

Refraction Corrected Transmission Ultrasound Computed Tomography for Application in Breast Imaging

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Joint Research With...

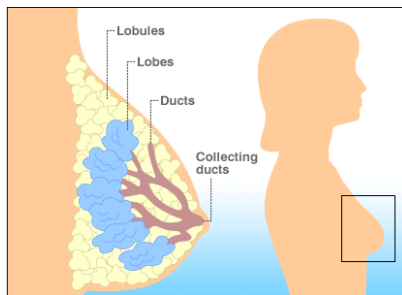


Motivation



Breast cancer is the dominant cancer in women

- in 2007 1.2 million women world-wide had breast cancer
- 30% mortality (465,000)



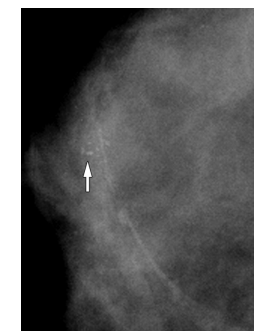
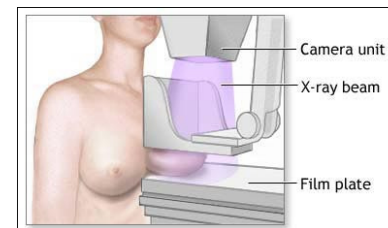
- cancer most common in the ducts (ductal carcinoma)
- cancer also frequent in the lobes or lobules (lobular carcinoma)
- cancer least frequent in the nipple, lymphatic vessels or skin

Early Detection: X-Ray Mammography



Most dominant screening method

- projection of a spread-out breast

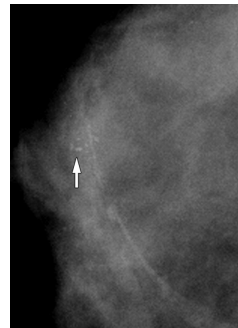
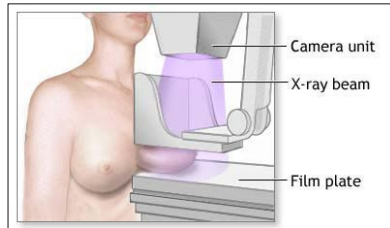


ductal carcinoma

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ductal carcinoma

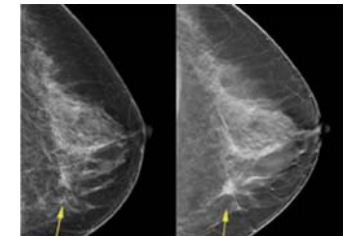
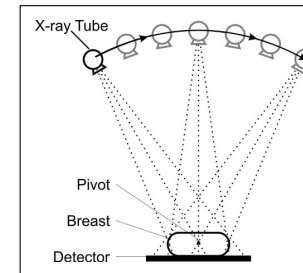
Shortcomings:

- radiation 2-4 times annual natural background radiation
- high false positive rate → 80% biopsies found benign
- breast compression very inconvenient
- post-compression lesions difficult to localize

Early Detection: 3D X-Ray

Tomosynthesis and 3D cone-beam CT

- both provide a slice-per-slice view



mammo

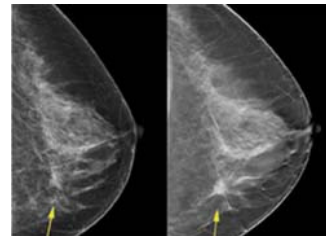
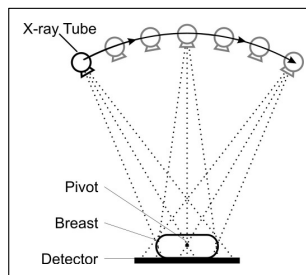
tomo

- much better resolve of small features
- eliminate shortcomings of compression

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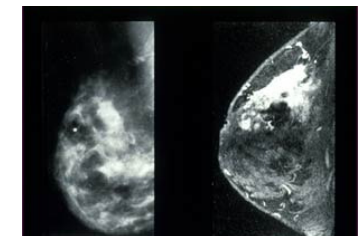
Shortcomings:

- radiation dose still remains

Early Detection: MRI

Most "luxurious" imaging method

- no compression, no radiation



X-ray mammo

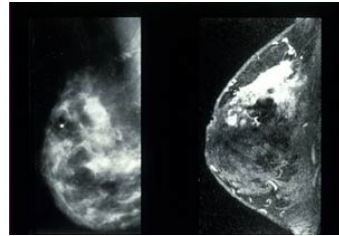
MRI

- able to detect tumors in even dense breasts (young women)
- able to detect early-stage tumors
→ advisable for women at high risk for breast cancer

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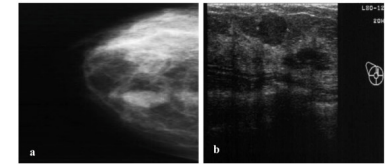
Shortcomings:

- high cost (\$1,000 vs. \$100)

Early Detection: Ultrasound (Echo)

Promising at first glance:

- no radiation, painless, inexpensive
- in fact, echo (reflective) US routinely used as adjunct modality



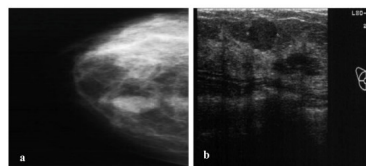
X-ray mammo

echo US

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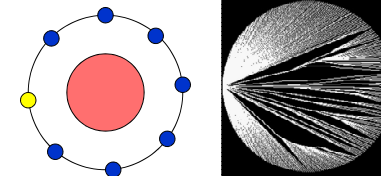
Shortcomings:

- relatively poor quality
- cannot differentiate malignant from benign masses
→ false positive rate will not improve

Ultrasound: Can We Do Better?

Use *transmission* ultrasound

- insert breast in water bath
- arrange piezo transducers as a ring around the breast
- one piezo fires and the others listen and record



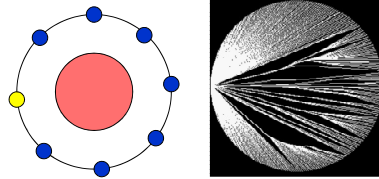
Record at each sensor:

- Time Of Flight (TOF): time of first detected peak
- attenuation: amplitude of first detected peak

Ultrasound: Can We Do Better?

Use *transmission* ultrasound **computed tomography (CT)**

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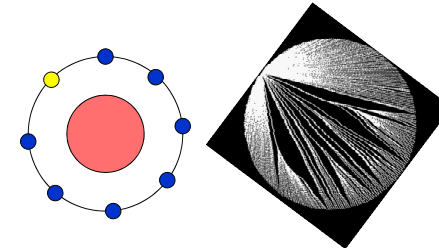
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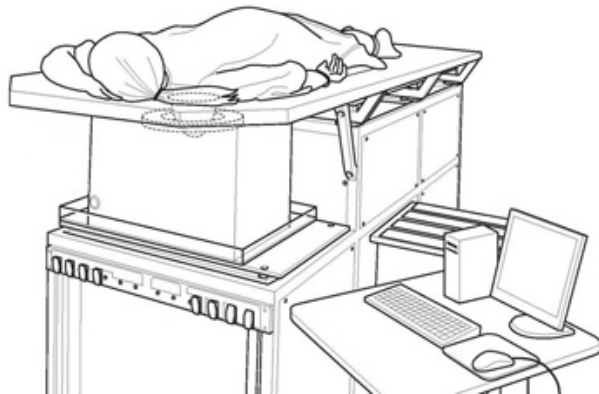
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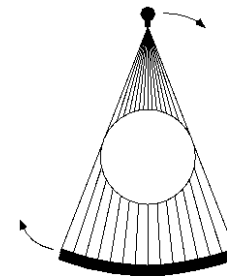
Possible Setup



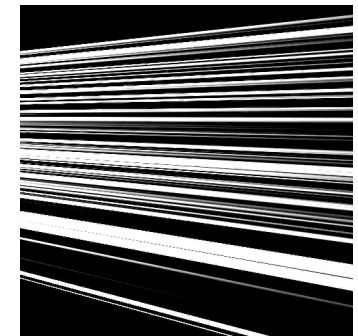
CT Reconstruction: A Primer

A quick primer:

- reconstruction is via back-projection
- linear rays are typically assumed
- well developed for X-ray data



acquisition:
rotating fan beam source

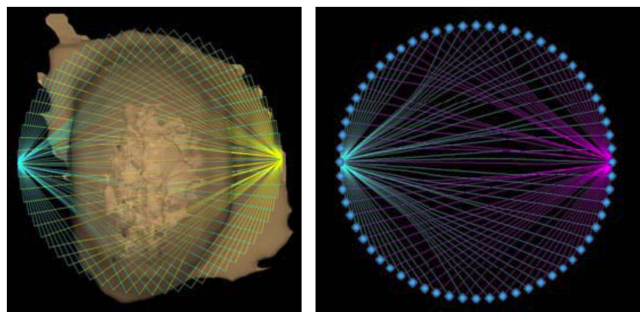


reconstruction:
back-projection of all data

Ultrasound CT: Important Distinctions

In contrast to X-ray CT

- rays are NOT straight

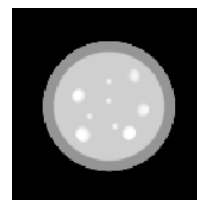


- refraction effects cannot be ignored

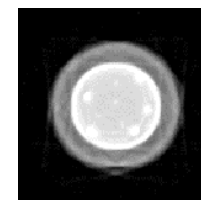
The Importance of Refraction

Reconstruction with and without considering refraction effects

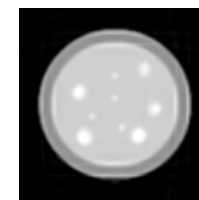
- phantom experiment (simulated data)
- TOF reconstruction



original



without refraction



with refraction

- the breast is a heterogeneous medium
→ proper refraction modeling is important for high fidelity
- this has been known for a long time

Energy Propagation Modeling

Ideally one should solve the acoustic wave equation

Obstacles:

- wave solvers are impractical for clinical routine
→ must obtain a reconstruction in 5 minutes tops
- existing methods for refraction modeling are awkward
- noisy ultrasound data require **iterative** reconstruction schemes
→ cannot afford costly energy propagation schemes

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Our key observations

- sensors look for TOF → the front of the acoustic wave
→ wave front tracking approach seems appropriate
- require an efficient wave tracking procedure
→ further accelerate on GPUs



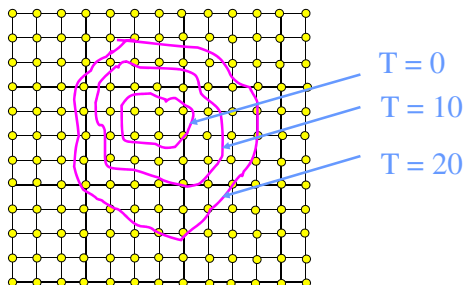
Wave Front Tracking

Propose the use of the Fast Marching Method (FMM)

- well known in computer vision
- also often used for distance transforms

FMM tracks the evolution of the frontier interface

- Step 1: move front under velocity V of grid points on frontier
 - Step 2: record frontier arrival time at each grid point as time field
- Repeat



Iterative CT Reconstruction: A Primer

Predictor - Corrector scheme

Start off with an initial estimate of the object

Simulate projections using this estimated object

- important: simulator should be physically accurate
→ *forward projection* step

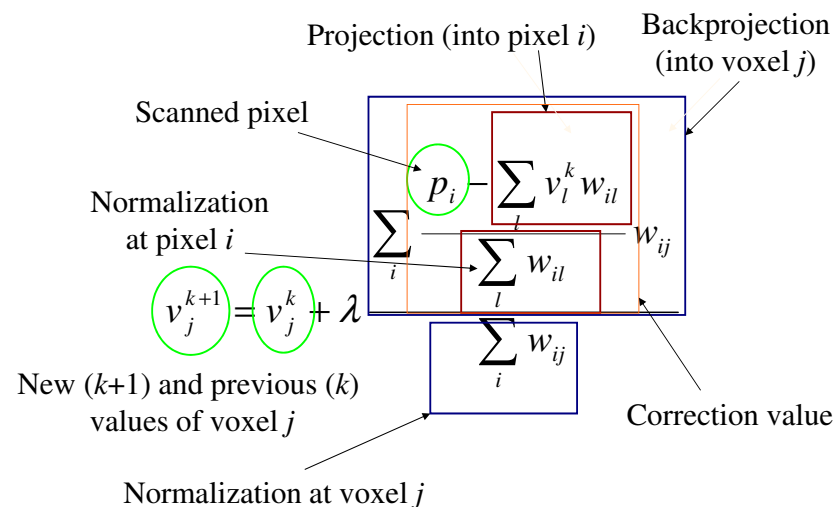
Compute the difference b/w simulated and collected data

Update estimated object by this difference (error)

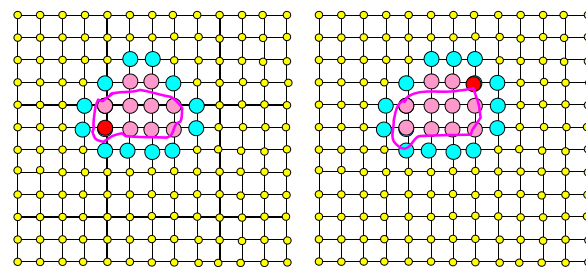
- spread the corrections across the grid
→ *back-projection* step

Iterate as long as corrections are significant

More Specifically: SART/SIRT



FMM-SART: Forward Projection



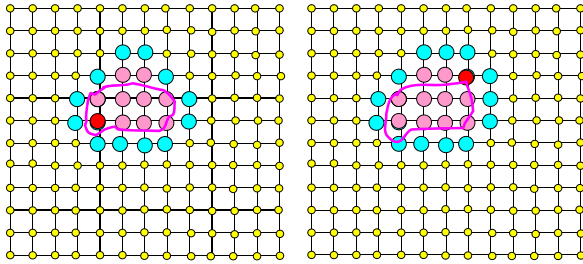
Expanding the wave:
candidate selection

Expanding the wave:
candidate inclusion

● frozen grid point ● narrow-band grid point

Eikonal equation : $(\partial t / \partial x)^2 + (\partial t / \partial y)^2 + (\partial t / \partial z)^2 = 1 / F^2(x, y, z)$

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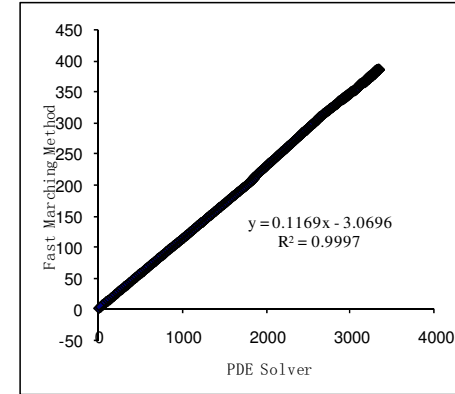
HAFFM: $\partial t / \partial x = (3t(x, y, z) - 4t(x-1, y, z) + t(x-2, y, z)) / 2$

Comparison With Physics Wave Solver

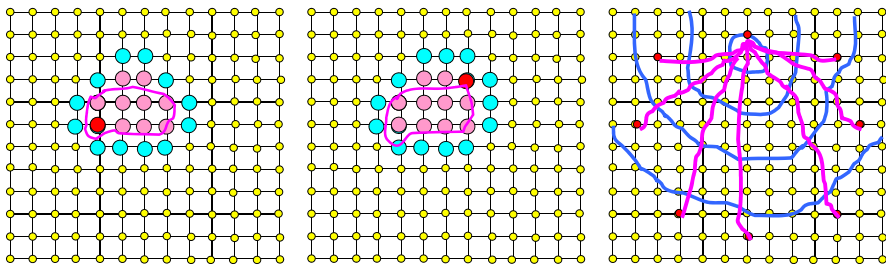


Nearly perfect correlation (F=99%) for TOF simulations

- 95% for attenuation simulations



FMM-SART: Back-Projection



Expanding the wave:
candidate selection

Expanding the wave:
candidate inclusion

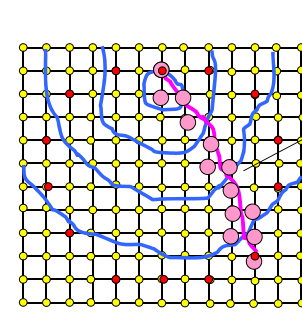
Accurate ray-tracing from
source to sensors

● frozen grid point ● narrow-band grid point

Eikonal equation : $(\partial t / \partial x)^2 + (\partial t / \partial y)^2 + (\partial t / \partial z)^2 = 1 / F^2(x, y, z)$

HAFFM: $\partial t / \partial x = (3t(x, y, z) - 4t(x-1, y, z) + t(x-2, y, z)) / 2$

FMM-SART: Complete Algorithm



Track wave front forward

Compute the ray length L

Compute Correction (TOV = Time Of Flight)
 $\Delta TOF = (TOF_{\text{simulated}} - TOF_{\text{collected}}) / L$

Back project along the ray direction
 $SV = d / t$

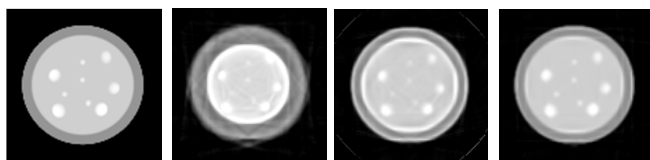
Sound Velocity (SV)
reconstruction

Process all detector rays

Begin next iteration with
near-orthogonal view

Results: Simple Phantom

Sound Speed



Original

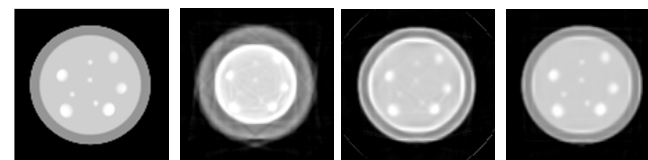
Straight rays

FMM

HAFMM

Results: Simple Phantom

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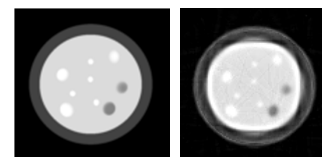
Original

Straight rays

FMM

HAFMM

Attenuation

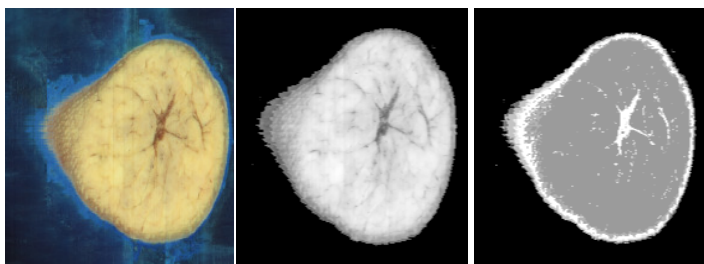


Original

HAFMM

Novel Breast Phantom

Constructed from NIH Visible Woman



A cryosection RGB slice

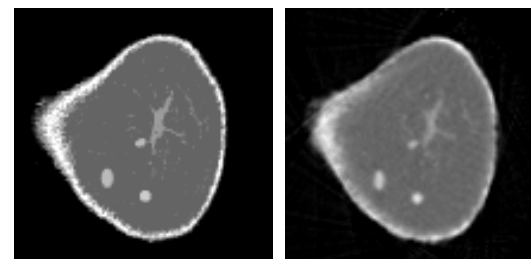
H value transformed to grey-scale

mapping to acoustic speed

Reconstructed Phantom With 3 Lesions

280 transducers

- realistic tissue properties (sound speed, attenuation)
- lesions 6-9 pixels large with densities from 100 to 250



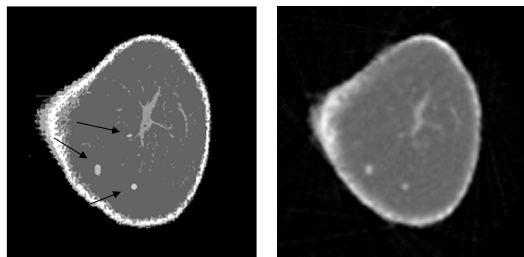
original

reconstructed

Study: Lesion Size

280 transducers

- realistic tissue properties (sound speed, attenuation)
- lesions as small as 2 pixels radius



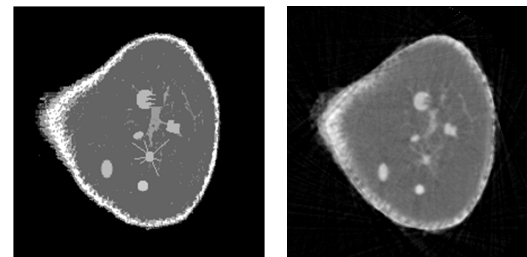
original

reconstructed

Study: Lesion Shape

280 transducers

- realistic tissue properties (sound speed, attenuation)
- lesion shape: spiculated, lobulated, obscured



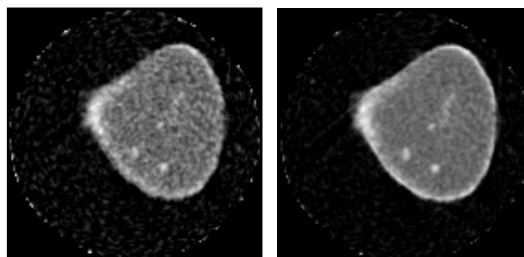
original

reconstructed

Study: Noise

280 transducers

- realistic tissue properties (sound speed, attenuation)
- noise levels: SNR = 5 and 10



SNR=5

SNR=10

Time Performance

Accelerated a variant of FMM (the FIM) on commodity graphics hardware (GPU)

- achieved an 80-fold speedup over CPU implementation
- clinical reconstruction time (5 min) for realistic dataset

Task	Grid size	FMM	FSM		FIM		
		CPU	CPU	Cluster-8 nodes	CPU	GPU (NVIDIA)	
						8086GTX	Tesla
Projection	128^2	0.025	0.031	0.007	0.038	0.00082	0.00072
Projection	256^2	0.097	0.180	0.039	0.189	0.0023	0.0022
Reconstr.	$128^2 \times 40$	2400	2649	506	3316	37.8	30.9
Reconstr.	$256^2 \times 44$	19200	32732	6393	37221	286.2	225.76

Conclusions and Future Work



Devised a high-accuracy transmission ultrasound framework for breast cancer screening

- clinical reconstruction speed achieved by GPU acceleration

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Preliminary studies have been undertaken using acquired ultrasound data

- more focused efforts underway

Questions?



Funding provided by NIH, NSF