For each of the four types of linked lists in the following table, what is the asymptotic worst-case running time for each dynamic-set operation listed?

<table>
<thead>
<tr>
<th></th>
<th>singly unsorted</th>
<th>singly sorted</th>
<th>doubly unsorted</th>
<th>doubly sorted</th>
</tr>
</thead>
<tbody>
<tr>
<td>Search($L, k$)</td>
<td>$O(N)$</td>
<td>$O(N)$</td>
<td>$O(N)$</td>
<td>$O(N)$-</td>
</tr>
<tr>
<td>Insert($L, x$)</td>
<td>$O(1)$</td>
<td>$O(N)$</td>
<td>$O(1)$</td>
<td>$O(N)$-</td>
</tr>
<tr>
<td>Delete($L, x$)</td>
<td>$O(N)^*$</td>
<td>$O(N)^*$</td>
<td>$O(1)$</td>
<td>$O(1)$</td>
</tr>
<tr>
<td>Successor($L, x$)</td>
<td>$O(N)$</td>
<td>$O(1)$</td>
<td>$O(N)$</td>
<td>$O(1)$</td>
</tr>
<tr>
<td>Predecessor($L, x$)</td>
<td>$O(N)$</td>
<td>$O(N)$</td>
<td>$O(N)$</td>
<td>$O(1)$</td>
</tr>
<tr>
<td>Minimum($L$)</td>
<td>$O(N)$</td>
<td>$O(1)$+</td>
<td>$O(N)$</td>
<td>$O(1)$+</td>
</tr>
<tr>
<td>Maximum($L$)</td>
<td>$O(N)$</td>
<td>$O(N)$</td>
<td>$O(N)$</td>
<td>$O(1)$</td>
</tr>
</tbody>
</table>

- I need a pointer to the predecessor! (*)
- I need a pointer to the tail! (+)
- Only bottlenecks in otherwise perfect dictionary! (-)
Binary Search Trees

“I think that I shall never see
a poem as lovely as a tree Poem’s
are wrote by fools like me but only
G-d can make a tree “
– Joyce Kilmer

Binary search trees provide a data structure which efficiently supports all six dictionary operations. A binary tree is a rooted tree where each node contains at most two children. Each child can be identified as either a left or right child.
A binary tree can be implemented where each node has left and right pointer fields, an (optional) parent pointer, and a data field.
A binary search tree labels each node in a binary tree with a single key such that for any node $x$, and nodes in the left subtree of $x$ have keys $\leq x$ and all nodes in the right subtree of $x$ have key’s $\geq x$. 
Left: A binary search tree. Right: A heap but not a binary search tree.
The search tree labeling enables us to find where any key is.
Start at the root - if that is not the one we want, search either left or right depending upon whether what we want is $\leq$ or $\geq$ then the root.
Searching in a Binary Tree

Dictionary search operations are easy in binary trees ... 

TREE-SEARCH(x, k)

if \((x = NIL) \text{ and } (k = \text{key}[x])\)

then return x

if \((k < \text{key}[x])\)

then return TREE-SEARCH(\text{left}[x], k)

else return TREE-SEARCH(\text{right}[x], k)

The algorithm works because both the left and right subtrees of a binary search tree are binary search trees – recursive structure, recursive algorithm. 

This takes time proportional to the height of the tree, \(O(h)\).
Maximum and Minimum

Where are the maximum and minimum elements in a binary tree?

TREE-MAXIMUM(X)

while \( \text{right}[x] \neq \text{NIL} \)
    do \( x = \text{right}[x] \)
return x

TREE-MINIMUM(x)
    while left[x] ≠ NIL
        do x = left[x]
    return x

Both take time proportional to the height of the tree, $O(h)$. 
Where is the predecessor?

Where is the predecessor of a node in a tree, assuming all keys are distinct?
If $X$ has two children, its predecessor is the maximum value in its left subtree and its successor the minimum value in its right subtree.
What if a node doesn’t have children?

If it does not have a left child, a node’s predecessor is its first left ancestor.
The proof of correctness comes from looking at the in-order traversal of the tree.
Tree-Successor$(x)$

if $\text{right}[x] \neq NIL$

then return Tree-Minimum$(\text{right}[x])$

$y \leftarrow p[x]$

while $(y \neq NIL)$ and $(x = \text{right}[y])$

do $x \leftarrow y$

$y \leftarrow p[y]$

return $y$

Tree predecessor/successor both run in time proportional to the height of the tree.
In-Order Traversal

Inorder-Tree-walk($x$)
if \( x \not= NIL \)
then Inorder-Tree-Walk(\( left[x] \))
    print \( key[x] \)
    Inorder-Tree-walk(\( right[x] \))

A-B-C-D-E-F-G-H
Tree Insertion

Do a binary search to find where it should be, then replace the termination NIL pointer with the new item.

Tree-insert($T$, $z$)

\begin{align*}
y &= \text{NIL} \\
x &= \text{root}[T] \\
\text{while } x \neq \text{NIL} & \text{ do } y = x
\end{align*}
if \( key[z] < key[x] \)
    then \( x = left[x] \)
else \( x = right[x] \)

\( p[z] \leftarrow y \)

if \( y = \text{NIL} \)
    then \( root[T] \leftarrow z \)
else if \( key[z] < key[y] \)
    then \( left[y] \leftarrow z \)
    else \( right[y] \leftarrow z \)

\( y \) is maintained as the parent of \( x \), since \( x \) eventually becomes \( \text{NIL} \).

The final test establishes whether the \( \text{NIL} \) was a left or right
turn from $y$.
Insertion takes time proportional to the height of the tree, $O(h)$. 
Tree Deletion

Deletion is somewhat more tricky than insertion, because the node to die may not be a leaf, and thus effect other nodes. Case (a), where the node is a leaf, is simple - just NIL out the parents child pointer. Case (b), where a node has one child, the doomed node can just be cut out. Case (c), relabel the node as its successor (which has at most one child when z has two children!) and delete the successor! This implementation of deletion assumes parent pointers to make the code nicer, but if you had to save space they could be dispensed with by keeping the pointers on the search path stored in a stack.
Tree-Delete($T$, $z$)

if ($\text{left}[z] = NIL$) or ($\text{right}[z] = NIL$)
    then $y \leftarrow z$
else $y \leftarrow \text{Tree-Successor}(z)$
if $\text{left}[y] \neq NIL$
    then $x \leftarrow \text{left}[y]$
else $x \leftarrow \text{right}[y]$
if $x \neq NIL$
    then $p[x] \leftarrow p[y]$
if $p[y] = NIL$
    then $\text{root}[T] \leftarrow x$
else if ($y = \text{left}[p[y]]$)
    then $\text{left}[p[y]] \leftarrow x$
else $\text{right}[p[y]] \leftarrow x$
if \((y <> z)\)
  then \(key[z] \leftarrow key[y]\)
  /* If \(y\) has other fields, copy them, too. */
return \(y\)

Lines 1-3 determine which node \(y\) is physically removed. Lines 4-6 identify \(x\) as the non-nil decendant, if any. Lines 7-8 give \(x\) a new parent. Lines 9-10 modify the root node, if necessary. Lines 11-13 reattach the subtree, if necessary. Lines 14-16 if the removed node is deleted, copy. Conclusion: deletion takes time proportional to the height of the tree.
Balanced Search Trees

All six of our dictionary operations, when implemented with binary search trees, take $O(h)$, where $h$ is the height of the tree.

The best height we could hope to get is $\lg n$, if the tree was perfectly balanced, since

$$\sum_{i=0}^{\lfloor \lg n \rfloor} 2^i \approx n$$

But if we get unlucky with our order of insertion or deletion, we could get linear height!

```
insert(a)
insert(b)
insert(c)
insert(d)
```
In fact, random search trees on average have $\Theta(\lg N)$ height, but we are worried about worst case height. We can’t easily use randomization - Why?
Perfectly Balanced Trees

Perfectly balanced trees require a lot of work to maintain:

If we insert the key 1, we must move every single node in the tree to rebalance it, taking $\Theta(n)$ time.
Therefore, when we talk about ”balanced” trees, we mean trees whose height is $O(lg \, n)$, so all dictionary operations (insert, delete, search, min/max, successor/predecessor) take $O(lg \, n)$ time.

*Red-Black trees* are binary search trees where each node is assigned a color, where the coloring scheme helps us maintain the height as $\Theta(lg \, n)$. 
Red-Black Tree Definition

Red-black trees have the following properties:

1. Every node is colored either red or black.
2. Every leaf (NIL pointer) is black.
3. If a node is red then both its children are black.
4. Every single path from a node to a descendant leaf contains the same number of black nodes.
What does this mean?

If the root of a red-black tree is black can we just color it red? No! For one of its children might be red.

If an arbitrary node is red can we color it black? No! Because now all nodes may not have the same black height.

What tree maximizes the number of nodes in a tree of black
What does a red-black tree with two real nodes look like?

Not (1) - consecutive reds  Not (2), (4) - Non-Uniform black
height
Red-Black Tree Height

Lemma: A red-black tree with \( n \) internal nodes has height at most \( 2 \lg(n + 1) \).

Proof: Our strategy; first we bound the number of nodes in any subtree, then we bound the height of any subtree.

We claim that any subtree rooted at \( x \) has at least \( 2^{bh(x)} - 1 \) internal nodes, where \( bh(x) \) is the black height of node \( x \).

Proof, by induction:

\[
bh(x) = 0 \rightarrow x \text{ is a leaf, } \rightarrow 2^0 - 1 = 0
\]

Now assume it is true for all tree with black height < \( bh(x) \).

If \( x \) is black, both subtrees have black height \( bh(x) - 1 \). If \( x \) is red, the subtrees have black height \( bh(x) \).
Therefore, the number of internal nodes in any subtree is

\[ n \geq 2^{bh(x)-1} - 1 + 2^{bh(x)-1} - 1 + 1 \geq 2^{bh(x)} - 1 \]
Now, let $h$ be the height of our red-black tree. At least half the nodes on any single path from root to leaf must be black if we ignore the root. Thus $bh(x) \geq h/2$ and $n \geq 2^{h/2} - 1$, so $n + 1 \geq 2^{h/2}$. This implies that $\lg(n + 1) \geq h/2$, so $h \leq 2\lg(n + 1)$.

Therefore red-black trees have height at most twice optimal. We have a balanced search tree if we can maintain the red-black tree structure under insertion and deletion.