Edge Detection Via Smoothing and Laplacian

We smooth to minimize noise effects and then we enhance. This leads to the Lapacianof-the-Gaussian (LOG) operator.

Basic Idea:

- (1) Smooth image through convolution with a Gaussian-shaped kernel to minimize noise.
- (2) Following Gaussian smoothing, Laplacian operator is applied.

(a) Take 1D function of the form $f(x) = -2u_{-1}(x) + 1$ Unit step

(b) Convolve this with a 1D Gaussian smoothing function, g(x), of the form $g(x) = (1/\sigma\sqrt{2\pi}) \exp(-x^2/2\sigma^2)$

which yields the blurred 1D image $f_2(x)$,

$$f_2(x) = 1 - 2 \int_{-\infty}^{x} (\sigma \sqrt{2\pi})^{-1} \exp(-t^2/2\sigma^2) dt$$

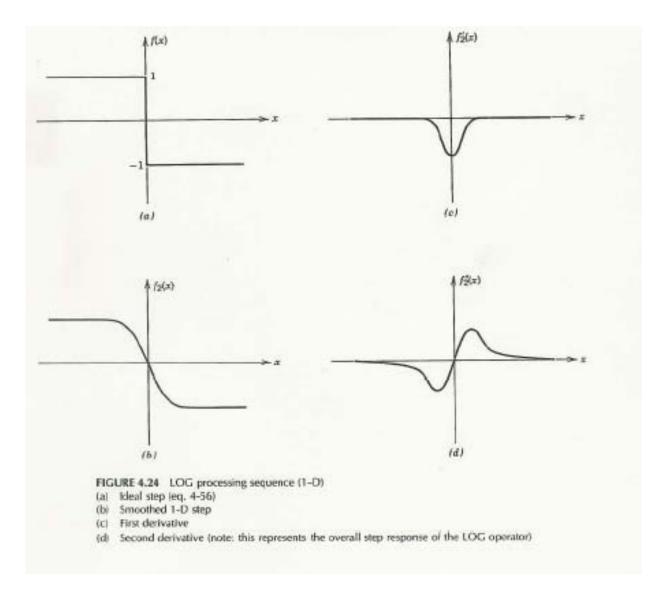
(c) Take the second derivative of $f_2(x)$:

$$f_2''(x) = \left(\frac{2x}{\sigma^3}\sqrt{2\pi}\right) \exp\left(-\frac{x^2}{2\sigma^2}\right)$$

This has zero crossing at x = 0.

 $f_2''(x)$ is the step response of LOG operator.





2D Gaussian smoothing operator in (x, y) coordinates is

$$G_{\sigma}(x,y) = \frac{1}{\sqrt{2\pi}\sigma^2} \exp\left(\frac{-(x^2+y^2)}{2\sigma^2}\right)$$

 $G_{g}(x, y)$ is circularly symmetric and the smoothing effect may be controlled through σ . $\sigma \to \infty$, more smoothing.

Set
$$f_{\sigma}(x, y, \theta) = f(x, y) * G_{\sigma}(x, y)$$
.

Since operator is circulary symmetric many times use a polar representation $G_{\sigma}(r)$ where $r = (x^2 + y^2)^{1/2}$

Note spatial extent of operator varies with σ . Now we mimic one-variable case:

$$f_{edge}(x, y) = \Delta(G_{\sigma}(x, y)^{*} f(x, y))$$

edge-
enhanced
image
$$= (\Delta G_{\sigma}(x, y))^{*} f(x, y)$$

$$\Delta G_{\sigma}(r) = \frac{1}{\pi \sigma^4} \left(\frac{r^2}{2\sigma^2} - 1 \right) \exp\left(\frac{-r^2}{2\sigma^2} \right)$$

To find edges, set

$$f_{edge}(x, y) = 0$$

 $\Delta G_{\sigma}(r)$ looks like an inverted Mexican sombrero. Called the *Sombrero function*.