# **Introduction to Medical Imaging**

**Lecture 12: MRI Imaging** 

Klaus Mueller

Computer Science Department Stony Brook University

#### The General Idea

Before going into the math, we shall pursue a more intuitive route to provide an explanation of the used approach

• see also "The basics of MRI" by Joseph Hornak http://www.cis.rit.edu/htbooks/mri

Recall that the Larmor frequency at which the nuclei spin is dependent on the magnetic field:  $\omega_0 = \gamma B_0$ 

#### Then how about this:

- if we could simply change the local frequency at each nuclei (or better, voxel) then we could select a voxel just by its frequency
- we would then measure its amplitude to get its density
- we learnt that frequency space is a good space for this

#### So how is this done?

- we can influence the local frequency by the local magnet field
- the local magnet field can be altered by adding a varying magnet field to the large existing one, B<sub>0</sub>

#### What We have Learned So Far...

#### Steady state:

- with just an axial B-field, the nuclei only spin along the z-direction which cannot be measured
- the nuclei also spin in an unsynchronized fashion, which sets their net effect to zero

#### Disturbed state:

- a transversal RF pulse (at Larmor frequency ω<sub>0</sub>) can bring the nuclei spins out of their z-alignment, creating a transversal component in the net magnetization vector
- this transversal RF pulse also synchronizes the spins
- this component can then be measured using (possibly the same) RF coils, whose axes are in the transversal plane (the xy-plane)

#### A remaining challenge is:

- we receive a single sinusoidal signal (at Larmor frequency  $\omega_0$ ) characterized by amplitude A and phase shift  $\theta_s \to 2$  knowns
- what we want is the density of nx·ny·nz individual voxels → nx·ny·nz unknowns
- how do we solve such an equation?

#### **Slice Selection**

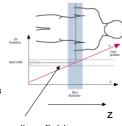
#### Step 1: slice coding

- select the slice s by coding the nuclei in that slice with a specific  $\omega_{\rm s}$
- this is done by adding a magnetic field linearly rising along z (called *gradient field*)
- now only the voxels in the selected slice spin at  $\omega_{\rm s}$

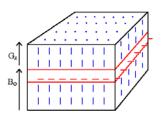
#### Step 2: RF pulse at $\omega_{\rm s}$

- this will only bring the nuclei in slice s into the transversal plane and sync them
- we could then measure a signal but it would still be a composite of all nuclei in the slice

Hence, more tagging is needed within the slice



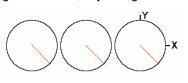
gradient field

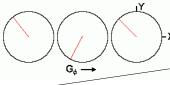


next set of slides based on web site Basics of MRI, by J. Hornak (RPI)

#### **The Phase Encoding Concept**

Once the slice has been selected we can impose another magnetic gradient field, say along x

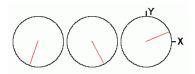




gradient field along x

• now the nuclei spin at different frequencies, varying along x

After releasing the gradient, the nuclei spin at the slice's Larmor frequency again, but an x-dependent phase shift angle remains



- · we need a method to measure this phase shift
- we also still need a method to distinguish different rows y

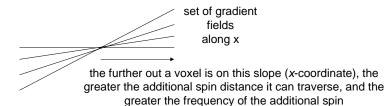
# **Decoding**

We could measure the RF signal and perform a Fourier transform

- this would give us *ny* frequencies
- however, we would like to measure *nx*·*ny* voxels

Need to generate more equations

- we can get these by performing nx different phase encodings
- for each phase encoding we use a gradient field with a different slope

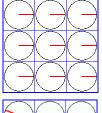


• each is then followed by a frequency encoding

Let's examine this by ways of a few examples

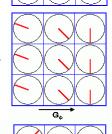
#### **Two-Dimensional Encoding**

After slice selection all nuclei in the slice spin at the same rate



Apply a phase encoding (along x)

 after gradient release, the column nuclei are distinguished by phase

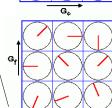


Apply another gradient field (now along y)

- do not release → frequency encoding
- now nuclei within a column can be distinguished by frequency

gradient field along y

gradient field along x



Frequency Encoding Direction

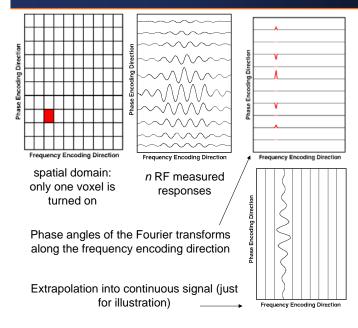
Fourier transform

along the phase

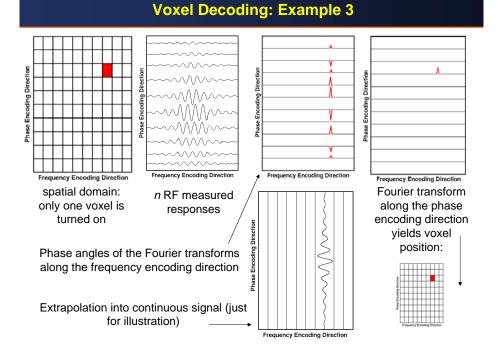
encoding direction yields voxel

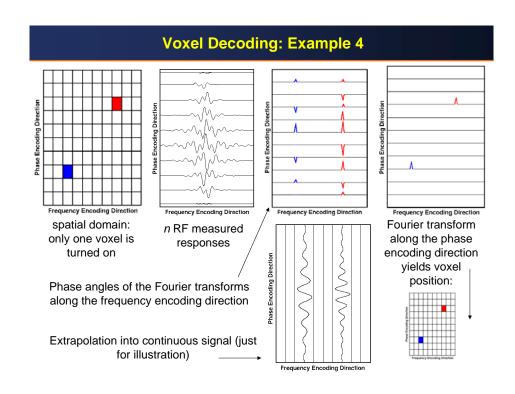
position:

# **Voxel Decoding: Example 1**



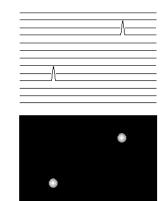
# **Voxel Decoding: Example 2** Frequency Encoding Direction Frequency Encoding Direction Frequency Encoding Direction spatial domain: Fourier transform n RF measured only one voxel is along the phase responses turned on encoding direction yields voxel position: Phase angles of the Fourier transforms along the frequency encoding direction Extrapolation into continuous signal (just for illustration) Frequency Encoding Direction





#### **Image Generation**

The spectra have amplitudes as well and an image can be generated



or more complex:

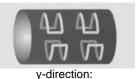


#### **Gradient Coils**

#### Field gradients, generated by coils, are essential in MRI



x-direction:





z-direction:

Examples:



surface coils



volume (quadrature) coil



head volume coil

#### More Formally... Slice Selection

Usually one selects a slice perpendicular to the z-axis

(but any slice orientation is possible)

Use linear magnetic field gradient  $G_z$ :

$$G = (G_x, G_y, G_z) = (0, 0, \frac{\partial B_z}{\partial z})$$

• the Larmor frequency of a slice is then:

$$\omega(z) = \gamma (B_0 + G_z z)$$

hence, a slice of thickness ∆z will resonate at frequencies:

$$\Delta \omega = \gamma G_z \Delta z$$

• and a RF pulse of freq. bandwidth BW resonates a slice of width:

There is a lower bound on  $\Delta z$ :

$$\Delta z = \frac{\Delta \omega}{\gamma G_{-}} = \frac{BW}{\gamma G_{-}}$$

• technical and safety limits on gradient strength G<sub>z</sub>

- · a very thin slice has too low SNR
- typically:  $\Delta z = 2 \text{ mm } (B_0 = 1.5 \text{T}), \Delta z = 3 \text{ mm } (B_0 = 1 \text{T})$

# Slice Selection: Example

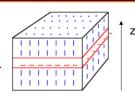
#### Dynamic cardiac sequence

• four cardiac chambers together with the heart valves in a plane parallel to the cardiac axis



# **Position Encoding: Spin Differentiation**

The slice selection RF pulse puts all nuclei within ∆z into a similar synchronized transverse spin (resonance)



- now all nuclei within the slice's (x,y)-plane have a transverse component
- these must be further encoded for spatial localization
- all nuclei rotate at  $\omega_0$ , in a synchronized fashion

Let's assume, for now, that we only have one x-beam of voxels

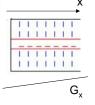
For encoding, we apply a field gradient  $G_{x}$  along x:

• this changes the transverse component frequency to:

$$\omega(x) = \gamma G_x x$$

• in complex notation:

$$M_x(t) = M_x(0)e^{-i\gamma G_x xt}$$



#### **Position Encoding: Signal Collection**

To collect signals from all x-beam voxels, we must integrate across the entire x-beam

The detected signal is: 
$$s(t) = \int_{-\infty}^{+\infty} \rho(x) e^{-i\gamma G_x x t} dx$$

 $\rho(x)$  is the (transverse) net magnetization density in x

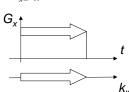
Defining 
$$k_x = \frac{\gamma}{2\pi} G_x t$$
 we get:  $s(t) = S(k_x) = \int_{x=-\infty}^{+\infty} \rho(x) \ e^{-i2\pi k_x x} dx$ 

Recall 1D Fourier Transform:  $F(k_x) = \int_{x=-\infty}^{+\infty} f(x) \ e^{-i2\pi k_x x} dx$ 

We can interpret this as:

$$s(t) = S(k_x) = F\{\rho(x)\}(k_x)$$

•  $k_{\rm x}$  grows as long as the gradient is active (as t increases)



#### The K-Theorem (1)

A generalization of what we have just seen

- position vector r = (x, y) and magnetization density  $\rho(x, y)$  are now 2D vectors
- the angular frequency is given by the dot product:  $\omega(r) = \gamma(\overrightarrow{G} \cdot r)$
- the measured signal becomes:

$$s(t) = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \rho(x, y) e^{-i\gamma(\overrightarrow{G} \cdot r)t} dx dy$$
$$= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \rho(x, y) e^{-i\gamma(G_x x + G_y y)t} dx dy$$

• recall the 2D Fourier Transform (and  $k_x = \frac{\gamma}{2\pi}G_x t$   $k_y = \frac{\gamma}{2\pi}G_y t$  )

$$F(k_x, k_y) = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f(x, y) e^{-i2\pi(k_x x + k_y y)} dx dy$$



• thus, MRI allows us to collect data along any line in k-space:

#### The K-Theorem (2)

Generalizing further into 3D:

$$s(t) = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \rho(x, y, z) e^{-i\gamma(\vec{G} \cdot r)t} dx dy dz$$

Taking into account relaxation effects  $g(t,T_1)$  and  $h(t,T_2)$ :

$$s(t) = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \rho(x, y, z) g(t, T_1) h(t, T_2) e^{-i\gamma(\overrightarrow{G} \cdot r)t} dx dy dz$$

MRI seeks techniques where the returned vales at (x,y,z) all have the same relaxation effects

- the relaxation effects allow MRI to obtain images of different contrasts, since different types of tissues have different  $g(t,T_1)$  and  $h(t,T_2)$
- thus, an MRI image is not (necessarily) just a proton density (ρ) image (but this can be obtained as well)

#### The K-Theorem (3)

We have seen that the time signal s(t) is equivalent to the Fourier Transform (FT) of the desired image

> 2D Fourier transform

- as mentioned, this data collection space is called *k-space*
- an inverse FT will produce the desired image



k-space image



spatial image

#### **Dephasing Phenomena**

Dephasing occurs when the vectors precess at different Larmor frequencies

• this results in a reduced (and noisy) receiver coil signal

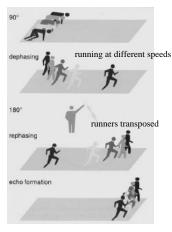
Distinguish between three types of dephasing phenomena:

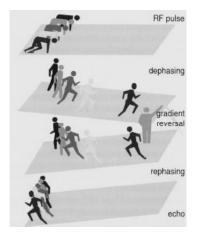
- 1. Spin-spin interaction:
  - irreversible, described by time constant T<sub>2</sub>
- 2. Magnetic field inhomogeneities:
  - reversible, described by time constant  $T_2^* < T_2$
  - due to inhomogeneous magnetic field and differences in magnetic susceptibility of the tissues (for example, iron is very susceptible and can change the local field significantly)
  - can be undone by a 180° RF pulse
- 3. Magnetic field gradients:
  - reversible, time constant  $T_2^{*"} < T_2^{*}$
  - undone with reversed gradient fields

#### **Rephasing: Runners Equivalent**

Rephasing is the process of undoing the effects of dephasing

• two types of rephasing, illustrated by the famous runner example



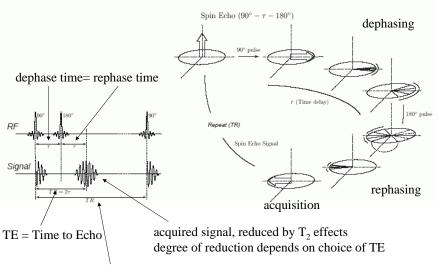


180° RF pulse

Gradient reversal

from: Frits Thorsen (U Bergen)

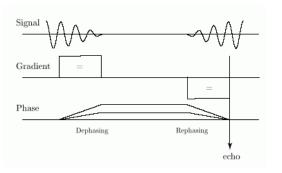
# Rephasing: 180 RF Pulse



TR = Repetition Time (can also be chosen for different effects)
large TR ensure that all protons are aligned with the z-axis before the next RF pulse

# **Rephasing: Gradient Reversal**

Opposite field gradients of same length and strength



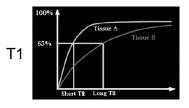
#### The Art of Choosing TR and TE

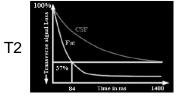
TR and TE can be varied to bring out proton density (PD), T1, and T2 properties of the tissue

Recall the Bloch relaxation formula:  $M_{xy} = M_{xy0}(1 - e^{-\frac{TR}{T1}}) e^{-\frac{TE}{T2}}$  where  $M_{xy0}$  is the transversal component at t=0

MRI seeks to bring out tissue contrast as manifested by differences in PD, T1, or T2 properties (T1/TR, T2/TE ratios)

- choose TE and TR according to the T1 and T2 constants of the target and adjacent tissues
- pick the imaging protocol that brings out these contrasts best
- this is called T1, T2, PD weighting



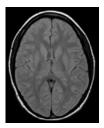


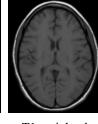
#### **Examples**

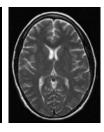
T1-weighting typically brings out anatomy better
T-2 weighting shows pathologies better

PD is used when T1/T2 densities are similar

Often, all are obtained and possibly fused









proton density

T1-weighted

T2-weighted

T1/T2 fused

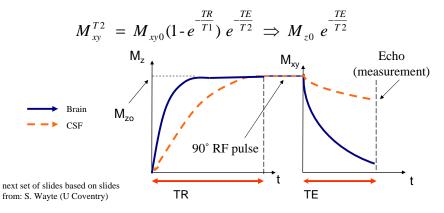
# **T2 Weighting**

# Long TR

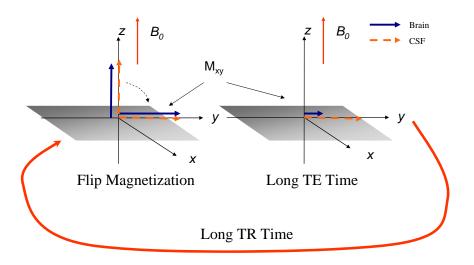
to give all tissue time to recover (back to M<sub>z0</sub>) and thus eliminate T1 weighting

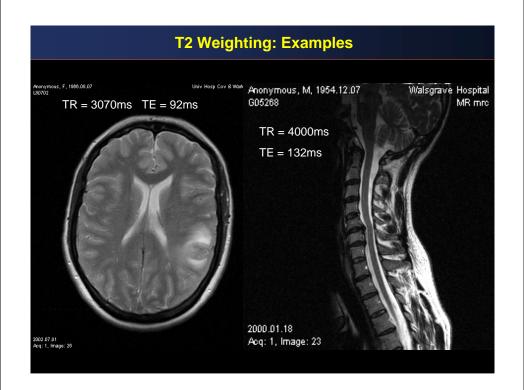
## Long TE

• to give T2 weighting time to develop



# **T2 Weighting**





#### **T1 Weighting**

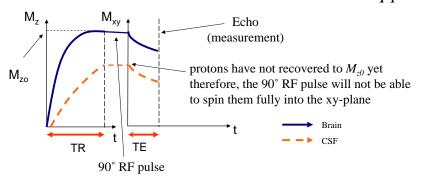
#### Short TR

• to bring out differences in T1 between tissues

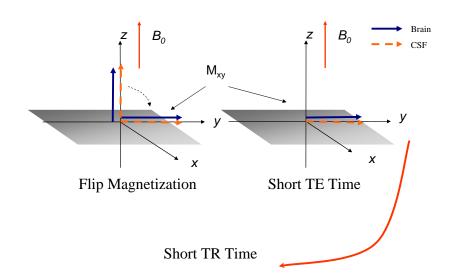
#### Short TE

• so differences in T2 do not have time to appear

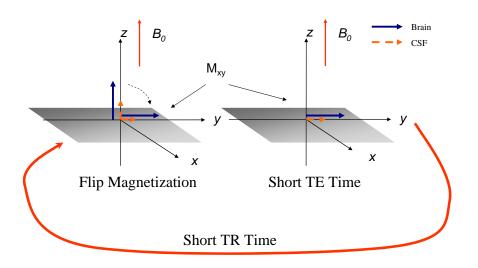
$$M_{xy}^{T1} = M_{xy0}(1 - e^{-\frac{TR}{T1}}) e^{-\frac{TE}{T2}} \Rightarrow M_{z0}(1 - e^{-\frac{TR}{T1}}) \Rightarrow M_{z0} \frac{TR}{T1}$$



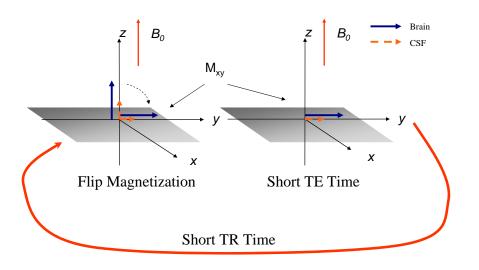
# **T1 Weighting: First Time Around**

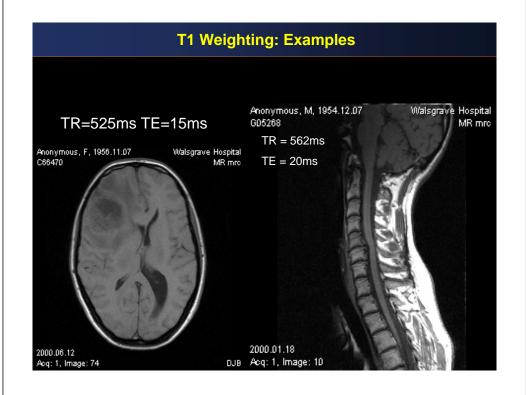


# **T1 Weighting: Second Time Around**



# **T1 Weighting: All Subsequent Rounds**





# T1 vs. T2 Weighting (1)

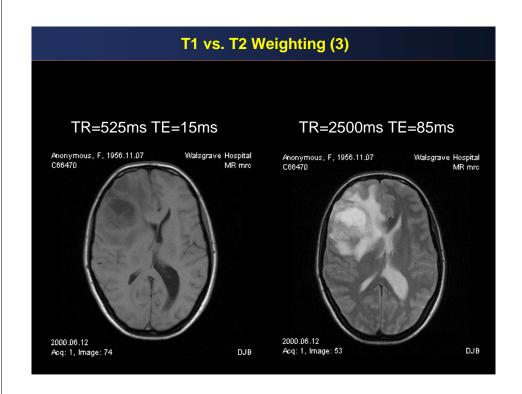
Substance	T1 Weighted	T2 Weighted
Water/Vitrious/CSF	black	light grey or white
Fat	white	light gey
Muscle	grey	grey
Air	black	black
Fatty bone marrow	white	Light grey
Brain white matter	light grey	grey
Brain grey matter	grey	Very light grey

T1 weighted short TR = 500ms short TE < 30ms T2 weighted long TR = 1500ms (3xT1 max) long TE > 80ms





# T1 vs. T2 Weighting (2) Anonymous, M, 1954.12.07 G05268 TR = 562ms TE = 20ms TE = 132ms 2000.01.18 Acq: 1, Image: 10 Anonymous, M, 1954.12.07 Walsgrave Hospital G05268 TR = 4000ms TE = 132ms



# **Proton Density Weighting**

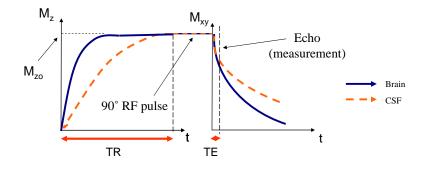
# Long TR

• to give all tissue time to recover and thus eliminate T1 weighting

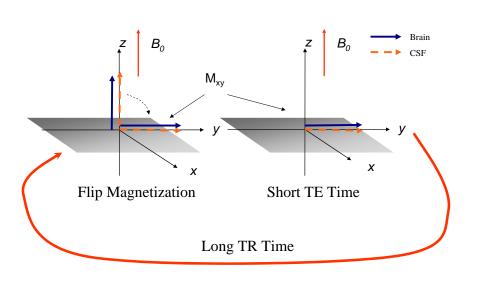
#### Short TE

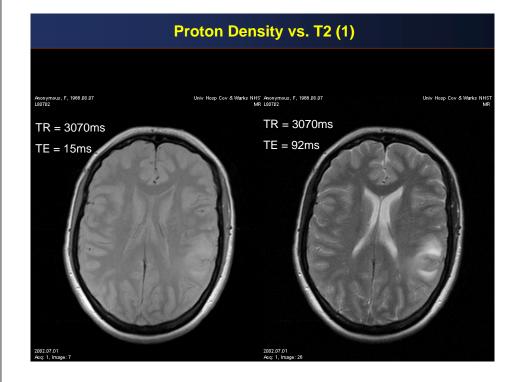
• to give no T2 weighting

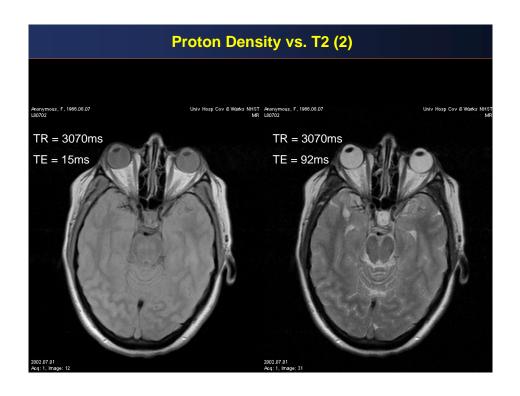
$$M_{xy}^{PD} = M_{xy0} (1 - e^{-\frac{TR}{T1}}) e^{-\frac{TE}{T2}} \Rightarrow M_{z0}$$



# **Proton Density Weighting**



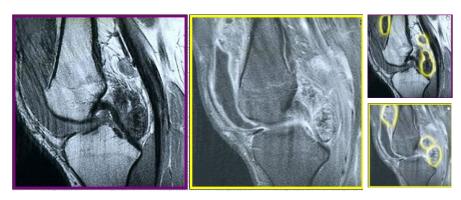




# **Proton Density vs. T1**

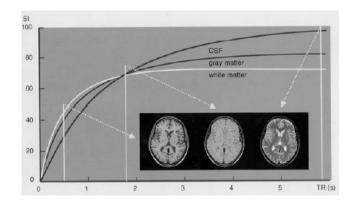
Knee with Pigmented Villonodular Synovitis (PVNS)

 example shows that PD and T1 weighting creates contrast for complementary features



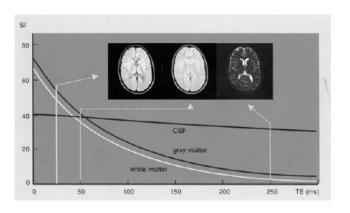
# **Contrast Dependence on TR**

Use TR to maximize contrast among tissues of interest



# **Contrast Dependence on TE**

Use TE to maximize contrast among tissues of interest

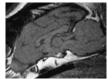


from: Frits Thorsen (U Bergen)

#### **Other Techniques**

#### Gadolinium injection

• can reduce T1 in certain tissues and therefore enhance T1 results



without



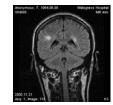
#### Inversion recovery

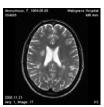
- can provide very strong contrast between tissues with different T1
- involves successive 180° and 90° pulses
- tends to be slower than regular T1

#### FLAIR=Fluid Attenuated Inversion Recovery

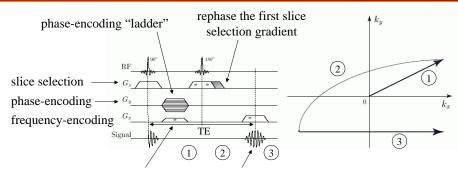
 used often to enhance lesions inside the brain in areas close to the fluid surrounding it

And many more...





#### **Sequences: Spin-Echo**



dephase (=pre-rephase) the frequency-encoding gradient

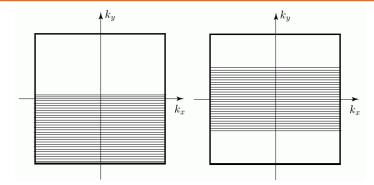
transverse component in phase again signal acquisition

Phase shift:  $\phi(y) = \gamma G_y y T_{phase-encoding}$ 

In k-space:  $G_y = mg_y$  where  $m \in Z$  and  $g_y = \text{constant}$ 

$$k_{y} = \frac{\gamma}{2\pi} m g_{y} T_{phase-encoding}$$

# **Spin-Echo: Practical Considerations**



Half-Fourier space acquisition: possible since spin density is a real function

Although faster, this is not done in practice since a full k-space acquisition improves SNR

Truncated Fourier space acquisition: requires fewer phase encoding steps

Also faster, but reduces the spatial resolution in the ydirection

# **Gradient-Echo Pulse Sequences**

Slow acquisition speed is a major drawback of Spin-Echo

• particularly in  $\rho$  and  $T_2\text{-weighted}$  protocols where TR is long to minimize  $T_1$  effects

Gradient-Echo is an alternative technique designed to overcome these limitations:

- flip angle is less than 90° (usually 20° 60°)
- no spin-echo due to absence of 180° rephasing pulse
- rephasing only by gradient reversal  $\rightarrow$  signal characteristics due to  $T_2^*$ , not  $T_2$

Could obtain images using the same TE, TR values than Spin-Echo

- but this would be not faster than Spin-Echo
- the signal would also be lower due to T<sub>2</sub>\* effects
- instead perform faster earlier acquisition
   → measure T₁ effects

with small flip angles short TRs return a larger signal



#### Comparison: 180° RF Pulse vs. Gradient Echo

180° RF compensates for magnetic field inhomogeneity effects

• example: ferromagnetic particles in a knee joint



Spin-Echo compensates for dephasing

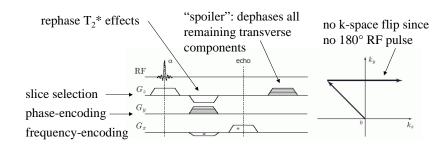
→ surrounding areas OK (with some geometric distortion)



Gradient-Echo cannot compensate for dephasing:

→ surrounding areas have no measurable signal

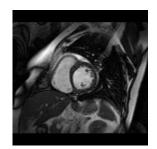
#### **Gradient-Echo: FLASH**



FLASH = Fast Low Angle Shot

typical image size (like in Spin-Echo): 256<sup>2</sup>

16 short axis cardiac images acquired with 2D FLASH Gradient-Echo sequence



# **Three-Dimensional Imaging**

Direct 3D imaging overcomes the problem with thin-slice selection that plagues 2D methods

Needed for many radiological examinations

• wrist, knee, ankle, ...

Requires a second phase-encoding gradient

$$\phi(y,z) = \gamma (mg_y y T_{phase-encoding} + ng_z z T_{slab-selection})$$

The setting of *n* selects the slice

Reconstruction by ways of a 3D FT

- obtain 16, 32, 100, ... 256<sup>2</sup> pixel slices
- assuming a slab thickness of 32 mm, can get 32 1 mm thin slices (impossible with 2D imaging)
- better SNR since each excitation selects all spins within the thick slice and not just a thin slice
- slower speed due to the multiple slices

# **Acquisition and Reconstruction Time**

#### Clinical practice:

- high-quality images useless if it takes tens of minutes to acquire them
- reconstruction time fast since FT implemented in special chips

#### Acquisition time TA determined by:

- total number of excitations
- multiplied by the interval between two successive excitations TR

#### More concretely:

- 2D pulse sequences:  $TA_{2D} = N_{ph} N_{ac} TR$
- 3D pulse sequences:  $TA_{3D} = N_{ph} N_{sl} N_{ac} TR$
- N<sub>ph</sub>: number of phase encoding steps
- N<sub>ac</sub>: number of acquisitions (to improve SNR sometimes multiple acquisitions are taken)
- N<sub>sl</sub>: number of slices (for 3D)

#### 3D Clinical Imaging Example: Brain







Coronal cut

Sagittal cut

Axial cut

#### Assume a 32 x 256 x 256 volume:

- N<sub>ac</sub>=1, N<sub>sl</sub>=32, N<sub>ph</sub>=256
- with Spin-Echo, TR=2000 ms  $\rightarrow$  TA<sub>3D</sub> = 4 hours (infeasible)
- with Gradient-Echo, TR=40ms → TA<sub>3D</sub> = 6 minutes (acceptable)

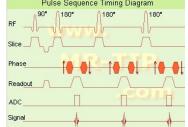
# **Fast Sequences: TurboSE**

#### SE sequence with 3-33 echos

- immediately after first echo apply new phase-encoding
- this selects a different line in k-space

#### Practice:

- divide k-space into *n* segments
- within each excitation, sample one line in each segment



# Example: T2-weighted imaging of a brain

- image size: 256x256
- TR=2500ms
- 4 segments
- · acquisition time:

$$TA_{2D} = \frac{1 \cdot 256 \cdot 2.5}{4} = 160 \text{ secs} < 3 \text{ minutes}$$

#### **Fast Imaging Sequences**

Recall acquisition time equation:

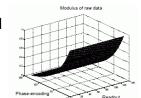
$$TA_{2D} = \frac{N_{ac}N_{ph}TR}{ETL}$$

#### Could get faster by

- decreasing TR (GE (gradient echo) vs. SE (spin echo) sequences)
- decreasing N<sub>ac</sub> (truncated or half Fourier imaging)
- or...generate and acquire multiple echos in one excitiation

# If ETL>1 then rows in k-space are sampled at different echo times

 however, dephasing of T2 (SE) or T2\* (GE) can not be neglected between two different echos, leading to:



$$S(k_x, k_y) = H(k_x, k_y)S(k_x, k_y)$$

this multiplication is a convolution in the spatial domain → blurring

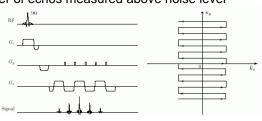
#### **Fast Sequences: HASTE and EPI**

#### Half-Fourier Acquisition with Single-shot Turbo Echo (HASTE)

- all echos are generated within one excitation  $\rightarrow$  ETL=N<sub>ph</sub>
- and thus: TA = TR (gives heavily T2-encoded images)
- in fact: TA = time required to generate and sample ETL echos
- typically: 100 phase-encoding steps take 1s
- application: (motion-less) liver and lung imaging (single breath-hold)

#### Echo planar imaging (EPI)

- fastest sequence available today (acquisition time 100ms)
- GE sequence (no 180º pulse required, in contrast to TSE, HASTE)
- T2\* dephasing limits number of echos measured above noise level
- maximum image size= 128x128
- requires high performance scanners to produce strong gradients
- used in functional MRI



# **Clinical Equipment**



Whole-body 1.5T Philips scanner (1.5 T, super-conducting magnet) standard diagnostic scanner



Open (C-shaped) scanner (0.2 T) helps with claustrophobia open space improves patient handling can be used for MRI-guided procedures SNR low and field homogeneity poor

#### **Operation**



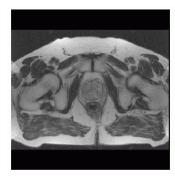


head coil

body coil

# Comparison: CT vs. MRI

Slice across a male prostate

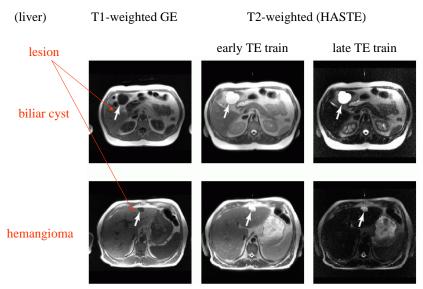


MRI image: T2-weighted turboSE (TE=120ms, TR=6s)



CT image: over-estimates size of prostate (black outline) since MRI can distinguish betyween prostate tissue (white outline) and adjacent peripheral structures

# **MRI Tissue Characterization**



hemangioma fades with TE (typical)

#### **Functional MRI (fMRI)**

#### Capitalizes on the oxygenation of cerebral bloodflow

- brain requires oxygen to function (via metabolic processes)
- active brain areas require more oxygen than inactive areas

#### Oxygen is transported in *hemoglobin* molecules

- in the arteries, hemoglobin carries 4 oxygen molecule
   → oxyhemoglobin
- in the capillaries, hemoglobin deliveres part of the oxgen to the neurons and carries only 2 oxygen molecules → deoxyhemoglobin

#### Distinguishing magnetic properties

- oxyhemoglobin is diamagnetic
- deoxyhemoglobin is paramagnetic → produces field inhomogeneities
   → these decrease T2\* of blood and surrounding tissue

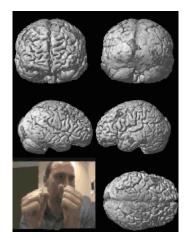
#### Knows as BOLD (Blood Oxygenation-Level Dependent effect)

- brain activation influences oxygen concentration in the blood
- this influences magnetic properties which can be measured with MRI

#### **fMRI Applications**

#### Get insight into:

- memory
- object recognition
- language
- visual cortex
- sensorimotor cortex



#### **Functional MRI (fMRI)**

# When brain cells are active, blood flow must increase to meet neuronal demands

- in fact, blood flow over-compensates
- → too much oxygen in active brain areas
- → T2\* is larger in active areas
- GE (gradient echo) techniques are very sensitive to T2\* variations
- use EPI (echo planar imaging) for fastest acquisition speed

#### Typical experimental setup and acqusition protocol:

- individual performs a certain experiment (for example, finger tapping) and MRI is taken
- acquire two images: one at rest and one under task
- subtract these two images to visualize the active areas

#### Many repetitions needed

- signal difference is very small (2-5%) → low SNR
- alternate periods at rest (30s) with active periods (30s) → 6 min total
- take images every 2-10 s and process statistically

#### **Diffusion Tensor Imaging (DTI)**

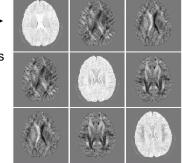
#### Capitalizes on the following facts:

- in different classes of tissue, diffusion of water molecules is different
- also, the diffusion is not isotropic → along fibers the diffusion is much greater than across fibers.

#### Acquisition and analysis

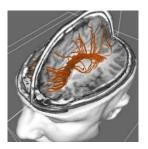
- diffusion-weighted images with diffusion gradients applied in different directions
- areas with high diffusion in that direction will appear dark
- pick a few diffusion directions for this
- perform eigenvector analysis → tensors

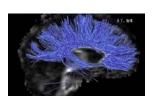




# **Diffusion Tensor Imaging (DTI)**

Brain fibers can now be tracked using the local tensors







# **Diffusion Tensor Imaging (DTI)**

