

Definite Logic Programs: Models

CSE 505 – Computing with Logic

Stony Brook University

<http://www.cs.stonybrook.edu/~cse505>

Logical Consequences of Formulae

- Recall: F is a *logical consequence* of P (i.e. $P \models F$)
iff

Every model of P is also a model of F .

- Since there are (in general) infinitely many possible interpretations, how can we check if F is a logical consequence of P ?
- Solution: choose (one) "canonical" model I such that

$$I \models P \quad \text{and} \quad I \models F \quad \rightarrow \quad P \models F$$

Definite Clauses

- A formula of the form $\mathbf{p}(t_1, t_2, \dots, t_n)$, where \mathbf{p}/n is an n -ary predicate symbol and t_i are all terms is said to be *atomic*.
- If \mathbf{A} is an atomic formula then:
 - \mathbf{A} is said to be a *positive literal*
 - $\neg\mathbf{A}$ is said to be a *negative literal*
- A formula of the form $\forall(\mathbf{L}_1 \vee \mathbf{L}_2 \vee \dots \vee \mathbf{L}_n)$ where each \mathbf{L}_i is a literal (negative or positive) is called a *clause*.
- A clause $\forall(\mathbf{L}_1 \vee \mathbf{L}_2 \vee \dots \vee \mathbf{L}_n)$ where exactly one literal is positive is called a *definite clause* (also called *Horn clause*).
 - A definite clause is usually written as:
 - $\forall(\mathbf{A}_0 \vee \neg\mathbf{A}_1 \vee \dots \vee \neg\mathbf{A}_n)$
 - or equivalently as: $\mathbf{A}_0 \leftarrow \mathbf{A}_1, \mathbf{A}_2, \dots, \mathbf{A}_n$.
- A *definite program* is a set of definite clauses.

Herbrand Universe

- Given an alphabet A , the set of all **ground terms** constructed from the constant and function symbols of A is called the *Herbrand Universe* of A (denoted by U_A).

- Consider the program:

$p(\text{zero})$.

$p(s(s(X))) \leftarrow p(X)$.

- The Herbrand Universe of the program's alphabet is: $U_A = \{\text{zero}, s(\text{zero}), s(s(\text{zero})), \dots\}$



Jacques Herbrand
(1908 –1931)

Herbrand Universe: Example

- Consider the "relations" program:

```
parent (pam, bob) .      parent (bob, ann) .  
parent (tom, bob) .     parent (bob, pat) .  
parent (tom, liz) .     parent (pat, jim) .  
grandparent (X, Y) :-  
    parent (X, Z) , parent (Z, Y) .
```

- The Herbrand Universe of the program's alphabet is:

$$U_A = \{\text{pam, bob, tom, liz, ann, pat, jim}\}$$

Herbrand Base

- Given an alphabet A , the set of all **ground atomic formulas** over A is called the *Herbrand Base* of A (denoted by B_A)

- Consider the program:

$p(\text{zero})$.

$p(s(s(X))) \leftarrow p(X)$.

- The Herbrand Base of the program's alphabet is: $B_A = \{p(\text{zero}), p(s(\text{zero})), p(s(s(\text{zero}))), \dots\}$

Herbrand Base: Example

- Consider the "relations" program:

```
parent (pam, bob) .      parent (bob, ann) .  
parent (tom, bob) .     parent (bob, pat) .  
parent (tom, liz) .     parent (pat, jim) .  
grandparent (X, Y) :-  
    parent (X, Z) , parent (Z, Y) .
```

- The Herbrand Base of the program's alphabet is:

$B_A = \{ \text{parent}(\text{pam}, \text{pam}), \text{parent}(\text{pam}, \text{bob}),$
 $\text{parent}(\text{pam}, \text{tom}), \dots, \text{parent}(\text{bob}, \text{pam}), \dots,$
 $\text{grandparent}(\text{pam}, \text{pam}), \dots, \text{grandparent}(\text{bob}, \text{pam}),$
 $\dots \}.$

Herbrand Interpretations and Models

- A Herbrand Interpretation of a program P is an interpretation I such that:
 - The domain of the interpretation: $|I| = U_P$
 - For every constant c : $c_I = c$
 - For every function symbol f/n :
$$f_I(x_1, \dots, x_n) = f(x_1, \dots, x_n)$$
 - For every predicate symbol p/n : $p_I \subseteq (U_P)^n$
(i.e. some subset of n -tuples of ground terms)
- A Herbrand Model of a program P is a Herbrand interpretation that is a model of P .

Herbrand Models

- All Herbrand interpretations of a program give the same “*meaning*” to the constant and function symbols
- Different Herbrand interpretations differ only in the “*meaning*” they give to the predicate symbols

Herbrand Models

- We often write a Herbrand model simply by listing the subset of the Herbrand base that is true in the model
 - Example: Consider our numbers program, where $\{p(\mathbf{zero}), p(\mathbf{s(s(zero))}), p(\mathbf{s(s(s(s(zero))))}), \dots\}$ represents the Herbrand model that treats $\mathbf{p_I} = \{\mathbf{zero}, \mathbf{s(s(zero))}, \mathbf{s(s(s(s(zero))))}, \dots\}$ as the meaning of \mathbf{p} .
 - If we have several predicates, the Herbrand interpretation would be a single set of all true predicates

Sufficiency of Herbrand Models

- Let P be a definite program. If I' is a model of P then $I = \{\mathbf{A} \in B_p \mid I' \models \mathbf{A}\}$ is a Herbrand model of P .

Proof (by contradiction):

- Assume that I' is a model of P but I (defined above) is not a model.
- Then there is some ground instance of a clause in P :

$$\mathbf{A}_0 \text{ :- } \mathbf{A}_1, \dots, \mathbf{A}_n.$$

- which is not true in I i.e., $I \models \mathbf{A}_1, \dots, I \models \mathbf{A}_n$ but $I \not\models \mathbf{A}_0$
- By definition of I then, $I' \models \mathbf{A}_1, \dots, I' \models \mathbf{A}_n$ but $I' \not\models \mathbf{A}_0$
- Thus, I' is not a model of P , which contradicts our earlier assumption.

Definite programs only

- Let P be a definite program. If I' is a model of P then $I = \{\mathbf{A} \in B_p \mid I' \models \mathbf{A}\}$ is a Herbrand model of P .
- This property holds only for definite programs!
 - Example: Consider $P = \{\neg p(a), \exists X.p(X)\}$
 - There are two Herbrand interpretations: $I_1 = \{p(a)\}$ and $I_2 = \{\}$
 - The first is not a model of P since $I_1 \not\models \neg p(a)$
 - The second is not a model of P since $I_2 \not\models \exists X.p(X)$
 - But there are non-Herbrand models, such as I :
 - $|I| = \mathbb{N}$ (the set of natural numbers)
 - $a_I = 0$
 - $p_I = \text{“is odd”}$

Properties of Herbrand Models

1. For any definite program P , if every Herbrand Model of P is also a Herbrand Model of F , then $P \models F$.
2. If M is a set of Herbrand Models of a definite program P , then $\bigcap M$ is also a Herbrand Model of P .
3. For every definite program P there is a **unique least model M_p** such that:
 - a) M_p is a Herbrand Model of P and,
 - b) for every Herbrand Model M , $M_p \subseteq M$.
4. $M_p =$ the set of all ground logical consequences of P .

Properties of Herbrand Models

- If M_1 and M_2 are Herbrand models of P , then $M = M_1 \cap M_2$ is a model of P .

Proof:

- Assume $M = M_1 \cap M_2$ is not a model.
- Then there is some clause $\mathbf{A}_0: \neg \mathbf{A}_1, \dots, \mathbf{A}_n$ such that $M \models \mathbf{A}_1, \dots, M \models \mathbf{A}_n$ but $M \not\models \mathbf{A}_0$
- Which means $\mathbf{A}_0 \notin M_1$ or $\mathbf{A}_0 \notin M_2$ by def. of \cap
- But $\mathbf{A}_1, \dots, \mathbf{A}_n \in M_1$ as well as M_2 .
- Hence one of M_1 or M_2 is not a model.

Properties of Herbrand Models

- There is a unique least Herbrand model.

Proof:

- Let M_1 and M_2 are two incomparable **minimal** Herbrand models (incomparable means neither one is a subset of the other), but $M = M_1 \cap M_2$ is also a Herbrand model (previous theorem), and $M \subset M_1$ or $M \subset M_2$
- Thus M_1 on M_2 is not minimal.

Least Herbrand Model

- The least Herbrand model M_p of a definite program P is the set of all ground logical consequences of the program:

$$M_p = \{A \in B_p \mid P \models \mathbf{A}\}$$

Proof:

- First, $M_p \supseteq \{A \in B_p \mid P \models \mathbf{A}\}$ (i.e., M_p is a superset of the logical consequences $\{A \in B_p \mid P \models \mathbf{A}\}$):
 - By definition of logical consequence, $P \models \mathbf{A}$ means that \mathbf{A} **must be in every model of P** and hence also in the least Herbrand model.

Least Herbrand Model

- Second, $M_p \subseteq \{A \in B_p \mid P \models A\}$ (i.e., M_p is a **subset** of the logical consequences $\{A \in B_p \mid P \models \mathbf{A}\}$):
 - Assume that \mathbf{A} is in M_p . Hence, \mathbf{A} is in **every** Herbrand model of P by def. of M_p (i.e., subset of all models)
 - Assume that \mathbf{A} is not true in some non-Herbrand model of P :
 $I' \models \neg \mathbf{A}$
 - By sufficiency of Herbrand models (i.e., If I' is a model of P then $I = \{A \in B_p \mid I' \models A\}$ is a Herbrand model of P), there is some Herbrand model I such that $I \models \neg \mathbf{A}$
 - Hence \mathbf{A} **cannot** be an element of the Herbrand model I
 - This contradicts that \mathbf{A} is in **every** Herbrand model of P , and their intersection M_p

Construction of Least Herbrand Models

- Definition: Immediate consequence operator:
 - Given an interpretation $I \subseteq B_p$, construct I' such that
$$I' = \{ \mathbf{A}_0 \in B_p \mid \mathbf{A}_0 \leftarrow \mathbf{A}_1, \dots, \mathbf{A}_n \text{ is a ground instance of a clause in } P \text{ and } \mathbf{A}_1, \dots, \mathbf{A}_n \in I \}$$
 - I' is said to be the *immediate consequence* of I written as $I' = Tp(I)$, where Tp is called the *immediate consequence operator*.
 - Consider the sequence:
$$\emptyset, Tp(\emptyset), Tp(Tp(\emptyset)), \dots, Tp^i(\emptyset), \dots$$
 - $M_p \supseteq Tp^i(\emptyset)$ for all i (M_p is a **superset** of all $Tp^i(\emptyset)$)
 - Let $Tp \uparrow \omega = \bigcup_{i=0, \infty} Tp^i(\emptyset)$
- Then $M_p = Tp \uparrow \omega$

Computing Least Herbrand Models: An Example

```

parent(pam, bob) .
parent(tom, bob) .
parent(tom, liz) .
parent(bob, ann) .
parent(bob, pat) .
parent(pat, jim) .

```

```

anc(X, Y) :-
    parent(X, Y) .
anc(X, Y) :-
    parent(X, Z) ,
    anc(Z, Y) .

```

M_1	\emptyset
$M_2 = T_P(M_1) =$	$\{ \text{parent}(\text{pam}, \text{bob}),$ $\text{parent}(\text{tom}, \text{bob}),$ $\text{parent}(\text{tom}, \text{liz}),$ $\text{parent}(\text{bob}, \text{ann}),$ $\text{parent}(\text{bob}, \text{pat}),$ $\text{parent}(\text{pat}, \text{jim}) \}$
$M_3 = T_P(M_2) =$	$\{ \text{anc}(\text{pam}, \text{bob}), \quad \text{anc}(\text{tom}, \text{bob}),$ $\text{anc}(\text{tom}, \text{liz}), \quad \text{anc}(\text{bob}, \text{ann}),$ $\text{anc}(\text{bob}, \text{pat}), \quad \text{anc}(\text{pat}, \text{jim}) \}$ $\cup M_2$
$M_4 = T_P(M_3) =$	$\{ \text{anc}(\text{pam}, \text{ann}), \quad \text{anc}(\text{pam}, \text{pat}),$ $\text{anc}(\text{tom}, \text{ann}), \quad \text{anc}(\text{tom}, \text{pat}),$ $\text{anc}(\text{bob}, \text{jim}) \} \cup M_3$
$M_5 = T_P(M_4) =$	$\{ \text{anc}(\text{pam}, \text{jim}), \quad \{ \text{anc}(\text{tom}, \text{jim}) \} \}$ $\cup M_4$
$M_6 = T_P(M_5) =$	M_5

Computing M_p

- Computing the least Herbrand model, M_p , as the **least fixed point** of T_p :
 - terminates for *Datalog* programs (i.e., programs **w/o function symbols**)
 - may not terminate in general (because it could be infinite)
 - For programs with function symbols
- Even for Datalog programs, computing least fixed point directly using the T_p operator is **wasteful** (known as **Naive** evaluation)
 - Note that $T_p^i(\emptyset) \subseteq T_p^{i+1}(\emptyset)$ for all i
 - We can calculate $\Delta T_p^{i+1}(\emptyset) = T_p^{i+1}(\emptyset) - T_p^i(\emptyset)$ [The difference between the sets computed in two successive iterations] (**this strategy is known as the semi-naive evaluation**)