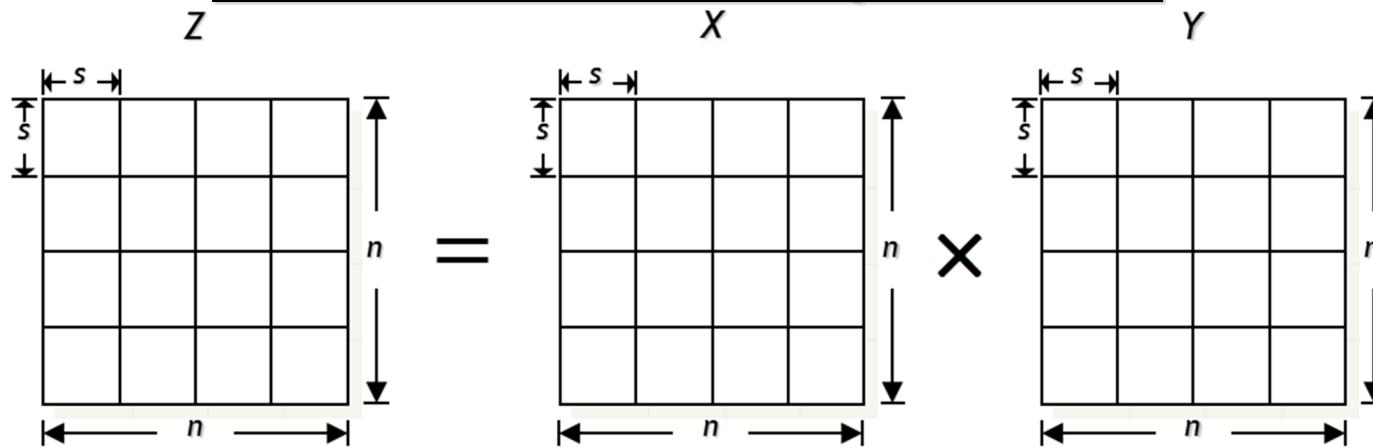
Block Matrix Multiplication



Block-MM(X, Y, Z, n)

1. *for* $i \leftarrow 1$ *to* n / s *do*
2. *for* $j \leftarrow 1$ *to* n / s *do*
3. *for* $k \leftarrow 1$ *to* n / s *do*
4. *Iter-MM($X_{ik}, Y_{kj}, Z_{ij}, s$)*

Block Matrix Multiplication



Suppose $p = \frac{n}{s} \times \frac{n}{s}$, and processor P_{ij} computes block Z_{ij} .

One master processor initially holds both X and Y , and sends all blocks X_{ik} and Y_{kj} for $k = 1, 2, \dots, \frac{n}{s}$ to each processor P_{ij} .

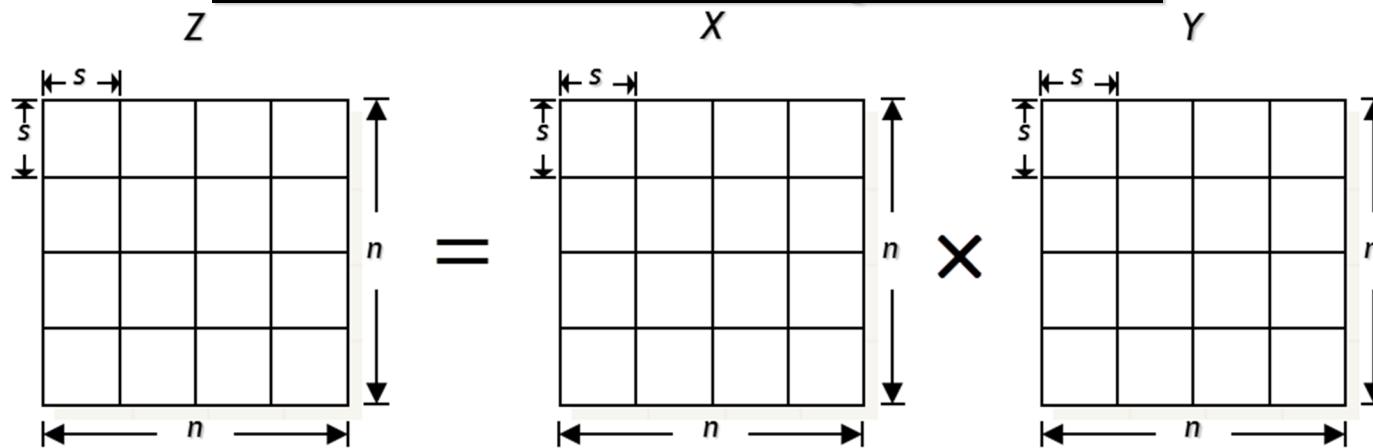
Thus $t_{comp} = \frac{n}{s} (2s^3 + s^2) = O(ns^2)$,

and $t_{comm} = \left(\frac{n}{s}\right)^2 (2(t_s + nst_w) + (t_s + s^2 t_w))$. (w/o broadcast)

For $s = \sqrt{n}$, $t_{comp} = O(n^2)$, and $t_{comm} = O(nt_s + n^{2.5}t_w)$

For $s = n^{\frac{2}{3}}$, $t_{comp} = O(n^{2+\frac{1}{3}})$, and $t_{comm} = O\left(n^{\frac{2}{3}}t_s + n^{2+\frac{1}{3}}t_w\right)$

Block Matrix Multiplication



Now consider one-to-group broadcasting.

Block row i of X , i.e., blocks X_{ik} for $k = 1, 2, \dots, \frac{n}{s}$, will be required by $\frac{n}{s}$ different processors, i.e., processors P_{ij} for $j = 1, 2, \dots, \frac{n}{s}$.

Similarly, for other block rows of X , and all block columns of Y .

As before, each P_{ij} computes block Z_{ij} and sends back to master.

$$\text{Hence, } t_{comm} = \frac{n}{s} (t_s + nst_w) \log\left(\frac{n}{s}\right) + \left(\frac{n}{s}\right)^2 (t_s + s^2 t_w).$$

Recursive Matrix Multiplication

Par-Rec-MM (X, Y, Z, n)

1. *if* $n = 1$ *then* $Z \leftarrow Z + X \cdot Y$
2. *else*
3. *in parallel do*
 - Par-Rec-MM (X_{11} , Y_{11} , Z_{11} , $n / 2$)*
 - Par-Rec-MM (X_{11} , Y_{12} , Z_{12} , $n / 2$)*
 - Par-Rec-MM (X_{21} , Y_{11} , Z_{21} , $n / 2$)*
 - Par-Rec-MM (X_{21} , Y_{12} , Z_{22} , $n / 2$)*
- end do*
4. *in parallel do*
 - Par-Rec-MM (X_{12} , Y_{21} , Z_{11} , $n / 2$)*
 - Par-Rec-MM (X_{12} , Y_{22} , Z_{12} , $n / 2$)*
 - Par-Rec-MM (X_{22} , Y_{21} , Z_{21} , $n / 2$)*
 - Par-Rec-MM (X_{22} , Y_{22} , Z_{22} , $n / 2$)*
- end do*

Assuming t_s and t_w are constants,

$$t_{comm}(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ 8t_{comm}\left(\frac{n}{2}\right) + \Theta(n^2), & \text{otherwise.} \end{cases}$$
$$= \Theta(n^3) \quad [\text{MT Case 1}]$$

Communication cost is too high!

Recursive Matrix Multiplication

Par-Rec-MM (X, Y, Z, n)

1. *if* $n = 1$ *then* $Z \leftarrow Z + X \cdot Y$
2. *else*
3. *in parallel do*

 Par-Rec-MM (X₁₁, Y₁₁, Z₁₁, n / 2)
 Par-Rec-MM (X₁₁, Y₁₂, Z₁₂, n / 2)
 Par-Rec-MM (X₂₁, Y₁₁, Z₂₁, n / 2)
 Par-Rec-MM (X₂₁, Y₁₂, Z₂₂, n / 2)

 end do
4. *in parallel do*

 Par-Rec-MM (X₁₂, Y₂₁, Z₁₁, n / 2)
 Par-Rec-MM (X₁₂, Y₂₂, Z₁₂, n / 2)
 Par-Rec-MM (X₂₂, Y₂₁, Z₂₁, n / 2)
 Par-Rec-MM (X₂₂, Y₂₂, Z₂₂, n / 2)

 end do

But with a $s \times s$ base case,

$$t_{comm}(n) = \begin{cases} \Theta(1), & \text{if } n \leq s, \\ 8t_{comm}\left(\frac{n}{2}\right) + \Theta(n^2), & \text{otherwise.} \end{cases}$$
$$= \Theta\left(\frac{n^3}{s}\right)$$

Parallel running time,

$$t_{comp}(n) = \Theta\left(\frac{n^3}{p} + ns^2\right) \quad (\text{how?})$$

For $s = n^{\frac{2}{3}}$,

$$t_{comp} = O\left(\frac{n^3}{p} + n^{2+\frac{1}{3}}\right),$$

and $t_{comm} = O(n^{2+\frac{1}{3}})$

Cannon's Algorithm

We decompose each matrix into $\sqrt{p} \times \sqrt{p}$ blocks of size $\frac{n}{\sqrt{p}} \times \frac{n}{\sqrt{p}}$ each.

We number the processors from $P_{0,0}$ to $P_{\sqrt{p}-1, \sqrt{p}-1}$.

Initially, P_{ij} holds A_{ij} and B_{ij} .

We rotate block row i of A to the left by i positions, and block column j of B upward by j positions.

So, P_{ij} now holds $A_{i,j+i}$ and $B_{i+j,j}$.

A _{0,0}	A _{0,1}	A _{0,2}	A _{0,3}
A _{1,0}	A _{1,1}	A _{1,2}	A _{1,3}
A _{2,0}	A _{2,1}	A _{2,2}	A _{2,3}
A _{3,0}	A _{3,1}	A _{3,2}	A _{3,3}

(a) Initial alignment of A

B _{0,0}	B _{0,1}	B _{0,2}	B _{0,3}
B _{1,0}	B _{1,1}	B _{1,2}	B _{1,3}
B _{2,0}	B _{2,1}	B _{2,2}	B _{2,3}
B _{3,0}	B _{3,1}	B _{3,2}	B _{3,3}

(b) Initial alignment of B

A _{0,0}	A _{0,1}	A _{0,2}	A _{0,3}
B _{0,0}	B _{1,1}	B _{2,2}	B _{3,3}
A _{1,1}	A _{1,2}	A _{1,3}	A _{1,0}
B _{1,0}	B _{2,1}	B _{3,2}	B _{0,3}
A _{2,2}	A _{2,3}	A _{2,0}	A _{2,1}
B _{2,0}	B _{3,1}	B _{0,2}	B _{1,3}
A _{3,3}	A _{3,0}	A _{3,1}	A _{3,2}
B _{3,0}	B _{0,1}	B _{1,2}	B _{2,3}

(c) A and B after initial alignment

A _{0,1}	A _{0,2}	A _{0,3}	A _{0,0}
B _{1,0}	B _{2,1}	B _{3,2}	B _{0,3}
A _{1,2}	A _{1,3}	A _{1,0}	A _{1,1}
B _{2,0}	B _{3,1}	B _{0,2}	B _{1,3}
A _{2,3}	A _{2,0}	A _{2,1}	A _{2,2}
B _{3,0}	B _{0,1}	B _{1,2}	B _{2,3}
A _{3,0}	A _{3,1}	A _{3,2}	A _{3,3}
B _{0,0}	B _{1,1}	B _{2,2}	B _{3,3}

(d) Submatrix locations after first shift

Cannon's Algorithm

P_{ij} now holds $A_{i,j+i}$ and

$B_{i+j,j}$.

P_{ij} multiplies these two submatrices, and adds the result to $C_{i,j}$.

Then in each of the next $\sqrt{p} - 1$ steps, each block row of A is rotated to the left by 1 position, and each block column of B is rotated upward by 1 position. Each P_{ij} adds the product of its current submatrices to $C_{i,j}$.

A _{0,0}	A _{0,1}	A _{0,2}	A _{0,3}
B _{0,0}	B _{1,1}	B _{2,2}	B _{3,3}
A _{1,1}	A _{1,2}	A _{1,3}	A _{1,0}
B _{1,0}	B _{2,1}	B _{3,2}	B _{0,3}
A _{2,2}	A _{2,3}	A _{2,0}	A _{2,1}
B _{2,0}	B _{3,1}	B _{0,2}	B _{1,3}
A _{3,3}	A _{3,0}	A _{3,1}	A _{3,2}
B _{3,0}	B _{0,1}	B _{1,2}	B _{2,3}

(c) A and B after initial alignment

A _{0,1}	A _{0,2}	A _{0,3}	A _{0,0}
B _{1,0}	B _{2,1}	B _{3,2}	B _{0,3}
A _{1,2}	A _{1,3}	A _{1,0}	A _{1,1}
B _{2,0}	B _{3,1}	B _{0,2}	B _{1,3}
A _{2,3}	A _{2,0}	A _{2,1}	A _{2,2}
B _{3,0}	B _{0,1}	B _{1,2}	B _{2,3}
A _{3,0}	A _{3,1}	A _{3,2}	A _{3,3}
B _{0,0}	B _{1,1}	B _{2,2}	B _{3,3}

(d) Submatrix locations after first shift

A _{0,2}	A _{0,3}	A _{0,0}	A _{0,1}
B _{2,0}	B _{3,1}	B _{0,2}	B _{1,3}
A _{1,3}	A _{1,0}	A _{1,1}	A _{1,2}
B _{3,0}	B _{0,1}	B _{1,2}	B _{2,3}
A _{2,0}	A _{2,1}	A _{2,2}	A _{2,3}
B _{0,0}	B _{1,1}	B _{2,2}	B _{3,3}
A _{3,1}	A _{3,2}	A _{3,3}	A _{3,0}
B _{1,0}	B _{2,1}	B _{3,2}	B _{0,3}

(e) Submatrix locations after second shift

A _{0,3} B _{3,0}	A _{0,0} B _{0,1}	A _{0,1} B _{1,2}	A _{0,2} B _{2,3}
A _{1,0} B _{0,0}	A _{1,1} B _{1,1}	A _{1,2} B _{2,2}	A _{1,3} B _{3,3}
A _{2,1} B _{1,0}	A _{2,2} B _{2,1}	A _{2,3} B _{3,2}	A _{2,0} B _{0,3}
A _{3,2} B _{2,0}	A _{3,3} B _{3,1}	A _{3,0} B _{0,2}	A _{3,1} B _{1,3}

(f) Submatrix locations after third shift

Cannon's Algorithm

Initial arrangement makes $\sqrt{p} - 1$ block rotations of A and B , and one block matrix multiplication per processor.

In each of the next $\sqrt{p} - 1$ steps, each processor performs one block matrix multiplication, and sends and receives one block each.

$$t_{comp} = 2\sqrt{p} \left(\frac{n}{\sqrt{p}}\right)^3 = O\left(\frac{n^3}{p}\right)$$

$$t_{comm} = 4(\sqrt{p} - 1)$$

$$\times \left(t_s + \left(\frac{n}{\sqrt{p}}\right)^2 t_w \right).$$

A _{0,0}	A _{0,1}	A _{0,2}	A _{0,3}
B _{0,0}	B _{1,1}	B _{2,2}	B _{3,3}
A _{1,1}	A _{1,2}	A _{1,3}	A _{1,0}
B _{1,0}	B _{2,1}	B _{3,2}	B _{0,3}
A _{2,2}	A _{2,3}	A _{2,0}	A _{2,1}
B _{2,0}	B _{3,1}	B _{0,2}	B _{1,3}
A _{3,3}	A _{3,0}	A _{3,1}	A _{3,2}
B _{3,0}	B _{0,1}	B _{1,2}	B _{2,3}

(c) A and B after initial alignment

A _{0,1}	A _{0,2}	A _{0,3}	A _{0,0}
B _{1,0}	B _{2,1}	B _{3,2}	B _{0,3}
A _{1,2}	A _{1,3}	A _{1,0}	A _{1,1}
B _{2,0}	B _{3,1}	B _{0,2}	B _{1,3}
A _{2,3}	A _{2,0}	A _{2,1}	A _{2,2}
B _{3,0}	B _{0,1}	B _{1,2}	B _{2,3}
A _{3,0}	A _{3,1}	A _{3,2}	A _{3,3}
B _{0,0}	B _{1,1}	B _{2,2}	B _{3,3}

(d) Submatrix locations after first shift

A _{0,2}	A _{0,3}	A _{0,0}	A _{0,1}
B _{2,0}	B _{3,1}	B _{0,2}	B _{1,3}
A _{1,3}	A _{1,0}	A _{1,1}	A _{1,2}
B _{3,0}	B _{0,1}	B _{1,2}	B _{2,3}
A _{2,0}	A _{2,1}	A _{2,2}	A _{2,3}
B _{0,0}	B _{1,1}	B _{2,2}	B _{3,3}
A _{3,1}	A _{3,2}	A _{3,3}	A _{3,0}
B _{1,0}	B _{2,1}	B _{3,2}	B _{0,3}

(e) Submatrix locations after second shift

A _{0,3}	A _{0,0}	A _{0,1}	A _{0,2}
B _{3,0}	B _{0,1}	B _{1,2}	B _{2,3}
A _{1,0}	A _{1,1}	A _{1,2}	A _{1,3}
B _{0,0}	B _{1,1}	B _{2,2}	B _{3,3}
A _{2,1}	A _{2,2}	A _{2,3}	A _{2,0}
B _{1,0}	B _{2,1}	B _{3,2}	B _{0,3}
A _{3,2}	A _{3,3}	A _{3,0}	A _{3,1}
B _{2,0}	B _{3,1}	B _{0,2}	B _{1,3}

(f) Submatrix locations after third shift

Cannon's Algorithm

What if initially, one master processor (say, $P_{0,0}$) holds all data (i.e., matrices A and B), and the same processor wants to collect the entire output matrix (i.e., C) at the end?

Processor $P_{0,0}$ initially sends $A_{i,j}$ and $B_{i,j}$ to processor $P_{i,j}$, and at the end processor $P_{i,j}$ sends back $C_{i,j}$ to $P_{0,0}$.

Since there are p processors, and each submatrix has size $\frac{n}{\sqrt{p}} \times \frac{n}{\sqrt{p}}$, the additional communication complexity:

$$3p \times \left(t_s + \left(\frac{n}{\sqrt{p}} \right)^2 t_w \right) = 3(pt_s + n^2 t_w).$$

So, the communication complexity increases by a factor of \sqrt{p} .