

cse357  
ARTIFICIAL INTELLIGENCE

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## Introduction to Predicate Resolution

**PART 1:** Introduction

**PART 2:** Prenex Normal Form and Skolemization

**PART 3:** Clauses and Unification

**PART 4:** Resolution

## PART 1: Introduction

## Introduction

The **resolution proof system** for Predicate Logic operates, as in propositional case on sets of **clauses** and uses a **resolution rule** as the only rule of inference.

The **first goal** of this part is to **define an effective process of transformation** of any formula **A** of a predicate language

$$\mathcal{L} = \mathcal{L}_{\{\neg, \cup, \cap, \Rightarrow\}}(\mathbf{P}, \mathbf{F}, \mathbf{C})$$

into its **logically equivalent set of clauses** **C<sub>A</sub>**

## Introduction

The **second goal** of this part is **extend** the definition of the **propositional resolution rule** to the case of **predicate languages**

**Observe** that we define, as in propositional case, a **clause** as a finite set of **literals**

We define, as before, a **literal** as an **atomic formula** or a **negation** of an **atomic formula**

The **difference** with **propositional resolution** is in the **language** we work with, i.e. what is a **predicate atomic formula** as opposed to **propositional atomic formula**

## Introduction

### Definition (Reminder)

An **atomic formula** of a **predicate language**  $\mathcal{L}(\mathbf{P}, \mathbf{F}, \mathbf{C})$  is any element of  $\mathcal{A}^*$  of the form

$$R(t_1, t_2, \dots, t_n)$$

where  $R \in \mathbf{P}$ ,  $\#R = n$  and  $t_1, t_2, \dots, t_n \in \mathbf{T}$

I.e.  $R$  is **n-ary relational symbol** and  $t_1, t_2, \dots, t_n$  are **any terms**

The set of all **atomic formulas** is denoted by  $\mathcal{AF}$  and is defined as

$$\mathcal{AF} = \{R(t_1, t_2, \dots, t_n) \in \mathcal{A}^* : R \in \mathbf{P}, t_1, t_2, \dots, t_n \in \mathbf{T}, n \geq 1\}$$

## Introduction

We use symbols  $R, Q, P, \dots$  with indices if necessary to **denote** the **atomic formulas**

We define formally the set **L** of all **literals** of  $\mathcal{L}(\mathbf{P}, \mathbf{F}, \mathbf{C})$  as follows

$$\mathbf{L} = \{R : R \in \mathcal{AF}\} \cup \{\neg R : R \in \mathcal{AF}\}$$

### Reminder:

A formula of a **predicate language** is an **open formula** if it does not contain any quantifiers, i.e. it is a formula build out of **atomic formulas** and **propositional connectives** only

## Introduction

A transformation a formula  $A$  of a predicate language into a logically equivalent set  $C_A$  of clauses means that we can **represent** the formula  $A$  as a **certain collection** of **atomic formulas** and **negations of atomic formula**

This means any formula  $A$  of a predicate language can be that **represented** as a certain collection of **open formulas**

In order to achieve this goal we **start** with of methods that allow the **transformation** of any formula  $A$  into an **open formula**  $A^*$  of some **larger language** such that  $A \equiv A^*$

The process is described in the following **PART 2**



## PART 2: Prenex Normal Form and Skolemization

## Some Basic Notions

Let  $\mathcal{L} = (\mathcal{A}, \mathbf{T}, \mathcal{F})$  be a predicate language **determined** by  $\mathbf{P}$ ,  $\mathbf{F}$ ,  $\mathbf{C}$  and the set of propositional connectives  $\{\neg, \cup, \cap, \Rightarrow\}$ , i.e.

$$\mathcal{L} = \mathcal{L}_{\{\neg, \cup, \cap, \Rightarrow\}}(\mathbf{P}, \mathbf{F}, \mathbf{C})$$

Given a formula  $A(x) \in \mathcal{F}$ ,  $t \in \mathbf{T}$ , and  $A(t)$  be a result of **substituting** the term  $t$  for **all free occurrences** of  $x$  in  $A(x)$

### Definition

We say that a term  $t \in \mathbf{T}$  is **free for**  $x$  **in**  $A(x)$ , if **no occurrence** of a variable in  $t$  becomes a **bound** occurrence in the formula  $A(t)$

## Some Basic Notions

Let  $A(x), A(x_1, x_2, \dots, x_n) \in \mathcal{F}$  and  $t, t_1, t_2, \dots, t_n \in \mathbf{T}$

$$A(t), A(t_1, t_2, \dots, t_n)$$

**denotes** the result of replacing respectively **all occurrences** of the free variables  $x, x_1, x_2, \dots, x_n$ , by the terms  $t, t_1, t_2, \dots, t_n$

**We assume** that  $t, t_1, t_2, \dots, t_n$  are **free for**  $x, x_1, x_2, \dots, x_n$ , respectively, **in**  $A$

The assumption that  $t \in \mathbf{T}$  is **free for**  $x$  **in**  $A(x)$  while substituting  $t$  for  $x$ , is **important** because otherwise we would **distort the meaning** of  $A(t)$

This is illustrated by the following example

## Examples

### Example 1

Let  $t = y$  and  $A(x)$  be

$$\exists y(x \neq y)$$

Obviously  $t$  is **not free** for  $y$  in  $A$

The **substitution** of  $t$  for  $x$  produces a formula  $A(t)$  of the form

$$\exists y(y \neq y)$$

which has a **different meaning** than  $\exists y(x \neq y)$

## Examples

### Example 2

Let  $A(x)$  be a formula

$$(\forall y P(x, y) \cap Q(x, z))$$

and  $t = f(x, z)$

We **substitute**  $t$  on a place of  $x$  in  $A(x)$  and we obtain a formula  $A(t)$  of the form

$$(\forall y P(f(x, z), y) \cap Q(f(x, z), z))$$

**None** of the occurrences of the variables  $x, z$  of  $t$  is **bound** in  $A(t)$ , hence we say that  $t = f(x, z)$  is **free** for  $x$  in  $(\forall y P(x, y) \cap Q(x, z))$

## Examples

### Example 3

Let  $A(x)$  be a formula

$$(\forall y P(x, y) \wedge Q(x, z))$$

The term  $t = f(y, z)$  is **not free** for  $x$  in  $A(x)$  because **substituting**  $t = f(y, z)$  on a place of  $x$  in  $A(x)$  we obtain now a formula  $A(t)$  of the form

$$(\forall y P(f(y, z), y) \wedge Q(f(y, z), z))$$

which contain a **bound** occurrence of the variable  $y$  of  $t$  in sub-formula  $(\forall y P(f(y, z), y))$

The other occurrence of  $y$  in sub-formula  $(Q(f(y, z), z))$  is **free**, but it is **not sufficient**, as for term to be **free for  $x$** , **all occurrences** of its variables has to be free in  $A(t)$

## Similar Formulas

Informally, we say that formulas  $A(x)$  and  $A(y)$  are **similar** if and only if  $A(x)$  and  $A(y)$  are the **same** except that  $A(x)$  has **free occurrences** of  $x$  in **exactly** those places where  $A(y)$  has **free occurrence of** of  $y$

We define it formally as follows

### Definition

Let  $x$  and  $y$  be two different variables. We say that the formulas  $A(x)$  and  $A(y) = A(x/y)$  are **similar** and denote it by

$$A(x) \sim A(y)$$

if and only if  $y$  is **free** for  $x$  in  $A(x)$  and  $A(x)$  **has no** free occurrences of  $y$

## Similar Formulas Examples

### Example 1

The formulas  $A(x): \exists z(P(x, z) \Rightarrow Q(x, y))$  and

$$A(y): \exists z(P(y, z) \Rightarrow Q(y, y))$$

are **not similar**;  $y$  is **free for  $x$**  in  $A(x)$  as **no occurrence** of  $y$  becomes a **bound** occurrence in the formula  $A(y)$  but the formula  $A(x)$  **has a free** occurrence of  $y$

### Example 2

The formulas  $A(x): \exists z(P(x, z) \Rightarrow Q(x, y))$  and

$$A(w): \exists z(P(w, z) \Rightarrow Q(w, y))$$

are **similar**;  $w$  is **free for  $x$**  in  $A(x)$  as **no occurrence** of  $w$  becomes a **bound** occurrence in the formula  $A(w)$  and the formula  $A(x)$  **has no free** occurrence of  $w$



## Renaming the Variables

### Fact Renaming the Variables

For any formula  $A(x) \in \mathcal{F}$ , if  $A(x)$  and  $A(y) = A(x/y)$  are similar, i.e.  $A(x) \sim A(y)$  then the following logical equivalences hold

$$\forall x A(x) \equiv \forall y A(y) \quad \text{and} \quad \exists x A(x) \equiv \exists y A(y)$$

### Example 3

We proved in **Example 2** that the formulas  $A(x) \sim A(w)$ , i.e.

$$\exists z (P(x, z) \Rightarrow Q(x, y)) \sim \exists z (P(w, z) \Rightarrow Q(w, y))$$

Hence by the **Fact** we get that

$$\forall x \exists z (P(x, z) \Rightarrow Q(x, y)) \equiv \forall w \exists z (P(w, z) \Rightarrow Q(w, y)),$$

$$\exists x \exists z (P(x, z) \Rightarrow Q(x, y)) \equiv \exists w \exists z (P(w, z) \Rightarrow Q(w, y))$$

## Renaming the Variables

### Replacement Theorem

For any formulas  $A, B \in \mathcal{F}$ ,

if  $B$  is a **sub-formula** of  $A$ , and  $A^*$  is the result of **replacing** zero or more occurrences of  $B$  in  $A$  by a formula  $C$ , and  $B \equiv C$ , then  $A \equiv A^*$

## Renaming Variables Theorem

### Theorem Renaming Variables

For any formula  $A(x), A(y), B \in \mathcal{F}$ ,

if  $A(x)$  and  $A(x/y)$  are similar, i.e.  $A(x) \sim A(y)$ , and the formula  $\forall xA(x)$  or the formula  $\exists xA(x)$  is a **sub-formula** of  $B$ , and  $B^*$  is the result of **replacing** zero or more occurrences of  $A(x)$  in  $B$  by a formula  $\forall yA(y)$  or by a formula  $\exists yA(y)$ , then

$$B \equiv B^*$$

## Naming Variables Apart

### Definition Naming Variables Apart

We say that a formula  $B$  has its variables **named apart** if **no two quantifiers** in  $B$  **bind the same variable** and **no bound variable** is also free

### Theorem Naming Variables Apart

Every formula  $A \in \mathcal{F}$  is **logically equivalent** to one in which all variables are **named apart**

We use the above theorems plus the **equational laws** for quantifiers to prove, as a next step a so called a **Prenex Form Theorem**. In order to do so we first we define an important notion of **prenex normal form** of a formula

## Prenex Normal Form

### Definition Prenex Normal Form

Any formula of the form

$$Q_1 x_1 Q_2 x_2 \dots Q_n x_n B$$

where each  $Q_i$  is a **universal** or **existential quantifier**, i.e.

for all  $1 \leq i \leq n$ ,  $Q_i \in \{\exists, \forall\}$ ,

and  $x_i \neq x_j$  for  $i \neq j$ ,

and the formula  $B$  contains no quantifiers,

is said to be in **Prenex Normal Form (PNF)**

We include the case  $n = 0$  when there are no quantifiers at all

## Prenex Normal Form Theorem

### **Theorem** Prenex Normal Form Theorem

There is an **effective procedure** for transforming any formula  $A \in \mathcal{F}$  into a formula  $B$  in **prenex normal form** such that

$$A \equiv B$$

We describe the **procedure** by induction on the number  $k$  of occurrences of connectives and quantifiers in  $A$

Let's consider now few examples

## Prenex Normal Form Example 1

### Example 1

Given a formula  $A$ :  $\forall x(P(x) \Rightarrow \exists xQ(x))$

**Find** its prenex normal form **PNF**

#### Step 1: Naming Variables Apart

We make all bound variables in  $A$  different, by **substituting**  $\exists xQ(x)$  by logically equivalent formula  $\exists yQ(y)$  in  $A$  as  $Q(x)$  and  $Q(x/y)$  **are similar**

We hence transformed  $A$  into an equivalent formula  $A'$

$$\forall x(P(x) \Rightarrow \exists yQ(y))$$

with all its **variables named apart**

## Prenex Normal Form Example 1

### Step 2: Pull Out Quantifiers

Now, we can apply the equational law

$$(C \Rightarrow \exists y Q(y)) \equiv \exists y (C \Rightarrow Q(y))$$

to the sub-formula  $B : (P(x) \Rightarrow \exists y Q(y))$  of  $A'$   
for  $C = P(x)$ , as  $P(x)$  does not contain the variable  $y$

We get its equivalent formula  $B^* : \exists y (P(x) \Rightarrow Q(y))$

We substitute now  $B^*$  on place of  $B$  in  $A'$  and get  $A''$

$$\forall x \exists y (P(x) \Rightarrow Q(y))$$

such that  $A'' \equiv A' \equiv A$

$A''$  is a required prenex normal form **PNF** for  $A$



## Prenex Normal Form Example 2

### Example 1

Let's now find **PNF** for the formula **A**:

$$(\exists x \forall y R(x, y) \Rightarrow \forall y \exists x R(x, y))$$

#### Step 1: Rename Variables Apart

Take a sub-formula  $B(x, y) : \forall y \exists x R(x, y)$  of **A**

Rename variables in  $B(x, y)$ , i.e. get

$$B(x/z, y/w) : \forall z \exists w R(z, w)$$

Replace  $B(x, y)$  by  $B(x/z, y/w)$  in **A** and get

$$(\exists x \forall y R(x, y) \Rightarrow \forall z \exists w R(z, w))$$

## Prenex Normal Form Example 2

### Step 2: Pull out quantifiers

We use corresponding equational laws for quantifiers to pull out **first** quantifiers  $\forall x \exists y$  and then quantifiers  $\forall z \exists w$  and get the following **PNF** for  $A$

$$\exists x \forall y \exists z \forall w (R(x, y) \Rightarrow R(z, w))$$

**Observe** we can also perform **Step 2** by pulling out **first** the quantifiers  $\forall z \exists w$  and then quantifiers  $\forall x \exists y$  and obtain **another PNF** for  $A$

$$\exists z \forall w \exists x \forall y (R(x, y) \Rightarrow R(z, w))$$

## Skolemization

As the next step we show how any formula  $A$  in its **prenex normal form PNF** can be **transformed** into a certain **open formula  $A^*$** , such that  $A \equiv A^*$

The open formula  $A^*$  belongs to a **richer language** than the language of the initial formula  $A$

The **transformation process** **adds new constants**, called **Skolem constants** and **new function symbols**, called **Skolem function symbols** to the initial language to which the formula  $A$  belongs

The whole **process** is called the **Skolemization** of the **initial language**

Such build **extension** of the initial language is called the **Skolem extension**

## Elimination of Quantifiers

Given a formula **A** be in its **Prenex Normal Form PNF**

$$Q_1 x_1 Q_2 x_2 \dots Q_n x_n B(x_1, x_2, \dots x_n)$$

where each  $Q_i$  is a **universal** or **existential** quantifier, i.e. for all  $1 \leq i \leq n$ ,  $Q_i \in \{\exists, \forall\}$ ,  $x_i \neq x_j$  for  $i \neq j$ , and  $B(x_1, x_2, \dots x_n)$  **contains no quantifiers**

We describe now a procedure of **elimination of all quantifiers** from the formula **PNFA**

The procedure transforms **PNF A** into a **logically equivalent open formula  $A^*$**

We assume that **A** is **closed**

If it is not closed we form its **closure** instead

Definition of **closure** follows

## Closure of a Formula

### Closure of a Formula

For any formula  $A \in \mathcal{F}$ , a **closure** of  $A$  is a **closed** formula  $A'$  obtained from  $A$  by **prefixing** in universal quantifiers all those variables that are **free** in  $A$ ; i.e. the following holds

if  $A(x_1, \dots, x_n)$  then  $A' \equiv A$  is

$$\forall x_1 \forall x_2 \dots \forall x_n A(x_1, x_2, \dots, x_n)$$

### Example

Let  $A$  be a formula

$$(P(x, y) \Rightarrow \neg \exists z R(x, y, z))$$

its **closure** i.e.  $A' \equiv A$  is

$$\forall x \forall y (P(x, y) \Rightarrow \neg \exists z R(x, y, z))$$

## Elimination of Quantifiers

Given a formula **A** in its **closed PNF** form

$$Q_1 x_1 Q_2 x_2 \dots Q_n x_n B(x_1, x_2, \dots, x_n)$$

We consider 3 cases

### Case 1

All quantifiers  $Q_i$  for  $1 \leq i \leq n$  are **universal**, i.e. the formula **A** is

$$\forall x_1 \forall x_2 \dots \forall x_n B(x_1, x_2, \dots, x_n)$$

We **replace** the formula **A** by the **open formula A\***

$$B(x_1, x_2, \dots, x_n)$$

## Elimination of Quantifiers

### Case 2

All quantifiers  $Q_i$  for  $1 \leq i \leq n$  are **existential**, i.e. formula  $A$  is

$$\exists x_1 \exists x_2 \dots \exists x_n B(x_1, x_2, \dots, x_n)$$

We **replace** the formula  $A$  by the **open formula**  $A^*$

$$B(c_1, c_2, \dots, c_n)$$

where  $c_1, c_2, \dots, c_n$  and **new individual constants added** to our original language  $\mathcal{L}$

We call such **individual constants** added to the original language **Skolem constants**

## Elimination of Quantifiers; Step 1

### Case 3

The quantifiers in **A** are **mixed**

We **eliminate mixed quantifiers** one by one and step by step depending on first, and then the consecutive quantifiers in the **closed PNF** formula **A**

$$Q_1 x_1 Q_2 x_2 \dots Q_n x_n B(x_1, x_2, \dots, x_n)$$

We have **two possibilities** for the first quantifier  $Q_1 x_1$ , namely **P1**  $Q_1 x_1$  is **universal** or **P2**  $Q_1 x_1$  is **existential**

Consider **P1**

First quantifier in **A** is universal, i. e. **A** is

$$\forall x_1 Q_2 x_2 \dots Q_n x_n B(x_1, x_2, \dots, x_n)$$

### Step 1

We **replace** **A** by the following formula **A<sub>1</sub>**

$$Q_2 x_2 Q_3 x_3 \dots Q_n x_n B(x_1, x_2, x_3, \dots, x_n)$$

We have **eliminated** the quantifier  $Q_1$  in this case



## Elimination of Quantifiers; Step 1

Consider **P2**

First quantifier in **A** is **existential**, i. e. **A** is

$$\exists x_1 Q_2 x_2 \dots Q_n x_n B(x_1, x_2, \dots, x_n)$$

We **replace** **A** by a following formula **A<sub>1</sub>**

$$Q_2 x_2 \dots Q_n x_n B(b_1, x_2, \dots, x_n)$$

where **b<sub>1</sub>** is a **new constant** symbol **added** to our original language  $\mathcal{L}$

We call such constant symbol added to the language **Skolem constant** symbol

We have **eliminated** the quantifier **Q<sub>1</sub>** in this case

We have covered **all cases** and this **ends** the **Step 1**

## Elimination of Quantifiers; Step 2

### Step 2 Elimination of $Q_2x_2$

Consider now the **PNF** formula  $A_1$  from **Step1- P1**

$$Q_2x_2 \dots Q_nx_n B(x_1, x_2, \dots x_n)$$

Remark that the formula  $A_1$  might not be closed

We have again two possibilities for elimination of the quantifier  $Q_2x_2$ , namely **P1**  $Q_2x_2$  is **universal** or **P2**  $Q_2x_2$  is **existential**

Consider **P1**

First quantifier in  $A_1$  is **universal**, i.e.  $A_1$  is

$$\forall x_2 Q_3x_3 \dots Q_nx_n B(x_1, x_2, x_3, \dots x_n)$$

We **replace**  $A_1$  by the following  $A_2$

$$Q_3x_3 \dots Q_nx_n B(x_1, x_2, x_3, \dots x_n)$$

We have **eliminated** the quantifier  $Q_2$  in this case

## Elimination of Quantifiers; Step 2

Consider **P2**

First quantifier in  $A_1$  is **existential**, i.e.  $A_1$  is

$$\exists x_2 Q_3 x_3 \dots Q_n x_n B(x_1, x_2, x_3, \dots x_n)$$

Observe that now the variable  $x_1$  is a **free** variable in  $B(x_1, x_2, x_3, \dots x_n)$  and hence in  $A_1$  We replace  $A_1$  by the following  $A_2$

$$Q_3 x_3 \dots Q_n x_n B(x_1, f(x_1), x_3, \dots x_n)$$

where  $f$  is a **new** one argument **functional symbol added** to our original language  $\mathcal{L}$

We call such functional symbols added to the original language **Skolem** functional symbols

We have **eliminated** the quantifier  $Q_2$  in this case

## Elimination of Quantifiers; Step 2

Consider now the **PNF** formula  $A_1$  from **Step1 - P2**

$$Q_2 x_2 Q_3 x_3 \dots Q_n x_n B(b_1, x_2, \dots x_n)$$

Again we have two cases

Consider **P1**

First quantifier in  $A_1$  is **universal**, i.e.  $A_1$  is

$$\forall x_2 Q_3 x_3 \dots Q_n x_n B(b_1, x_2, x_3, \dots x_n)$$

We replace  $A_1$  by the following  $A_2$

$$Q_3 x_3 \dots Q_n x_n B(b_1, x_2, x_3, \dots x_n)$$

We have **eliminated** the quantifier  $Q_2$  in this case

## Elimination of Quantifiers; Step 2

Consider **P2**

First quantifier in  $A_1$  is **existential**, i.e.  $A_1$  is

$$\exists x_2 Q_3 x_3 \dots Q_n x_n B(b_1, x_2, x_3, \dots, x_n)$$

We replace  $A_1$  by the following  $A_2$

$$Q_3 x_3 \dots Q_n x_n B(b_1, b_2, x_3, \dots, x_n)$$

where  $b_2 \neq b_1$  is a **new Skolem constant** symbol **added** to our original language  $\mathcal{L}$

We have **eliminated** the quantifier  $Q_2$  in this case

We have covered **all cases** and this **ends** the **Step 2**

## Elimination of Quantifiers; Step 3

### Step 3 Elimination of $Q_3x_3$

Let's now consider, as an **example** a formula  $A_2$  from **Step 2**;  
**P1** i.e. the formula

$$Q_3x_3 \dots Q_nx_n B(x_1, x_2, x_3, \dots x_n)$$

We have again **2 choices** to consider, but will describe only the following

**P2** First quantifier in  $A_2$  is **existential**, i. e.  $A_2$  is

$$\exists x_2 Q_4x_4 \dots Q_nx_n B(x_1, x_2, x_3, x_4, \dots x_n)$$

Observe that now the variables  $x_1, x_2$  are **free** variables in  $B(x_1, x_2, x_3, \dots x_n)$  and hence in  $A_2$

We replace  $A_2$  by the following  $A_3$

$$Q_4x_4 \dots Q_nx_n B(x_1, x_2, g(x_1, x_2), x_4 \dots x_n)$$

where  $g$  is a **new** two argument **functional symbol** **added** to our original language  $\mathcal{L}$

We have **eliminated** the quantifier  $Q_3$  in this case

## Elimination of Quantifiers; Step i

### Step i

At each **Step i** for  $1 \leq i \leq n$ ) we build a **binary tree** of possibilities **P1**  $Q_i x_i$  is **universal** or **P2**  $Q_i x_i$  is **existential** and as result we obtain a

formula  $A_i$  with one less quantifier

The elimination process builds a sequence of formulas

$$A, A_1, A_2, \dots, A_n = A^*$$

where the formula  $A$  belongs to our original language

$$\mathcal{L} = \mathcal{L}_{\{\neg, \cup, \cap, \Rightarrow\}}(\mathbf{P}, \mathbf{F}, \mathbf{C}),$$

the **open** formula  $A^*$  belongs to its **Skolem extension**

The **Skolem extension**  $S\mathcal{L}$  is obtained from  $\mathcal{L}$  in the quantifiers elimination process and

$$S\mathcal{L} = \mathcal{L}_{\{\neg, \cup, \cap, \Rightarrow\}}(\mathbf{P}, \mathbf{F} \cup \mathbf{SF}, \mathbf{C} \cup \mathbf{SC})$$

## Elimination of Quantifiers Result

**Observe** that in the elimination process an **universal** quantifier introduces **free** variables in the formula

$$B(x_1, x_2, \dots, x_n)$$

The **elimination** of an **existential** quantifier that follows **universal** quantifiers introduces a **new functional** symbol with number of arguments equal the number of universal quantifiers preceding it

The **elimination** of an **existential** quantifier that **does not** follow any **universal** quantifiers introduces a **new constant** symbol

The resulting **open** formula  $A^*$  is logically equivalent to the  $\exists$ PNF formula  $A$



## Example 1

### Example 1

Let  $A$  be a closed **PNF** formula

$$\forall y_1 \exists y_2 \forall y_3 \exists y_4 B(y_1, y_2, y_3, y_4)$$

We eliminate  $\forall y_1$  and get a formula  $A_1$

$$\exists y_2 \forall y_3 \exists y_4 B(y_1, y_2, y_3, y_4)$$

We eliminate  $\exists y_2$  by replacing  $y_2$  by  $h(y_1)$

$h$  is a **new** one argument **functional** symbol **added** to our original language  $\mathcal{L}$

We get a formula  $A_2$

$$\forall y_3 \exists y_4 B(y_1, h(y_1), y_3, y_4)$$

## Example 1

Given the formula  $A_2$

$$\forall y_3 \exists y_4 B(y_1, h(y_1), y_3, y_4)$$

We eliminate  $\forall y_3$  and get a formula  $A_3$

$$\exists y_4 B(y_1, h(y_1), y_3, y_4)$$

We eliminate  $\exists y_4$  by replacing  $y_4$  by  $f(y_1, y_3)$ , where  $f$  is a **new** two argument **functional** symbol **added** to our original language  $\mathcal{L}$

We get a formula  $A_4$  that is our resulting **open** formula  $A^*$

$$B(y_1, h(y_1), y_3, f(y_1, y_3))$$

## Example 2

### Example 2

Let now  $A$  be a **PNF** formula

$$\exists y_1 \forall y_2 \forall y_3 \exists y_4 \exists y_5 \forall y_6 B(y_1, y_2, y_3, y_4, y_4, y_5, y_6)$$

We eliminate  $\exists y_1$  and get a formula  $A_1$

$$\forall y_2 \forall y_3 \exists y_4 \exists y_5 \forall y_6 B(b_1, y_2, y_3, y_4, y_4, y_5, y_6)$$

where  $b_1$  is a **new constant** symbol **added** to our original language  $\mathcal{L}$

We eliminate  $\forall y_2, \forall y_3$  and get formulas  $A_2, A_3$ ; here is the formula  $A_3$

$$\exists y_4 \exists y_5 \forall y_6 B(b_1, y_2, y_3, y_4, y_4, y_5, y_6)$$

## Example 2

We eliminate  $\exists y_4$  and get a formula  $A_4$

$$\exists y_5 \forall y_6 B(b_1, y_2, y_3, g(y_2, y_3), y_5, y_6)$$

where  $g$  is a **new** two argument **functional** symbol **added** to our original language  $\mathcal{L}$

We eliminate  $\exists y_5$  and get a formula  $A_5$

$$\forall y_6 B(b_1, y_2, y_3, g(y_2, y_3), h(y_2, y_3), y_6)$$

where  $h$  is a **new** two argument **functional** symbol **added** to our original language  $\mathcal{L}$

We eliminate  $\forall y_6$  and get a formula  $A_6$  that is the resulting **open** formula  $A^*$

$$B(b_1, y_2, y_3, g(y_2, y_3), h(y_2, y_3), y_6)$$

## Open Formulas to Clauses

### Definition (Reminder)

An **atomic formula** of a **predicate language**  $\mathcal{L}(\mathbf{P}, \mathbf{F}, \mathbf{C})$  is any element of  $\mathcal{A}^*$  of the form

$$R(t_1, t_2, \dots, t_n)$$

where  $R \in \mathbf{P}$ ,  $\#R = n$  and  $t_1, t_2, \dots, t_n \in \mathbf{T}$

I.e.  $R$  is  **$n$ -ary relational symbol** and  $t_1, t_2, \dots, t_n$  are **any terms**

The set of all **atomic formulas** is denoted by  $\mathcal{AF}$  and is defined as

$$\mathcal{AF} = \{R(t_1, t_2, \dots, t_n) \in \mathcal{A}^* : R \in \mathbf{P}, t_1, t_2, \dots, t_n \in \mathbf{T}, n \geq 1\}$$

## Literals and Open Formulas

**Definition** We use symbols  $R, Q, P, \dots$  with indices if necessary to **denote** the **atomic formulas**

We define formally the set **L** of all **literals** of  $\mathcal{L}(\mathbf{P}, \mathbf{F}, \mathbf{C})$  as follows

$$\mathbf{L} = \{R : R \in \mathcal{AF}\} \cup \{\neg R : R \in \mathcal{AF}\}$$

### Definition

A set  $\mathcal{OF}$  of all **open formulas** of a predicate language  $\mathcal{L} = \mathcal{L}_{\{\neg, \cup, \cap, \Rightarrow\}}(\mathbf{P}, \mathbf{F}, \mathbf{C})$  is the **smallest** set for which the following conditions are satisfied

- (1)  $\mathcal{AF} \subseteq \mathcal{OF}$  (atomic formulas are open formulas)
- (2) If  $A \in \mathcal{OF}$ , then  $\neg A \in \mathcal{OF}$
- (3) If  $A, B \in \mathcal{OF}$ , then  $(A \cup B), (A \cap B), (A \Rightarrow B) \in \mathcal{OF}$

## Decomposition Rules for Open Formulas

Here are the **decomposition rules** needed to transform open formulas into logically equivalent sets of clauses

### Disjunction decomposition rules

$$(U) \frac{\Gamma', (A \cup B), \Delta}{\Gamma', A, B, \Delta}, \quad (\neg U) \frac{\Gamma', \neg(A \cup B), \Delta}{\Gamma', \neg A, \Delta ; \Gamma', \neg B, \Delta}$$

### Conjunction decomposition rules

$$(\cap) \frac{\Gamma', (A \cap B), \Delta}{\Gamma', A, \Delta ; \Gamma', B, \Delta}, \quad (\neg \cap) \frac{\Gamma', \neg(A \cap B), \Delta}{\Gamma', \neg A, \neg B, \Delta}$$

where  $\Gamma' \in \mathbf{L}^*$   $\Delta \in \mathcal{OF}^*$ ,  $A, B \in \mathcal{OF}$

## Decomposition Rules

### Implication decomposition rules

$$(\Rightarrow) \frac{\Gamma', (A \Rightarrow B), \Delta}{\Gamma', \neg A, B, \Delta}, \quad (\neg \Rightarrow) \frac{\Gamma', \neg(A \Rightarrow B), \Delta}{\Gamma', A, \Delta ; \Gamma', \neg B, \Delta}$$

### Negation decomposition rule

$$(\neg\neg) \frac{\Gamma', \neg\neg A, \Delta}{\Gamma', A, \Delta}$$

where  $\Gamma' \in \mathbf{L}^*$ ,  $\Delta \in \mathbf{OF}^*$ ,  $A, B \in \mathbf{OF}$



## Tree Decomposition Rules

We write the **decomposition rules** in a **visual tree form** as follows

### Tree Decomposition Rules

( $\cup$ ) rule

$$\Gamma', (A \cup B), \Delta$$
$$| (\cup)$$
$$\Gamma', A, B, \Delta$$

## Tree Decomposition Rules

$(\neg\cup)$  rule

$$\Gamma', \neg(A \cup B), \Delta$$

$$\bigwedge(\neg\cup)$$

$$\Gamma', \neg A, \Delta \quad \Gamma', \neg B, \Delta$$

$(\cap)$  rule

$$\Gamma', (A \cap B), \Delta$$

$$\bigwedge(\cap)$$

$$\Gamma', A, \Delta \quad \Gamma', B, \Delta$$

## Tree Decomposition Rules

$(\neg\cup)$  rule

$$\Gamma', \neg(A \cap B), \Delta$$

$$| (\neg\cap)$$

$$\Gamma', \neg A, \neg B, \Delta$$

$(\Rightarrow)$  rule

$$\Gamma', (A \Rightarrow B), \Delta$$

$$| (\cup)$$

$$\Gamma', \neg A, B, \Delta$$

## Tree Decomposition Rules

$(\neg \Rightarrow)$  rule

$$\Gamma', \neg(A \Rightarrow B), \Delta$$

$$\wedge (\neg \Rightarrow)$$

$$\Gamma', A, \Delta$$

$$\Gamma', \neg B, \Delta$$

$(\neg \neg)$  rule

$$\Gamma', \neg \neg A, \Delta$$

$$\mid (\neg \neg)$$

$$\Gamma', A, \Delta$$

## Decomposable, Indecomposable

### Definition: Decomposable Formula

A formula that is **not a literal**, i.e.  $A \in \mathcal{OF} - \mathbf{L}$  is called a **decomposable formula**

### Definition: Decomposable Sequence

A sequence  $\Gamma$  that contains a **decomposable formula** is called a **decomposable sequence**

### Definition: Indecomposable Sequence

A sequence  $\Gamma'$  built only out of literals, i.e.  $\Gamma' \in \mathbf{L}^*$  is called an **indecomposable sequence**

## Definitions and Observations

### Observation 1

Decomposition rules are functions with disjoint domains, i.e.

For any **decomposable** sequence, i.e. for any  $\Gamma \notin L^*$

there is **exactly one** decomposition rule that can be applied to it

This rule is **determined** by the **first decomposable formula** in  $\Gamma$  and by the **main connective** of that formula

### Observation 2

If the **main connective** of the **first** decomposable formula is  $\cup, \cap, \Rightarrow,$

then the **decomposition rule** determined by it is  $(\cup), (\cap), (\Rightarrow),$  respectively

## Definitions and Observations

### Observation 3

If the **main connective** of the **first** decomposable formula **A** is negation  $\neg$

then the **decomposition rule** is determined by the **second connective** of the formula **A**

The corresponding **decomposition rules** are

$(\neg \cup)$ ,  $(\neg \cap)$ ,  $(\neg \neg)$ ,  $(\neg \Rightarrow)$

### Observation 4

For any sequence  $\Gamma \in \mathcal{OF}^*$ ,

$\Gamma \in \mathbf{L}^*$  or  $\Gamma$  is in the **domain** of **exactly one** of  
**Decomposition Rules**

## Decomposition Tree Definition

### Definition: Decomposition Tree $T_A$

For each  $A \in \mathcal{OF}$ , a **decomposition tree**  $T_A$  is a tree build as follows

#### Step 1.

The formula  $A$  is the **root** of  $T_A$

For any other **node**  $\Gamma$  of the tree we follow the steps below

#### Step 2.

If  $\Gamma$  is **indecomposable** then  $\Gamma$  becomes a **leaf** of the tree



## Decomposition Tree Definition

### Step 3.

If  $\Gamma$  is **decomposable**, then we **traverse**  $\Gamma$  from **left** to **right** and identify the **first decomposable formula**  $B$

**We put** its premiss as a **node below**, or its left and right premisses as the left and right **nodes below**, respectively

### Step 4.

We **repeat** steps 2 and 3 until we obtain only **leaves**

## Decomposition Tree and Clauses

Directly from **Observations 1 - 4** and the fact that premisses and conclusion in all decomposition rules are logically equivalent we get the following

### Theorem

For any  $A \in \mathcal{OF}$ , its decomposition tree  $T_A$  is unique and its leaves form a set of clauses that is logically equivalent to the formula  $A$

More precisely, let  $\Gamma_1, \Gamma_2, \dots, \Gamma_n \in \mathbf{L}^*$  be all leaves of  $T_A$

The set of all clauses corresponding to the formula  $A$  is

$$\mathbf{C}_A = \{\{\Gamma_1\}, \{\Gamma_2\}, \dots, \{\Gamma_n\}\}$$

and

$$\mathbf{C}_A \equiv A$$

## Example

The tree  $T_A$

$$(((P(x) \Rightarrow Q(y)) \wedge \neg R(x)) \vee (P(x) \Rightarrow R(x)))$$

| ( $\vee$ )

$$((P(x) \Rightarrow Q(y)) \wedge \neg R(x)), (P(x) \Rightarrow R(x))$$

$\wedge$  ( $\wedge$ )

$$(P(x) \Rightarrow Q(y)), (P(x) \Rightarrow R(x)) \quad \neg R(x), (P(x) \Rightarrow R(x))$$

| ( $\Rightarrow$ )

$$\neg P(x), Q(y), (P(x) \Rightarrow R(x))$$

| ( $\Rightarrow$ )

$$\neg R(x), \neg P(x), R(x)$$

| ( $\Rightarrow$ )

$$\neg P(x), Q(y), \neg P(x), R(x)$$

## Example

The leaves of  $\mathbf{T}_A$  are

$$\neg P(x), Q(y), \neg P(x), R(x) \quad \text{and} \quad \neg R(x), \neg P(x), R(x)$$

The clauses corresponding to the leaves are

$$C_1 = \{\neg P(x), Q(y), R(x)\} \quad \text{and} \quad C_2 = \{\neg R(x), \neg P(x), R(x)\}$$

The set of all clauses corresponding to the formula  $A$  is

$$\mathbf{C}_A = \{C_1, C_2\}$$

$$\mathbf{C}_A = \{\{\neg P(x), Q(y), R(x)\}, \{\neg R(x), \neg P(x), R(x)\}\}$$

## Unification

**Unification** is the process of determining whether **two** atomic formulas, i.e. **two positive literals** can be made identical by appropriate **substitution** for their variables

**Unification** is an essential part of resolution

**Unification** is defined in terms of a notion of a **substitution**

## Substitution

Intuitively, a **substitution** is a set of associations between **variables** and **terms** in which

1. each **variable** is associated with **at most one term**, and
2. **no variable** with an associated **term** occurs within any of the associated **terms**

## Substitution

### Example

The following is a well defined **substitution**

$$\{x/c, y/f(b), z/w\}$$

and the following is **not a substitution**

$$\{x/g(y), y/f(x)\}$$

as the variable  $x$  which is **associated** with term  $g(y)$ , occurs in the term  $f(x)$  **associated** with  $y$ ;

the variable  $y$  occurs in term  $g(y)$  **associated** with variable  $x$

## Unification

Given two positive literals  $P_1 = P(x, y, z)$  and  
 $P_2 = P(c, f(b), w)$

The substitution  $\{x/c, y/f(b), z/w\}$  **unifies**  $P_1$  and  $P_2$ , as  
when **applied** to  $P_1$  produces  $P_2$ , i.e.

$$\begin{aligned} P_1\{x/c, y/f(b), z/w\} &= P(x, y, z)\{x/c, y/f(b), z/w\} \\ &= P(c, f(b), w) = P_2 \end{aligned}$$