CSE528 Computer Graphics: Theory, Algorithms, and Applications

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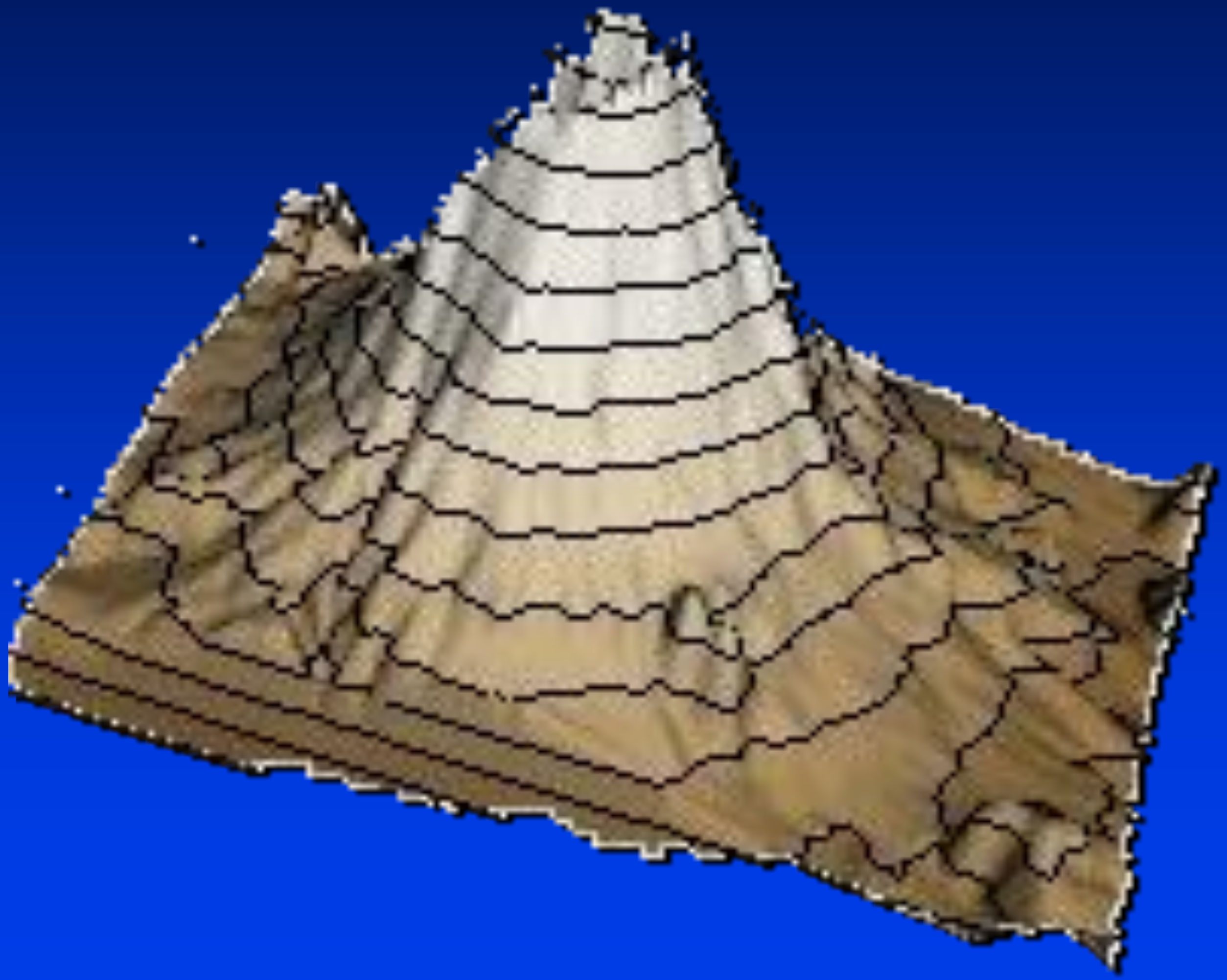
Implicit Surfaces

Height Function - Geology – Terrain Modeling

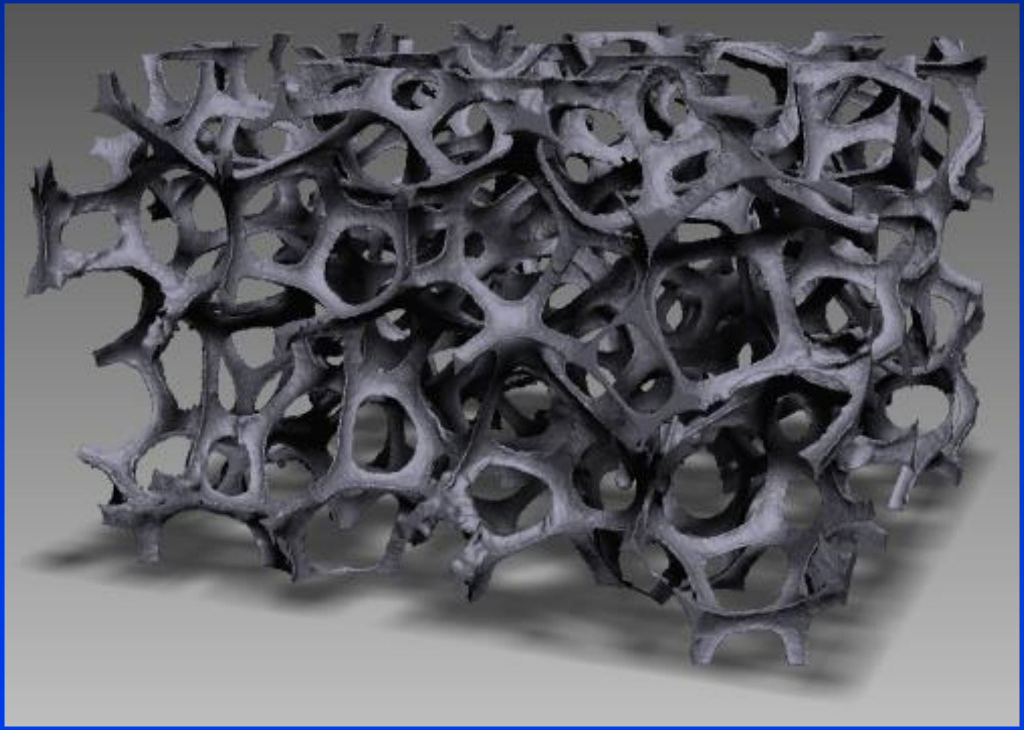


Implicit Surfaces

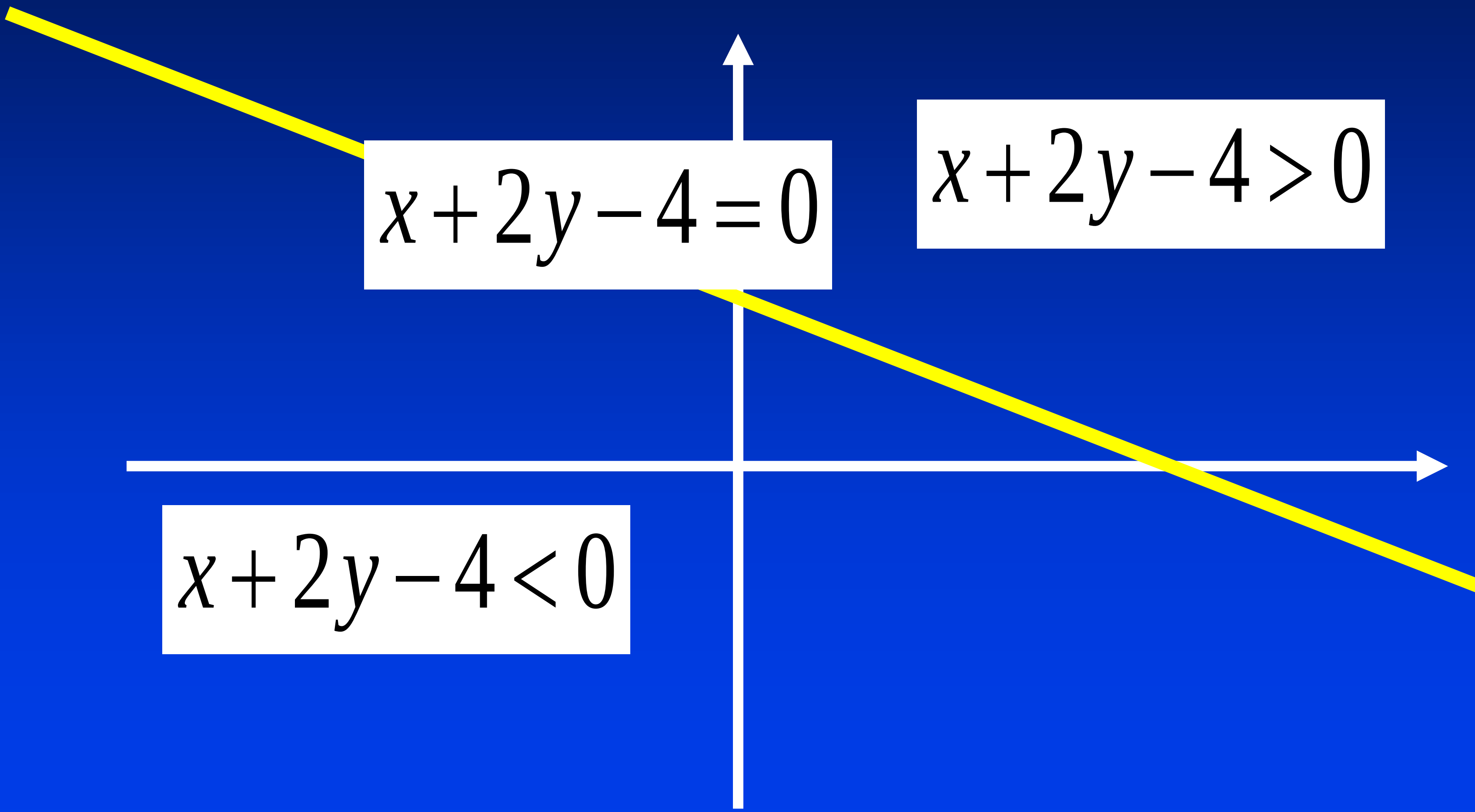
- Defined by (algebraic) functions
- Some surfaces can be represented as the vanishing points of functions (defined over 3D space)
  – Places where a function $f(x,y,z)=0$

Implicit Surfaces

$$F(x, y, z) = 0$$



Straight Line (Implicit Representation)



Straight Line

- Mathematics (Implicit Representation)

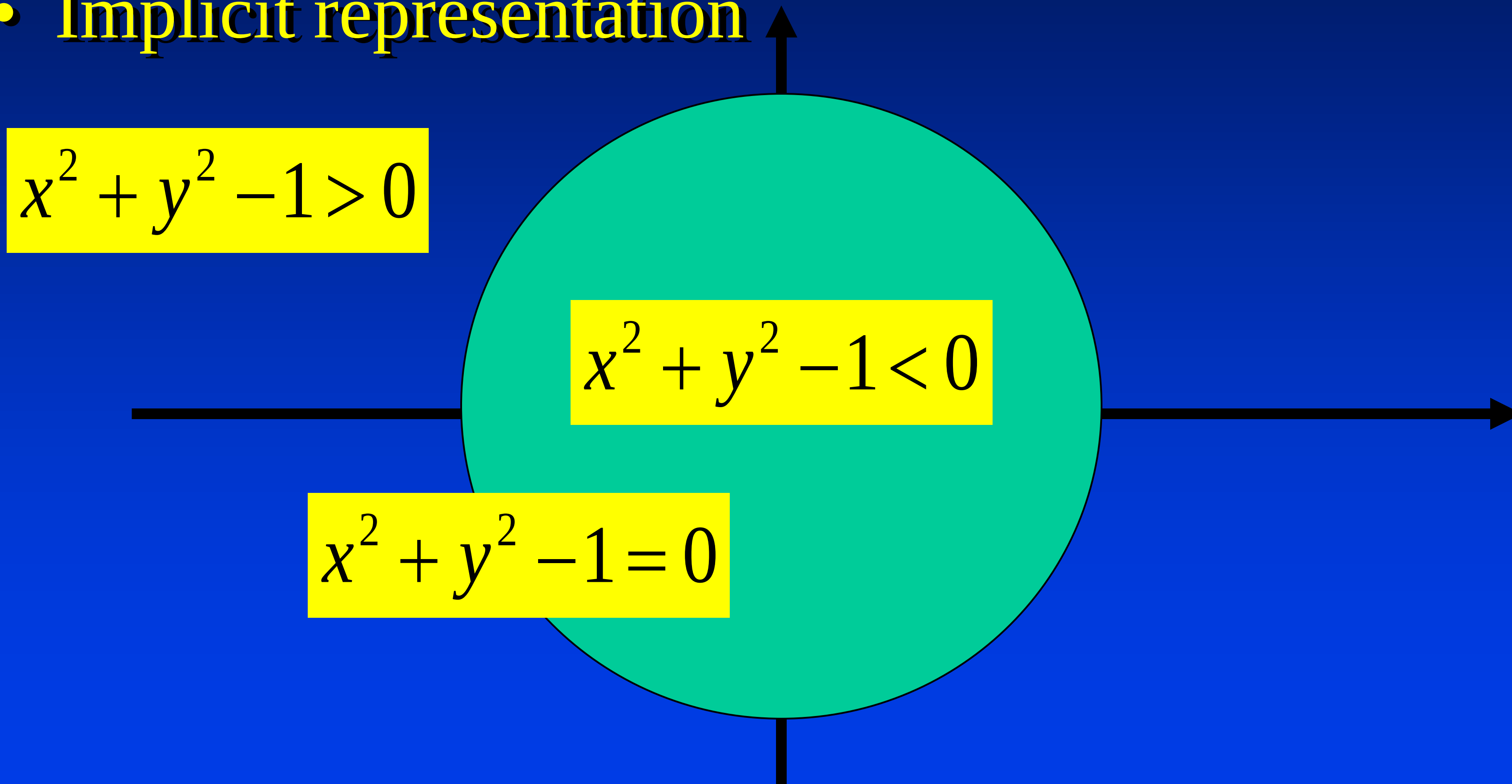
$$ax + by + c = 0$$
$$+\alpha(ax + by + c) = 0$$
$$-\alpha(ax + y + c) = 0$$

- Example

$$x + 2y - 4 = 0$$

Circle

- Implicit representation



Conic Sections

- Mathematics
- Examples
  - Ellipse
  - Hyperbola
  - Parabola
  - Empty set
  - Point
  - Pair of lines
  - Parallel lines
  - Repeated lines

$$ax^2 + 2bxy + cy^2 + dx + ey + f = 0$$

$$2x^2 + 3y^2 - 5 = 0$$
$$2x^2 - 3y^2 - 5 = 0$$
$$2x^2 + 3y = 0$$
$$2x^2 + 3y^2 + 1 = 0$$
$$2x^2 + 3y^2 = 0$$
$$2x^2 - 3y^2 = 0$$
$$2x^2 - 7 = 0$$
$$2x^2 = 0$$

Conics

- Parametric equations of conics
- Generalization to higher-degree curves
- How about non-planar (spatial) curves

Conics

$$Ax^2 + 2Bxy + Cy^2 + 2Dx + 2Ey + F = 0$$

$$\mathbf{PQP}^T = 0$$

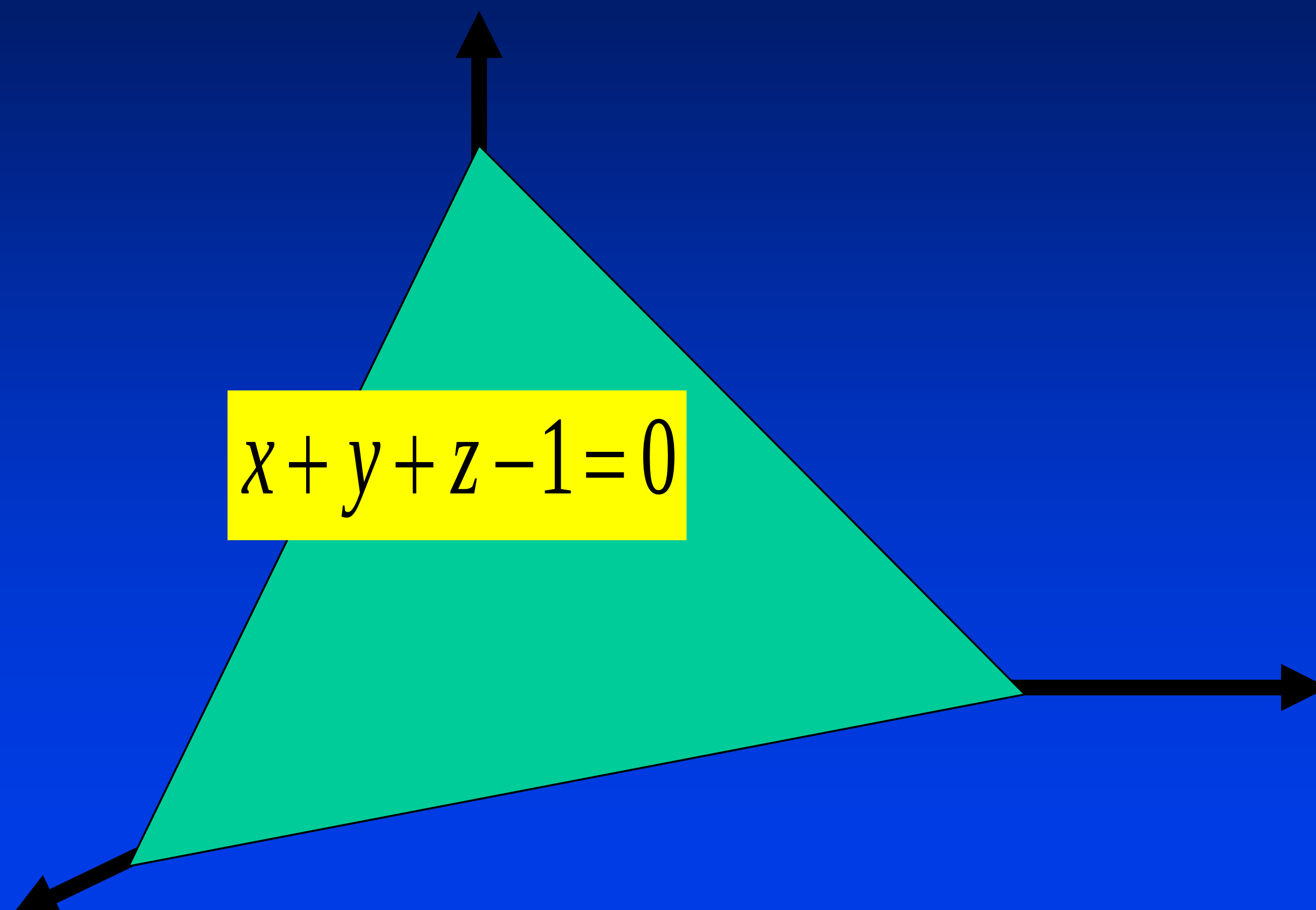
$$\mathbf{Q} = \begin{bmatrix} A & B & D \\ B & C & E \\ D & E & F \end{bmatrix}$$

$$\mathbf{P} = [x \quad y \quad 1]$$

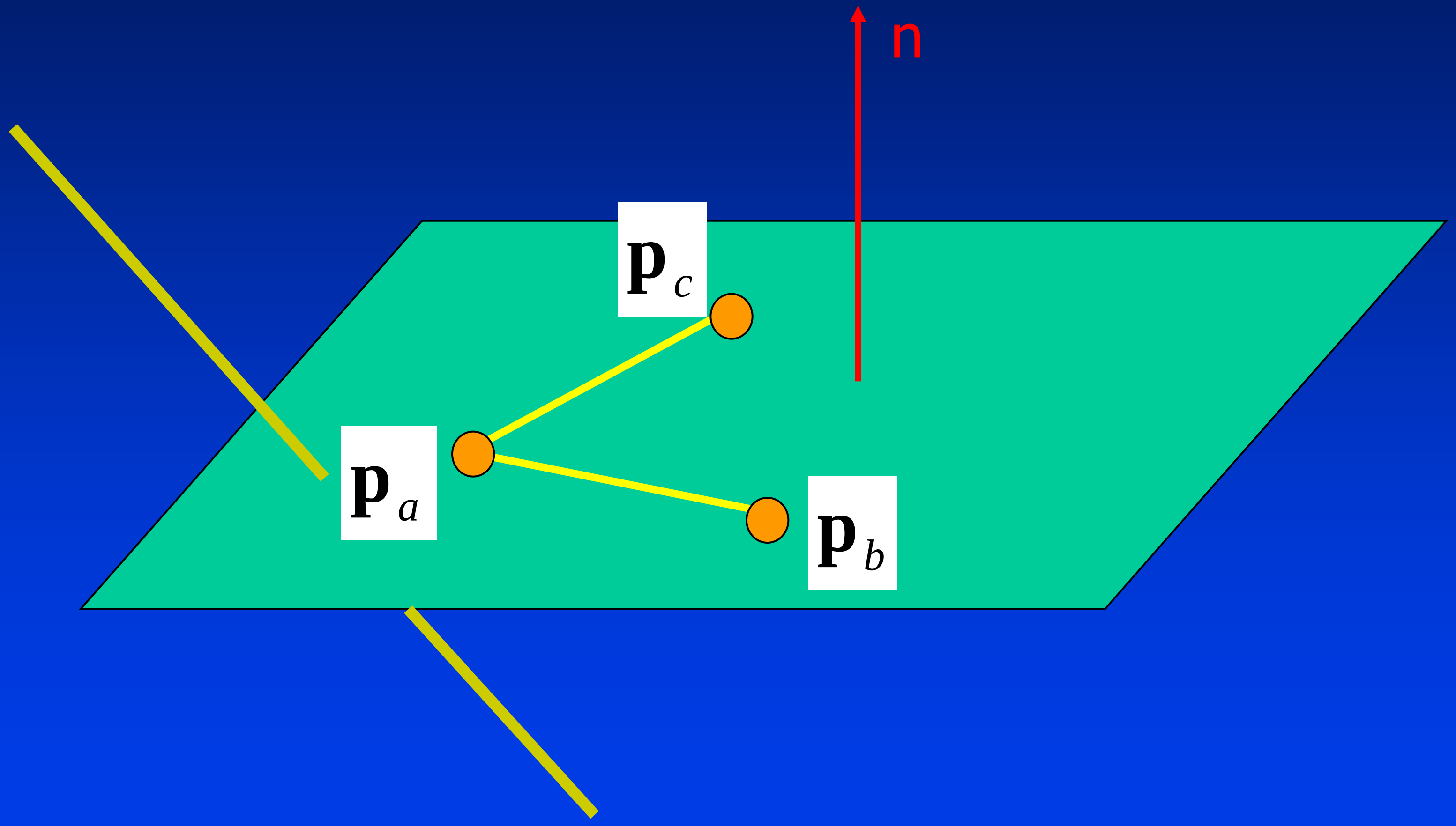
Table 2.1 Conic curve characteristics

k	$\lvert\mathbf{Q}\rvert$	Other conditions	Type
0	$\neq 0$		Parabola
0	0	$C \neq 0, E^2 - CF > 0$	Two parallel real lines
0	0	$C \neq 0, E^2 - CF = 0$	Two parallel coincident lines
0	0	$C \neq 0, E^2 - CF < 0$	Two parallel imaginary lines
0	0	$C = B = 0, D^2 - AF > 0$	Two parallel real lines
0	0	$C = B = 0, D^2 - AF = 0$	Two parallel coincident lines
0	0	$C = B = 0, D^2 - AF < 0$	Two parallel imaginary lines
<0	0		Point ellipse
<0	$\neq 0$	$-C\lvert\mathbf{Q}\rvert > 0$	Real ellipse
<0	$\neq 0$	$-C\lvert\mathbf{Q}\rvert < 0$	Imaginary ellipse
<0	$\neq 0$		Hyperbola
<0	0		Two intersecting lines

Plane



Plane and Intersection



Plane

- Example $x + y + z - 1 = 0$
- General plane equation $ax + by + cz + y = 0$
- Normal of the plane

$$\mathbf{n} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

- Arbitrary point on the plane

$$\mathbf{p}_a = \begin{bmatrix} a_x \\ a_y \\ a_z \end{bmatrix}$$

Plane

- Plane equation derivation

$$(x-a_x)a+(y-a_y)b+(z-a_z)c=0$$

$$ax+by+cz-(a_xa+a_yb+a_zc)=0$$

- Parametric representation (given three points on the plane and they are non-collinear!)

$$\mathbf{p}(u,v)=\mathbf{p}_a+(\mathbf{p}_b-\mathbf{p}_a)u+(\mathbf{p}_c-\mathbf{p}_a)v$$

Plane

- Explicit expression (if c is non-zero)

$$z = -\frac{1}{c}(ax + by + d)$$

- Line-Plane intersection

$$\mathbf{l}(u) = \mathbf{p}_0 + (\mathbf{p}_1 - \mathbf{p}_0)u$$

$$(\mathbf{n})(\mathbf{p}_0 + (\mathbf{p}_1 - \mathbf{p}_0)u) + d = 0$$

$$u = -\frac{\mathbf{n}\mathbf{p}_0}{\mathbf{n}\mathbf{p}_1 - \mathbf{n}\mathbf{p}_0} = -\frac{plane(\mathbf{p}_0)}{plane(\mathbf{p}_1) - plane(\mathbf{p}_0)}$$

Circle

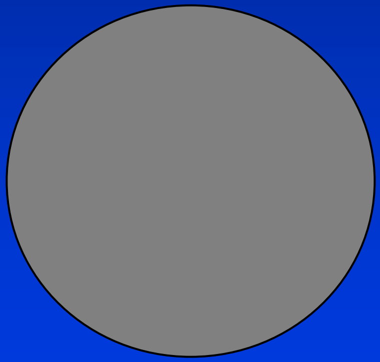
- Implicit equation $x^2 + y^2 - 1 = 0$
- Parametric function
$$\mathbf{c}(\theta) = \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix}$$
$$0 <= \theta <= 2\pi$$
- Parametric representation using rational polynomials (the first quadrant)
$$x(u) = \frac{1-u^2}{1+u^2}$$
$$y(u) = \frac{2u}{1+u^2}$$
$$u \in [0,1]$$
- Parametric representation is not unique!

What are Implicit Surfaces?

- 2D Geometric shapes that exist in 3D space
- Surface representation through a function $f(x, y, z) = 0$
- Most methods of analysis assume f is continuous and not everywhere 0.

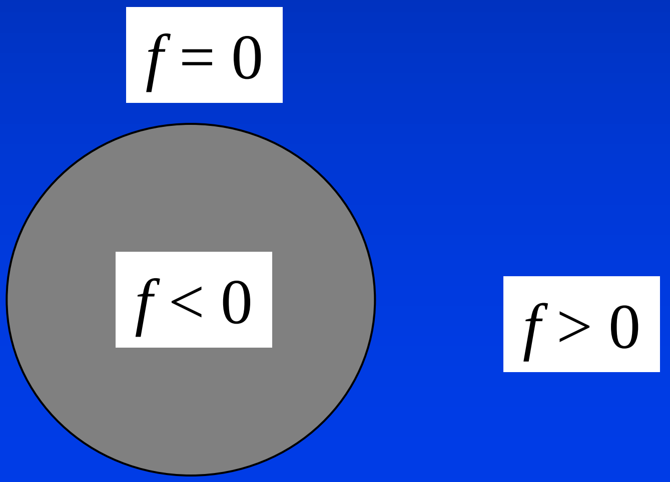
Example of an Implicit Surface

- 3D Sphere centered at the origin
  - $x^2 + y^2 + z^2 = r^2$
  - $x^2 + y^2 + z^2 - r^2 = 0$



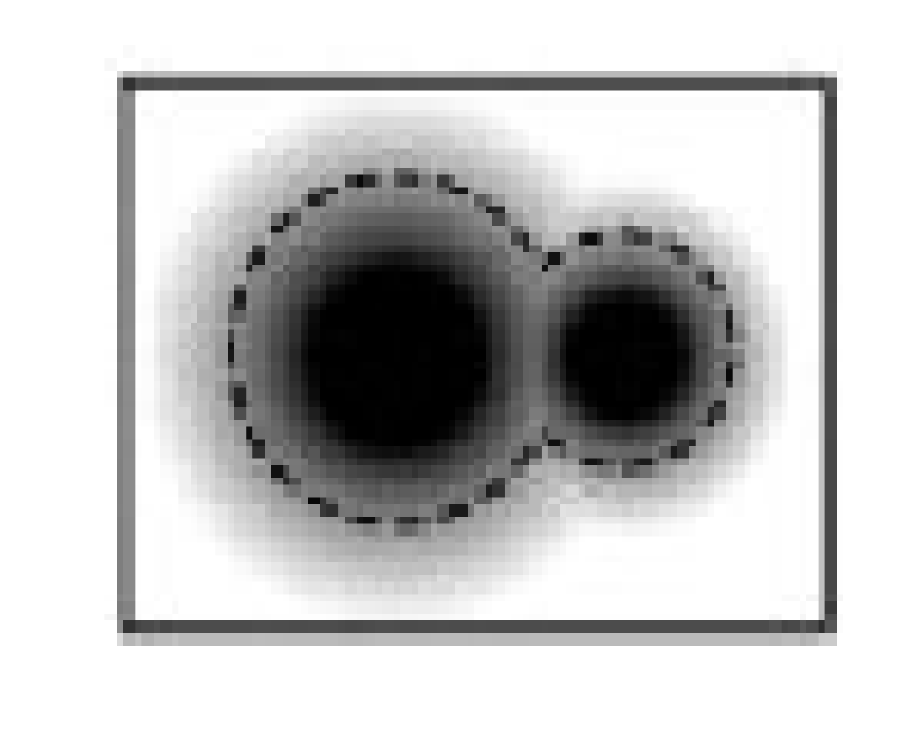
Point Classification

- Inside Region: f < 0
- Outside Region: f > 0
- Or vice versa depending on the function



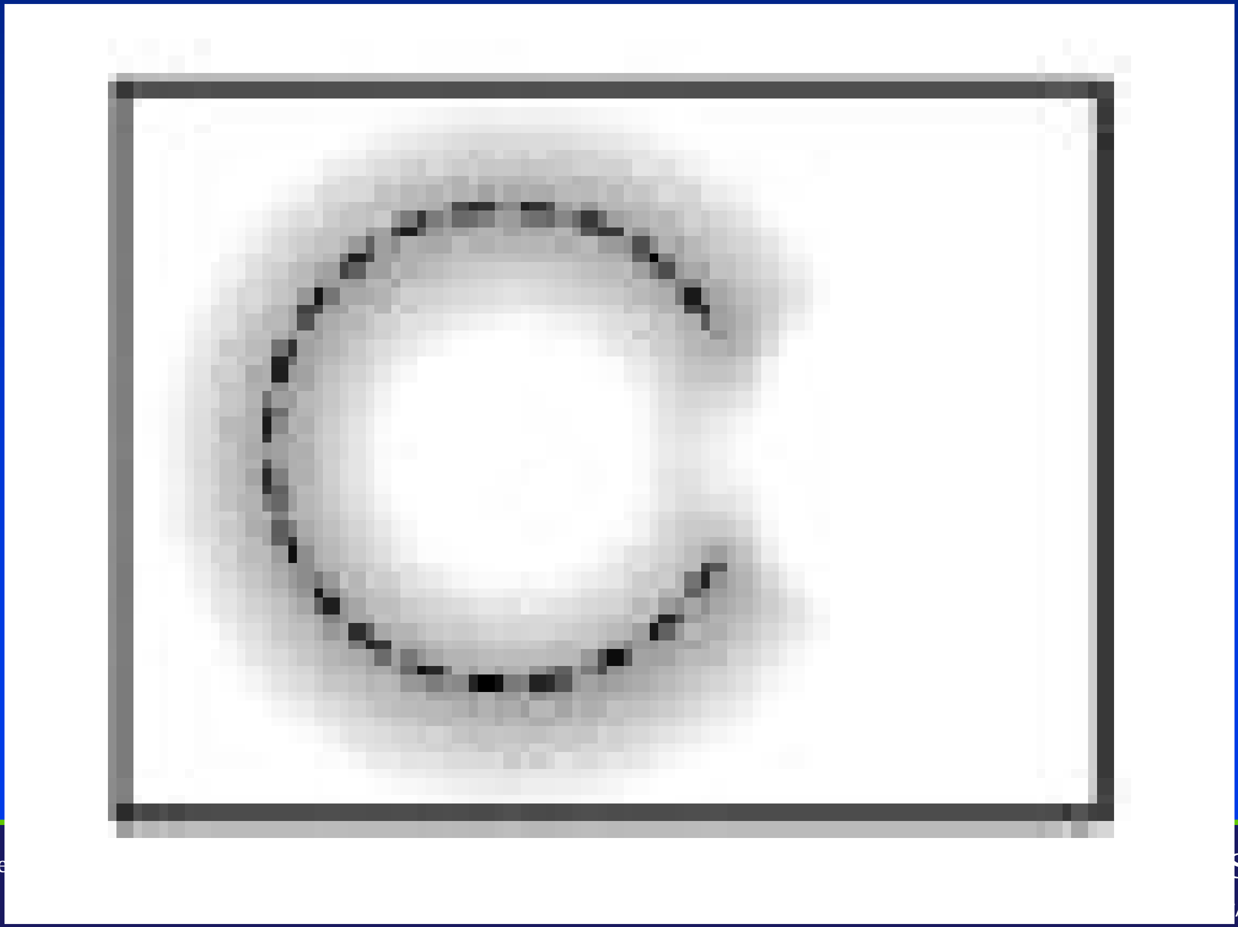
Manifold

- A 2D Manifold separates space into a natural inner and natural outer region
- A manifold surface contains no holes or dangling edges



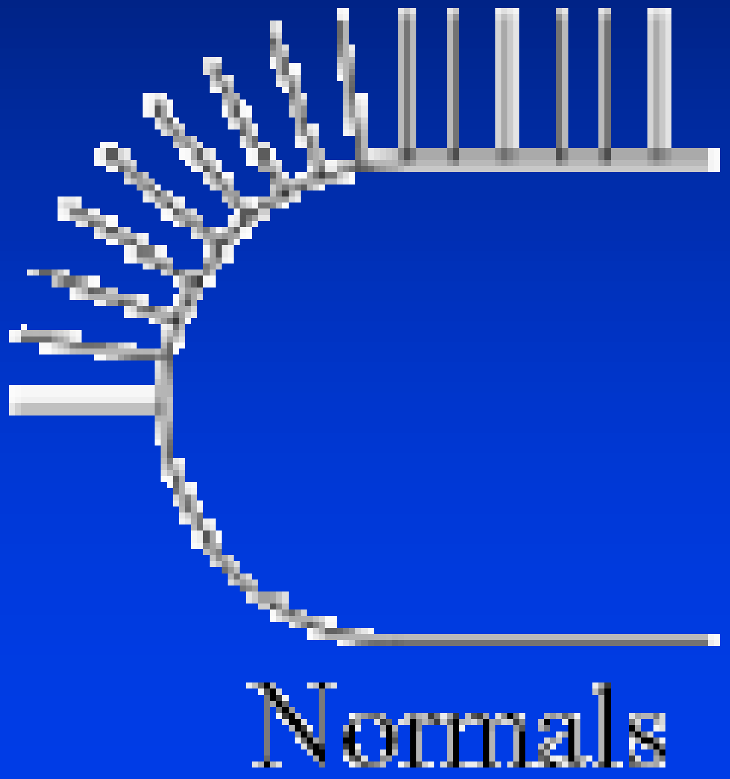
Manifold

- It is difficult to determine enclosed region in non-manifold surfaces



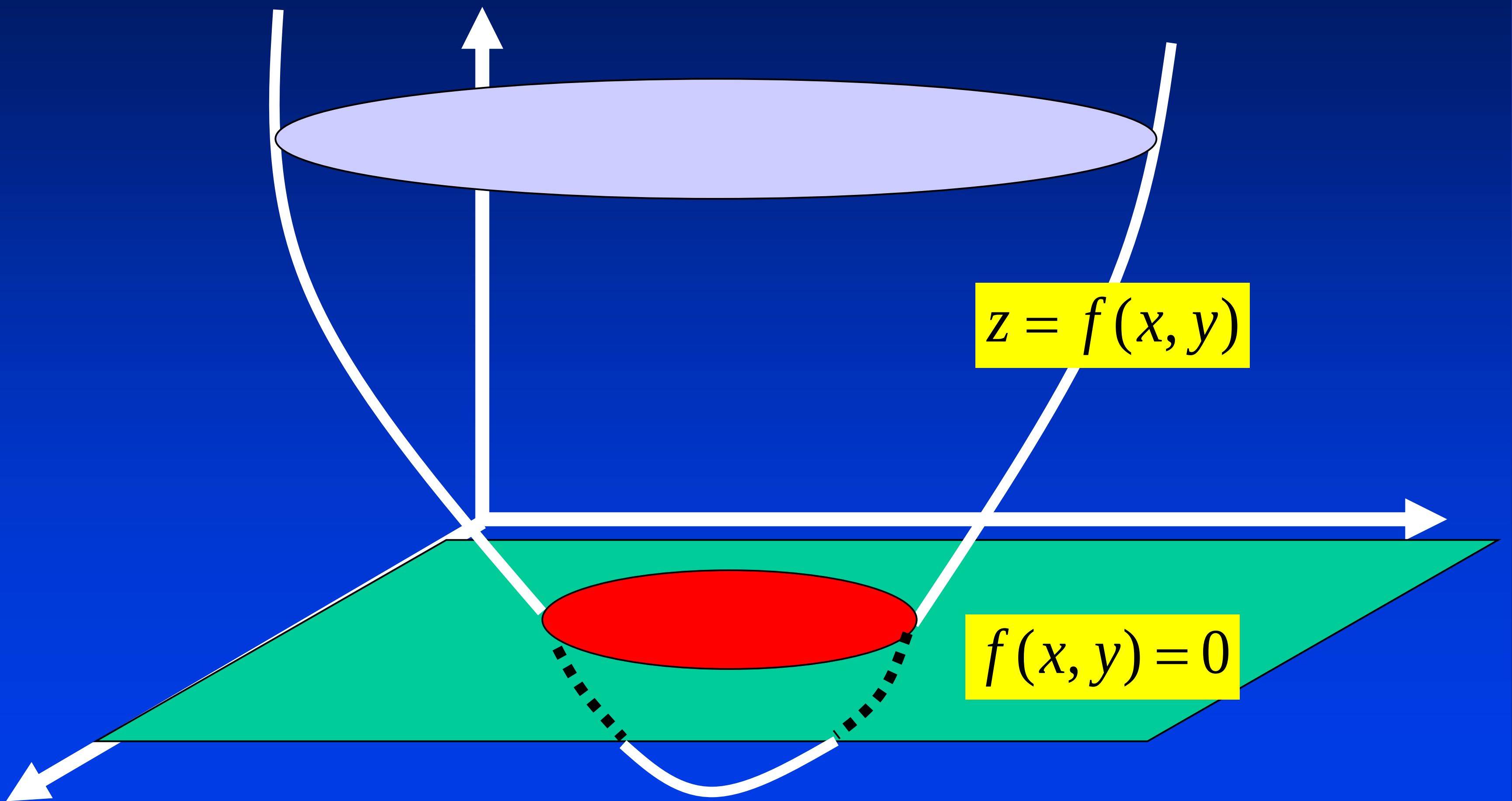
Surface Normals

- Usually gradient of the function
  - $\nabla f(x,y,z) = (\delta f/\delta x, \delta f/\delta y, \delta f/\delta z)$
- Points at increasing f



Properties of Implicits

- Easy to check if a point is inside the implicit surface or NOT
  - Simply evaluate f at that point
- Fairly easy to check ray intersection
  - Substitute ray equation into f for simple functions
  - Binary search


$z = f(x, y)$
$f(x, y) = 0$

Implicit Equations for Curves

- Describe an implicit relationship
- Planar curve (point set) $\{(x,y) \mid f(x,y)=0\}$
- The implicit function is not unique

$$\{(x,y) \mid +\alpha f(x,y)=0\}$$

$$\{(x,y) \mid -\alpha f(x,y)=0\}$$

- Comparison with parametric representation

$$\mathbf{p}(u)=\begin{bmatrix} x(u) \\ y(u) \end{bmatrix}$$

Implicit Equations for Curves

- Implicit function is a level-set

$$\begin{cases} z = & f(x, y) \\ z = & 0 \end{cases}$$

- Examples (straight line and conic sections)

$$ax + by + c = 0$$

$$ax^2 + 2bxy + cy^2 + dx + ey + f = 0$$

- Other examples
  - Parabola, two parallel lines, ellipse, hyperbola, two intersection lines

Implicit Functions for Curves

- Parametric equations of conics
- Generalization to higher-degree curves
- How about non-planar (spatial) curves

Implicit Equations for Surfaces

- Surface mathematics $\{(x,y,z) \mid f(x,y,z)=0\}$
- Again, the implicit function for surfaces is not unique

$$\{(x,y,z) \mid +\alpha f(x,y,z)=0\}$$
$$\{(x,y,z) \mid -\alpha f(x,y,z)=0\}$$

- Comparison with parametric representation

$$\mathbf{p}(u,v)=\begin{bmatrix} x(u,v) \\ y(u,v) \\ z(u,v) \end{bmatrix}$$

Implicit Equations for Surfaces

- Surface defined by implicit function is a level-set

$$\begin{cases} w = & f(x,y,z) \\ w = & 0 \end{cases}$$

- Examples
  - Plane, quadric surfaces, tori, superquadrics, blobby objects
- Parametric representation of quadric surfaces
- Generalization to higher-degree surfaces

Quadric Surfaces

- Implicit functions
- Examples

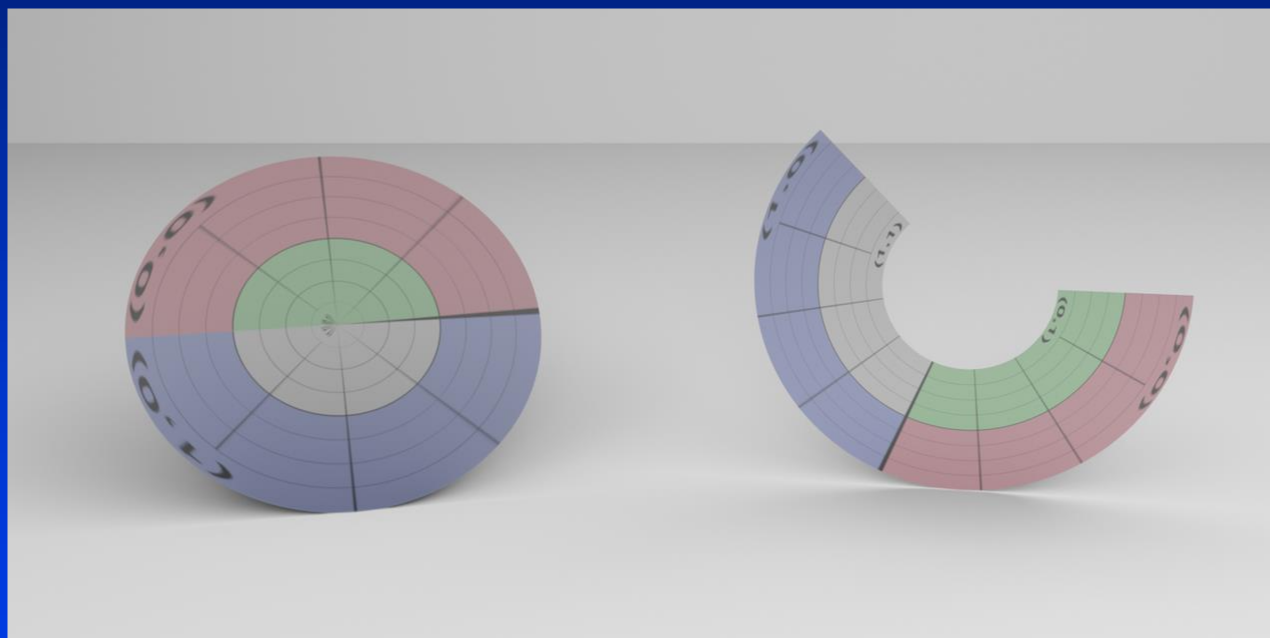
$$ax^2 + by^2 + cz^2 + dxy + exz + fyz + gx + hy + jz + k = 0$$

  - Sphere
  - Cylinder
  - Cone
  - Paraboloid
  - Ellipsoid
  - Hyperboloid

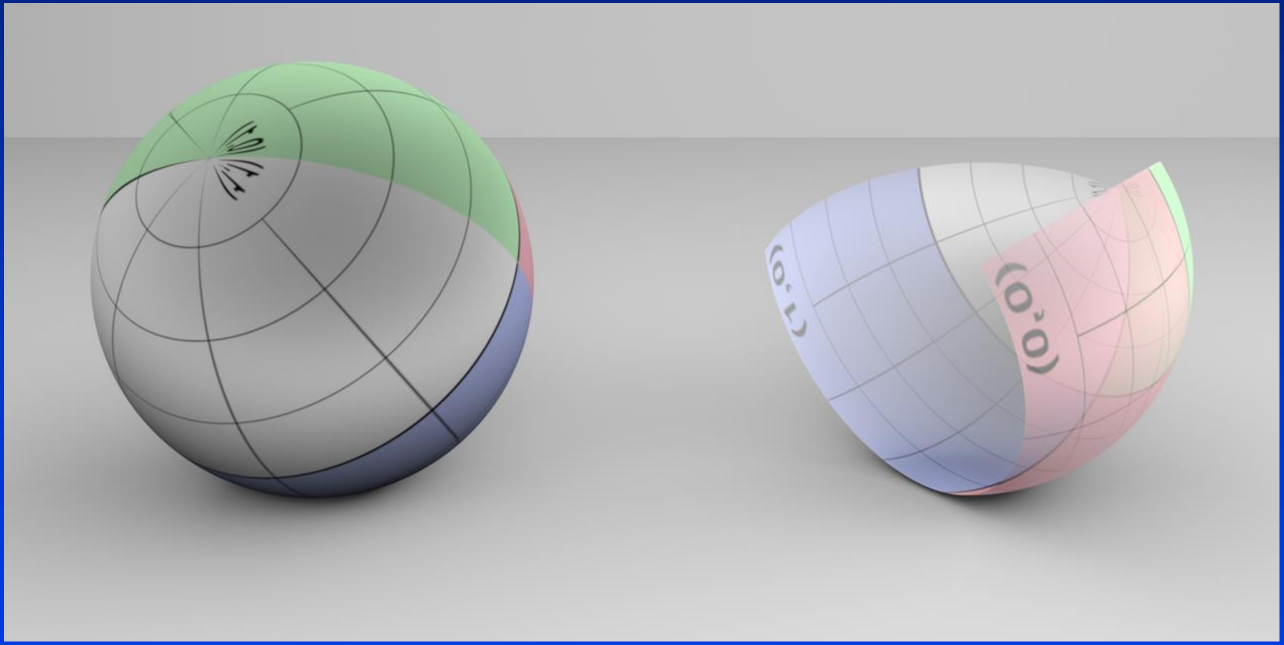
$$x^2 + y^2 + z^2 - 1 = 0$$
$$x^2 + y^2 - 1 = 0$$
$$x^2 + y^2 - z^2 = 0$$
$$x^2 + y^2 + z = 0$$
$$2x^2 + 3y^2 + 4z^2 - 5 = 0$$
$$x^2 + y^2 - z^2 + 4 = 0$$

- More
  - Two parallel planes, two intersecting planes, single plane, line, point

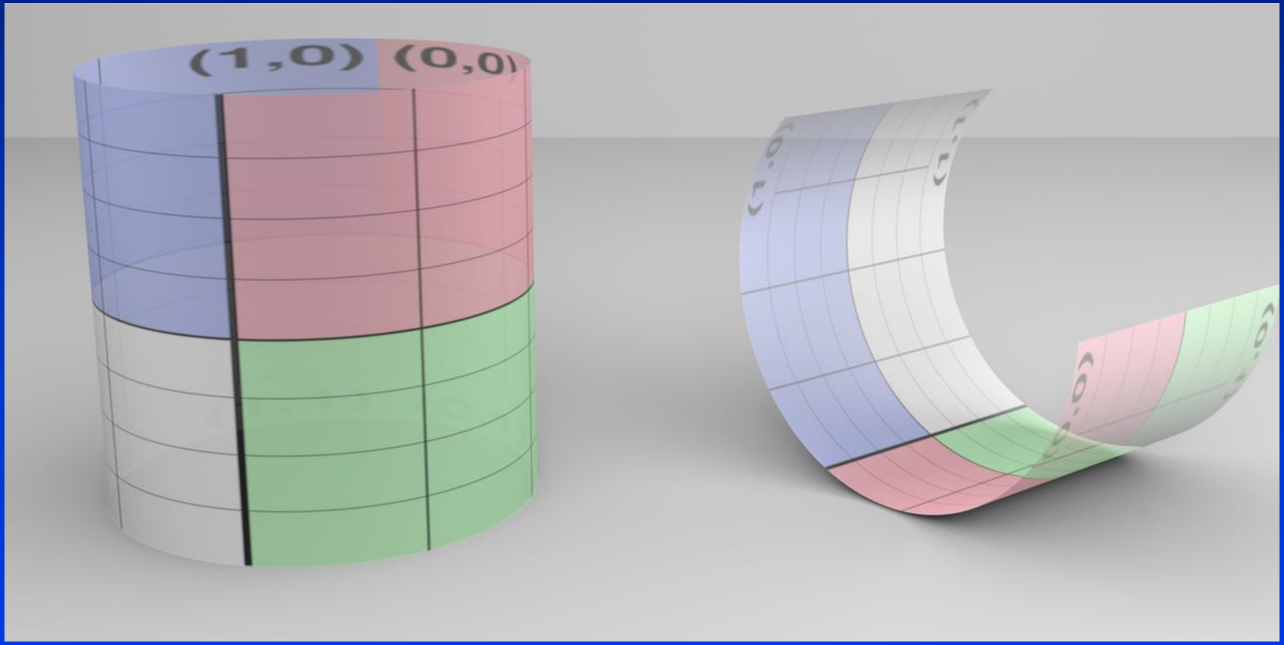
Disk



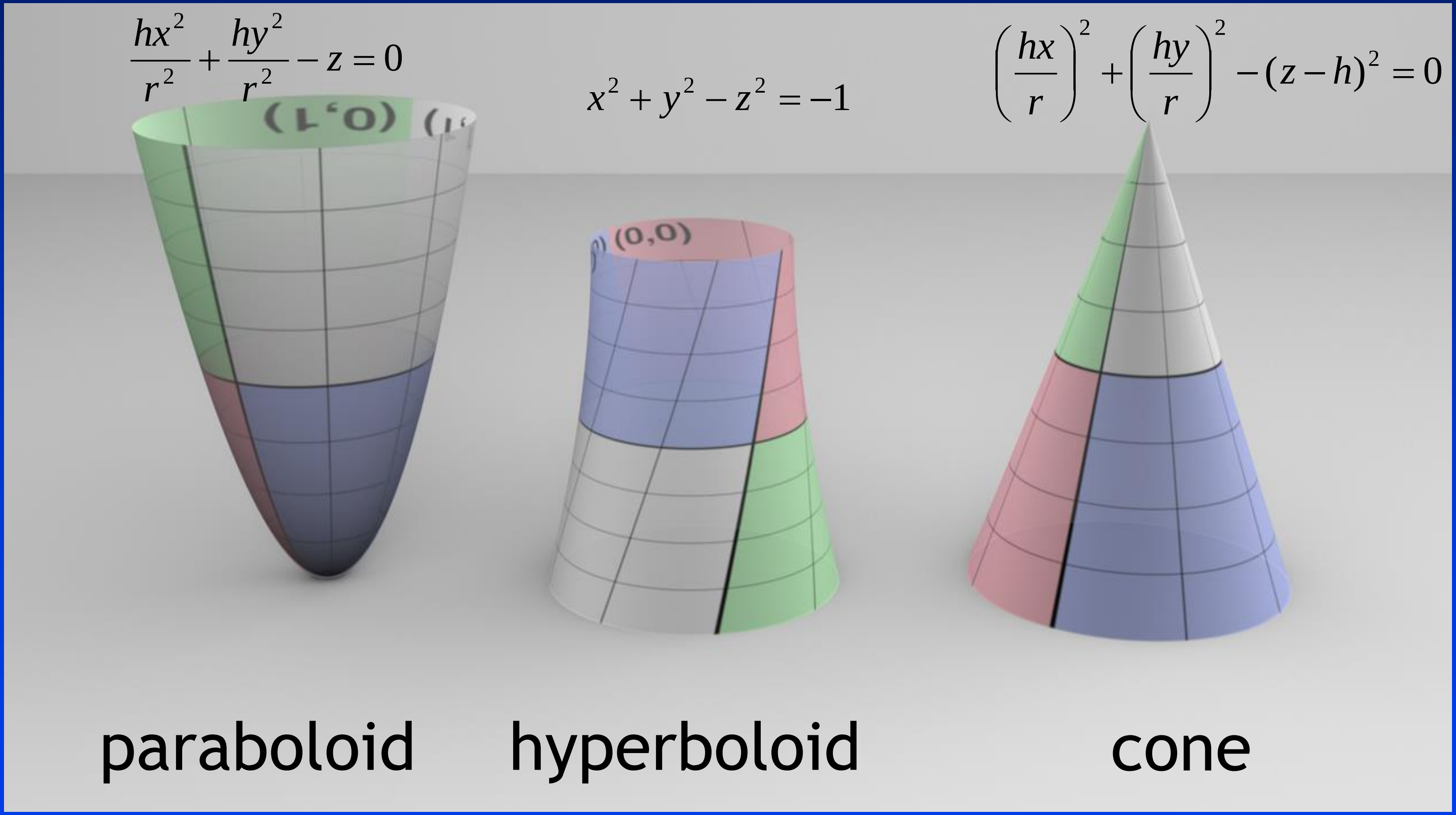
Sphere



Cylinder



Other Quadrics



Quadric Surfaces

- Implicit surface equation

$$f(x,y,z) = ax^2 + by^2 + cz^2 + 2dxy + 2eyz + 2fxz + 2gx + 2hy + 2jz + k = 0$$

- An alternative representation

$$P^{\mathrm{T}} \bullet Q \bullet P = 0$$

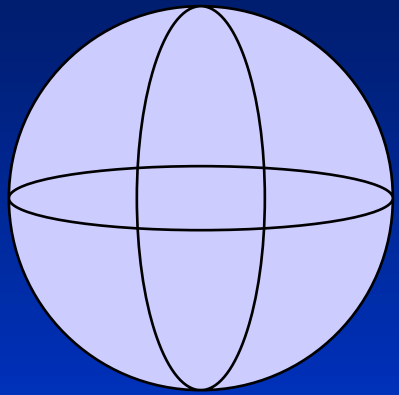
with

$$Q = \begin{bmatrix} a & d & f & g \\ d & b & e & h \\ f & e & c & j \\ g & h & j & k \end{bmatrix} \qquad P = \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

Quadrics: Parametric Rep.

- Sphere

$$x^2 + y^2 + z^2 - r^2 = 0$$
$$x = r\cos(\alpha)\cos(\beta)$$
$$y = r\cos(\alpha)\sin(\beta)$$
$$z = r\sin(\alpha)$$
$$\alpha \in [-\frac{\pi}{2}, \frac{\pi}{2}]; \beta \in [-\pi, \pi]$$



- Ellipsoid

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} - 1 = 0$$
$$x = a\cos(\alpha)\cos(\beta)$$
$$y = b\cos(\alpha)\sin(\beta)$$
$$z = c\sin(\alpha)$$
$$\alpha \in [-\frac{\pi}{2}, \frac{\pi}{2}]; \beta \in [-\pi, \pi]$$

- Geometric meaning of these parameters

Quadric Surfaces

- Modeling advantages
  - computing the surface normal
  - testing whether a point is on the surface
  - computing *z* given *x* and *y*
  - calculating intersections of one surface with another

Superquadrics

- Geometry (generalization of quadrics)
- Superellipse

$$\left(\frac{x}{a^{1}}\right)^{\frac{2}{s}}+\left(\frac{y}{a^{2}}\right)^{\frac{2}{s}}-1=0$$

- Superellipsoid

$$\left(\left(\frac{x}{a_1}\right)^{\frac{2}{s_2}}+\left(\frac{y}{a_2}\right)^{\frac{2}{s_2}}\right)^{\frac{s_2}{s_1}}+\left(\frac{z}{a_3}\right)-1=0$$

- Parametric representation

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix}=\begin{bmatrix} a_1\cos^{s_1}(\alpha)\sin^{s_2}(\beta) \\ a_2\cos^{s_1}(\alpha)\sin^{s_2}(\beta) \\ a_3\sin^{s_2}(\alpha) \end{bmatrix}$$

$$\alpha\in[-\frac{\pi}{2},\frac{\pi}{2}];\beta\in[-\pi,\pi)$$

- What is the meaning of these control parameters?

Types of Implicit Surfaces

- Mathematic
  - Polynomial or *Algebraic*
  - Non polynomial or *Transcendental*
    - Exponential, trigonometric, etc.
- Procedural
  - Black box function

Generalization

- Higher-degree polynomials

$$\sum_i \sum_j \sum_k a_{ijk} x^i y^j z^k = 0$$

- Non polynomials

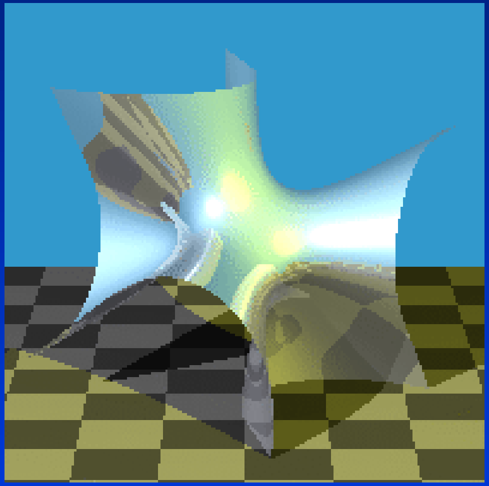
Algebraic Function

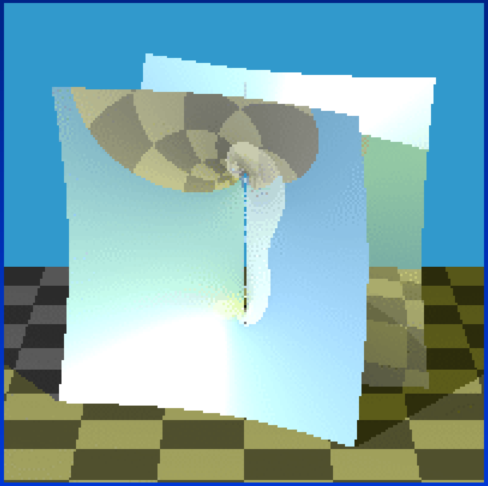
- Parametric representation is popular, but…
- Formulation

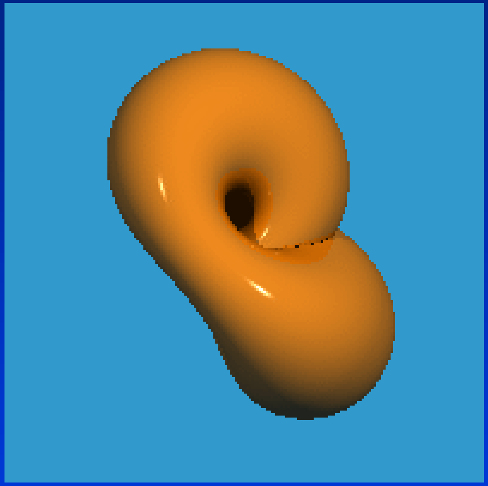
$$\sum_i \sum_j \sum_k a_{ijk} x^i y^j z^k = 0$$

- Properties…
  - Powerful, but lack of modeling tools

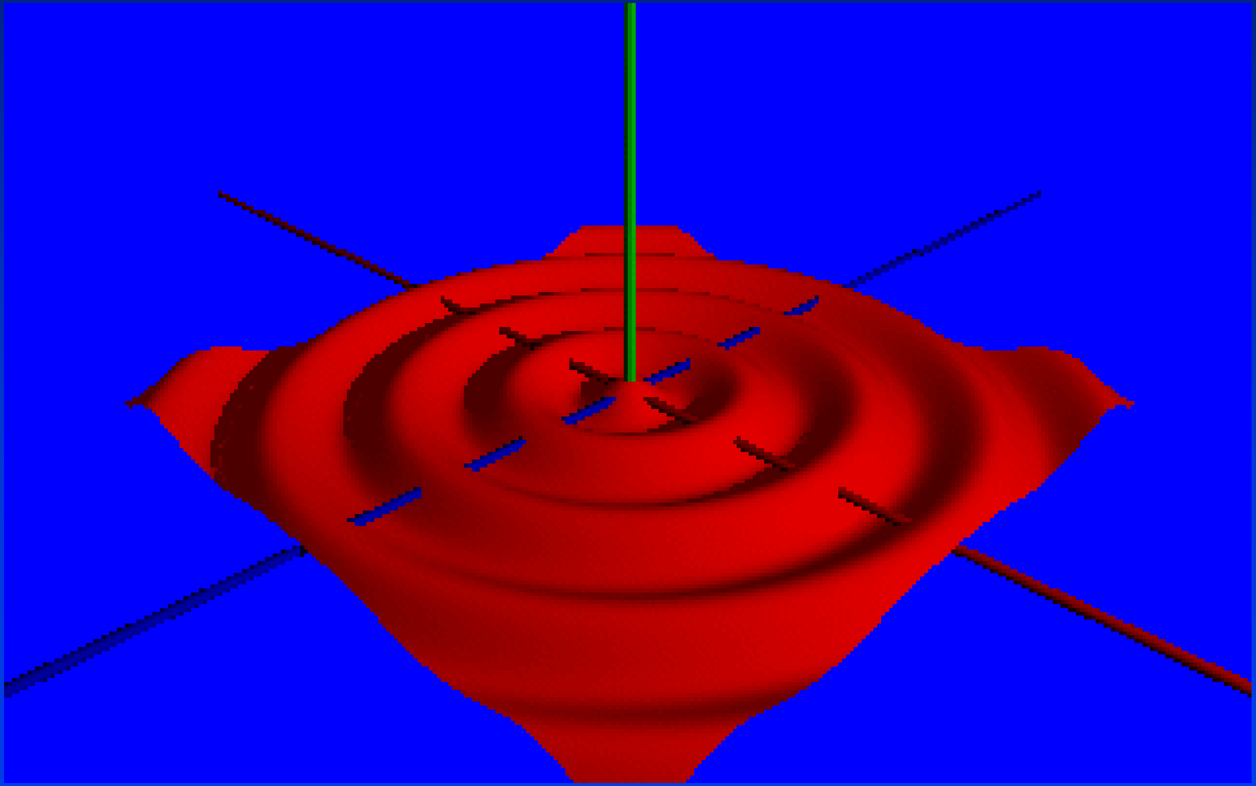
Algebraic Surfaces


Cubic

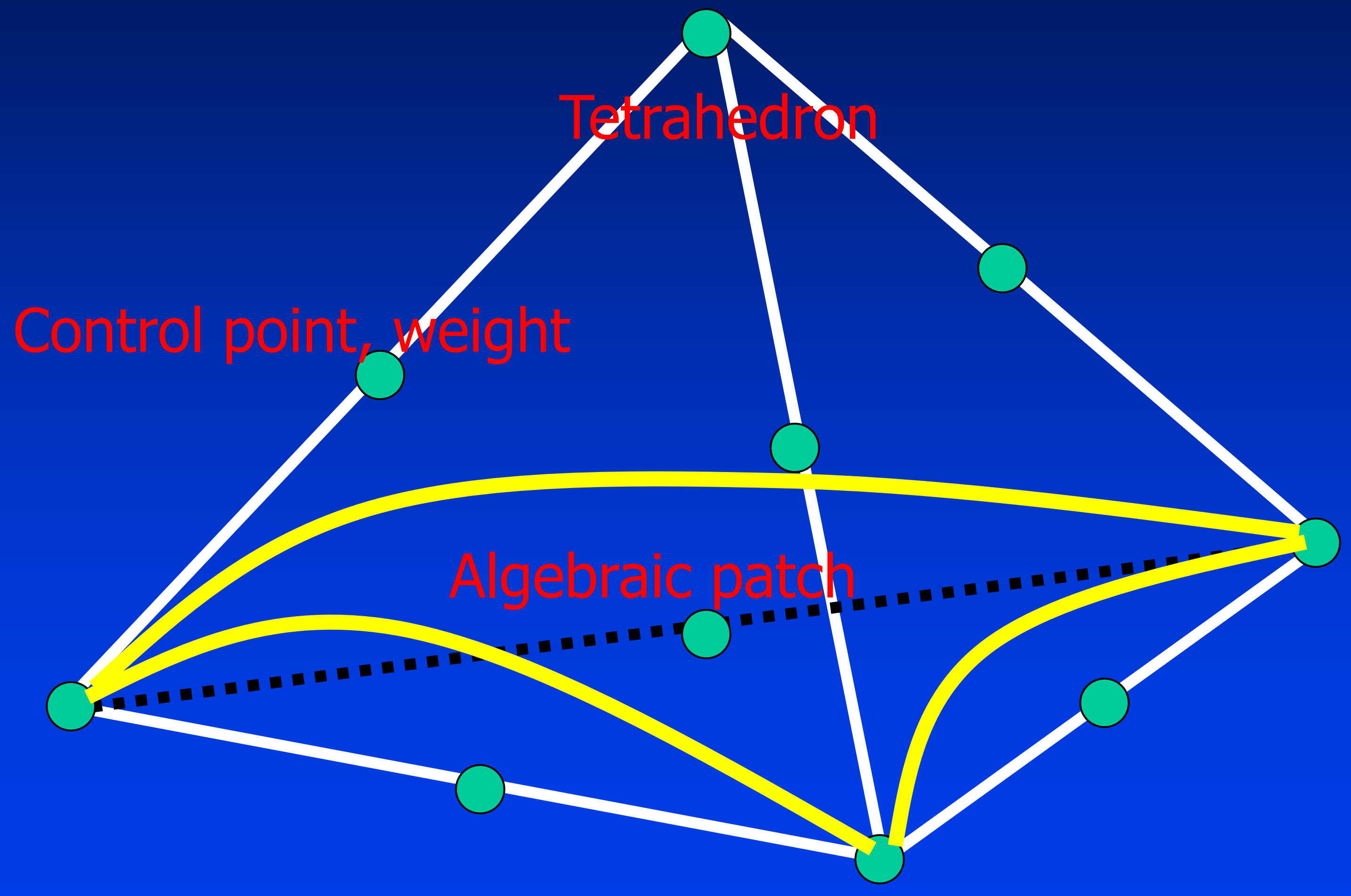

Degree 4


Degree 6

Non-Algebraic Surfaces



Algebraic Patch



Algebraic Patch

- A tetrahedron with non-planar vertices

$$\mathbf{v}_{n000}, \mathbf{v}_{0n00}, \mathbf{v}_{00n0}, \mathbf{v}_{000n}$$

- Trivariate barycentric coordinate (r,s,t,u) for p

$$\mathbf{p} = r\mathbf{v}_{n000} + s\mathbf{v}_{0n00} + t\mathbf{v}_{00n0} + u\mathbf{v}_{000n}$$
$$r + s + t + u = 1$$

- A regular lattice of control points and weights

$$\mathbf{p}_{ijkl} = \frac{i\mathbf{v}_{n000} + j\mathbf{v}_{0n00} + k\mathbf{v}_{00n0} + l\mathbf{v}_{000n}}{n}$$
$$i, j, k, l >= 0; i + j + k + l = n$$

Algebraic Patch

- There are (n+1)(n+2)(n+3)/6 control points. A weight w(I,j,k,l) is also assigned to each control point
- Algebraic patch formulation

$$\sum_{i}\sum_{j}\sum_{k}\sum_{l=n-i-j-k} w_{ijkl}\frac{n!}{i!\,j!\,k!\,l!}r^i s^j t^k u^l = 0$$

- Properties
  - Meaningful control, local control, boundary interpolation, gradient control, self-intersection avoidance, continuity condition across the boundaries, subdivision

Spatial Curves

- Intersection of two surfaces

$$\begin{cases} f(x,y,z)=0 \\ g(x,y,z)=0 \end{cases}$$

Algebraic Solid

- Half space $\{(x,y,z) \mid f(x,y,z) <= 0\}; or$
  $\{(x,y,z) \mid f(x,y,z) >= 0\}$
- Useful for complex objects (refer to notes on solid modeling)

$$\mathbf{f}(x,y,z) = \begin{bmatrix} f_1(x,y,z) \\ f_2(x,y,z) \\ f_3(x,y,z) \\ \cdots \end{bmatrix} = \mathbf{0}$$

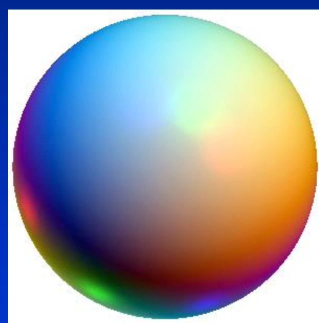
Implicit Surfaces: Applications

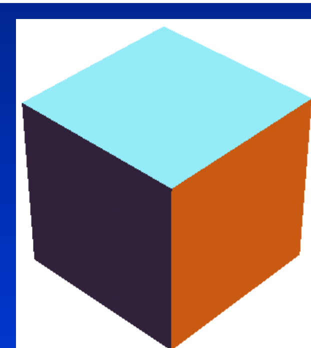
- Zero sets of implicit functions.

$$f(x, y, z) = 0$$

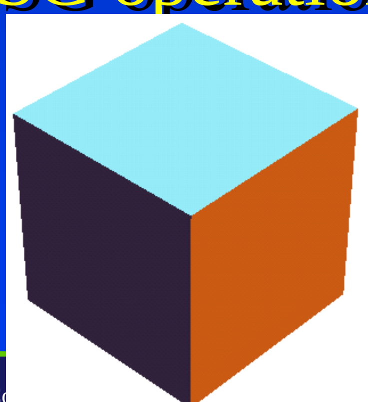
$$r^2 - x^2 - y^2 - z^2 > 0$$

$$(l - |x| > 0) \cap (l - |y| > 0) \cap (l - |z| > 0)$$





- CSG operations.



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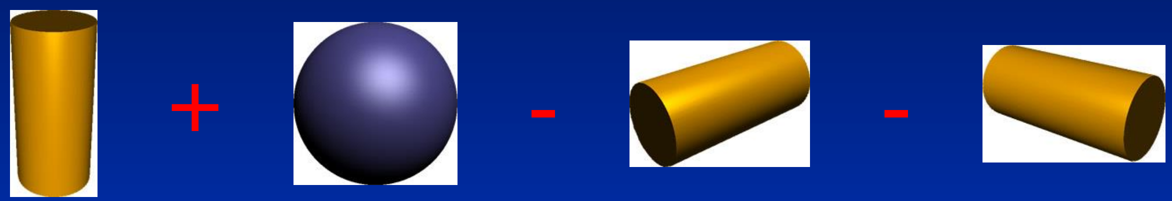
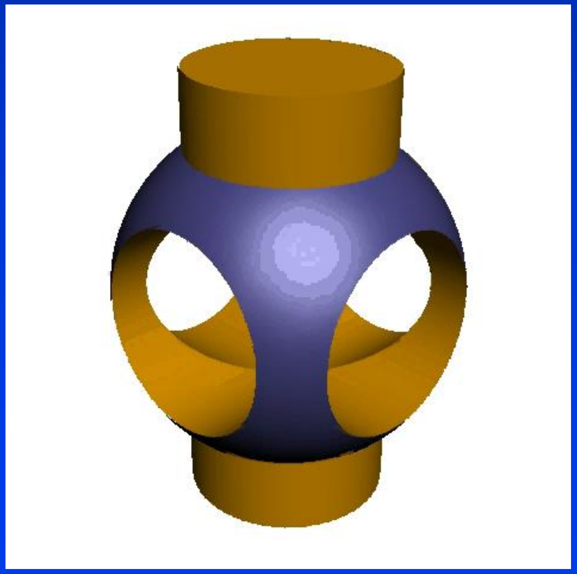
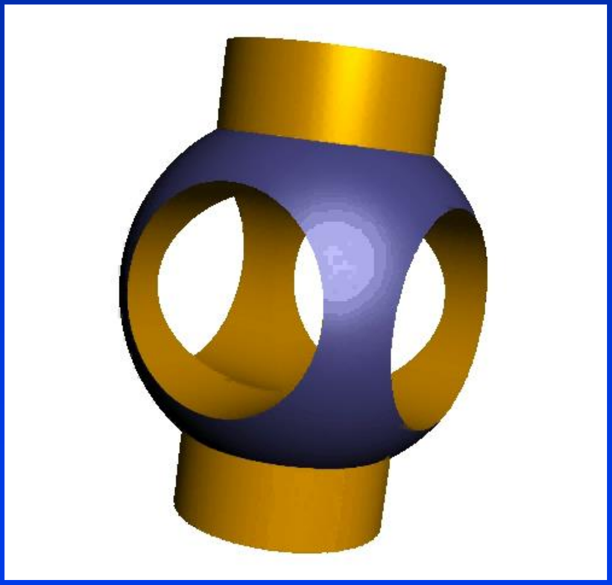
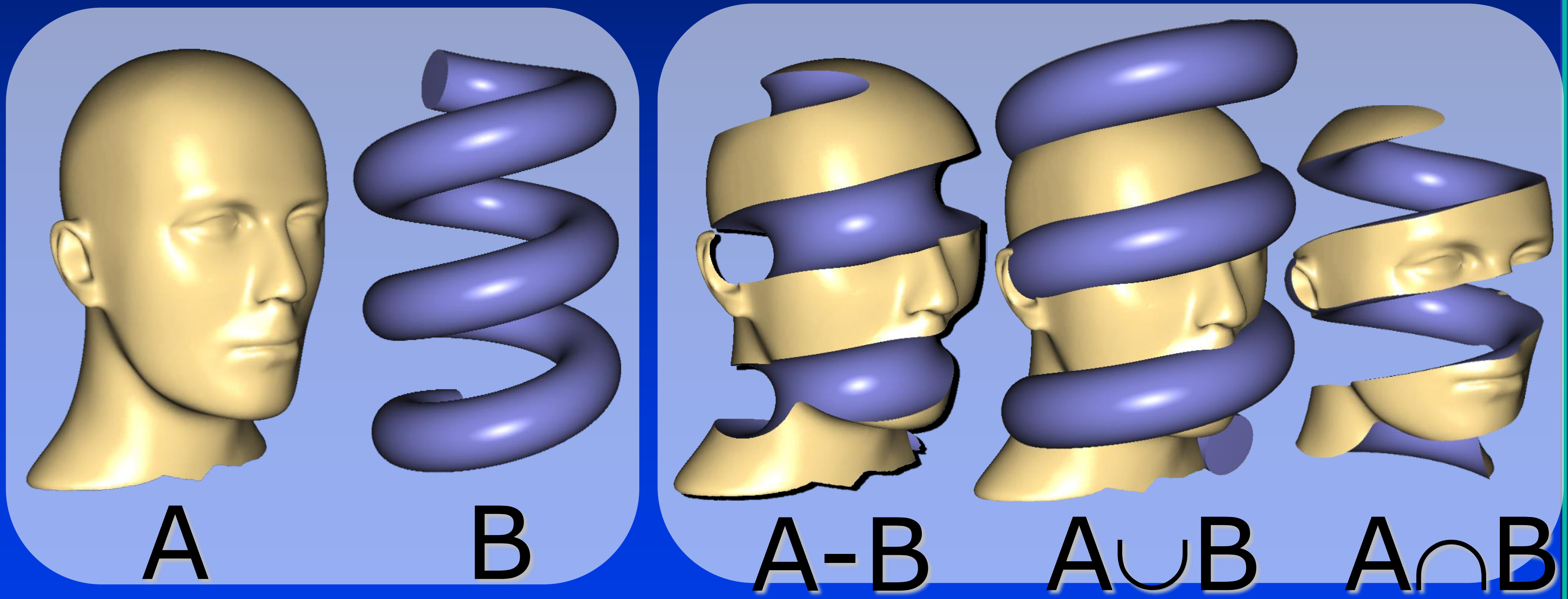
Boolean Operations



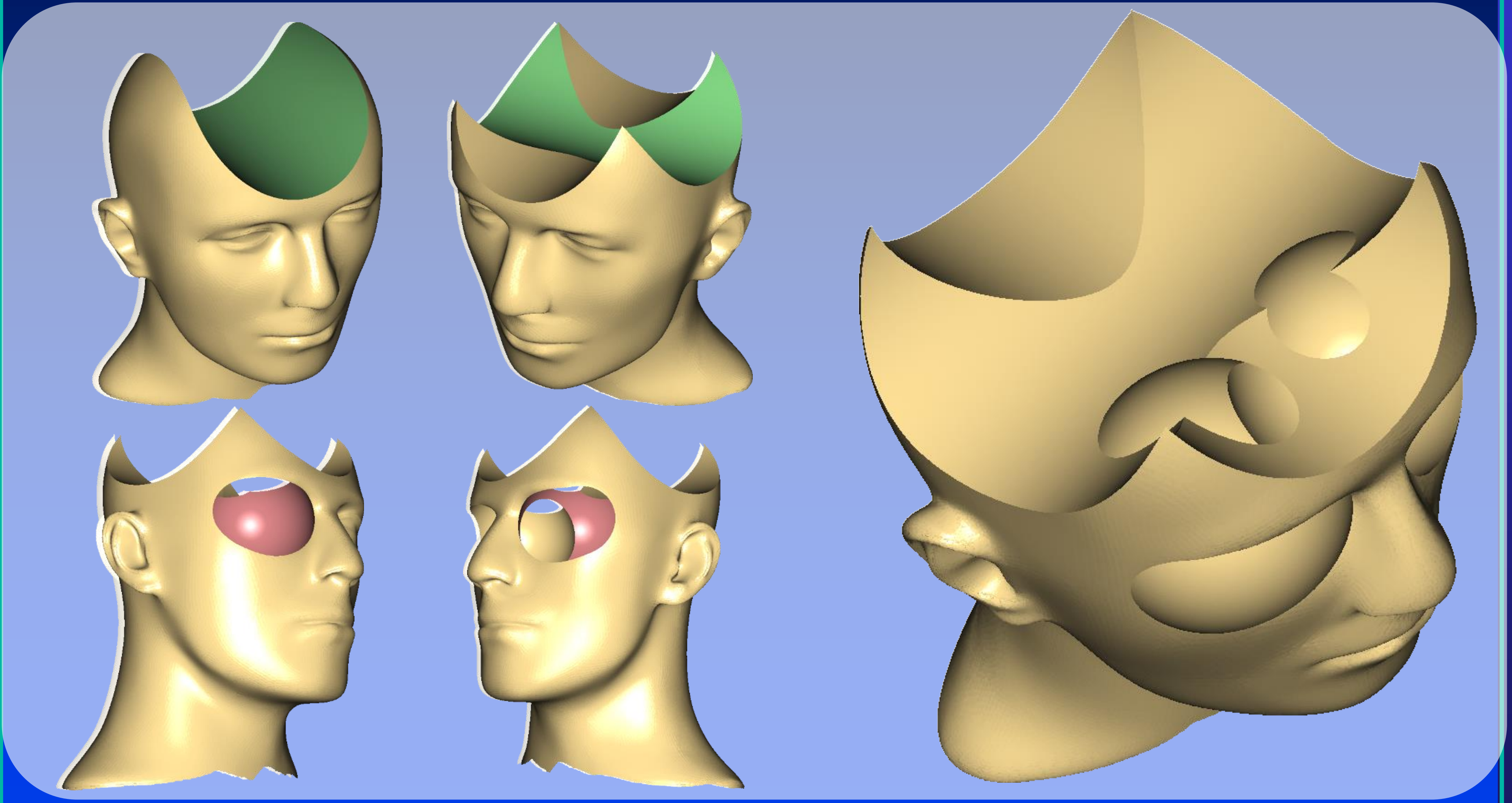




Boolean Operations



Boolean Operations



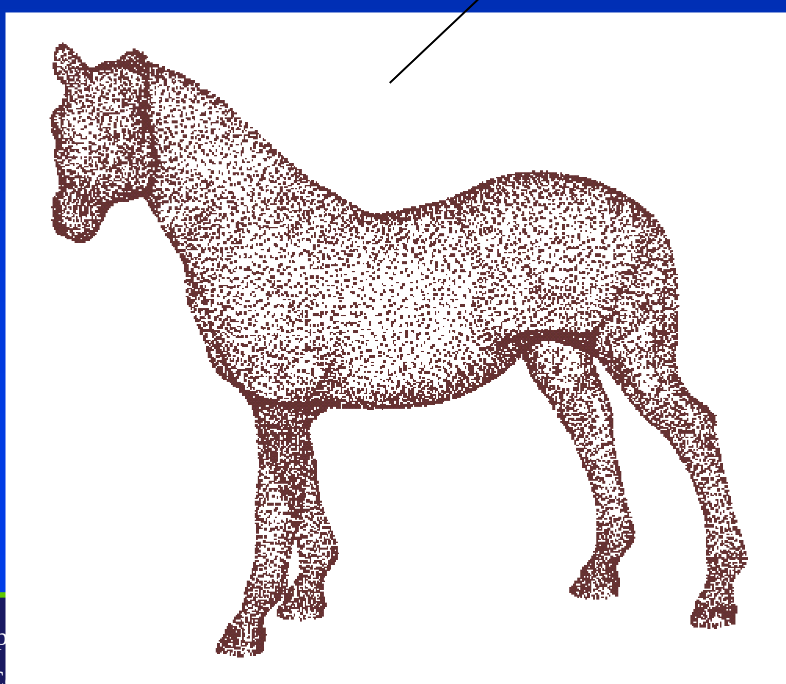
Radial Basis Function: Applications

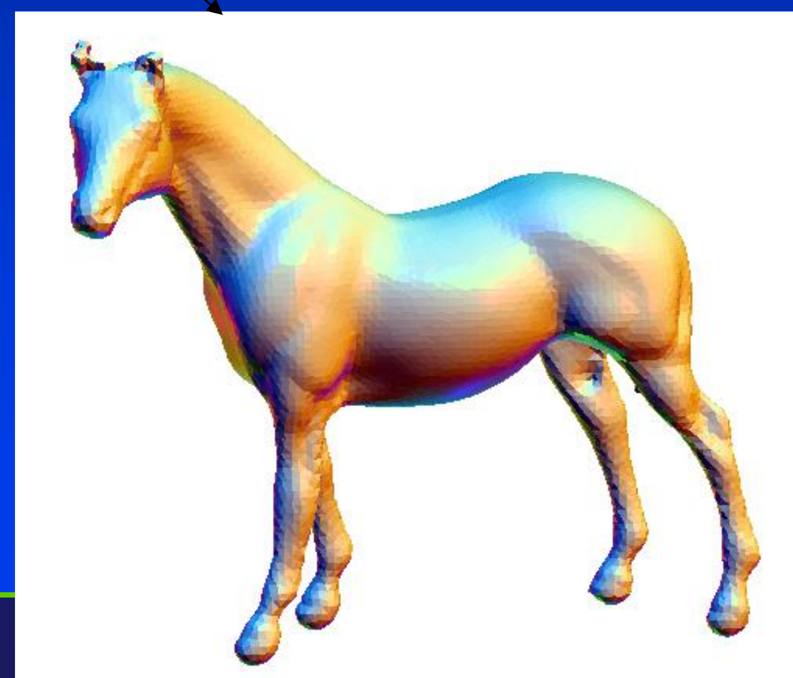
Carr et al. "Reconstruction and Representation of 3D Objects with Radial Basis Functions", *SIGGRAPH2001*

$$f(\mathbf{x}) = \sum_i \lambda_i \Phi(\mathbf{x} - \mathbf{c_i}) + p(\mathbf{x})$$

RBF fitting

Visualization of *f=0*





Implicit Functions

- Long history: classical algebraic geometry
- Implicit and parametric forms
  - Advantages
  - Disadvantages
- Curves, surfaces, solids in higher-dimension
- Intersection computation
- Point classification
- Larger than parameter-based modeling
- Unbounded geometry
- Object traversal
- Evaluation

Implicit Functions

- Efficient algorithms, toolkits,software
- Computer-based shape modeling and design
- Geometric degeneracy and anomaly
- Algebraic and geometric operations are often closed
- Mathematics: algebraic geometry
- Symbolic computation
- Deformation and transformation
- Shape editing, rendering, and control

Implicit Functions

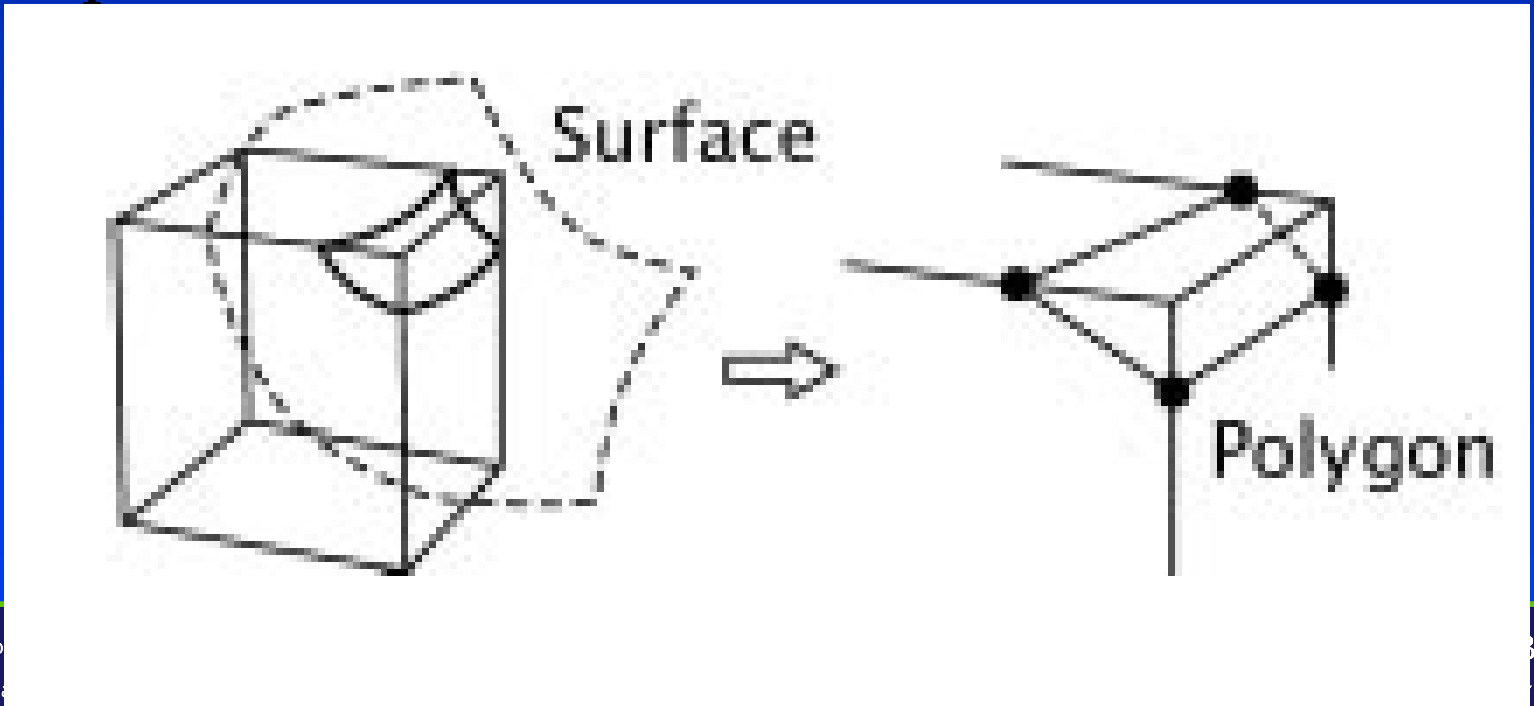
- Conversion between parametric and implicit forms
- Implicitization vs. parameterization
- Strategy: integration of both techniques
- Approximation using parametric models

Polygonization

- Conversion of implicit surface to polygonal mesh
- Display implicit surface using polygons
- Real-time approximate visualization method
- Two steps
  - Partition space into cells
  - Fit a polygon to surface in each cell

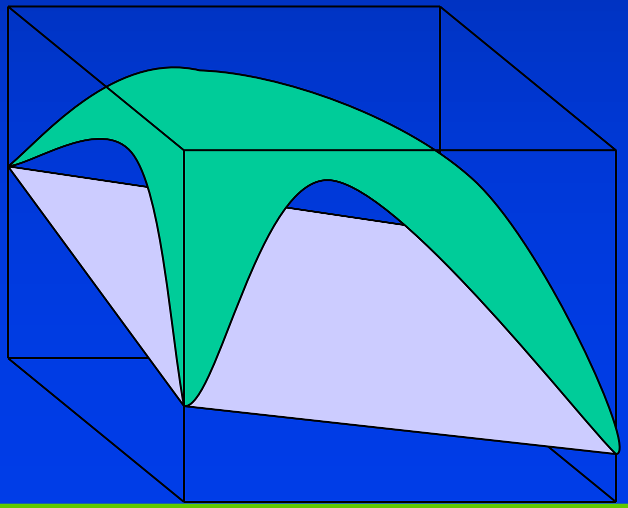
Polygonal Representation

- Partition space into convex cells
- Find cells that intersect the surface (*traverse cells*)
- Compute surface vertices

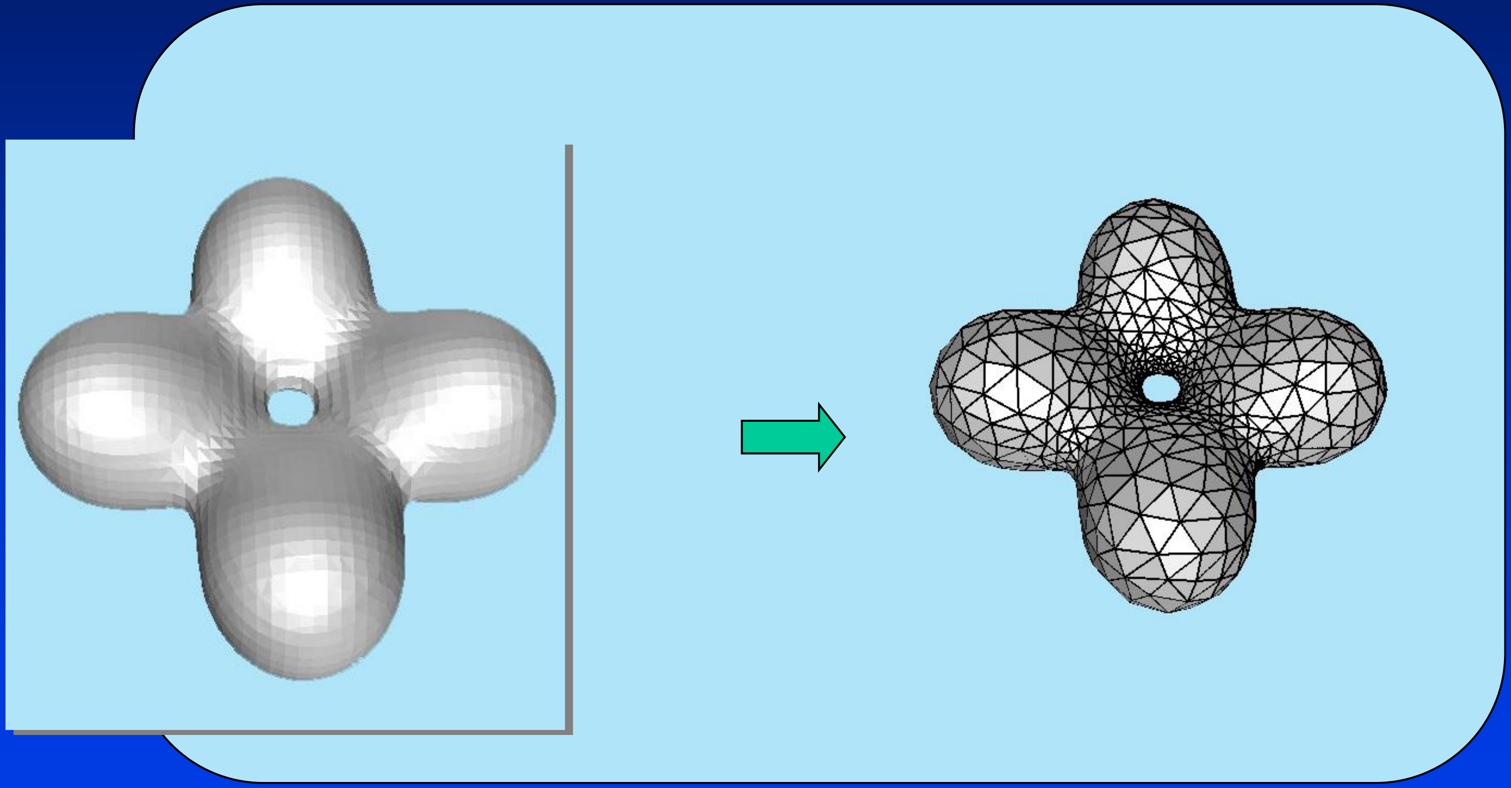


Cell Polygonization

- We will need to find those cells that actually contain parts of surface
- Need to approximate surface within cell
- Basic idea: use piecewise-linear approximation (polygon)



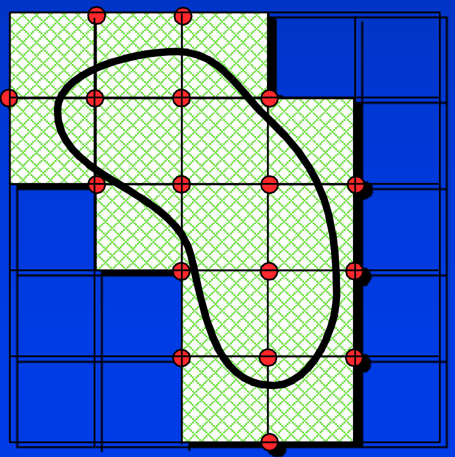
Implicit Surface (Polygonal Representation)



$$F: R^3 \Rightarrow R,\ \Sigma = F^{-1}(0)$$

Spatial Partitioning

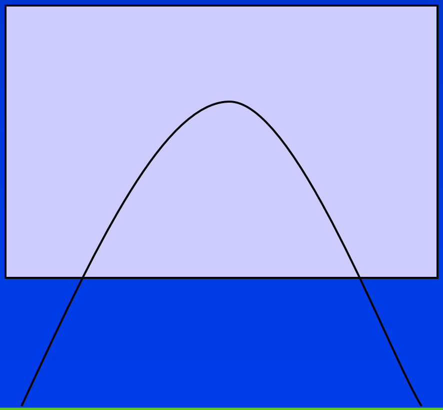
- Exhaustive enumeration
  - Divide space into regular lattice of cells
  - Traverse cells in order to arrive at polygonization



Space Partitioning Criteria

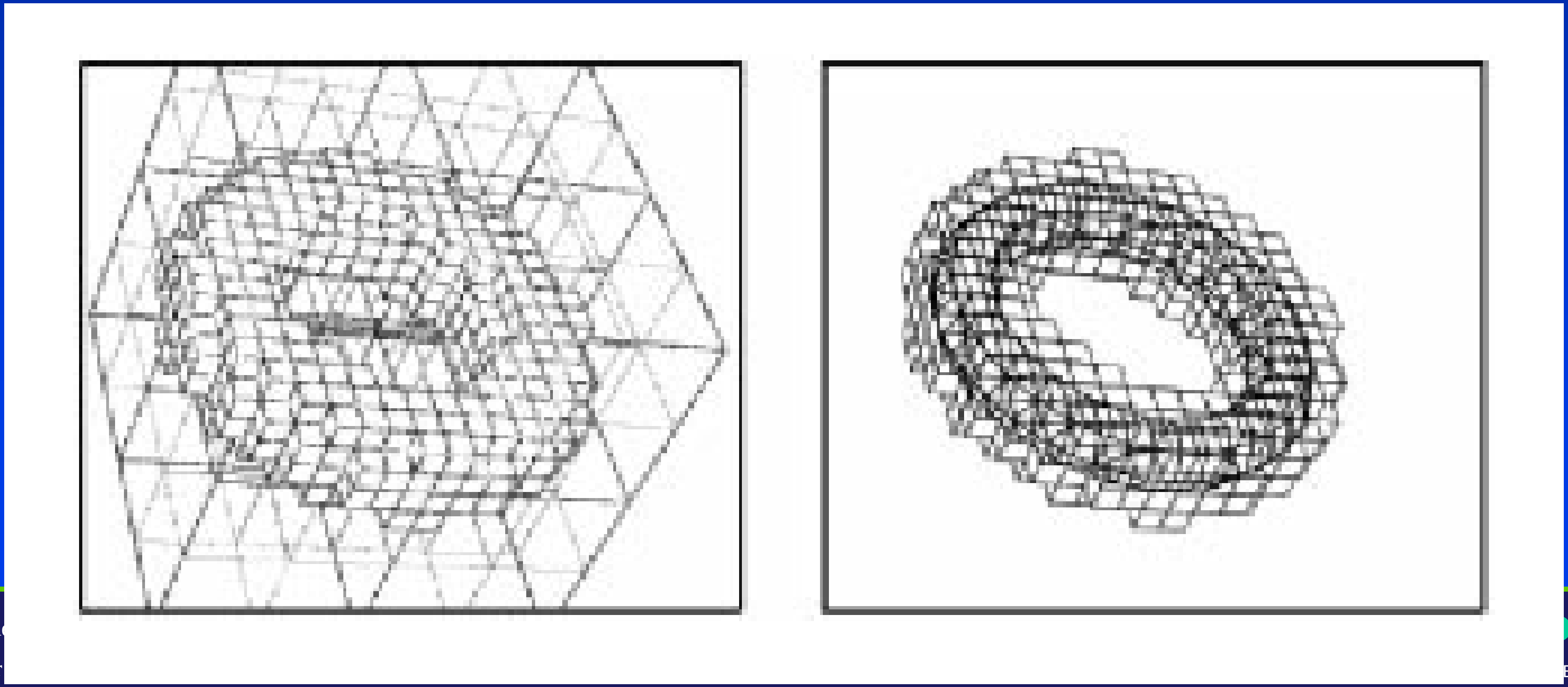
How do we know if a cell actually contains the surface?

- Straddling Cells
  - At least one vertex inside and outside surface
  - Non-straddling cells can still contain surface
- Guarantees
  - Interval analysis
  - Lipschitz condition



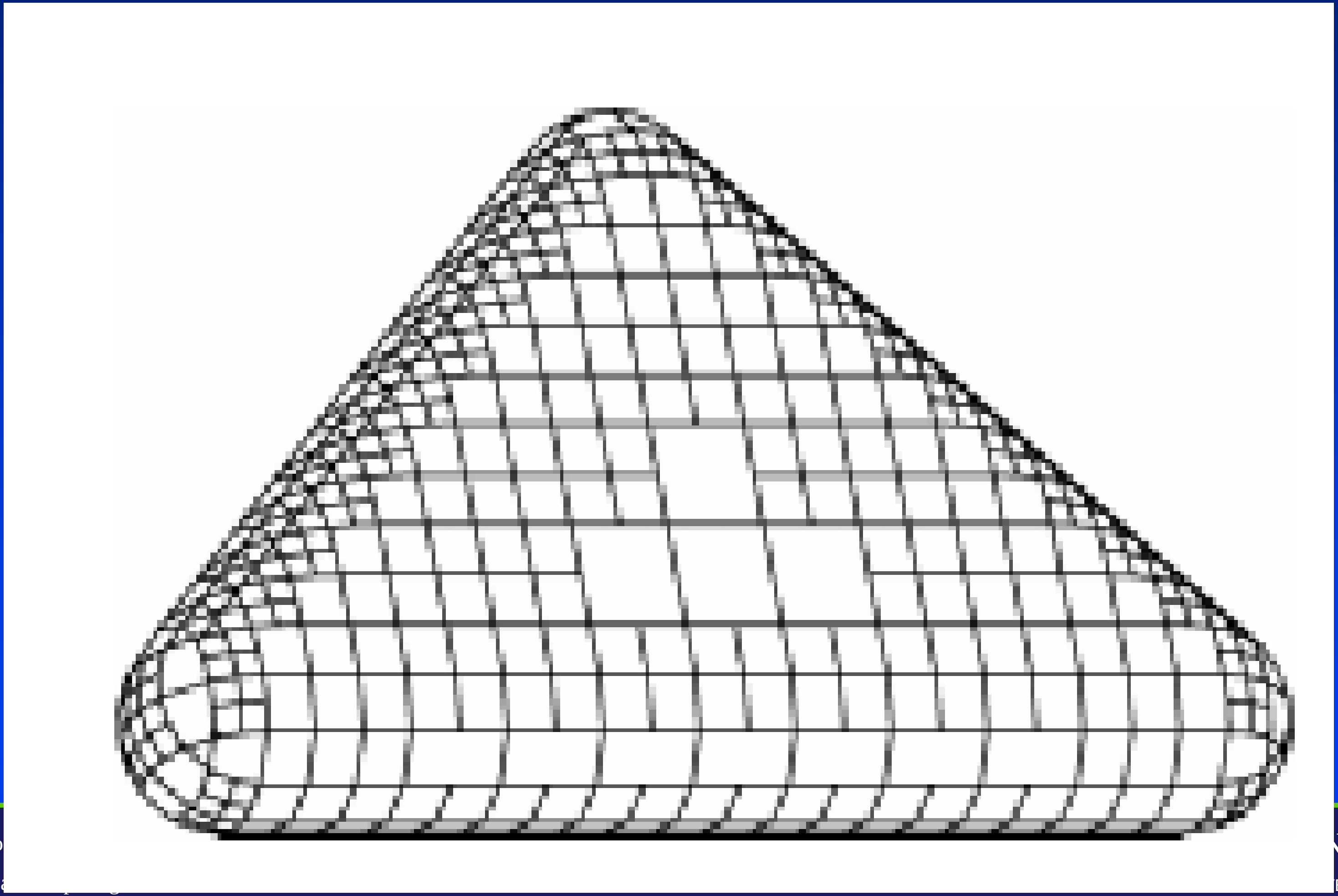
Spatial Partitioning

- Subdivision
  - Start with root cell and subdivide
  - Continue subdividing
  - traverse cells



Spatial Partitioning

- Adaptive polygonization



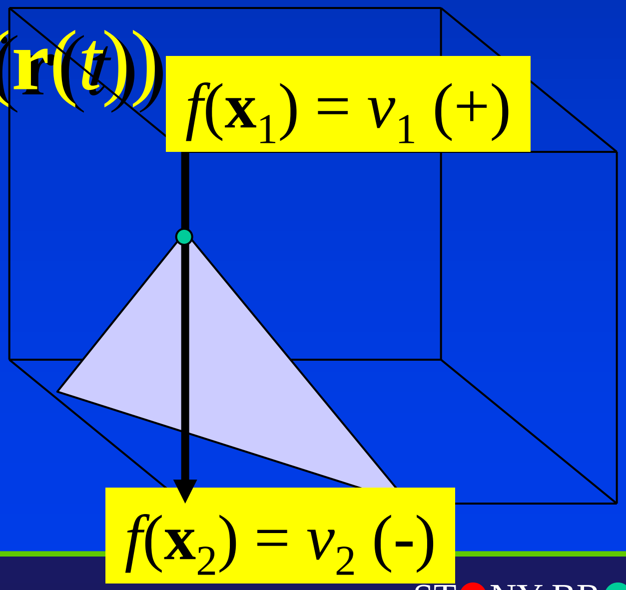
Surface Vertex Computations

- Determine where implicit surface intersects cell edges
- EITHER linear interpolate function values to approximate
- OR numerically find zero of $f(\mathbf{r}(t))$

$$\mathbf{r}(t) = \mathbf{x}_1 + t(\mathbf{x}_2 - \mathbf{x}_1)$$

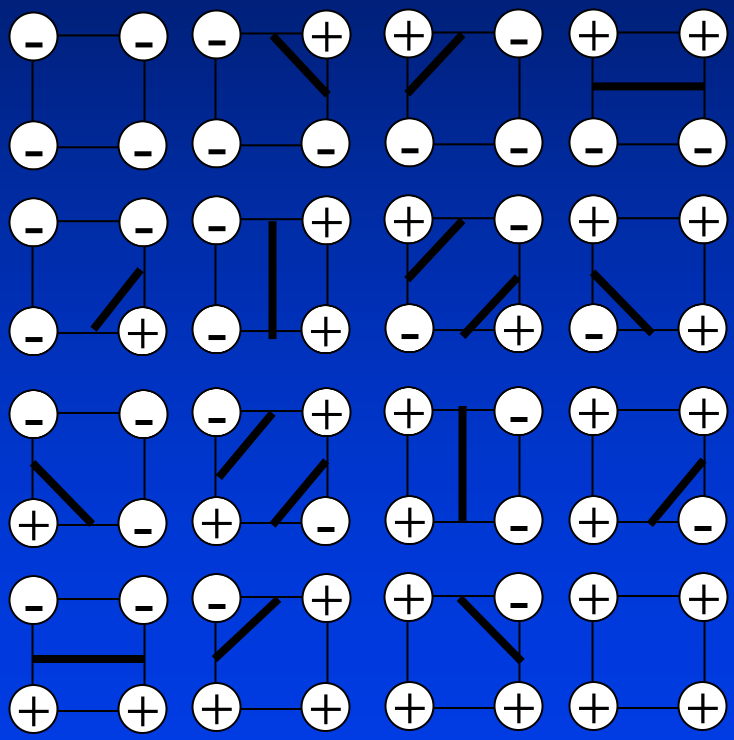
$$0 \le t \le 1$$

$$\mathbf{x} = \frac{v_1}{v_1 + v_2}\mathbf{x}_1 + \frac{v_2}{v_1 + v_2}\mathbf{x}_2$$

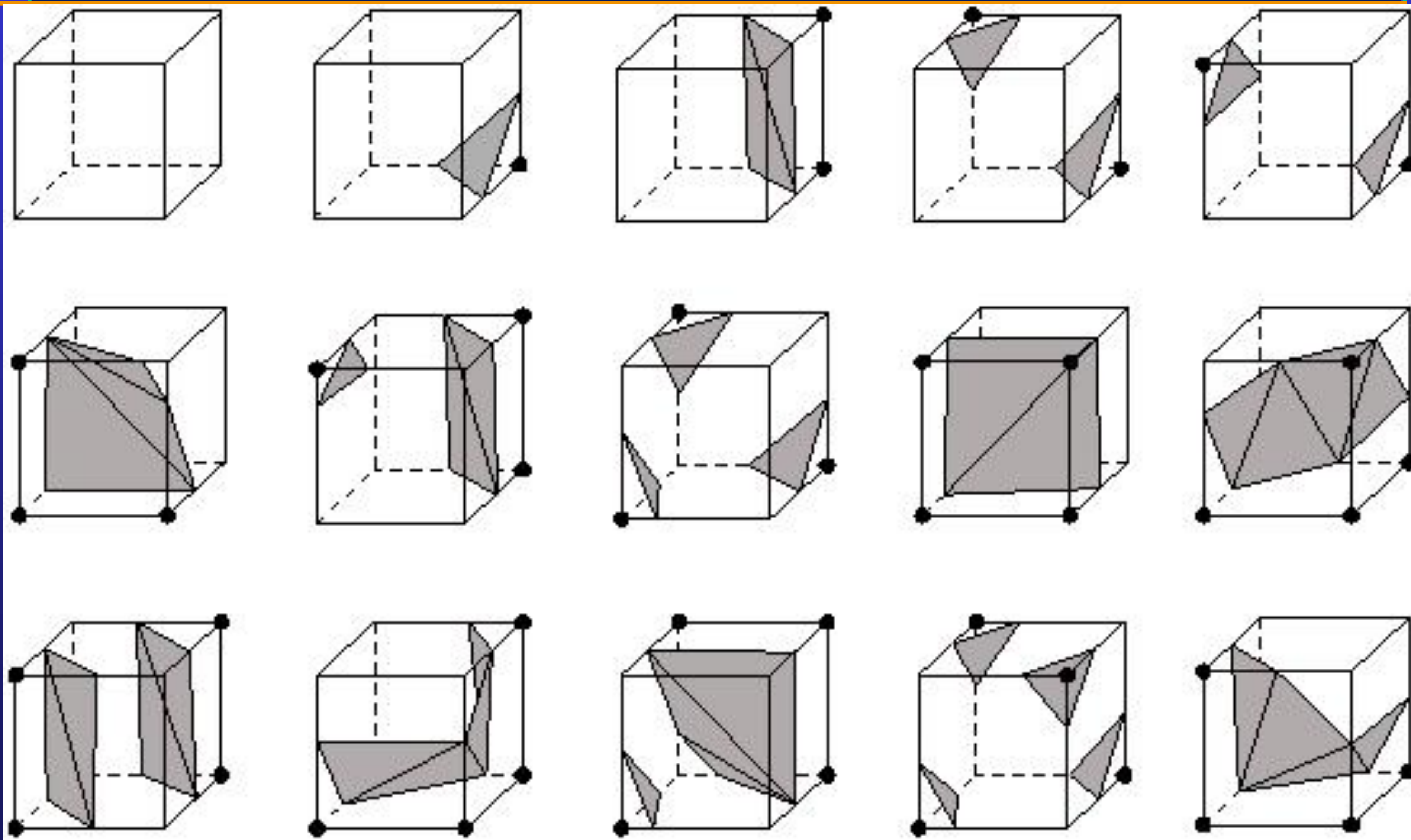


Polygonal Shape

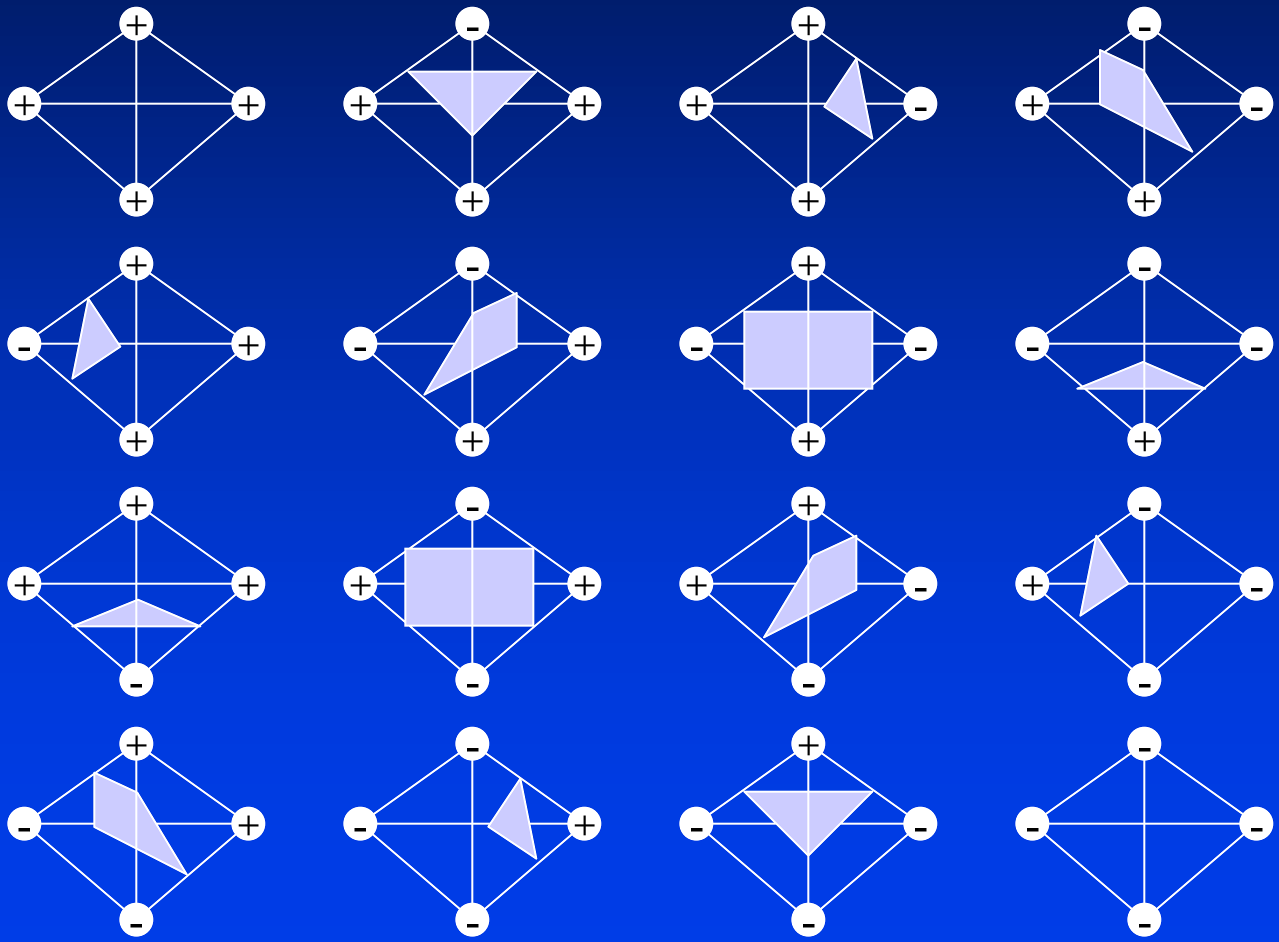
- Use table indexed by vertex signs and consider all possible combinations
- Let + be 1, - be 0
- Table size
  - Tetrahedral cells: 16 entries
  - Cubic cells: 256 entries
- E.g., 2-D - 16 square cells



Determining Intersections

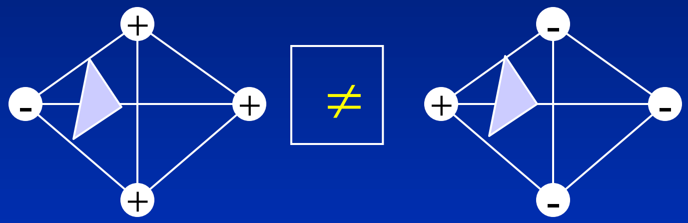


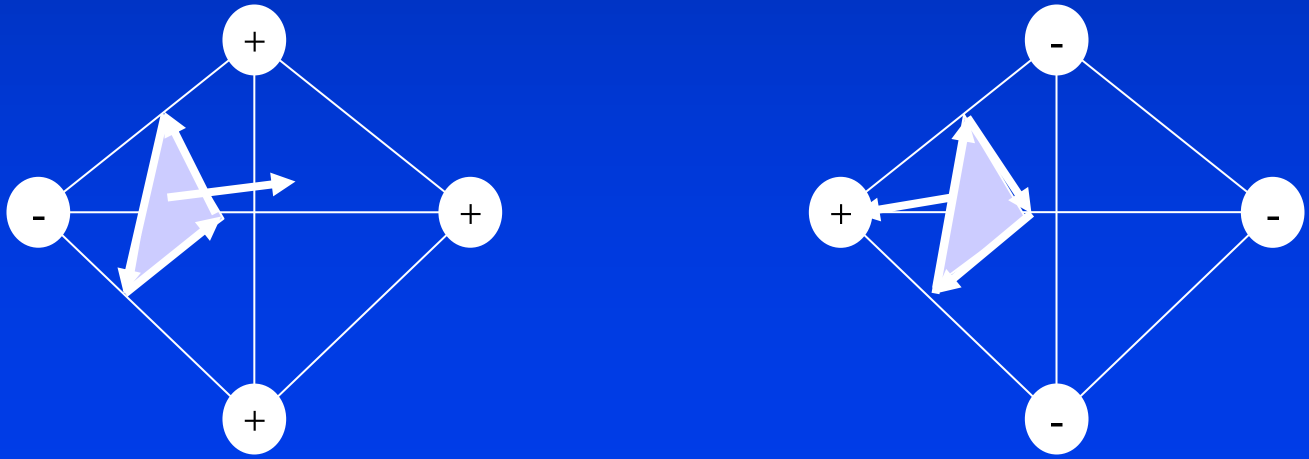
Tetrahedral Cell Polygons



Orientation

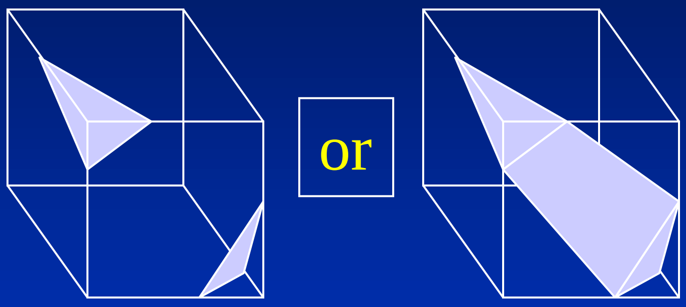
- Consistency allows polygons to be drawn with correct orientation
- Supports backface culling

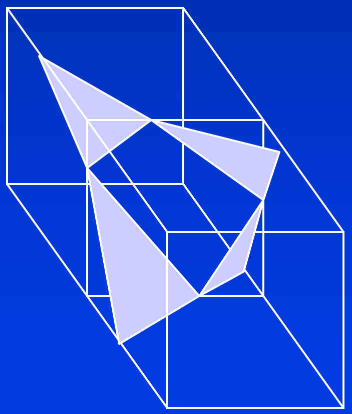




Problem: Ambiguity

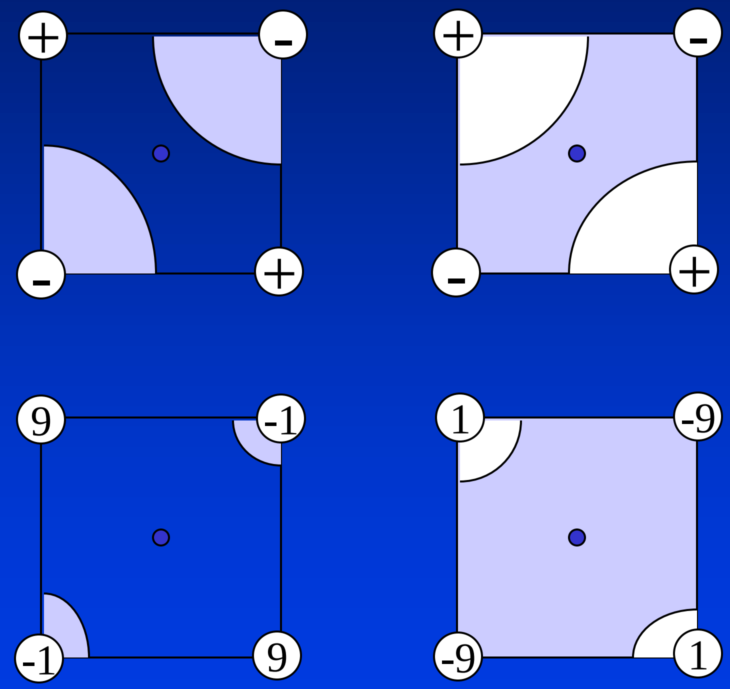
- Some cell-corner-value configurations yield more than one consistent polygon
- Only for cubes, not tetrahedra (why?)
- In 3-D can yield holes in surface!
- How can we resolve these ambiguities?





Topological Inference

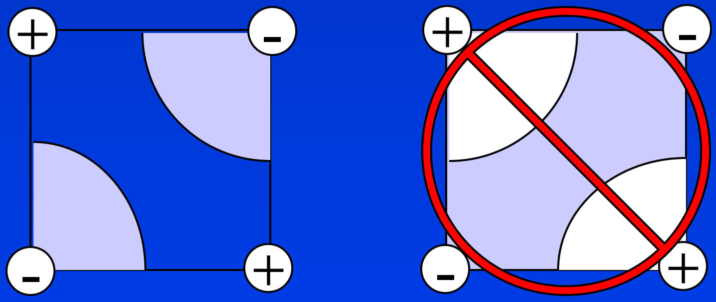
- Sample a point in the center of the ambiguous face
- If data is discretely sampled, bilinearly interpolate samples



$$p(s,t) = (1\text{-}s)(1\text{-}t)\ a + s\ (1\text{-}t)\ b + (1\text{-}s)\ t\ c + s\ t\ d$$

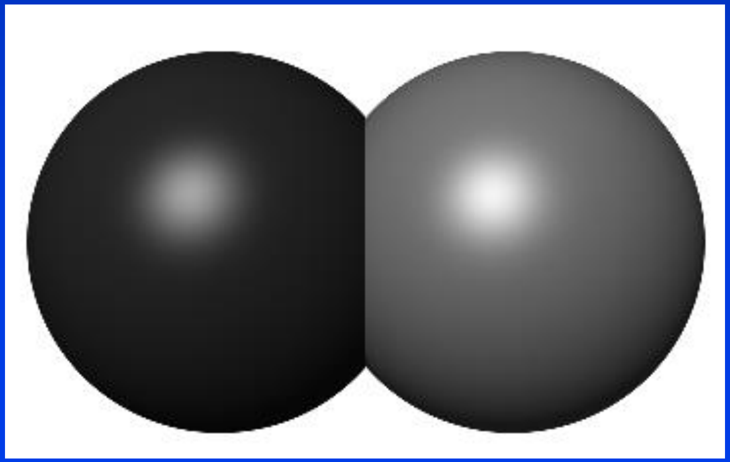
Preferred Polarity

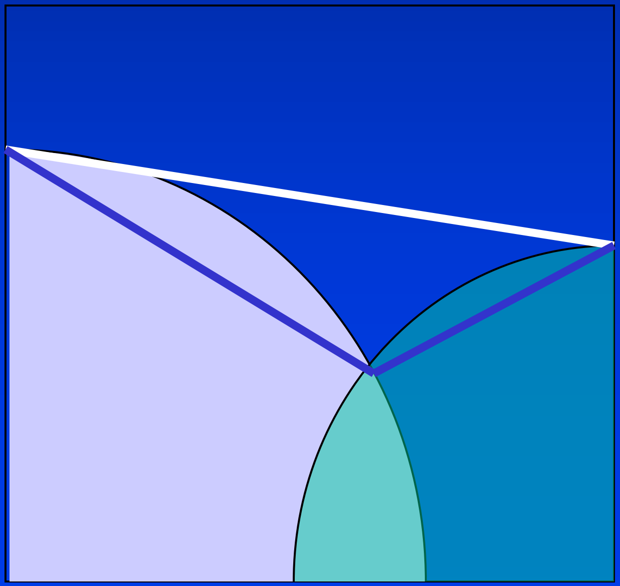
- Assume ambiguous face centers always +
- (or always –)
- Preference can be encoded into table



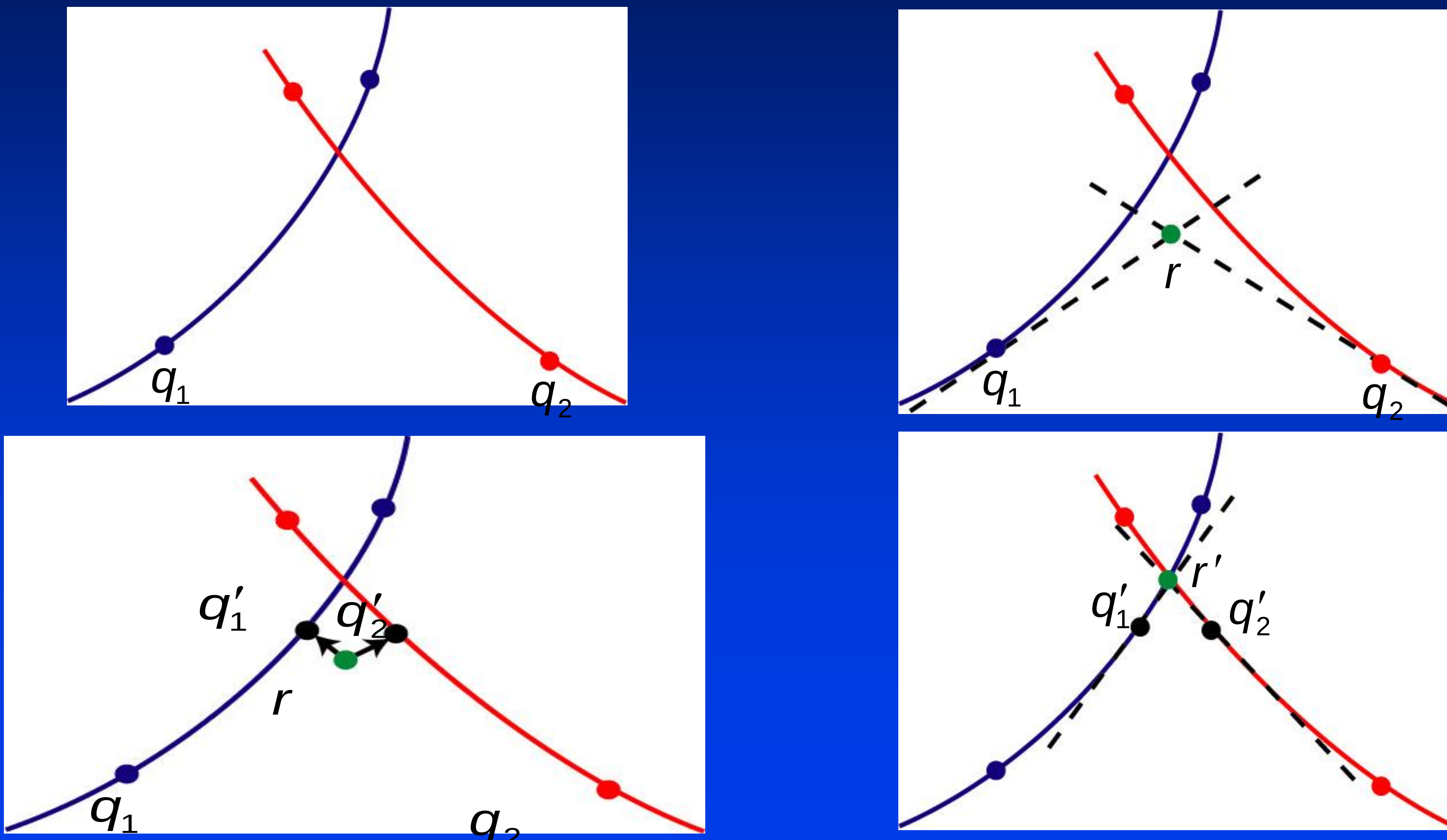
CSG Polygonization

- Polygonization can smooth crease edges caused by CSG operations
- Polygonization needs to add polygon vertices along crease edges



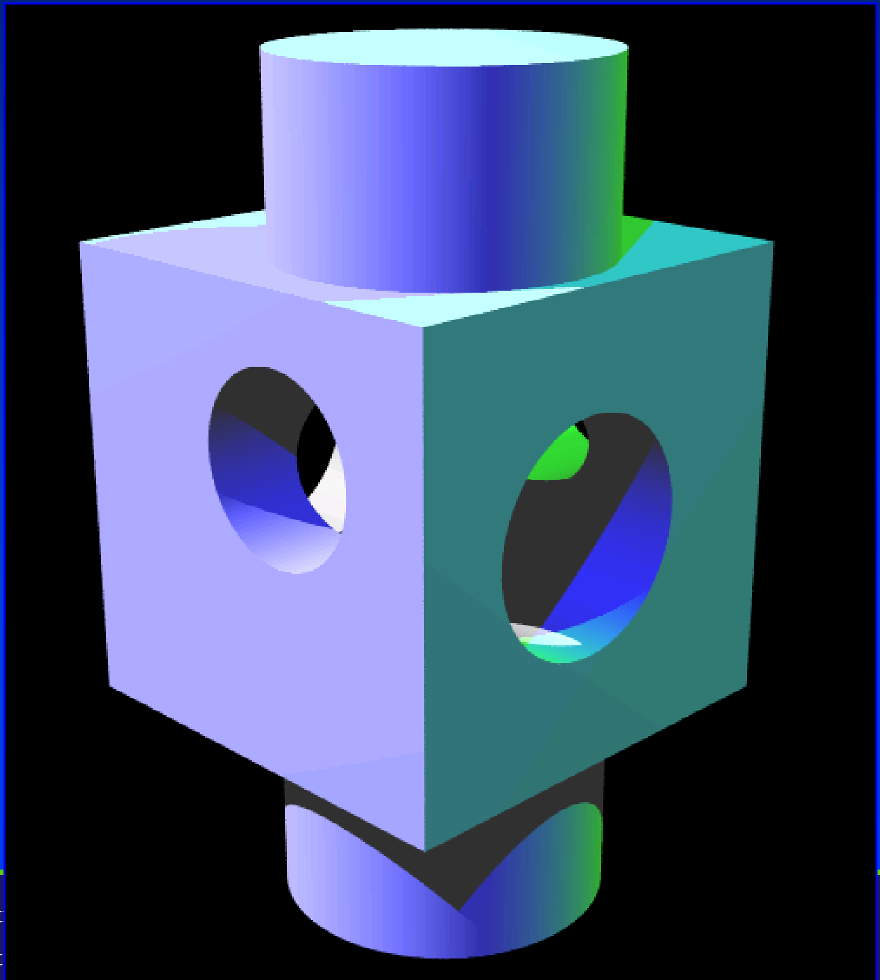


Computing Intersections



Visualization of Implicit Surfaces

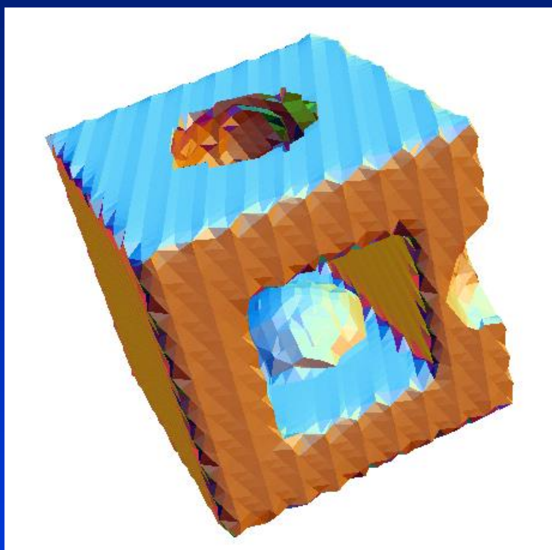
Ray-tracing



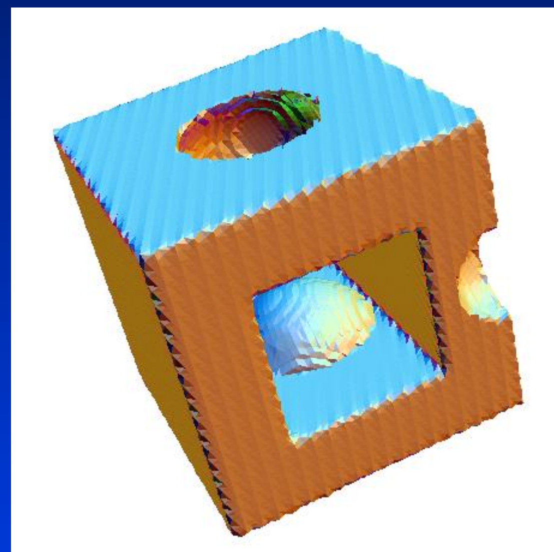
Polygonization
(e.g. Marching cubes method)

Problem of Polygonization

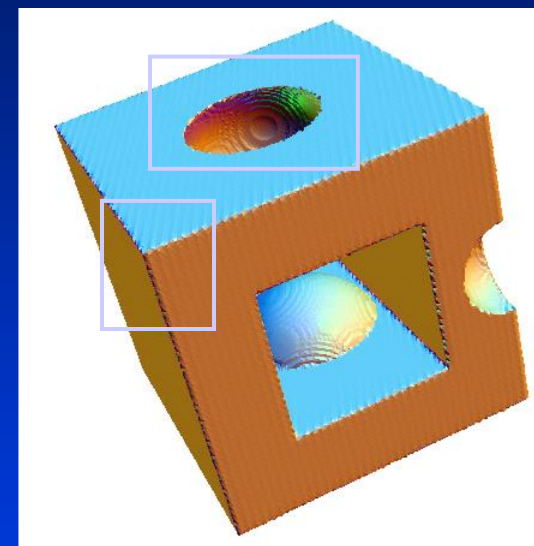
50^3 grid



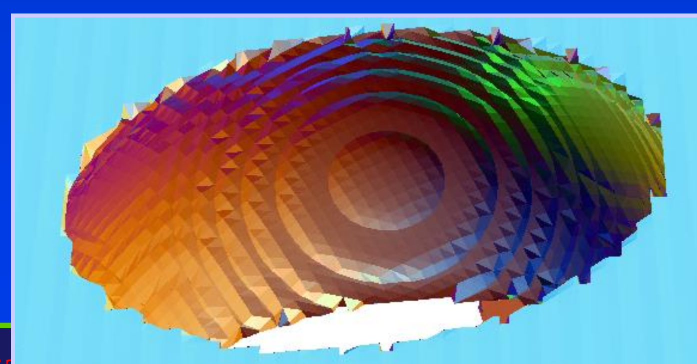
100^3 grid

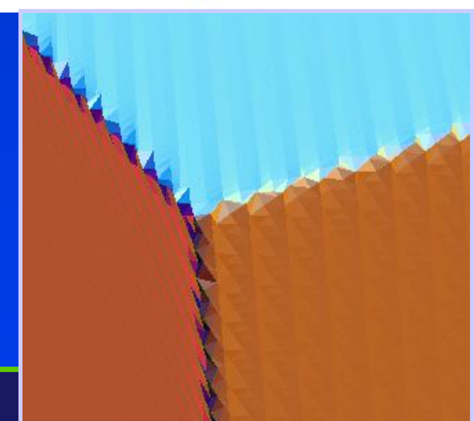


200^3 grid



- Sharp features are broken





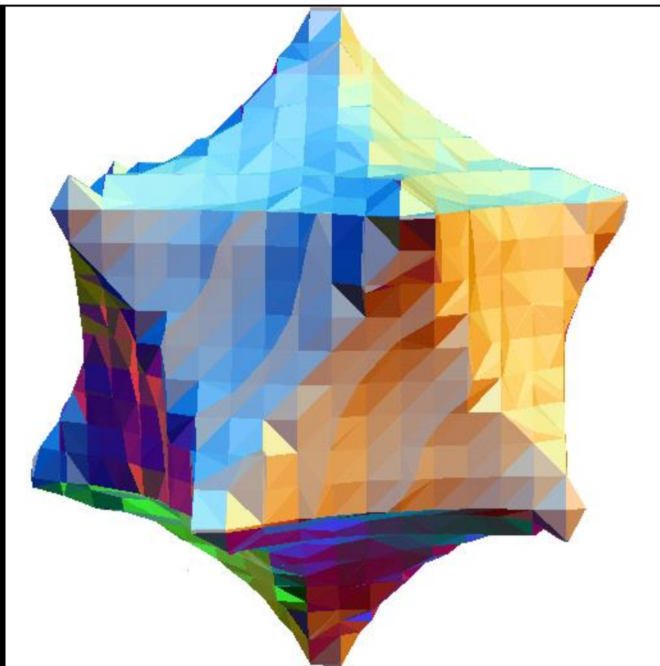
Reconstruction of Sharp Features

Input

Implicit function : $f(x, y, z)$

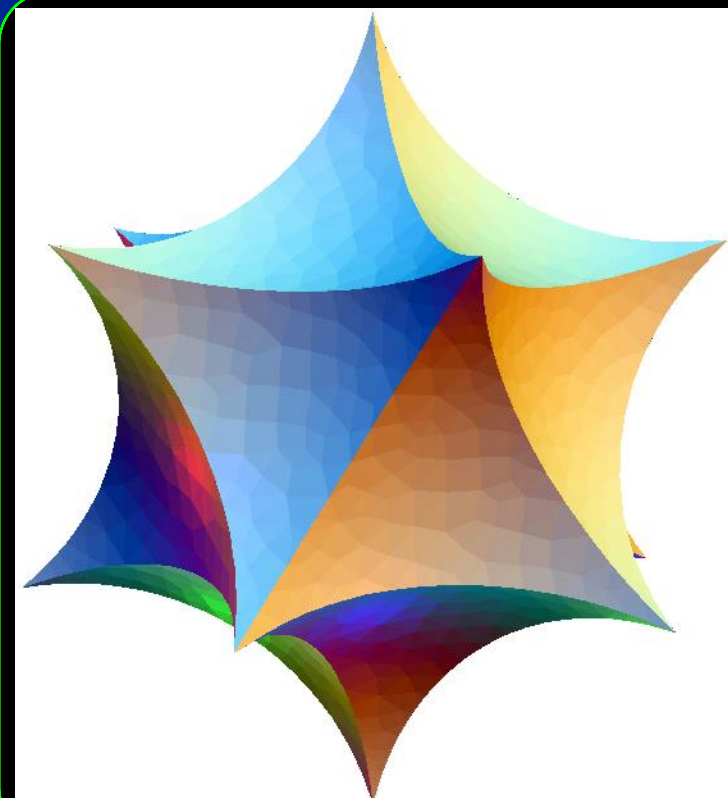
and

Rough Polygonization
(Correct topology)



Post-processing

Output



Rendering Implicit Surfaces

- Raytracing or its variants can render them directly
  - The key is to find intersections with Newton's method
- For polygonal renderer, must convert to polygons
- Advantages:
  - Good for organic looking shapes such as human body
  - Reasonable interfaces for design
- Disadvantages:
  - Difficult to render and control when animating
  - Being replaced with subdivision surfaces, it appears

Implicit Surfaces vs Polygons

- Advantages
  - Smoother and more precise
  - More compact
  - Easier to interpolate and deform
- Disadvantages
  - More difficult to display in real time

Implicits vs Parameter-Based Representations

- Advantages
  - Implicits are easier to blend and morph
  - Interior/Exterior description
  - Ray-trace
- Disadvantages
  - Rendering
  - Control

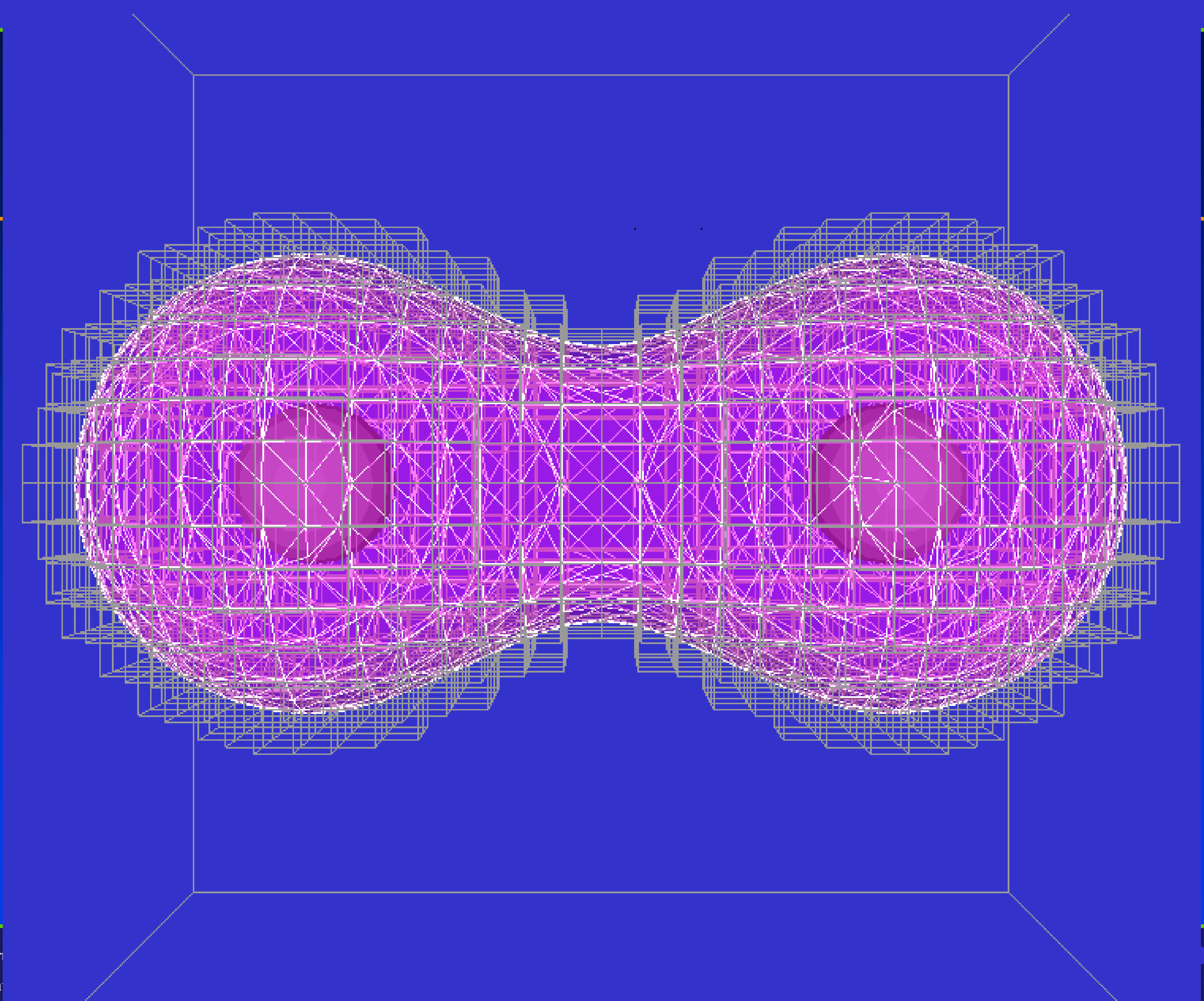
Blobs and Metaballs

- Define the location of some points
- For each point, define a function on the distance to a given point, *(x,y,z)*
- Sum these functions up, and use them as an implicit function
- Question: If I have two special points, in 2D, and my function is just the distance, what shape results?
- More generally, use Gaussian functions of distance, or other forms
  - Various results are called blobs or metaballs

Blobby Models

- Blobby models [Blinn 82], also known as metaballs [Nishimura and Hirai 85] or soft objects [Wyvill and Wyvill 86, 88]
- A blobby model — a center surrounded by a density field, where the density attributed to the center decreases with distance from the center.
- By simply summing the influences of each blobby model on a given location, we can obtain very smooth blends of the spherical density fields.

$$G(x, y, z) = \sum_i g_i(x, y, z) - threshold = 0$$



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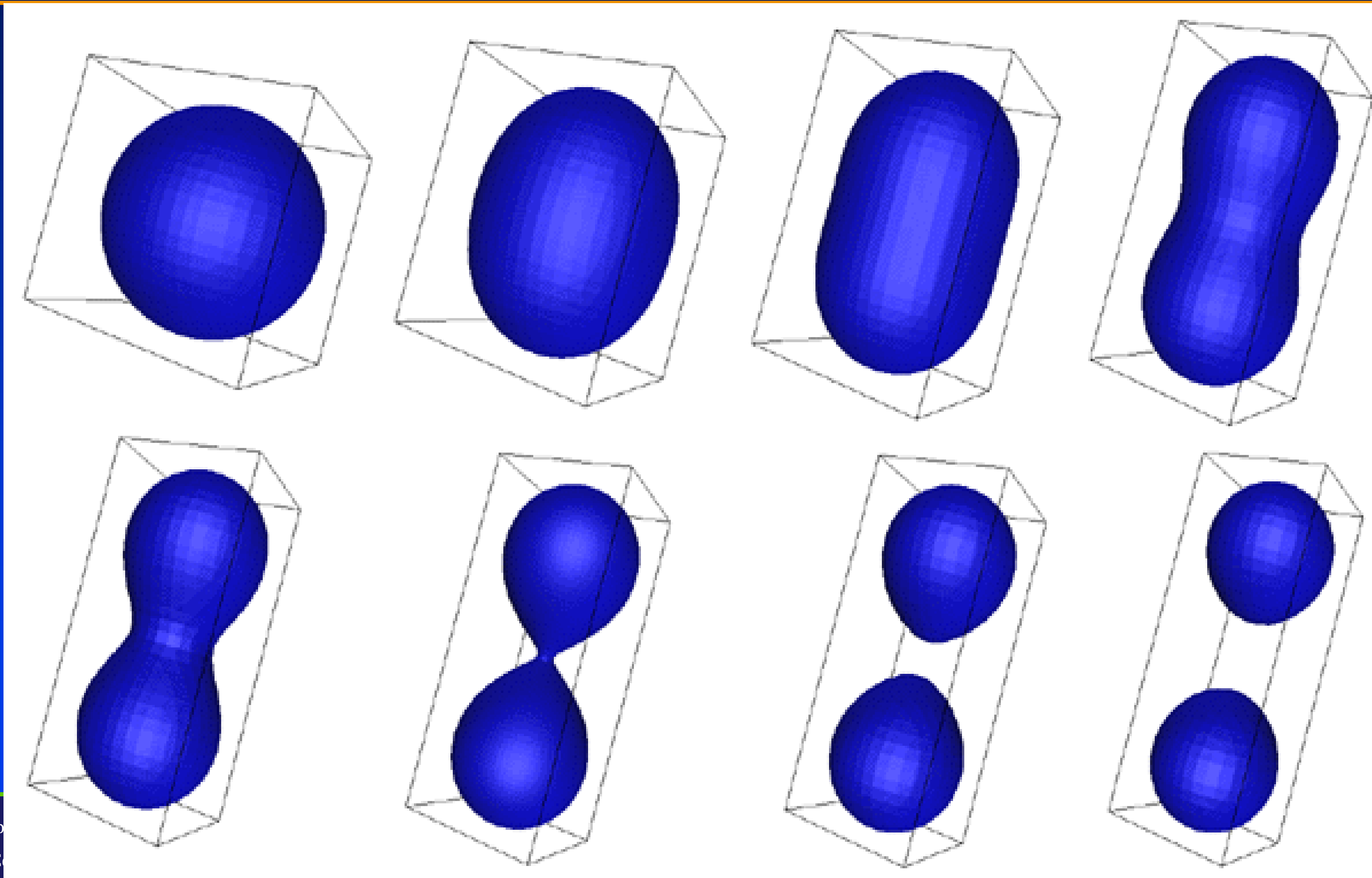
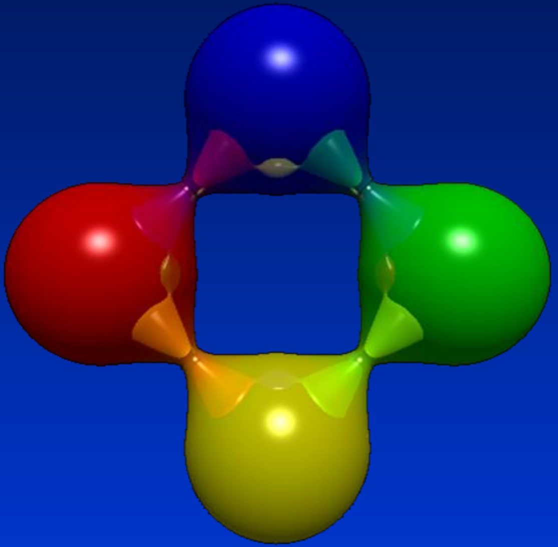
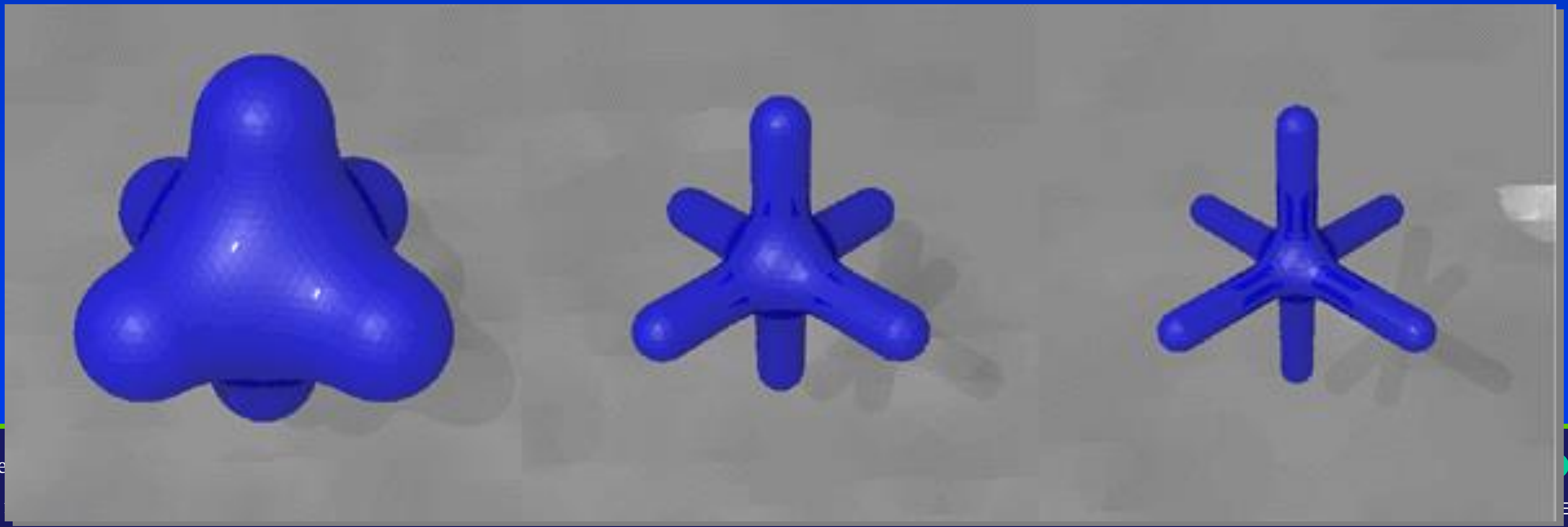
Distance Functions



Case Studies: Distance Functions

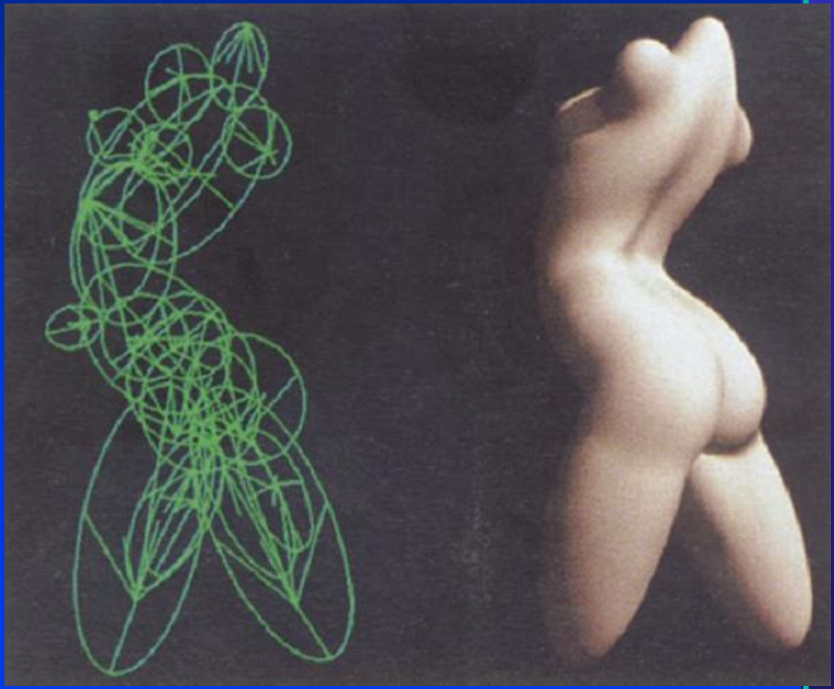
- $D(\mathbf{p}) = R$
  - Sphere: Distance to a point
  - Cylinder: Distance to a line
  - More examples





Design Using Blobs

- None of these parameters allow the designer to specify exactly where the surface is actually located.
- A designer only has indirect control over the shape of a blobby implicit surface.
- Blobby models facilitate the design of smooth, complex, organic-appearing shapes.



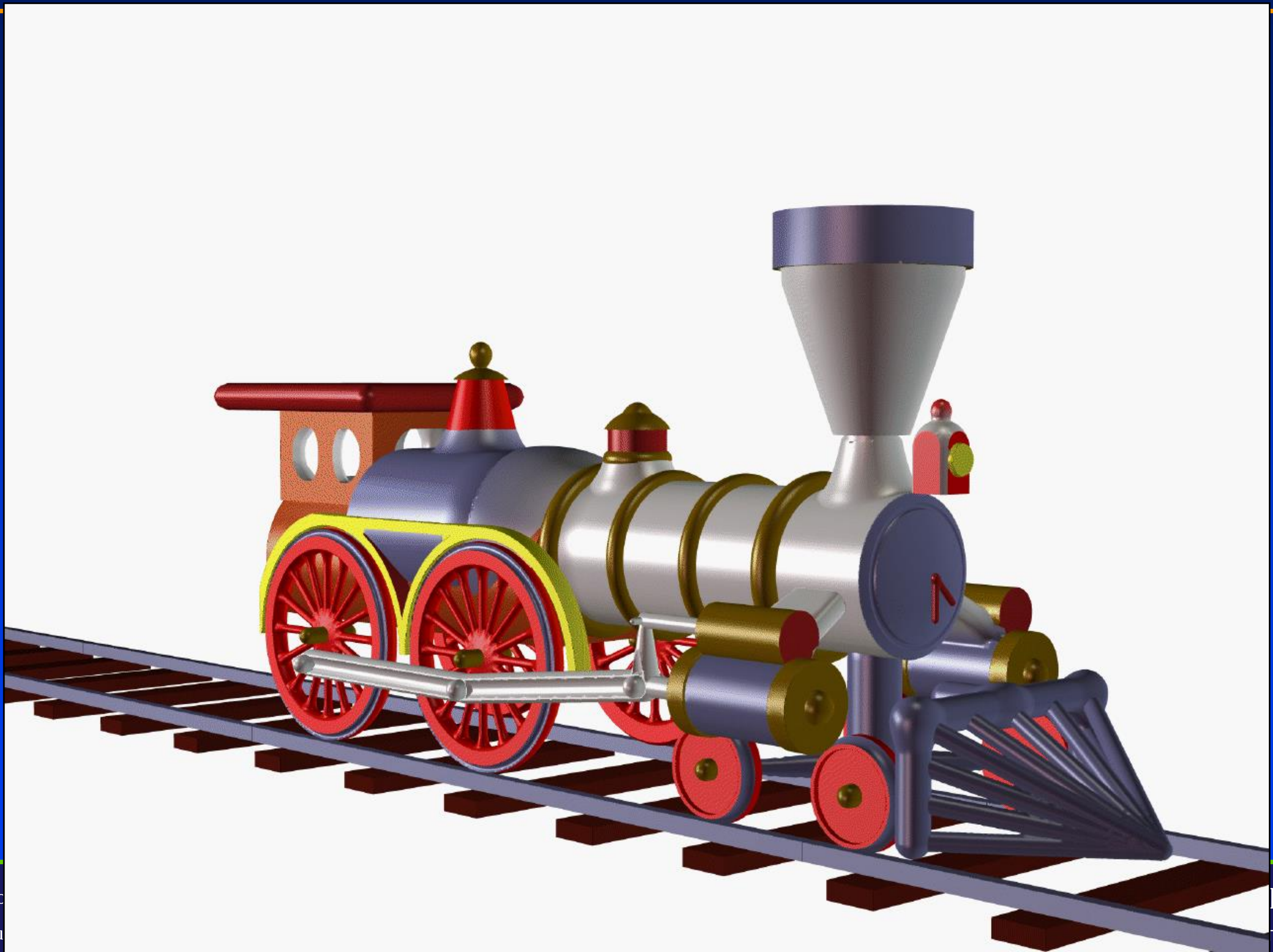
Example with Blobs

Rendered with POVray. Not everything is a blob, but the characters are.

What Is It?

- “Metaball, or ‘Blobby’, Modeling is a technique which uses implicit surfaces to produce models which seem more ‘organic’ or ‘blobby’ than conventional models built from flat planes and rigid angles”

Examples



Examples

Blobby Modeling: Its Utility

- Organic forms and nonlinear shapes
- Scientific modeling (electron orbitals, some medical imaging)
- Muscles and joints with skin
- Rapid prototyping
- CAD/CAM solid geometry

Mathematics for Blobby Models

- Implicit equation:

$$f(x,y,z) = \sum_{i=1}^{n_{blobs}} w_i g_i(x,y,z) = d$$

- The w_i are weights – just numbers
- The g_i are functions, one common choice is:

$$g_i(\mathbf{x}) = e^{\frac{-(\mathbf{x}-c_i)^2}{\sigma_i}}$$

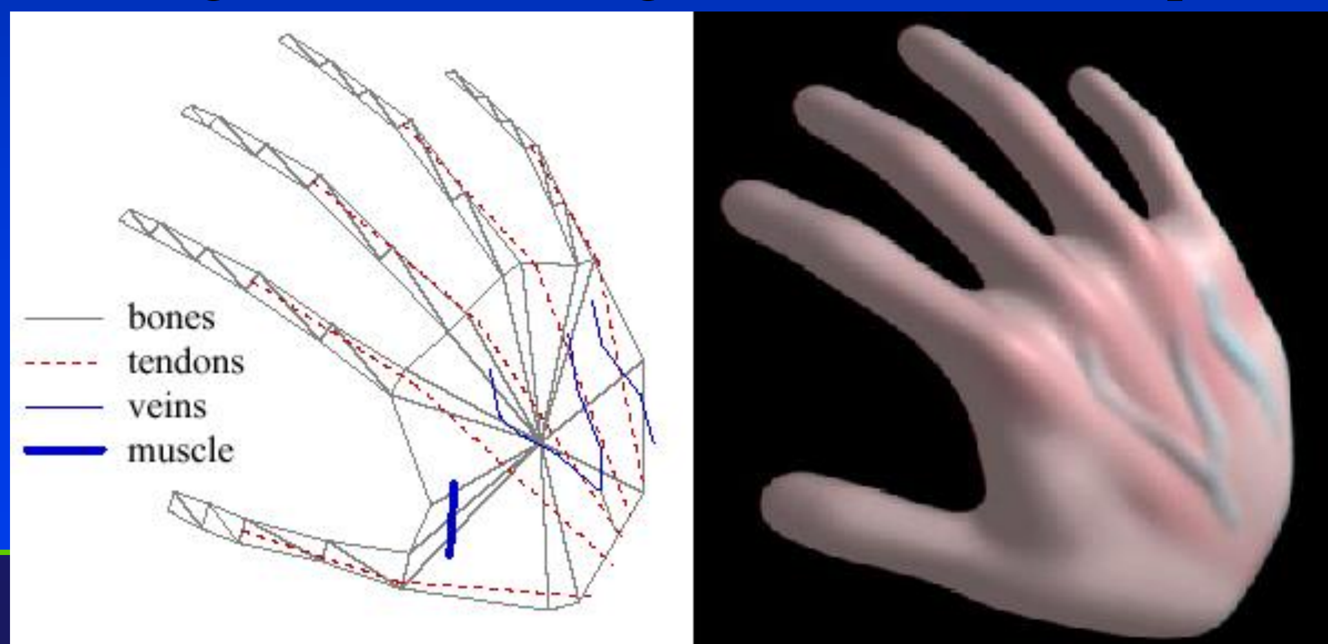
  – c_i and σ_i are parameters

Skeletal Design

- Use skeleton technique to design implicit surfaces and solids toward interactive speed.
- Each skeletal element is associated with a locally defined implicit function.
- These local functions are blended using a polynomial weighting function.
  - [Bloomenthal and Wyvill 90, 95, 97] defined skeletons consisting of *points*, *splines*, *polygons*.
  - 3D skeletons [Witkin and Heckbert 94] [Chen 01]

Skeletal Design

- Global and local control in three separate ways:
  - Defining or manipulating of the skeleton;
  - Defining or adjusting those implicit functions defined for each skeletal element;
  - Defining a blending function to weight the individual implicit functions.



Rendering Implicit Surfaces

- Some methods can render then directly
  - Raytracing - find intersections with Newton's method
- For polygonal renderer, must convert to polygons
- Advantages:
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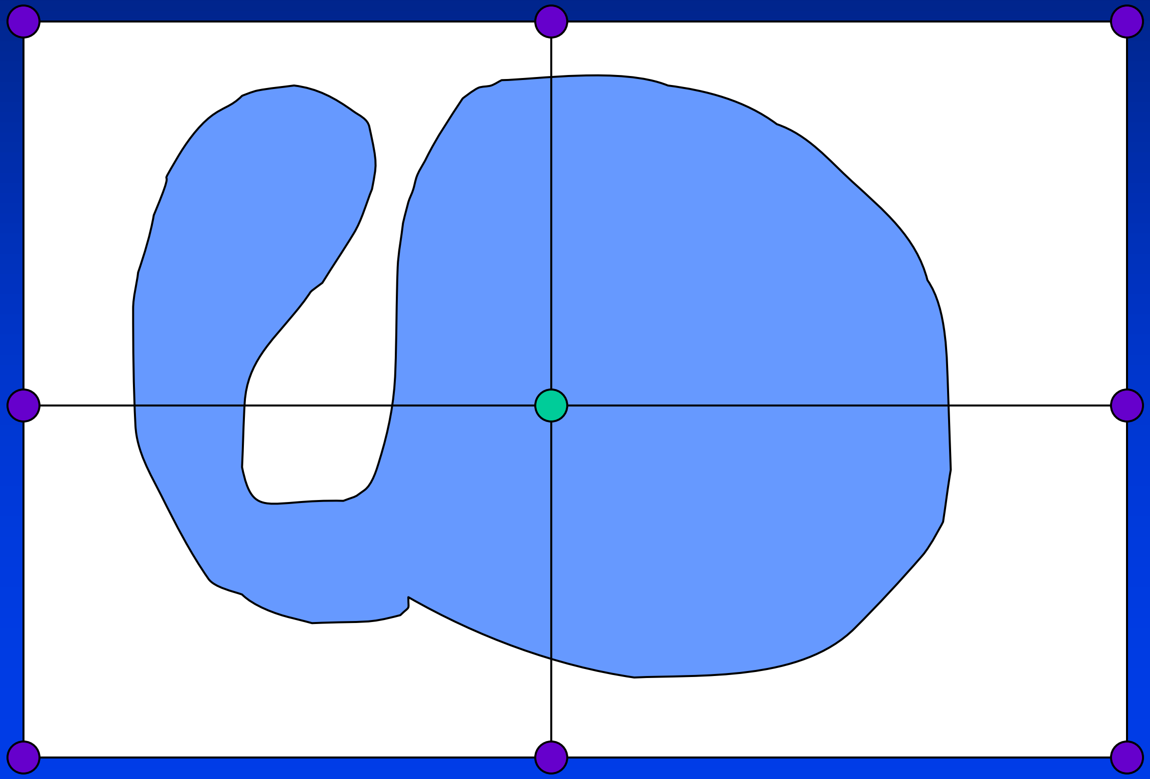
  - Reasonable interfaces for design
- Disadvantages:
  - Difficult to render and control when animating
  - Being replaced with subdivision surfaces, it appears

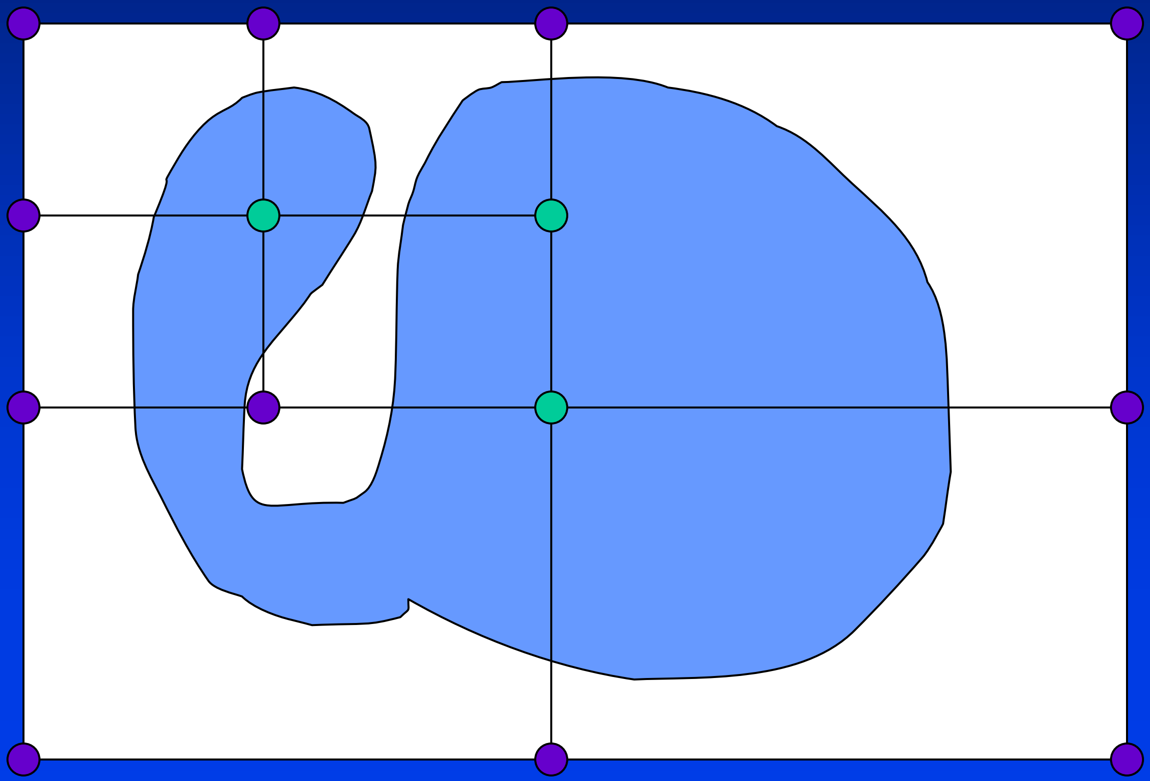
Display Implicit Surfaces

- Recursive subdivision:



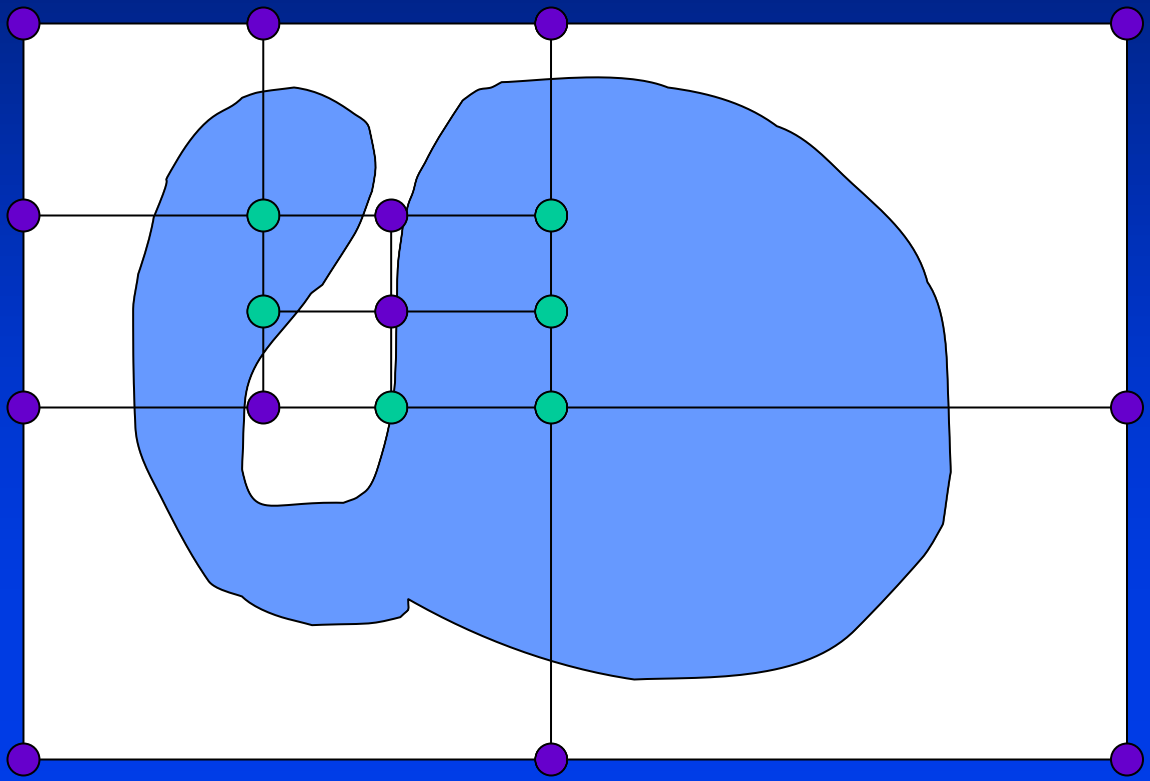
Display Implicit Surfaces

- Recursive subdivision:



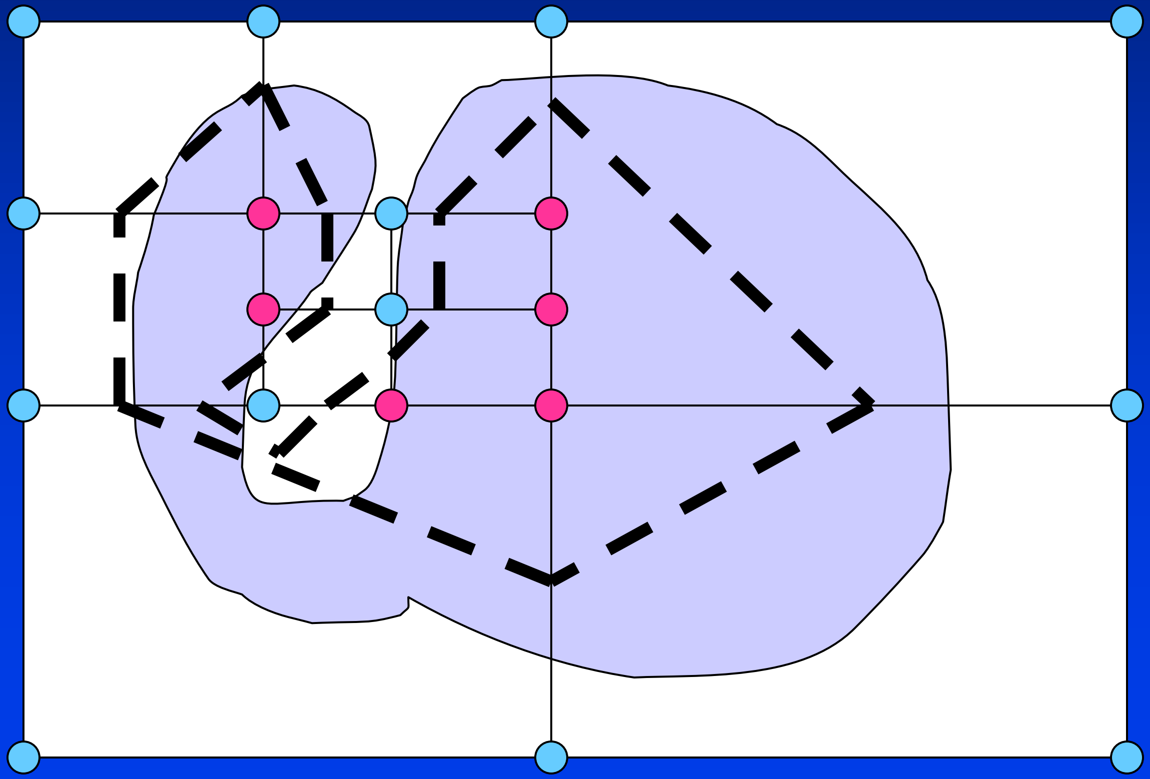
Display Implicit Surfaces

- Recursive subdivision:

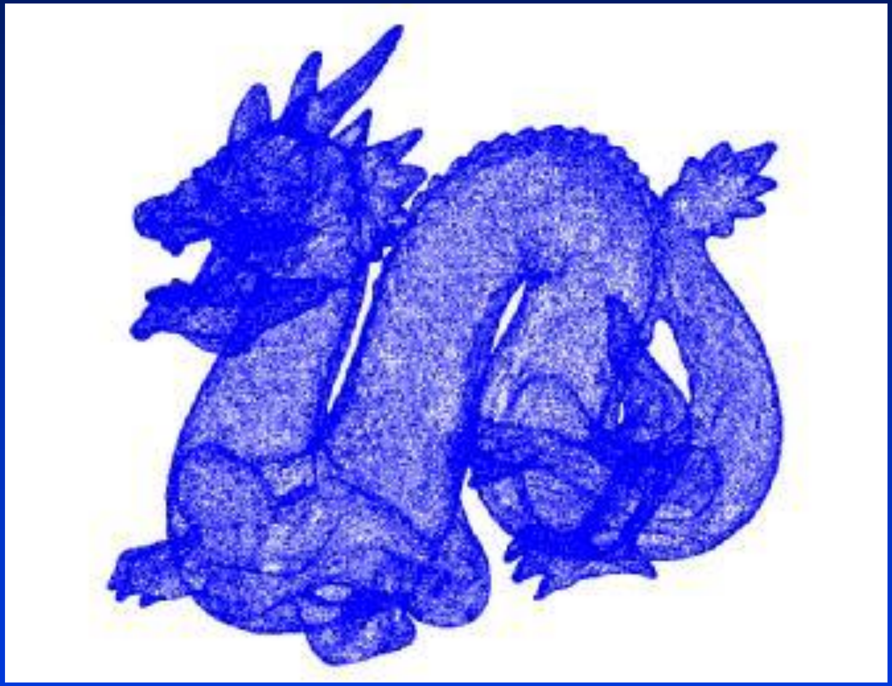


Display Implicit Surfaces

- Find the edges, separating hot from cold:



Compression

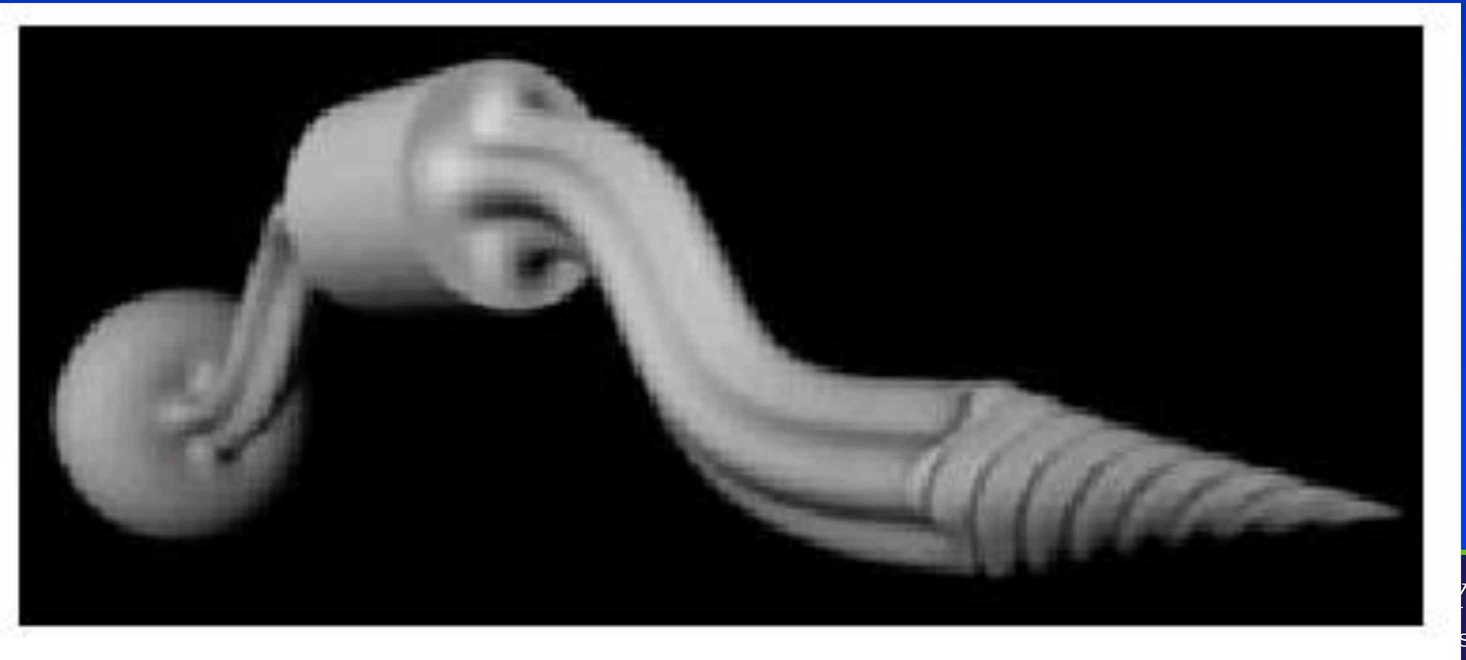


Mesh of 473,000 vertices
and 871,000 facets

Implicit function of 32,000 terms

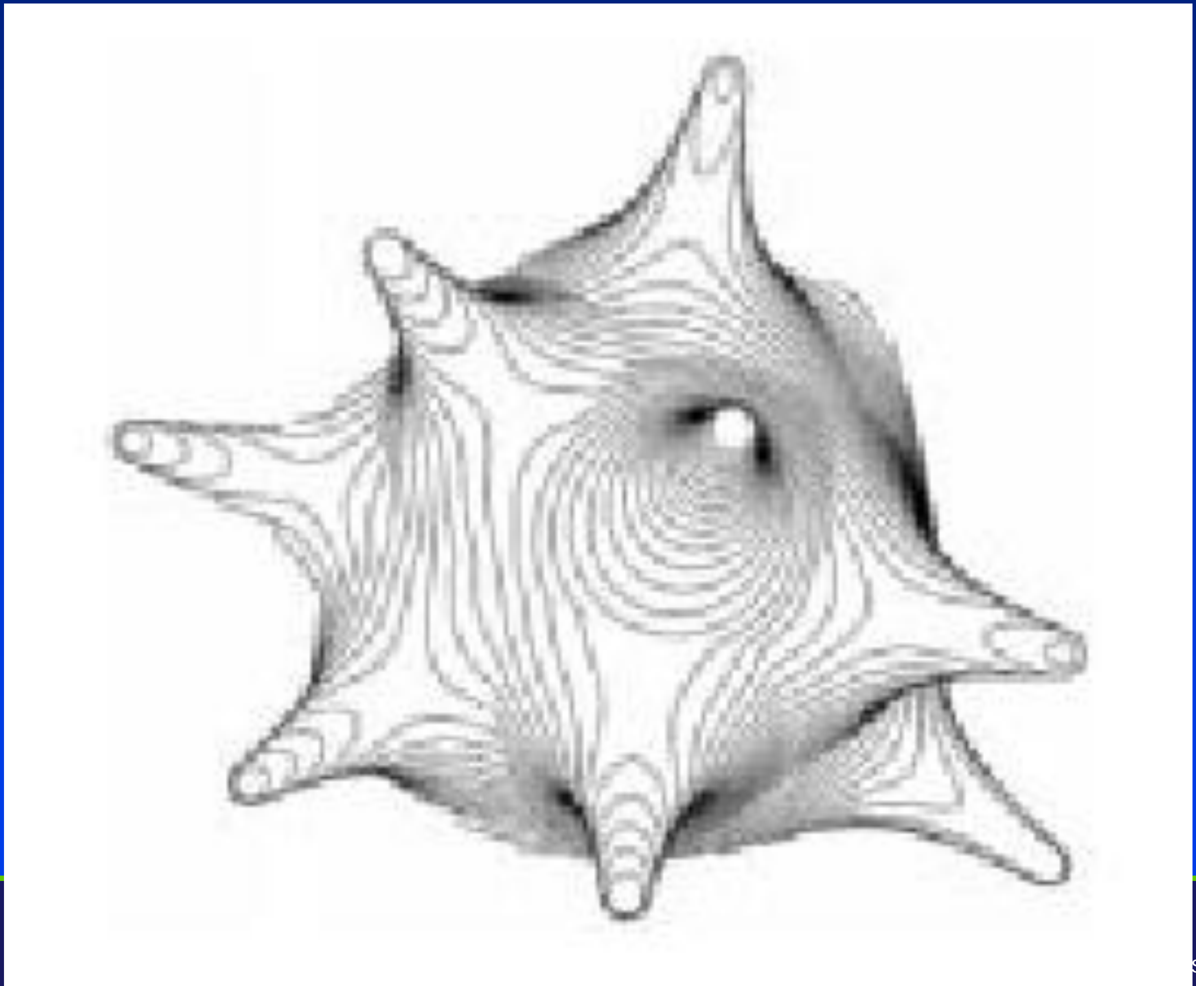
Deformation

- **p**' = D(**p**)
- D maps each point in 3-space to some new location
- Twist, bend, taper, and offset



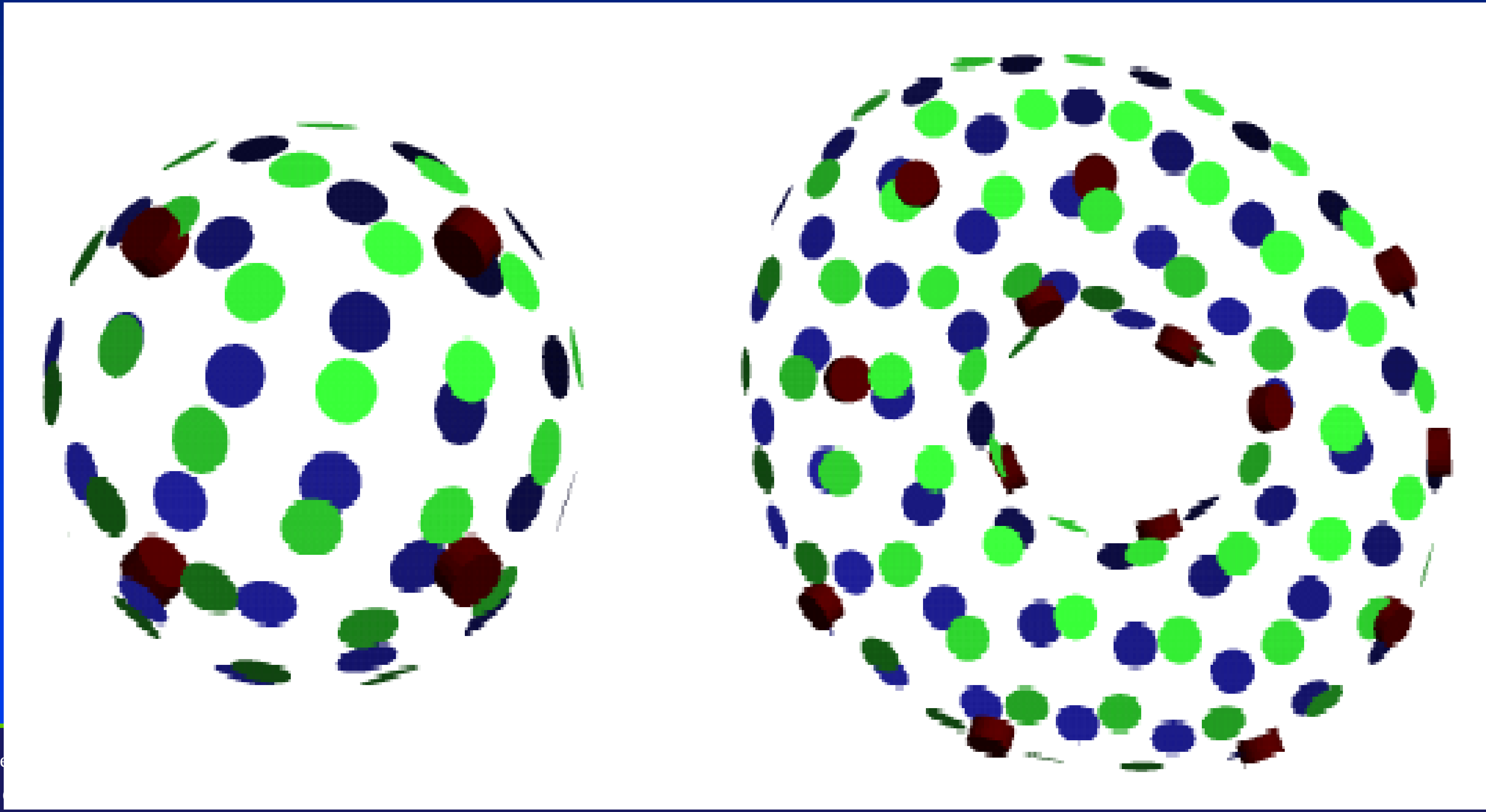
Visualization

- Contours



Visualization

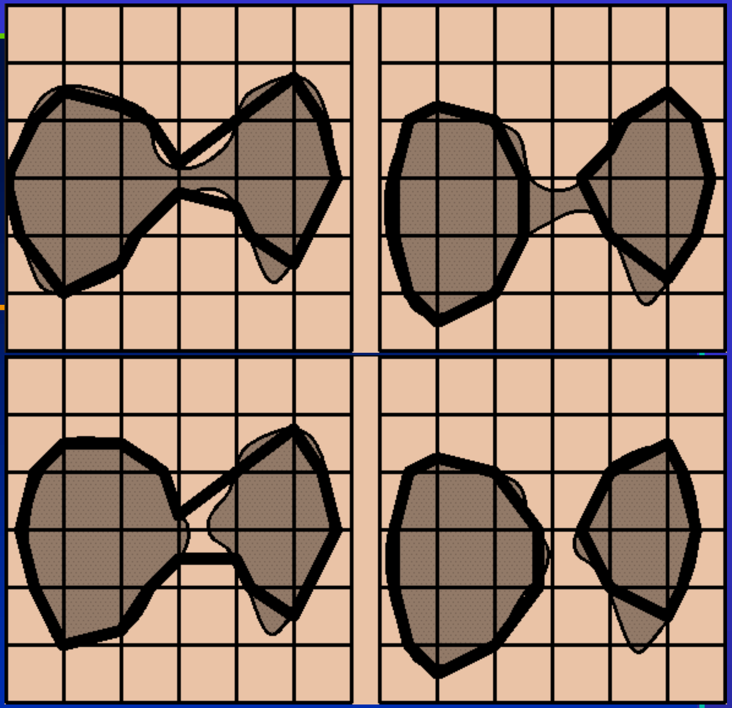
- Particle Display



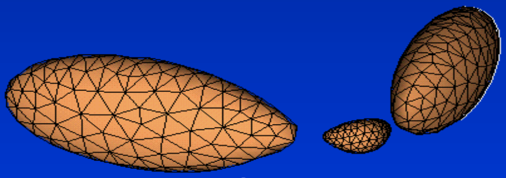
Particle Systems

- Witkin Heckbert S94
- Constrain particle system to implicit surface (Implicit surface $f = 0$ becomes constraint surface $C = 0$)
- Particles exert repulsion forces onto each other to spread out across surface
- Particles subdivide to fill open gaps
- Particles commit suicide if overcrowded
- Display particle as oriented disk
- Constrain implicit surface to particles!

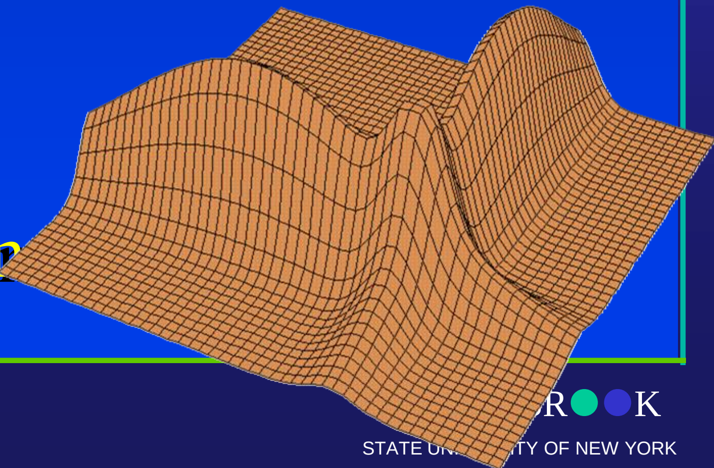
Meshing Particles



- Stander Hart S97
- Use particles as vertices
- Connect vertices into mesh
- Problems:
  - Which vertices should be connected?
  - How should vertices be reconnected when surface moves?

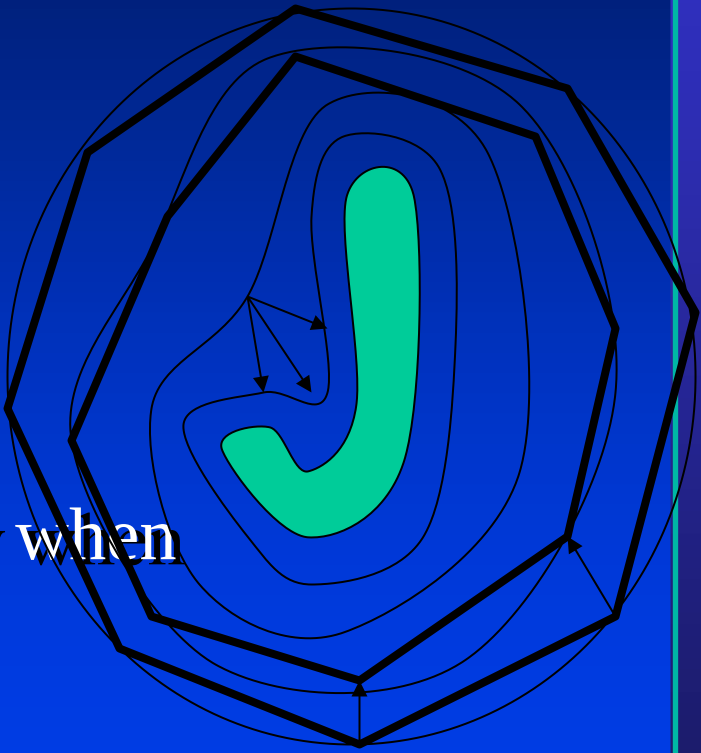


- Solution: Morse theory
- Track/find critical points of function in topology of implicit surface



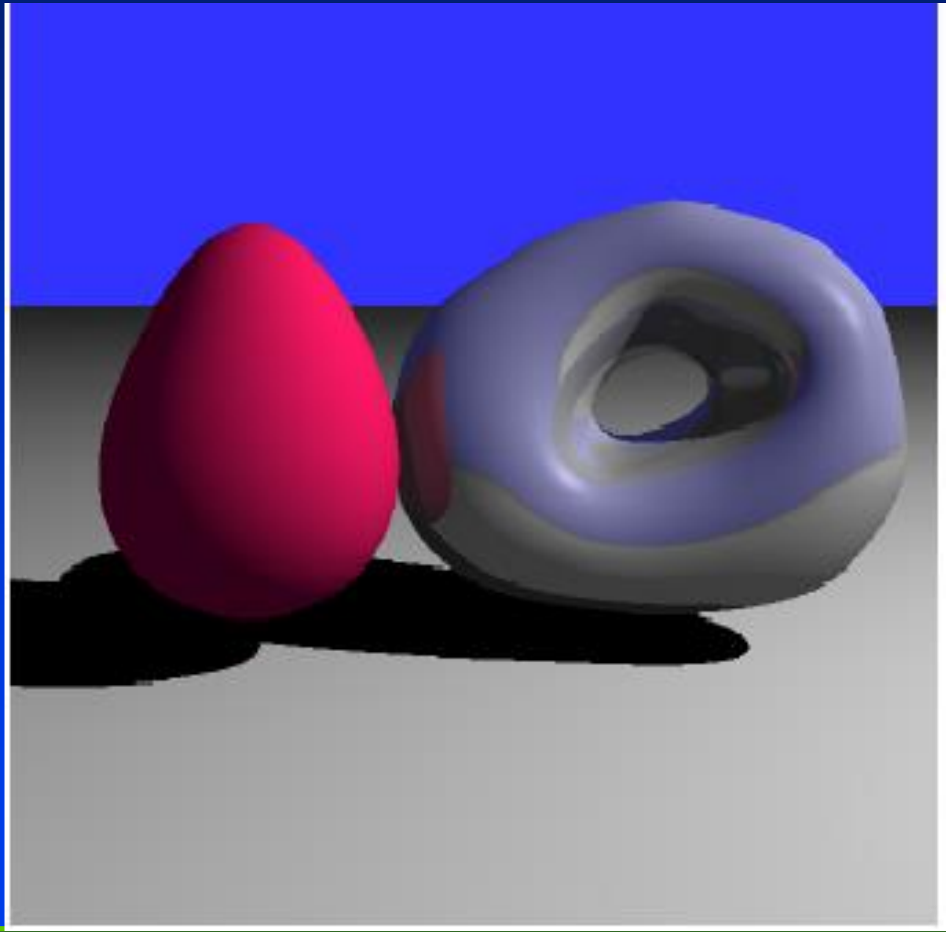
Shrink-wrapping Mechanism

- Look at family of surfaces $f^{-1}(s)$ for $s > 0$
- For s large, $f^{-1}(s)$ spherical
- Polygonize sphere
- Reduce s to zero
  - Allow vertices to track surface
  - Subdivide polygons as necessary when curvature increases

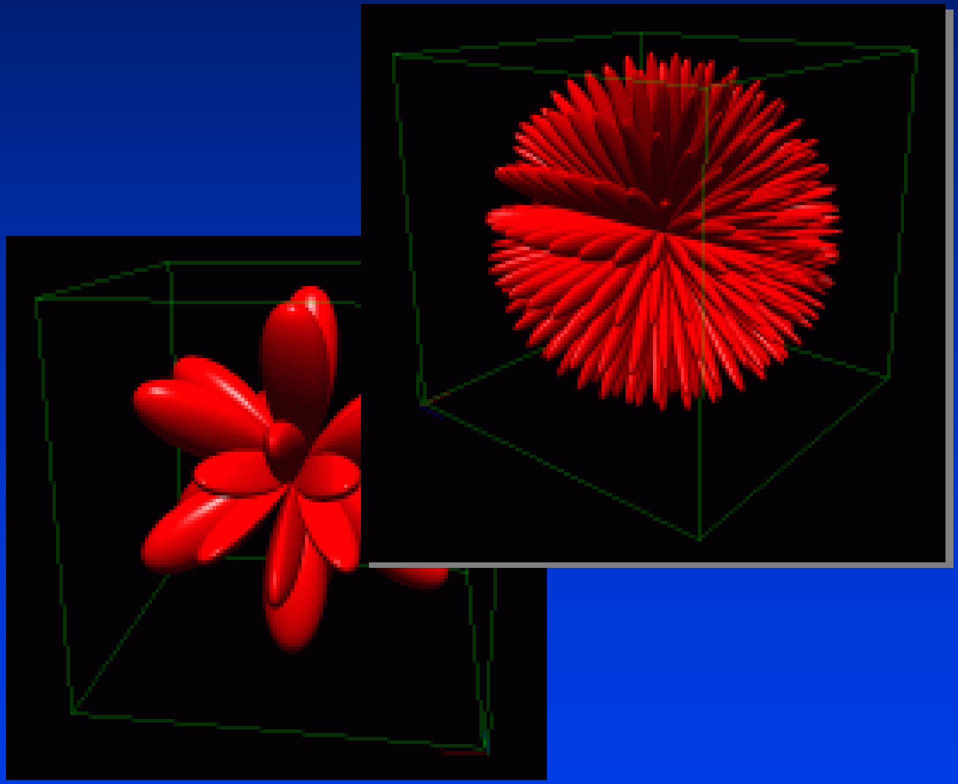


Visualization

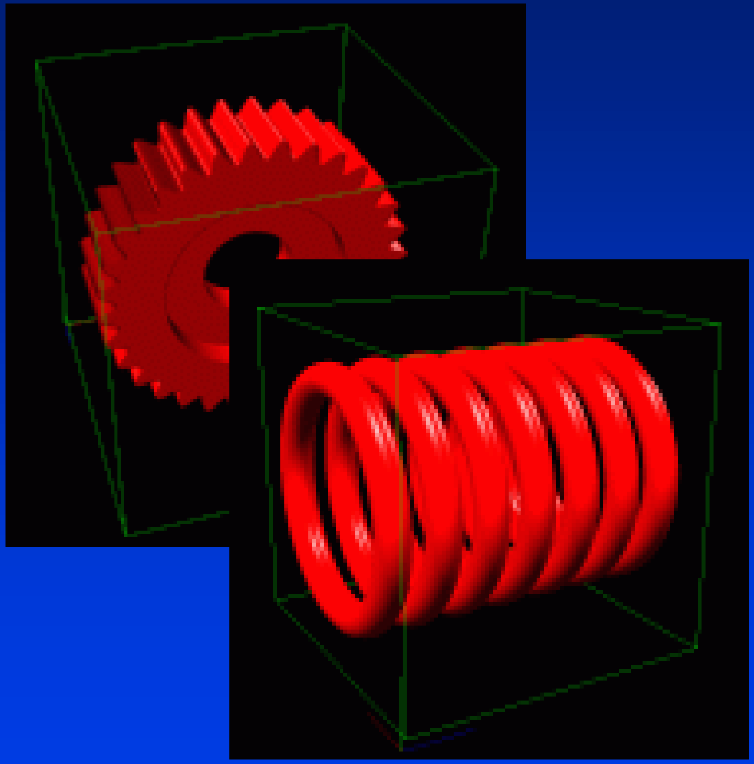
- Ray Tracing



Other Coordinate Systems



Spherical Coordinates



Cylindrical Coordinates

Summary

- Surface defined implicitly by $f(p) = 0$
- Easy to test if point is on surface, inside, or outside
- Easy to handle blending, interpolation, and deformation
- Difficult to render